

Parameter Identification and Model Ranking of Thomas Networks

CMSB 2012
The Royal Society, London



David Šafránek

Adam Streck, Juraj Kolčák
Masaryk University Brno

Hannes Klarner, Heike Siebert
Freie Universität Berlin

5th October, 2012

Outline

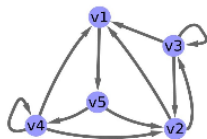
- 1 Motivation and Background
- 2 Proposed Methodology and its Implementation
- 3 Performance Evaluation and Case Studies

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- 2 Proposed Methodology and its Implementation
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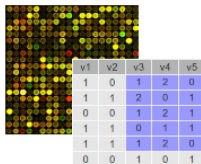
Motivation: Learn More about Regulatory Networks

Gene Regulatory Network



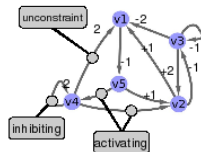
Predicted structure
(databases, literature, ...)

Observations

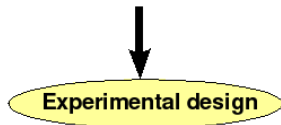


Discrete time series

Hypothesis

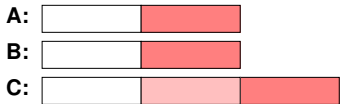
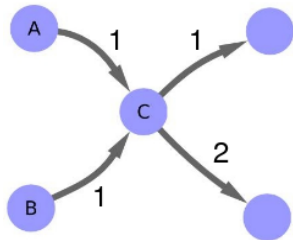


What kind of interactions?



Modeling tools: C. Chaouiya, et al. 2003, GINsim., H. de Jong et al. 2002, GNA.
Data processing: I. Shmulevich, et al. 2002. Binary analysis and optimization-based normalization of gene expression data.; E. Dimitrova, et al. 2010. Discretization of time series data.

From Structure to Dynamics



$$\emptyset \rightarrow 0$$



$$\{A\} \rightarrow 2$$



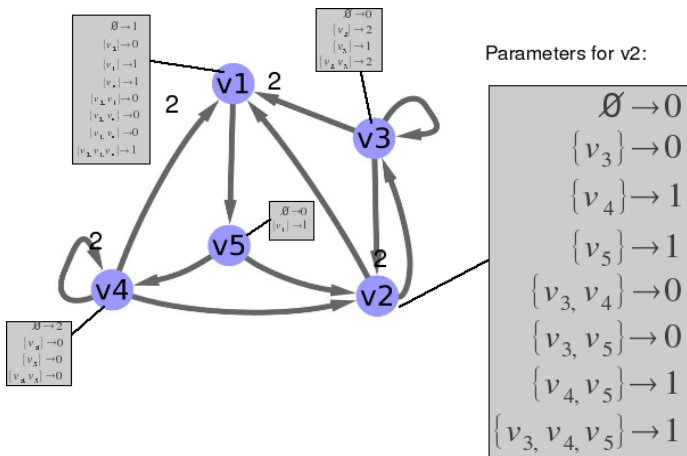
$$\{B\} \rightarrow 2$$



$$\{A, B\} \rightarrow 1$$

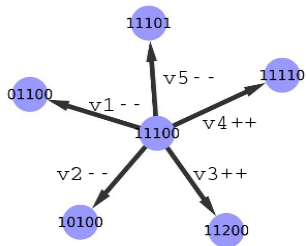
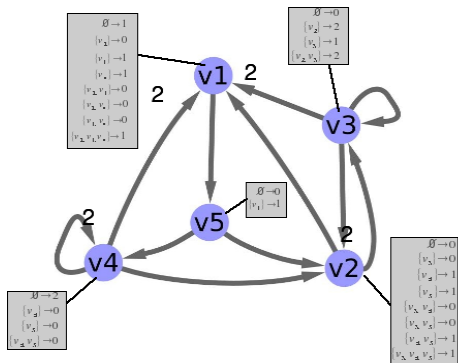
R. Thomas and R. d'Ari, CRC Press 1990. Biological feedback.

Parameterization of Regulatory Networks



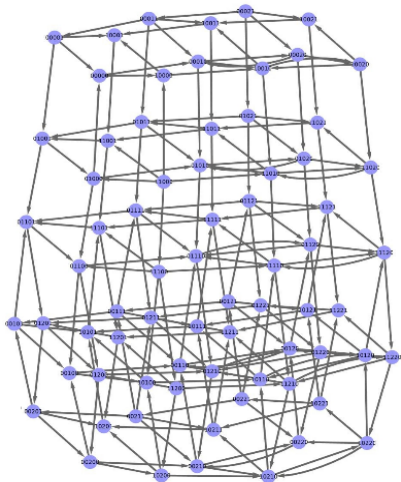
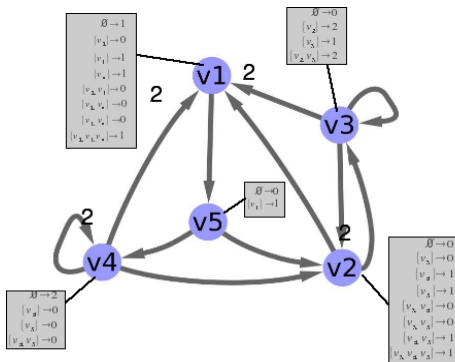
Target values assigned to regulatory contexts for all nodes make a **PARAMETER SET (parameterization)**.

Dynamics as a State Transition Graph



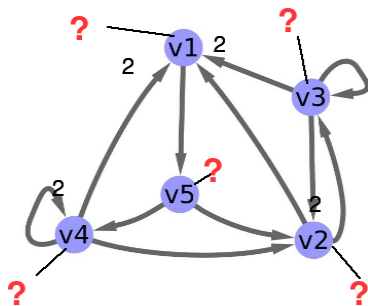
R. Thomas and R. d'Ari, CRC Press 1990. Biological feedback.

Dynamics as a State Transition Graph



R. Thomas and R. d'Ari, CRC Press 1990. Biological feedback.

Parameter Identification Problem

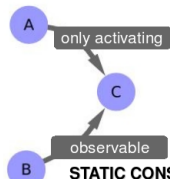


Number of possible parameterizations of a single node is **exponential** w.r.t. the node's in-degree.

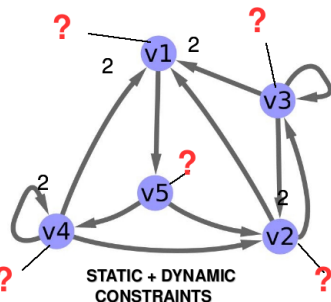
(more precisely w.r.t. the number of regulatory contexts)

Parameter Identification Problem: Solutions

Interaction labels



Corblin 2009

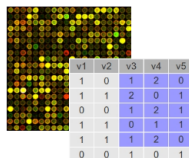


STATIC + DYNAMIC CONSTRAINTS

Batt 2010

Klärner 2011

Time series



DYNAMIC CONSTRAINTS

Bernot 2004

Barnat 2012

G. Bernot et al. in JTB 2004: Application of formal methods to biological regulatory networks: extending Thomas asynchronous logical approach with temporal logic.

Corblin et al. in BioSystems 2009: A declarative constraint-based method for analyzing discrete gene regulation networks.

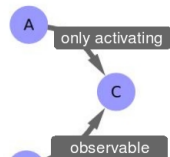
Batt et al. in Bioinf. 2010: Efficient parameter search for qualitative models of regulatory networks using symbolic model checking.

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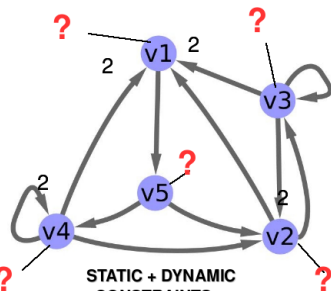
Parameter Identification Problem: Solutions

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STATIC CONSTRAINTS

Corblin 2009

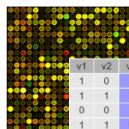


STATIC + DYNAMIC CONSTRAINTS

Batt 2010

Klärner 2011

Time series



| | v1 | v2 | v3 | v4 | v5 |
|---|----|----|----|----|----|
| 1 | 0 | 1 | 2 | 0 | |
| 1 | 1 | 1 | 2 | 0 | 1 |
| 0 | 0 | 1 | 0 | 2 | 1 |
| 1 | 1 | 1 | 0 | 1 | 1 |
| 1 | 1 | 1 | 1 | 2 | 0 |
| 0 | 0 | 0 | 1 | 0 | 1 |

DYNAMIC CONSTRAINTS

Bernot 2004

Barnat 2012

CMSB 2012

+ PARAMETERIZATION CLASSIFICATION

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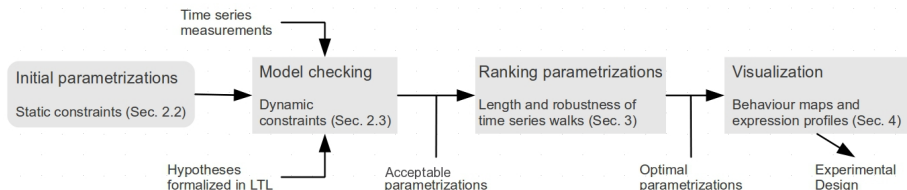
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Our Contribution



- a prototype tool chain:

Parsybone – <https://github.com/sybila/Parsybone.git>

ParameterFilter – <https://github.com/sybila/ParameterFilter.git>

- distributed computation of acceptable parameterizations
- employing witnesses (counterexamples) to rank obtained parameterizations
- visualization of the results (export to Cytoscape)

Time-series Measurement as a Dynamic Constraint

Time-series measurement

| v1 | v2 | v3 | v4 | v5 |
|----|----|----|----|----|
| 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 2 | 2 | 1 |

Encoded in LTL:

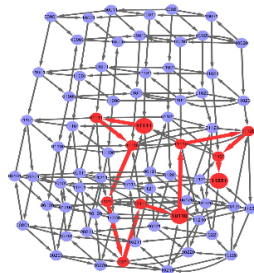
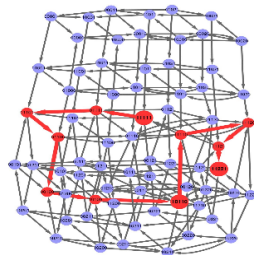
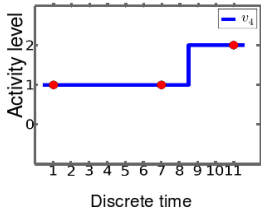
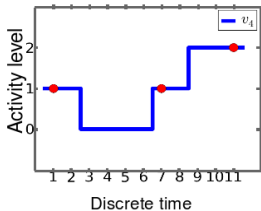
$$\sigma(1) = \bigwedge_{i=1}^5 v_i = 1$$

$$\sigma(2) = \bigwedge_{i \in \{1,2,4\}} v_i = 1 \wedge \bigwedge_{i \in \{2,5\}} v_i = 0$$

$$\sigma(3) = \bigwedge_{i \in \{1,2,5\}} v_i = 1 \wedge \bigwedge_{i \in \{3,4\}} v_i = 2$$

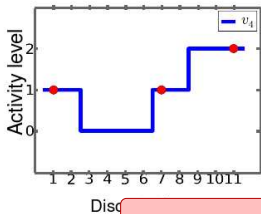
$$\varphi = \sigma(1) \wedge \mathbf{F}(\sigma(2) \wedge \mathbf{F}(\sigma(3)))$$

Expression of v4 along red path

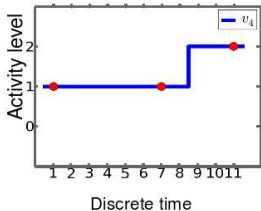


Time-series Measurement as a Dynamic Constraint

Expression of v_4 along red path



time-series walks



Time-series measurement

| v1 | v2 | v3 | v4 | v5 |
|----|----|----|----|----|
| 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 2 | 2 | 1 |

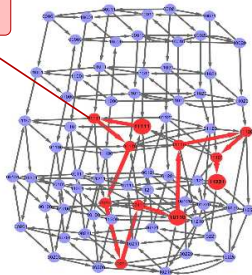
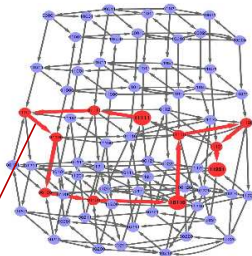
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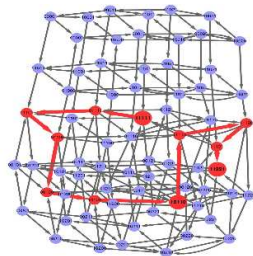
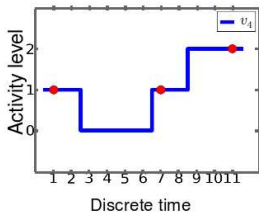
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Time-series Measurement as a Dynamic Constraint

Expression of v4 along red path



Time-series measurement

| v1 | v2 | v3 | v4 | v5 |
|----|----|----|----|----|
| 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 2 | 2 | 1 |

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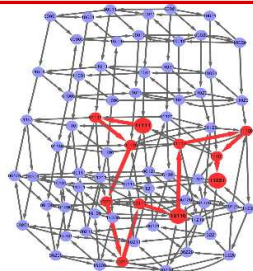
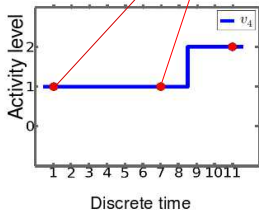
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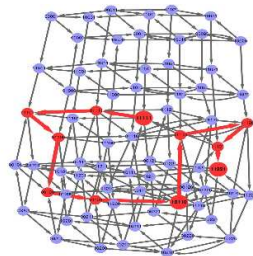
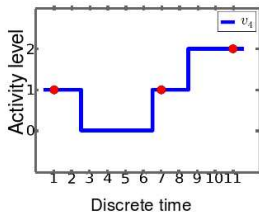
$$\varphi = \sigma(1) \wedge (\sigma(1) \mathbf{U} (\sigma(2) \wedge \mathbf{F}(\sigma(3))))$$

monotonicity between 1st and 2nd measurement



Time-series Measurement as a Dynamic Constraint

Expression of v4 along red path



Time-series measurement

| v1 | v2 | v3 | v4 | v5 |
|----|----|----|----|----|
| ? | 1 | 1 | 1 | ? |
| 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 2 | 2 | 1 |

Encoded in LTL:

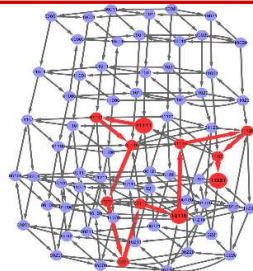
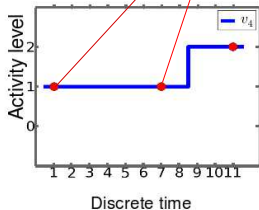
$$\sigma(1) = \bigwedge_{i=2}^4 v_i = 1$$

$$\sigma(2) = \bigwedge_{i \in \{1,2,4\}} v_i = 1 \wedge \bigwedge_{i \in \{2,5\}} v_i = 0$$

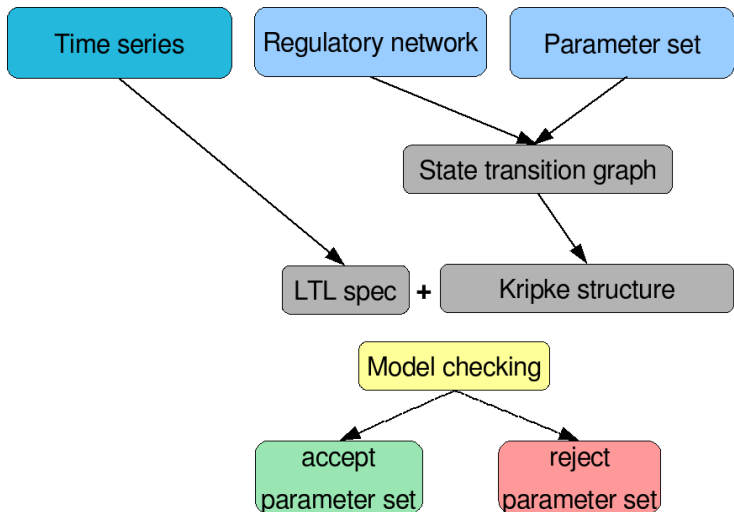
$$\sigma(3) = \bigwedge_{i \in \{1,2,5\}} v_i = 1 \wedge \bigwedge_{i \in \{3,4\}} v_i = 2$$

$$\varphi = \sigma(1) \wedge (\sigma(1) \mathbf{U} (\sigma(2) \wedge \mathbf{F}(\sigma(3))))$$

monotonicity between 1st and 2nd measurement

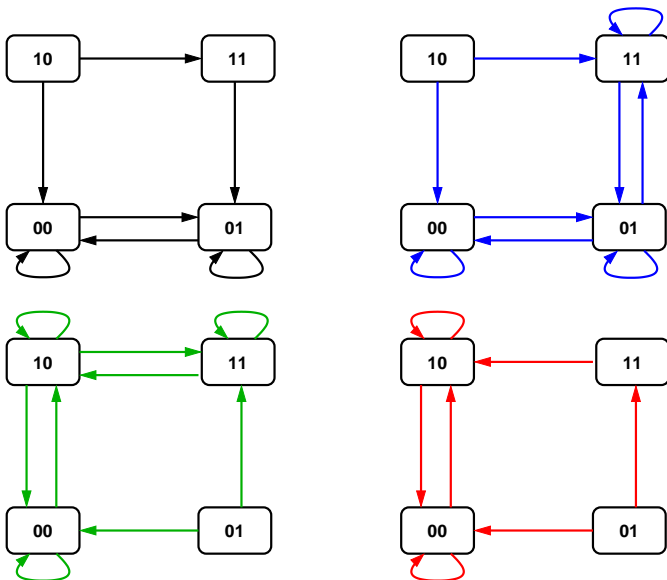


Identifying Parameters by Model Checking

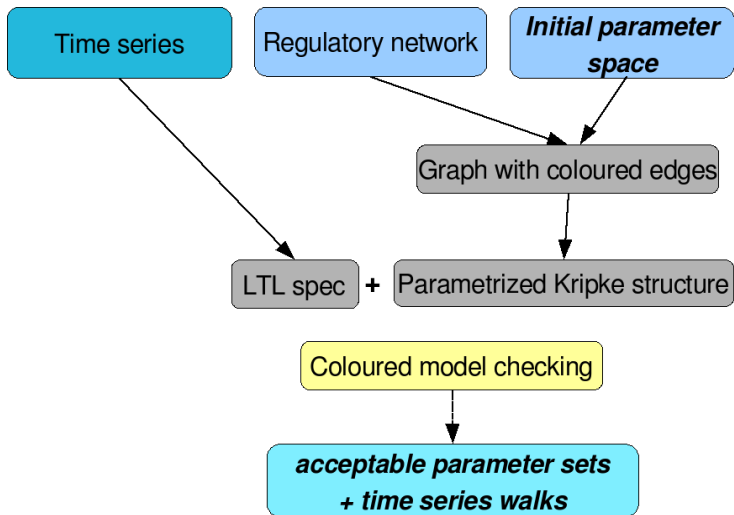


Naive approaches: G. Bernot et al. in JTB 2004; H. Klarner et al. in CMSB 2011

Effect of Parameters on State Transition Graph



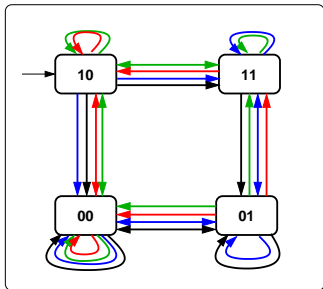
Identifying Parameters by Coloured Model Checking



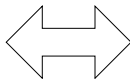
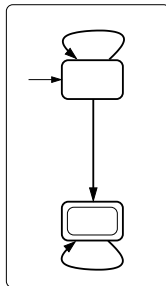
Heuristics: J. Barnat et al. in TCBB 2012; refined in the presented paper

Identifying Parameters by Coloured Model Checking

parameterized Kripke structure of the model



never claim Buchi automaton



$[A=1, B=0] \ \& \ F([A=0, B=0])$

return accepting paths of the product automaton
respective parameter sets are acceptable
we decide on all parameterizations at once

parameter sets acceptable for the dynamic constraint

time-series walks of acceptable parametrizations

Model Checking on Coloured Graphs

Idea

- represent each parameterization by a distinct colour
- find accepting cycles and get colours enabling accepting paths

Procedure

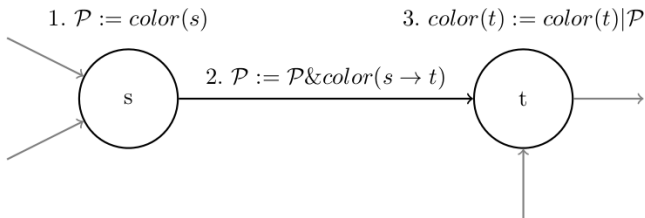
- 1 compute initial mapping of colours to states
 - ⇒ propagate colours through the entire graph (BFS reachability)
 - ⇒ accepting states know all colours by which they are reached
- 2 for each reachable accepting cycle aggregate the valid colours

Model Checking on Coloured Graphs

Implementation

- explicit representation of indexed parameter sets (ordered bit vectors)
- parameter space split to exclusive blocks equal to size of integer type
- each block contains “close” parameter sets
- data-parallel distribution: blocks evenly distributed over the cluster

| ... | P_{i-1} | P_i | P_{i+1} | ... |
|-----|-----------|-------|-----------|-----|
| | | : | | |
| ... | 1 | 0 | 0 | ... |
| ... | 0 | 1 | 0 | ... |
| ... | 0 | 0 | 1 | ... |
| | | : | | |



Parameterization Ranking: Length Cost

- theoretically infinitely many time-series walks
- fix a dynamic constraint and focus on compatible **shortest walks**
 - ▶ penalize unnecessarily higher energy cost
 - ▶ avoid complex model realizations of the constraint
- assign each parameterization its **length cost** – the length of a shortest time-series walk
- consider parameterizations with minimum length cost

Parameterization Ranking: Robustness

- non-deterministic dynamics caused by asynchronicity
- how can we interpret walks with less options to walk off the “optimal path” and miss the expected final state of the time-series?
- the property of the model, but...
 - ▶ another classification of parameterizations

- **local robustness:**

property of a state – $\frac{\text{number of valid successors}}{\text{out degree}}$

- **global robustness:**

property of a walk – product of local robustness over all states of the walk

- **model robustness:**

property of a parameterization – average of global robustness over all time-series walks

Parameterization Ranking: Robustness

- non-deterministic dynamics caused by asynchronicity
- how can we interpret walks with less options to walk off the “optimal path” and miss the expected final state of the time-series?
- the property of the model, but...
 - ▶ another classification of parameterizations
- **local robustness – approximated:**

$$\text{Prob}(x) = \frac{1}{\text{out_degree}(x)}$$

- **global robustness:**
property of a walk – product of local robustness over all states of the walk
- **model robustness:**
property of a parameterization – average of global robustness over all time-series walks

Parameterization Ranking: Overall Procedure

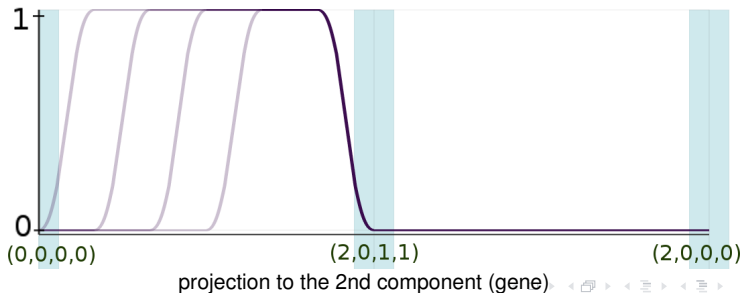
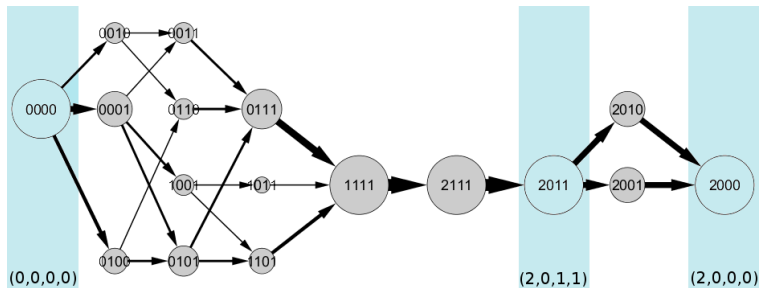
INPUT: regulatory network, initial parameter space, static and dynamic constraints

OUTPUT: subset of the initial parameter space containing optimal parameterizations

- 1 Remove parametrizations violating static constraints
- 2 Compute parameterizations acceptable by dynamic constraints
- 3 Select parametrizations with minimal length cost
- 4 Select parametrizations with maximal robustness

Visualising Results

Behaviour Maps and Expression Profiles

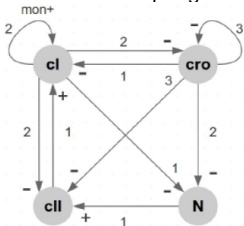


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Scalability Evaluation

GRN of Bacteriophage λ



Lysogenic time-series

| cI | cII | cro | N |
|----|-----|-----|---|
| 0 | 0 | 0 | 0 |
| 2 | 1 | 0 | 1 |
| 2 | 0 | 0 | 0 |

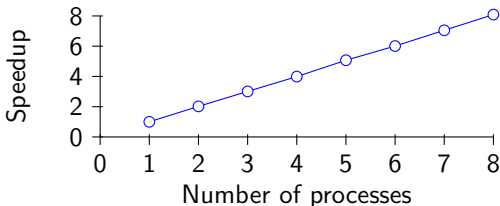
Lytic time-series

| cI | cII | cro | N |
|----|-----|-----|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 2 | 1 |
| 0 | 0 | 2 | 0 |
| 0 | 0 | 3 | 0 |
| 0 | 0 | 2 | 0 |

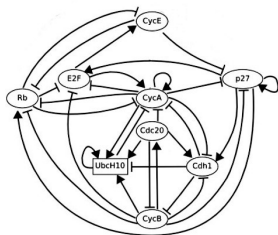
[Thieffry et al. 1995]

- conjunction of both time-series lead to 537 parametrizations
- required memory: $\leq 3\text{MB}$

| Process count | Average runtime |
|---------------|-----------------|
| 1 | 5.315 s |
| 2 | 2.634 s |
| 3 | 1.767 s |
| 4 | 1.332 s |
| 5 | 1.048 s |
| 6 | 0.884 s |
| 7 | 0.754 s |
| 8 | 0.657 s |



Performance Evaluation



GRN of Mammalian Cell Cycle
[Fauré et al. 2006]

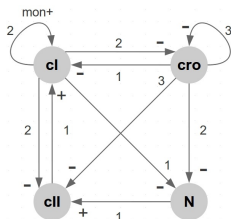
- a time-series with 8 measurements
- $6.8 \cdot 10^8$ initial parametrizations
- $3.1 \cdot 10^8$ acceptable parametrizations computed
- setup: 8 processes running on 2 CPUs with 4 cores each
- required memory: $\leq 15\text{MB}$

| Process ID | Runtime | Result set size | Process ID | Runtime | Result set size |
|------------|---------|-----------------|------------|---------|-----------------|
| 1 | 29.07 h | 38,522,403 | 5 | 29.70 h | 38,523,691 |
| 2 | 31.08 h | 38,521,943 | 6 | 28.81 h | 38,523,255 |
| 3 | 27.22 h | 38,521,656 | 7 | 29.55 h | 38,522,328 |
| 4 | 32.32 h | 38,522,343 | 8 | 28.83 h | 38,523,020 |

Case Studies

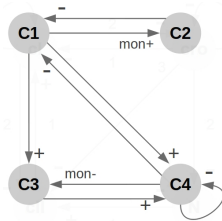


Bacteriophage λ^1



[Thieffry et al. 1995]

Rat neural system²



[Wahde et al. 2001]

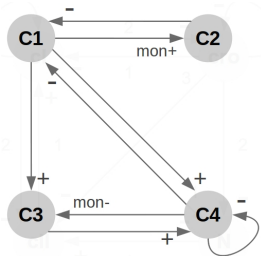
| | | |
|-----------------------|------------------|------------------|
| Init. Parameter Space | $6.9 \cdot 10^9$ | $2.6 \cdot 10^5$ |
| Static Constraints | $8.2 \cdot 10^4$ | 162 |
| Dynamic Constraints | 537 | 108 |
| Length Cost (min) | 28 (length 9) | 108 (length 5) |
| Robustness (max) | 3 (9.7%) | 4 (75%) |

¹ CMSB 2012 Proceedings

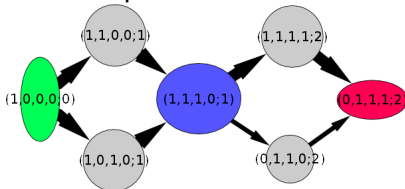
² FI MU Technical Report

Rat Neural System: Inferring New Hypothesis

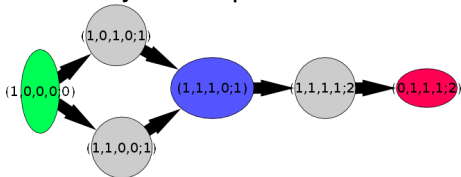
[Wan 1998, Wahde 2001]



Shortest paths



Maximally robust paths



Predicted Hypothesis

Genes in cluster 4 express before the cluster 1 expression starts to degrade.

Conclusions

Achievements

- computational improvement in model checking-based parameter identification for Thomas networks
- ranking procedures for distinguishing the models

Future work

- *vast amount of data generated...what to do next?*
 - ▶ more sophisticated model ranking (biologically relevant criteria)
 - ▶ finding commonalities in models, e.g., for refining static constraints (CMSB 2011)

Thank you for your attention!