## Honors Project 18: Rotation and Quadric Surfaces

If we rotate the xy-coordinate axes counter-clockwise through an angle  $\theta$  about the origin then we obtain a uv-coordinate system which is related to the xy-coordinate system by

$$u = x \cos \theta - y \sin \theta$$
$$v = x \sin \theta + y \cos \theta$$

One reason such rotations are useful is that they allow us to identify the graph of any quadratic equation

$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$

as a conic whose equation in standard form is

$$A'u^{2} + C'v^{2} + D'u + E'v + F' = 0$$

(that is, whose which has no *uv*-term). (The required rotation angle is  $\theta = \frac{1}{2} \operatorname{Cot}^{-1} \frac{A-C}{B}$ .) Thus we may classify the graphs of all second degree equations in x and y as conic sections.

Can the same thing be done for equations of the form

$$Ax^{2} + By^{2} + Cz^{2} + Dxy + Exz + Fyz + Gx + Hy + Iz + J = 0$$

and quadric surfaces in  $\mathbb{R}^3$ ?