

### 3.5.4. Two simple averaging models for decomposition.

$\mathbf{x} = [x_1, \dots, x_n]^T$  ... uniform sample vector of the time series  
 $X = \{X_t | t \in \mathbb{Z}\}$   
 $\mathbf{e} = [e_1, \dots, e_n]^T$  ... random errors  
 $t \in \{1, 2, \dots, n\}$

We are assuming both models:

- additive:  $X_t = Tr_t + Sz_t + C_t + E_t$  (AM)

or

- multiplicative:  $X_t = Tr_t Sz_t C_t E_t$  (MM).

Let  $d$  be the period length of  $Sz_t$ , and  $n = md$ . We introduce a matrix  $m \times d$

$$X = \begin{bmatrix} x_1 & \dots & x_k & \dots & x_d \\ x_{d+1} & \dots & x_{d+k} & \dots & x_{2d} \\ \vdots & \dots & \vdots & \dots & \vdots \end{bmatrix} = [x_{j,k}],$$

where  $x_{j,k} = x_{(j-1)d+k}$  (e.g.  $j$ =year,  $k$ =month).

Let us denote as  $\text{vec}$  the operator rearranging columns of a matrix downwards into one column vector. Then we can write  $\mathbf{x} = \text{vec}(X^T)$ .

MATLAB:  $X = \text{reshape}(\mathbf{x}, d, m)$ .

The  $j$ -row  $X(j, :)$  stands for samples from  $j$ -th cycle of  $Sz_t$  including  $Tr_t, C_t$  and  $E_t$ .

The  $k$ -th column  $X(:, k)$  gathers samples which are at  $k$ -th position within each cycle, again including all components  $Tr_t, C_t$  and  $E_t$ .

Let  $E = [e_{j,k}]$  be the matrix of errors defined alike.

The seasonal component  $Sz_t$  is fully determined by its values in one cycle  $\mathbf{s} := (s_1, \dots, s_d) := (Sz_1, \dots, Sz_d)$  with mean  $\bar{s} := \frac{s_1 + \dots + s_d}{d}$  satisfying:

$$\bar{s} = \begin{cases} 0 & \text{v AM} \\ 1 & \text{v MM} \end{cases} \quad (3.5.2)$$

We are going to find estimates  $\hat{s}_k$  fulfilling (3.5.2).

### 3.5.4.1. The small trend method [MATLAB: `szsmtf`]

Assumptions:

$\overline{Tr}_t + C_t$ , or  $Tr_t C_t$  should be approximately constant within each cycle of  $Sz_t$ :

$$\left. \begin{array}{l} \text{AM: } x_{j,k} - s_k - e_{j,k} = Tr_t + C_t \approx m_j \\ \text{MM: } x_{j,k} / (s_k e_{j,k}) = Tr_t C_t \approx m_j \end{array} \right\} \text{ in } j\text{-th period, } t = (j-1)d + k.$$

Algorithm:

(1)  $\hat{m}_j = \frac{1}{d} \sum_{k=1}^d x_{j,k}$  ... estimate of  $m_j$  for  $j = 1, \dots, m$ .

(2) for  $k = 1, \dots, d$  we compute:

$$\text{AM: } \hat{s}_k = \frac{1}{m} \sum_{j=1}^m \underbrace{(x_{j,k} - \hat{m}_j)}_{\approx s_k + e_{j,k}}$$

$$\text{MM: } \hat{s}_k = \frac{1}{m} \sum_{j=1}^m \underbrace{x_{j,k} / \hat{m}_j}_{\approx s_k e_{j,k}}$$

It is easy to see that these estimates fulfil (3.5.2):

$$\begin{aligned} \text{AM: } \overline{\hat{s}} &= \frac{1}{d} \sum_{k=1}^d \left( \frac{1}{m} \sum_{j=1}^m (x_{j,k} - \hat{m}_j) \right) \\ &= \frac{1}{m} \sum_{j=1}^m \left( \underbrace{\frac{1}{d} \sum_{k=1}^d x_{j,k}}_{\hat{m}_j} - \underbrace{\frac{1}{d} \sum_{k=1}^d \hat{m}_j}_{\hat{m}_j} \right) = 0 \end{aligned}$$

$$\begin{aligned} \text{MM: } \overline{\hat{s}} &= \frac{1}{d} \sum_{k=1}^d \left( \frac{1}{m} \sum_{j=1}^m \frac{x_{j,k}}{\hat{m}_j} \right) \\ &= \frac{1}{m} \sum_{j=1}^m \frac{1}{\hat{m}_j} \underbrace{\frac{1}{d} \sum_{k=1}^d x_{j,k}}_{\hat{m}_j} = \frac{1}{m} m = 1. \end{aligned}$$

To be continued with the steps of 3.5.4.3.

### 3.5.4.2. Moving average method [MATLAB: szma]

We introduce vector  $\mathbf{w} = (w_{-q}, \dots, w_q)^T$  of equal weights for the common moving average filter:

$$\begin{aligned} \mathbf{w} &= \frac{1}{d} \underbrace{(1, 1, \dots, 1)}_{(2q+1) \times}^T && \text{for odd } d = 2q + 1, \\ \mathbf{w} &= \frac{1}{d} \underbrace{(1/2, 1, \dots, 1, 1/2)}_{(2q+1) \times}^T && \text{for even } d = 2q. \end{aligned}$$

We start with the moving average operation:

$$\widehat{m}_t = \begin{cases} \sum_{\tau=-q}^q w_\tau x_{t+\tau} & \text{for } q+1 \leq t \leq n-q, \\ x_t & \text{for } 1 \leq t \leq q \text{ or } n-q+1 \leq t \leq n. \end{cases}$$

By the construction of weights, exactly the whole seasonal cycle is being averaged at each position of vector  $\mathbf{w}$ . In addition to suppressing the noise component  $e_t$ , this averaging eliminates the seasonal component  $Sz_t$  as well due to its zero/unit mean in the AM/MM layout.

That is why the the following assumptions are justified:

Assumptions:

$$\left. \begin{aligned} \text{AM: } x_t - Sz_t - e_t &= Tr_t + C_t \approx \widehat{m}_t \\ \text{MM: } x_t / (Sz_t e_t) &= Tr_t C_t \approx \widehat{m}_t \end{aligned} \right\} \text{ for } q+1 \leq t \leq n-q.$$

Algorithm:

- (1) After having the vector of values smoothed by the moving average operation we rearrange it into a matrix of size  $m \times d$  with cycles row-by-row, following the analogy with  $\mathbf{x}$ :  
 $\widehat{\mathbf{m}} = (\widehat{m}_1, \dots, \widehat{m}_n)^T =: \text{vec}(\widehat{M}^T)$ , where  $\widehat{M} =: [\widehat{m}_{j,k}]$ .  
Then  $X - \widehat{M}$  in AM, or  $X / \widehat{M} = [x_{j,k} / \widehat{m}_{j,k}]$  in MM, have the structure shown below, where there are  $q$  zeros, or ones at the beginning of the first, and at the end of the last cycle.

For odd  $d$ :

$$X - \widehat{M} = \begin{bmatrix} 0 & \dots & 0 & \bullet & \bullet & \dots & \bullet \\ \vdots & & & & & \vdots & \\ \bullet & \dots & \bullet & \bullet & 0 & \dots & 0 \end{bmatrix},$$

or

$$X./\widehat{M} = \begin{bmatrix} 1 & \dots & 1 & \bullet & \bullet & \dots & \bullet \\ \vdots & & & & & \vdots & \\ \bullet & \dots & \bullet & \bullet & 1 & \dots & 1 \end{bmatrix}.$$

For even  $d$ :

$$X - \widehat{M} = \begin{bmatrix} 0 & \dots & 0 & \bullet & \dots & \bullet \\ \vdots & & & & \vdots & \\ \bullet & \dots & \bullet & 0 & \dots & 0 \end{bmatrix},$$

or

$$X./\widehat{M} = \begin{bmatrix} 1 & \dots & 1 & \bullet & \dots & \bullet \\ \vdots & & & & \vdots & \\ \bullet & \dots & \bullet & 1 & \dots & 1 \end{bmatrix}.$$

(2) For  $k = 1, \dots, d$  is computed:

$$\text{in AM: } \tilde{s}_k = \frac{1}{m - \delta_k} \sum_{j=1}^m \underbrace{(x_{j,k} - \widehat{m}_{j,k})}_{\approx s_k + e_{j,k}},$$

$$\text{in MM: } \tilde{s}_k = \frac{1}{m - \delta_k} [(\sum_{j=1}^m \underbrace{x_{j,k} / \widehat{m}_{j,k}}_{\approx s_k e_{j,k}}) - \delta_k].$$

$$\text{where } \delta_k = \begin{cases} 0 & \text{for } k = \frac{d+1}{2} \text{ (with odd } d \text{ and } k = q+1) \\ 1 & \text{otherwise} \end{cases}.$$

(3)  $\bar{s} = \frac{1}{d} \sum_{k=1}^d \tilde{s}_k$ .

(4) We have to center the estimates to assure the validity of (3.5.2):

$$\widehat{s}_k = \tilde{s}_k - \bar{s} \text{ in AM, or } \widehat{s}_k = \tilde{s}_k / \bar{s} \text{ in MM for } k = 1, \dots, d.$$

Again we continue with the steps of 3.5.4.3.

### 3.5.4.3. The separation of $Tr_t$ and $Sz_t$

- (5) Periodization:  $\widehat{S}_{z_{k+jd}} = \widehat{s}_k$  for  $k = 1, \dots, d$  and  $j = 0, 1, \dots, m-1$ .
- (6) Separating the seasonal component  $Sz_t$ :  
 $y_t := x_t - \widehat{S}_{z_t} \approx Tr_t + C_t + e_t$  in AM, or  $y_t := x_t / \widehat{S}_{z_t} \approx Tr_t C_t e_t$  in MM for  $t = 1, \dots, n$ .
- (7) In  $y_t$  the component  $Tr_t + C_t$ , or  $Tr_t C_t$  of  $y_t$  (possibly after logarithmic transformation in MM) is estimated using appropriate method (e.g. that of section 3.5.1 or 3.5.2). Just only trend may be estimated putting  $q = 0$  in 3.5.1 or using smoothing techniques described in next sections, and then individually separate the cyclic component  $C_t$ :
- (8) Separating the cyclic component  $C_t$ :  
 $C_t + e_t \approx y_t - \widehat{Tr}_t$  in AM, or  $C_t e_t \approx y_t / \widehat{Tr}_t$  in MM.
- (9) Analyzing periodic components of  $C_t + e_t$   
or log-transformed  $C_t e_t$  in MM, using periodogram and periodicity tests of 3.4.3. Now these tests have chance to be sensitive to harmonics of the weak cyclic component, which is no more dominated by the presence the other components. Step (7) may be then repeated to obtain final decomposition of  $Tr_t$  and  $C_t$  with improved model for  $C_t$ .

### 3.5.4.4. Eliminating $Sz_t$ by differencing at lag $d$ (see 3.5.3(1)).

#### Assumptions:

$x_t = Sz_t + m_t + e_t$ , where  $m_t = Tr_t + C_t$ , and the period length of  $C_t$  is significantly longer than that of  $Sz_t$ .

#### Algorithm:

- (1)  $y_t := x_t - x_{t-d} = \underbrace{Sz_t - Sz_{t-d}}_{\approx 0} + \underbrace{m_t - m_{t-d}}_{\tilde{m}_t} + \underbrace{e_t - e_{t-d}}_{\tilde{e}_t}$ ,  
 $t = d+1, \dots, n$ .
- (2) We estimate  $\tilde{m}_t$  as of 3.5.4.3(7)–(9) where, of course,  $\tilde{m}_t = m_t - m_{t-d}$  are to be interpreted like seasonal fluctuations.