#### Definite integral





Eudoxos, Archimedes Newton, Leibniz Riemann





## **Area and Definite Integrals**

УA

Let us determine the area R bounded by the graph of the function  $f(x) \ge 0$  and the axis x on the interval  $\langle a, b \rangle$ . Let's do the following: Divide the interval  $\langle a, b \rangle$  into n partial intervals

$$\langle x_1, x_2 \rangle, \langle x_2, x_3 \rangle, \dots, \langle x_n, x_{n+1} \rangle$$
, where  $a = x_1 < x_2 < \dots, x_n < x_{n+1} = b$ .

The searched area can be estimated using the expression

$$S(R) \approx \sum_{i=1}^{n} S(R_i) = \sum_{i=1}^{n} f(x_i) \cdot (x_{i+1} - x_i)$$

If there is a limit for  $n \to \infty$ , we write that  $S(R) = \int_{a}^{b} f(x) dx$  and we call it a definite integral of f(x) on  $\langle a, b \rangle$ .

Number *a* is called lower limit of the integral, number *b* is called upper limit of the integral. We say that f(x) is integrable on given interval. **Remark:** For the existence of the integral f(x)on  $\langle a, b \rangle$  it is sufficient that the function is continuous here (it can be shown that even a milder assumption is enough)



http://demonstrations.wolfram.com/IntegrationByRiemannSums/ http://demonstrations.wolfram.com/ContinuousFunctionsAreIntegrable/

## **Properties of Definite Integrals**

The concept of a definite integral can be extended to cases where  $a \ge b$ :



if  $\forall x \in \langle a, b \rangle$ :  $f(x) \ge g(x)$  then also  $\int_a^b f(x) dx \ge \int_a^b g(x) dx$ .

**Theorem:** For f(x) and g(x) integrable over  $\langle a, b \rangle$  and arbitrary constants  $\alpha, \beta$ , there exists definite integral of a function  $\alpha f(x) + \beta g(x)$  over  $\langle a, b \rangle$  and:  $\int_{a}^{b} (\alpha f(x) + \beta g(x)) dx = \alpha \int_{a}^{b} f(x) dx + \beta \int_{a}^{b} g(x) dx.$ 

# **Computation of Definite Integral**

**Theorem:** Integral as a function of the upper limit: For f(x) integrable over  $\langle a, b \rangle$  and arbitrary  $x_0 \in \langle a, b \rangle$  is following true: The function  $F(x) := \int_{x_0}^x f(t)dt$  is continuous over  $\langle a, b \rangle$  and in the case of continuity of f(x) we have: F'(x) = f(x) (so, for continuous f(x) is F(x) its antiderivative.) **Theorem:** Newton's formula:

Let f(x) be continuous over  $\langle a, b \rangle$  and F(x) be any of its antiderivatives, then:

 $\int_{a}^{b} f(x) dx = F(b) - F(a),$ 

we also write  $\int_{a}^{b} f(x) dx = [F(x)]_{a}^{b} = F(b) - F(a)$ **Problem:** Find definite integral for f(x) = x + 1, a = 1, b = 3.

Solution: 
$$\int_{1}^{3} (x+1) dx = \left[ \frac{x^2}{2} + x \right]_{1}^{3} = \frac{9}{2} + 3 - (\frac{1}{2} + 1) = 6.$$

**Problem:** Find definite integral for  $f(x) = \sqrt[3]{x}$ , a = 0, b = 1. **Solution:**  $\int_0^1 \sqrt[3]{x} dx = \left[\frac{3x^{\frac{4}{3}}}{4}\right]_0^1 = \frac{3}{4}$ .

http://demonstrations.wolfram.com/IntuitionForTheFundamentalTheoremOfCa lculus/

### Integration methods

Integration by parts in definite integal: If the functions u(x), v(x) have continuous derivatives on  $\langle a, b \rangle$ , then

$$\int_{a}^{b} u'(x) \cdot v(x) \, dx = [u(x) \cdot v(x)]_{a}^{b} - \int_{a}^{b} u(x) \, v'(x) \, dx$$
  
Example:  $\int_{0}^{1} x \ln(x+1) \, dx = \begin{vmatrix} u' = x & v = \ln(x+1) \\ u = \frac{x^{2}}{2} & v' = \frac{1}{x+1} \\ u = \frac{x^{2}}{2(x+1)} \, dx = \frac{1}{2} (\ln 2 - 0) - \int_{0}^{1} \frac{x^{2}+1-2}{2(x+1)} \, dx = \frac{1}{2} \ln 2 - \frac{1}{2} \int_{0}^{1} \left(x - 1 + \frac{1}{x+1}\right) \, dx = \frac{1}{2} \ln 2 - \frac{1}{2} \left[\frac{x^{2}}{2} - x + \ln(x+1)\right]_{0}^{1} = \frac{1}{2} \ln 2 - \frac{1}{4} + \frac{1}{2} - \frac{1}{2} \ln 2 - 0 = \frac{1}{4}$ 

Substitution in definite integration continuous on  $\varphi(\langle a, b \rangle)$ ,  $\int_{a}^{b} f(\varphi(x)) \varphi'(x) dx = \int_{\varphi(a)}^{\varphi(b)} f(u) du$ Substitution in definite integal: If  $u = \varphi(x)$  has continuous derivative on  $\langle a, b \rangle$  and if f(u) is Example:  $\int_{-1}^{0} \frac{x+1}{x^2+2x+3} dx = \frac{1}{2} \int_{-1}^{0} \frac{2x+2}{x^2+2x+3} dx = \begin{vmatrix} u = x^2+2x+3, & u(-1) = 2, \\ du = (2x+2)dx, & u(0) = 3 \end{vmatrix} = \frac{1}{2} \int_{2}^{3} \frac{1}{u} du = \frac{1}{2}$  $\frac{1}{2} [\ln(u)]_2^3 = \frac{1}{2} \ln\left(\frac{3}{2}\right).$ **Comment:** The antiderivative of  $\frac{x+1}{x^2+2x+3}$  is  $\frac{1}{2} \ln(x^2+2x+3)$ . The definite integral can be written as  $\left[\frac{1}{2} \ln(x^2+2x+3)\right]_{-1}^{0}$  that is equivalent to  $\frac{1}{2} [\ln(u)]_{2}^{3}$ . Thus, it is not necessary to substitute back  $u = x^2 + 2x + 3$  in the Newton formula; we can just transform the limits.

#### Improper integral



Infinite interval of integration  $(a = -\infty \text{ or } b = \infty)$ **Definition:** We define  $\int_{a}^{\infty} f(x) dx = \lim_{t \to \infty} \int_{a}^{t} f(x) dx$ , if the limit converges. Otherwise, we say that the integral diverges. We define by analogy

$$\int_{-\infty}^{b} f(x) \, dx = \lim_{t \to -\infty} \int_{t}^{b} f(x) \, dx$$

Example: 
$$\int_{2}^{\infty} \frac{1}{x^{2}} dx = \lim_{t \to \infty} \int_{2}^{t} \frac{1}{x^{2}} dx = \lim_{t \to \infty} \left[ -\frac{1}{x} \right]_{2}^{t} = \lim_{t \to \infty} \left( -\frac{1}{t} \right) + \frac{1}{2} = 0 + \frac{1}{2} = \frac{1}{2}$$

**Definition:** Integral  $\int_{-\infty}^{\infty} f(x) dx$  is said to be convergent, if both integrals  $\int_{-\infty}^{c} f(x) dx$ ,  $\int_{c}^{\infty} f(x) dx$  converge for some  $c \in \mathbb{R}$ . We define

$$\int_{-\infty}^{\infty} f(x)dx = \int_{-\infty}^{c} f(x) dx + \int_{c}^{\infty} f(x) dx$$

$$\begin{aligned} \mathbf{Example:} \int_{-\infty}^{\infty} \frac{1}{x^2 - 2x + 5} \, dx &= \int_{-\infty}^{\infty} \frac{1}{(x - 1)^2 + 4} \, dx = \begin{vmatrix} 2t = x - 1 \\ 2dt = dx \end{vmatrix} = \int_{-\infty}^{\infty} 2\frac{dt}{4t^2 + 4} = \\ \frac{1}{2} \int_{-\infty}^{\infty} \frac{1}{t^2 + 1} \, dt &= \frac{1}{2} \int_{-\infty}^{0} \frac{1}{t^2 + 1} \, dt + \frac{1}{2} \int_{0}^{\infty} \frac{1}{t^2 + 1} \, dt = \frac{1}{2} \begin{bmatrix} arctg(t) \end{bmatrix}_{-\infty}^{0} + \frac{1}{2} \begin{bmatrix} arctg(t) \end{bmatrix}_{0}^{\infty} = \\ \frac{1}{2} \begin{pmatrix} 0 - \begin{pmatrix} -\frac{\pi}{2} \end{pmatrix} \end{pmatrix} + \frac{1}{2} \begin{pmatrix} \frac{\pi}{2} - 0 \end{pmatrix} = \frac{\pi}{2} \end{aligned}$$

# Improper integral

#### Integrals of unbounded functions

**Definition:** For the function f(x) that is unbounded for x approaching to b, but is bounded in an *b* interval (a, t) for any  $t \in (a, b)$ , we define

$$\int_a^b f(x) \, dx = \lim_{t \to b^-} \int_a^t f(x) \, dx \, ,$$

if the limit does exist. Otherwise, we say that the integral diverges. By analogy, it is defined for a function that is not bounded in point a:

$$\int_a^b f(x) \, dx = \lim_{t \to a+} \int_t^b f(x) \, dx.$$

Example: 
$$\int_0^1 1/\sqrt[5]{x} dx = \lim_{t \to 0+} \int_t^1 x^{\frac{-1}{5}} dx = \lim_{t \to 0+} \left[ \frac{5x^{\frac{4}{5}}}{4} \right]_t^1 = \lim_{t \to 0+} \left( \frac{5}{4} - 5\frac{\sqrt[5]{t^4}}{4} \right) = \frac{5}{4} - 0 = \frac{5}{4}.$$

**Comment:** If the function f(x) is not bounded at  $c \in (a, b)$ , we define:

 $\int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{c}^{b} f(x) dx$ , if both integrals on the right-hand side exist. **Problem:** Find  $\int_{0}^{2} \frac{1}{x-1} dx$ .

Wrong solution:  $\int_0^2 \frac{1}{x-1} dx = [\ln|x-1|]_0^2 = \ln 1 - \ln 1 = 0$ 

Correct solution: The function is not defined for x = 1, so  $\int_0^2 \frac{1}{x-1} dx = \int_0^1 \frac{1}{x-1} dx + \int_1^2 \frac{1}{x-1} dx = \lim_{\substack{t \to 1^+ \\ \text{http://demonstrations.wolfram.com/ImproperIntegrals/}} \int_0^2 \frac{1}{x-1} dx = \int_0^1 \frac{1}{x-1} dx + \int_1^2 \frac{1}{x-1} dx + \int_1^2 \frac{1}{x-1} dx = \int_0^1 \frac{1}{x-1} dx + \int_1^2 \frac{1}{x-1} dx +$ 

x

 $\int_{a}^{b} f(x) dx$