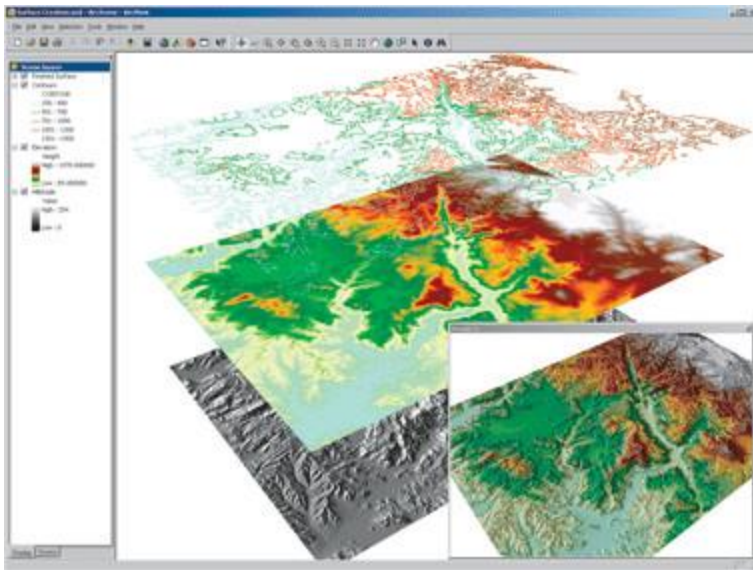
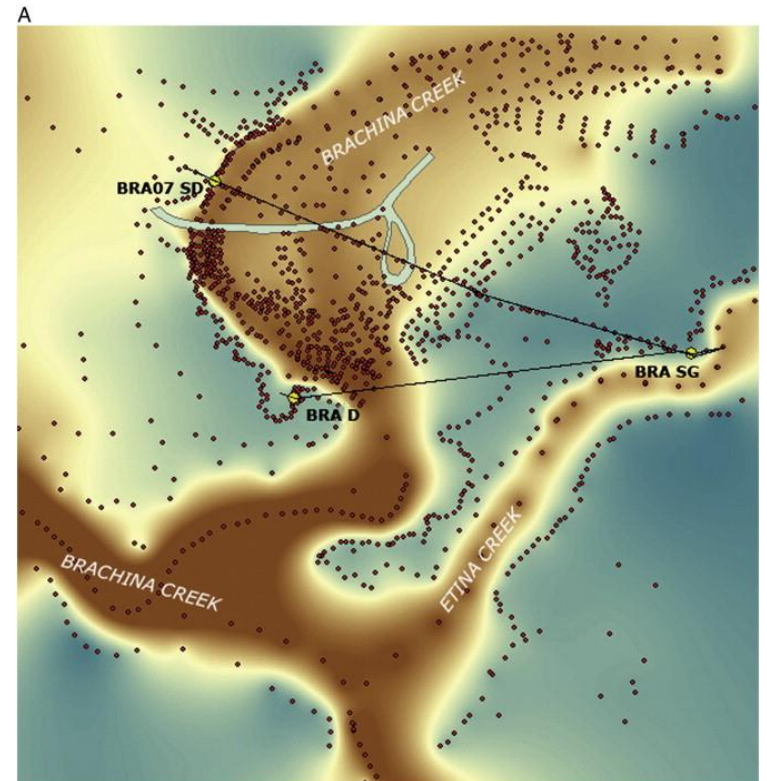


developers.google.com

# 5. Geospatial data visualization



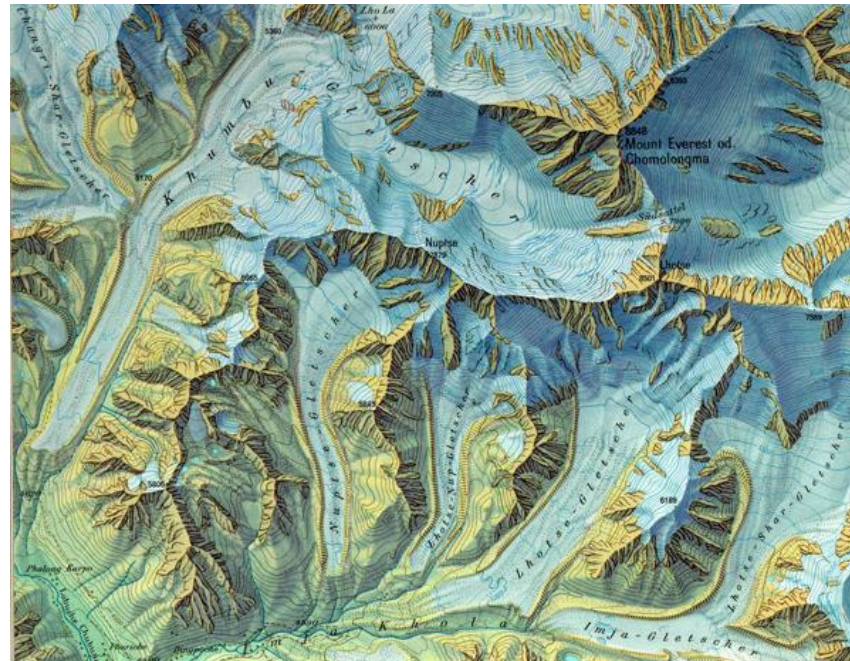
www.esri.fi



www.sciencedirect.com

# Geospatial data

- Describe objects or events of the real world
- Often denoted as **geovisualization**



# Domains of usage

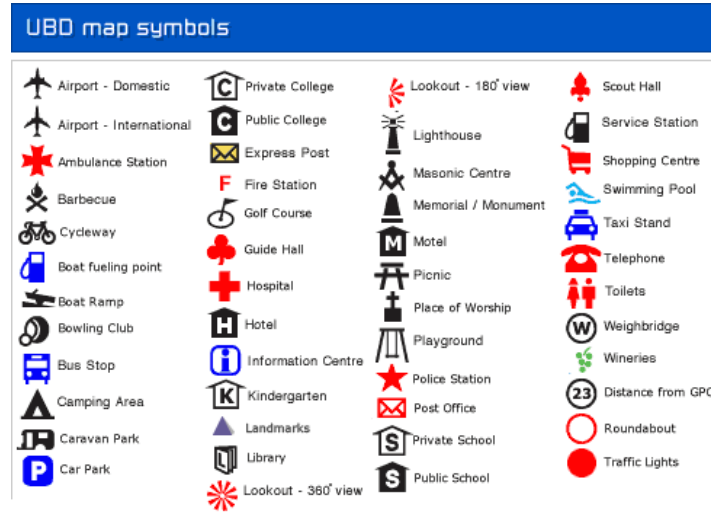
- Climate change
- Level of unemployment
- Level of education
- Analysis of customer's behaviour
- Credit card payments
- Criminality statistics
- ...

# Points, lines, areas

- Maps consist of these three basic types of items
- Spatial events are divided according to their dimension:
  - Point events – 0-dimensional
  - Line events – 1-dimensional
  - Area events – 2-dimensional
  - Surface events – 2,5-dimensional

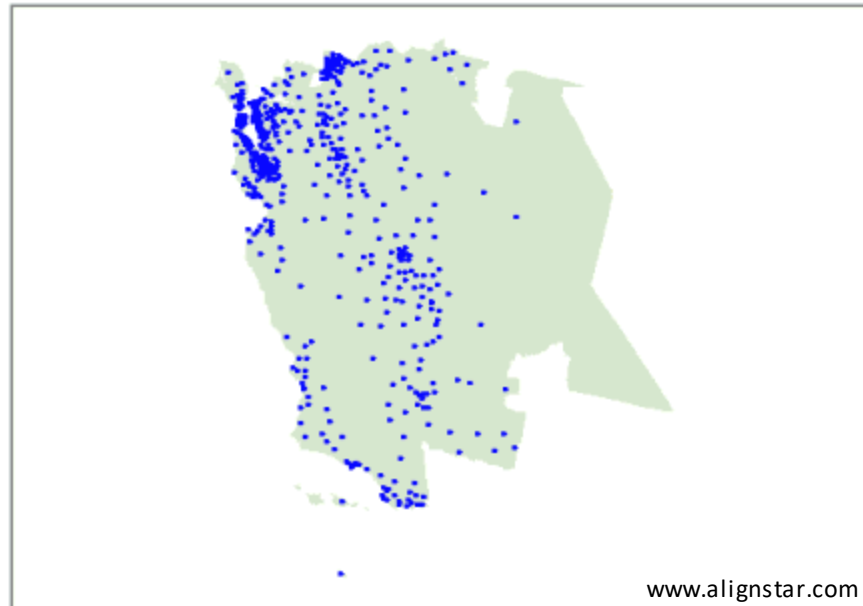
# Types of maps

- Maps of symbols



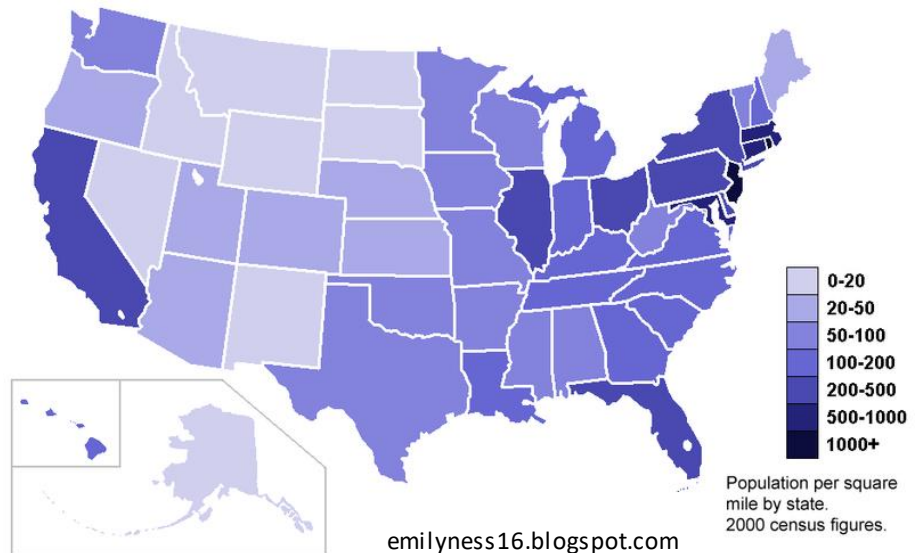
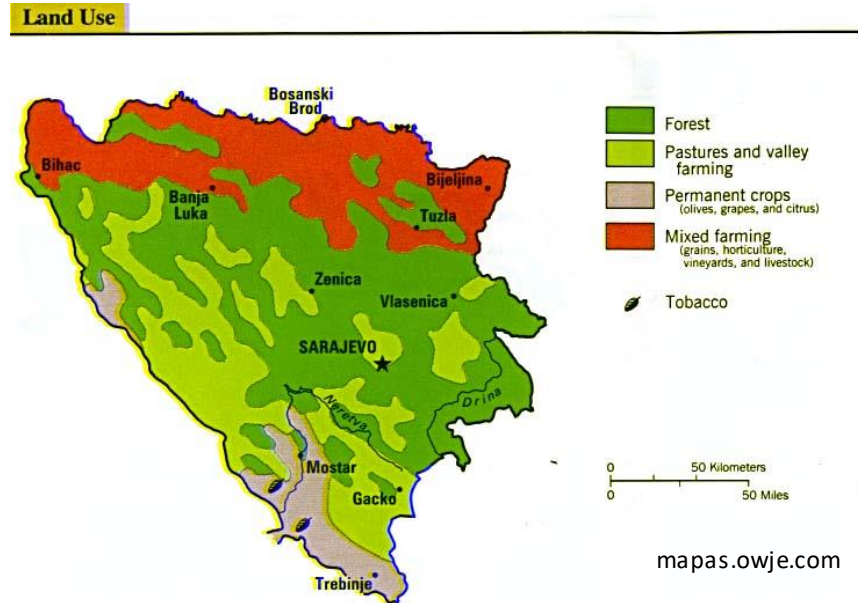
wildernessnavigation.blogspot.com

- Point maps



# Types of maps

- Land use maps
- Choropleth maps



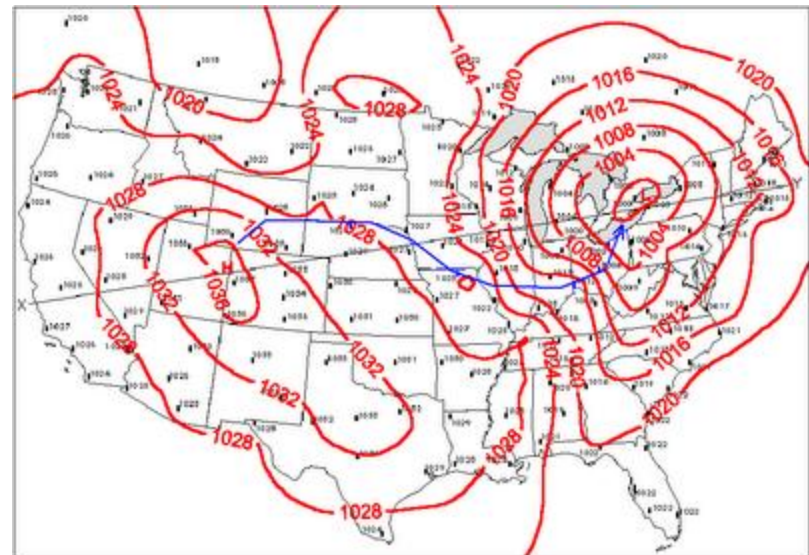
# Types of maps

- Line diagrams



[commons.wikimedia.org](https://commons.wikimedia.org)

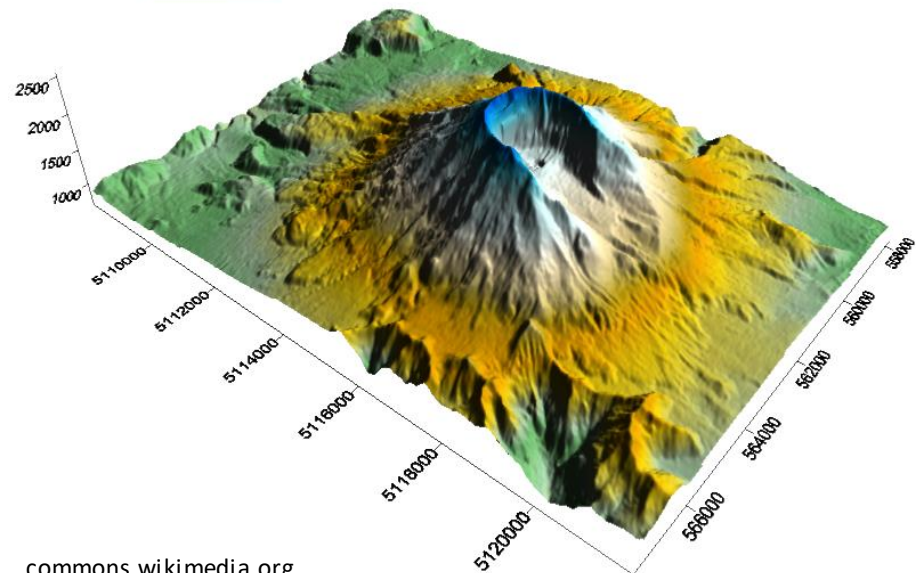
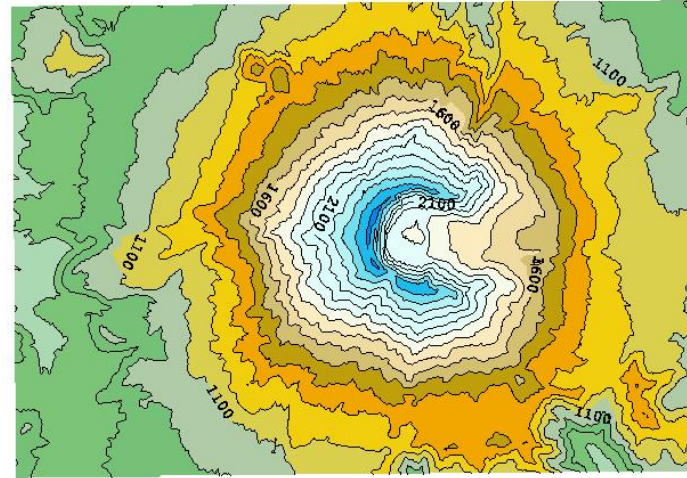
- Isoline diagrams



[pawsonemonkey.blogspot.com](http://pawsonemonkey.blogspot.com)

# Types of maps

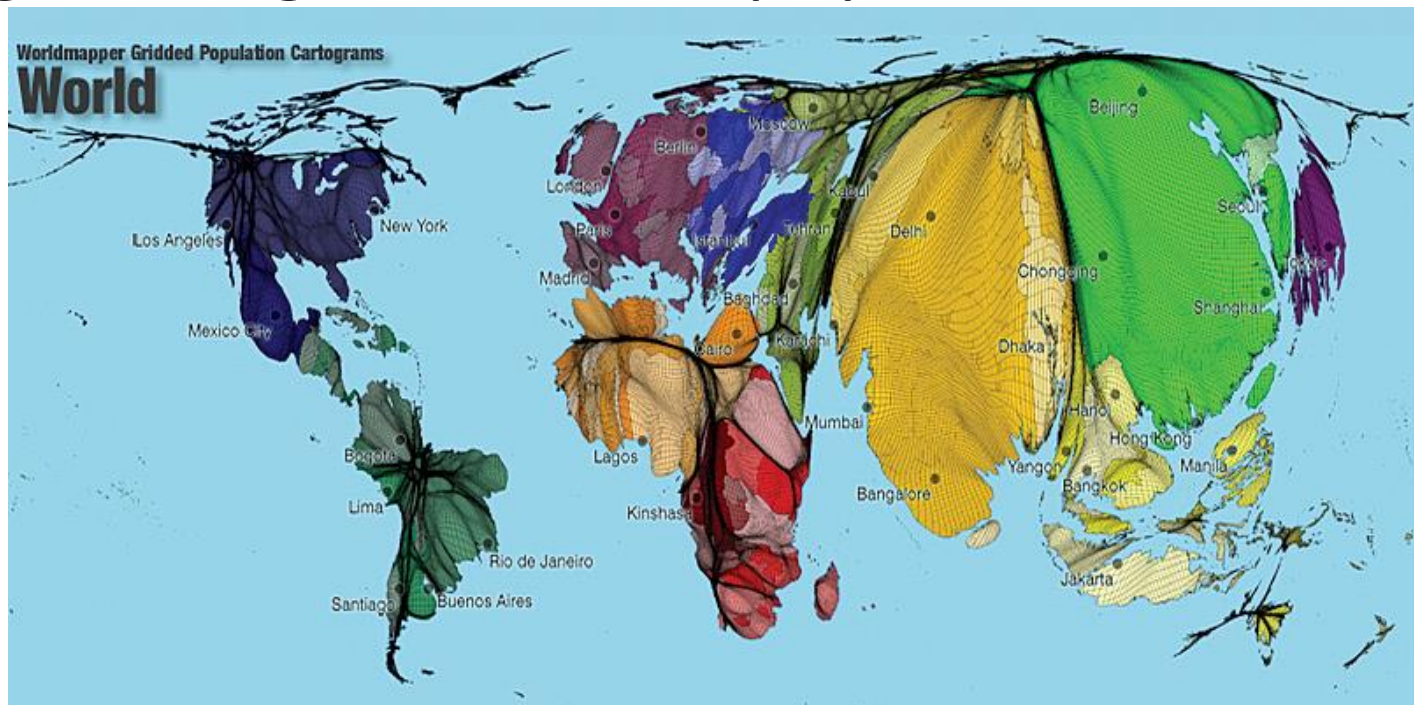
- Surface maps





# Different types of representation

- Same data visualized using different types of maps
- E.g., cartogram – world population

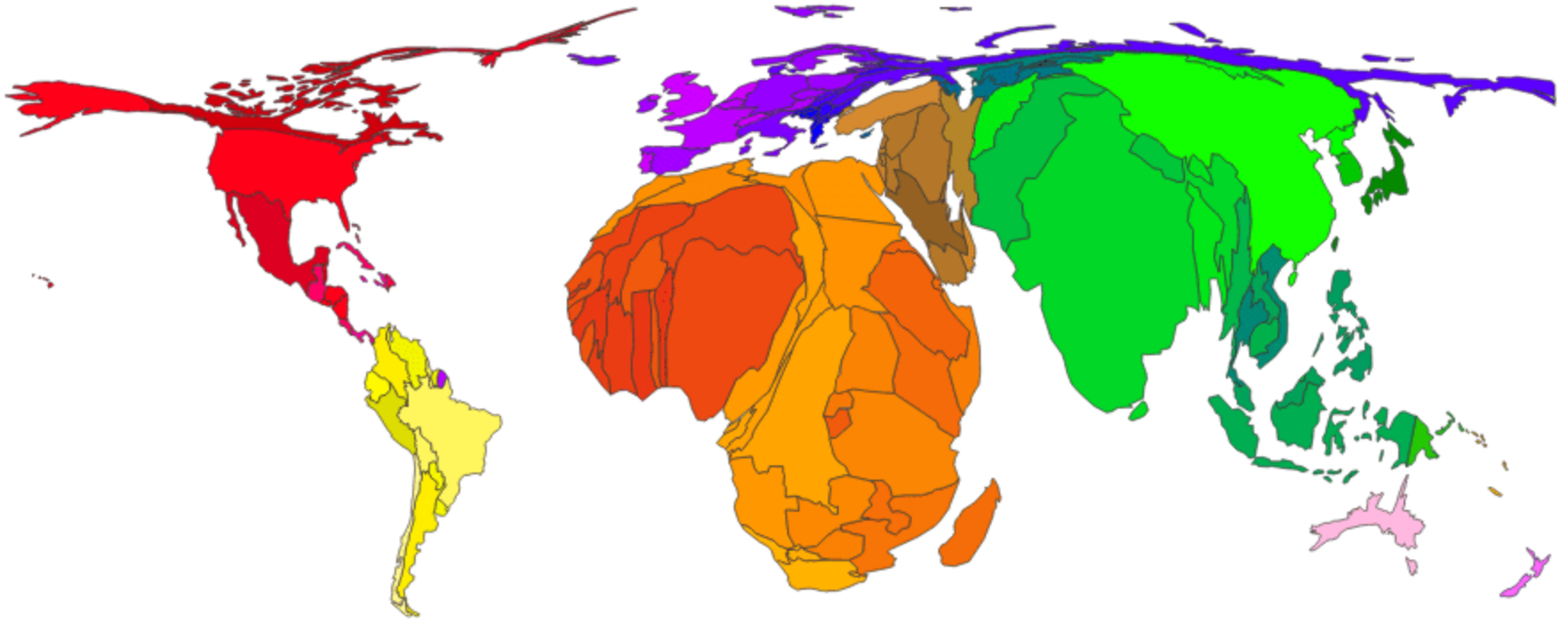


# Cartograms

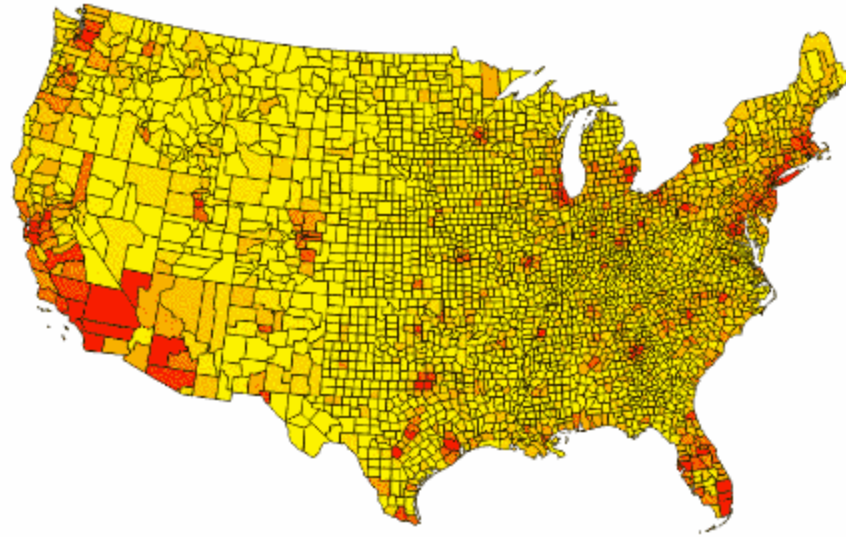
**2100**

**11.2 billion**

World Population



# Animated cartograms



# Exploratory geovisualization

- Interaction is crucial
  - Cooperation with the user
  - Interactive querying
- Combination of maps with:
  - Statistical visualization – bar charts, line charts
  - Complex techniques for multidimensional data visualization (e.g., parallel coordinates)

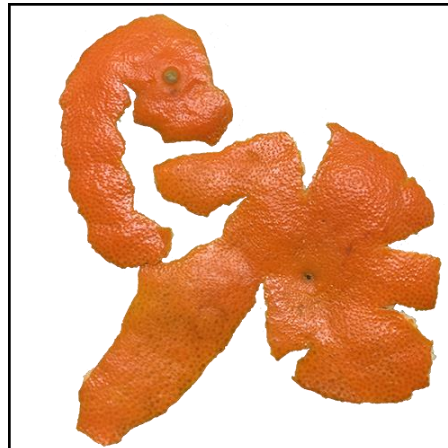
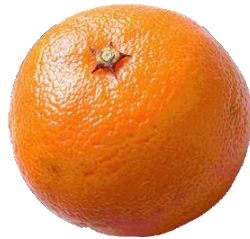
# Map projection

- Mapping of positions on the globe to positions on screen (from sphere to plane)
- Defined as:

$$\Pi: (\lambda, \phi) \rightarrow (x, y)$$

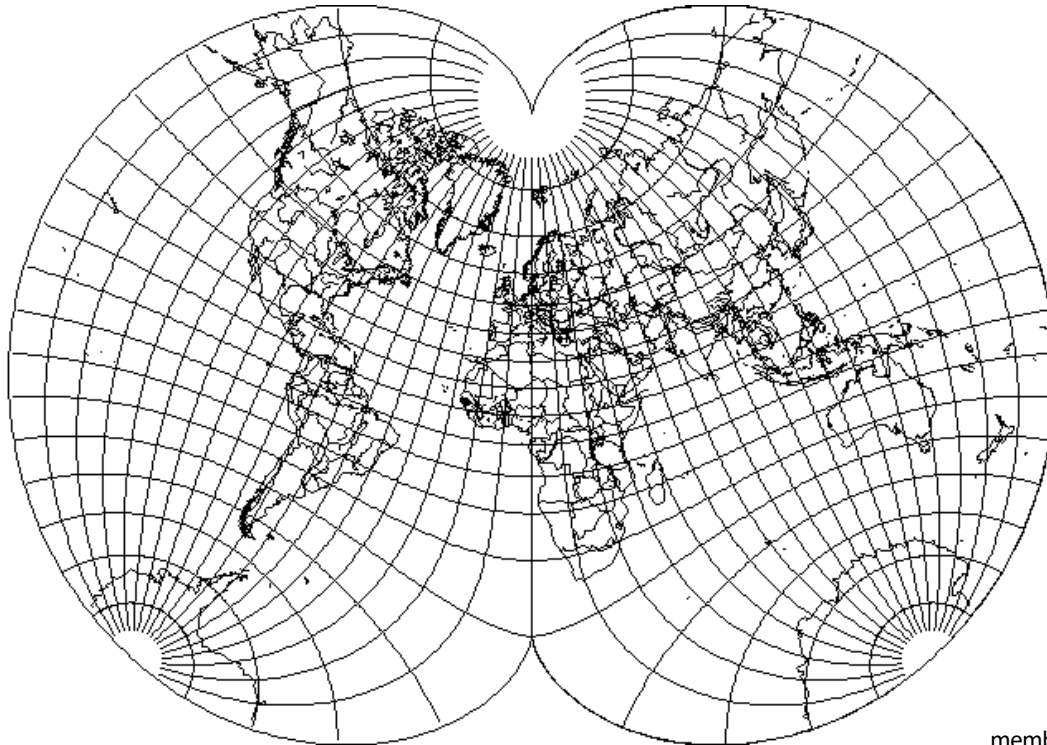
where  $\lambda$  is longitude in range  $[-180, 180]$

$\phi$  is latitude in range  $[-90, 90]$



# Map projections

- Conformal projections
  - Preserve local angles  $\rightarrow$  shapes, the area is not preserved



# Map projections

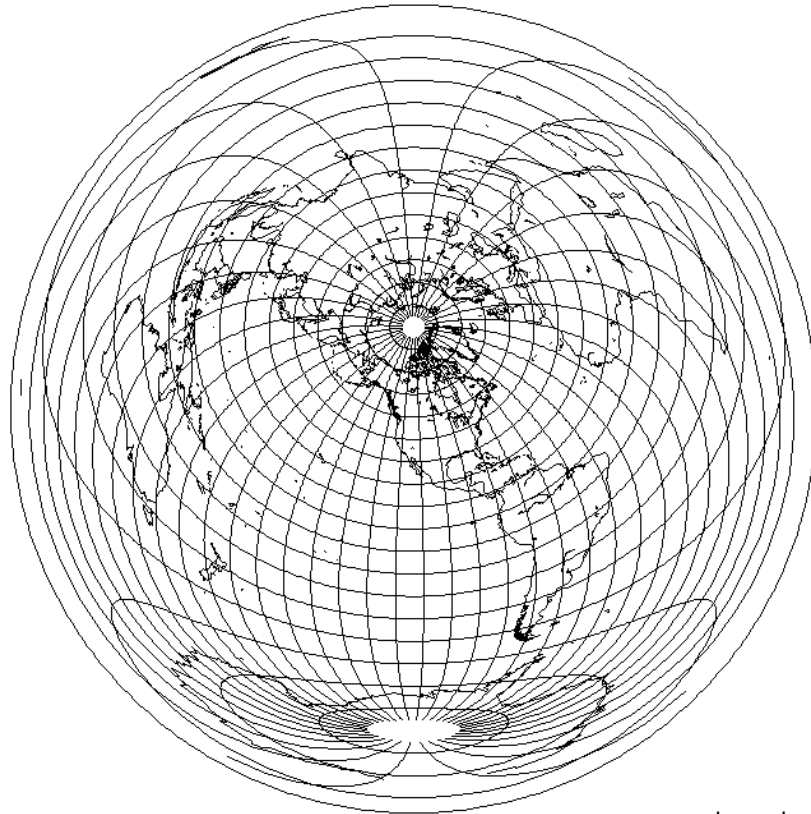
- Equivalent projections, equal area
  - Show only part of the map, distorts shape and angles



The Lambert planar equal-area projection is mathematically derived to display the property of equivalence.

# Map projections

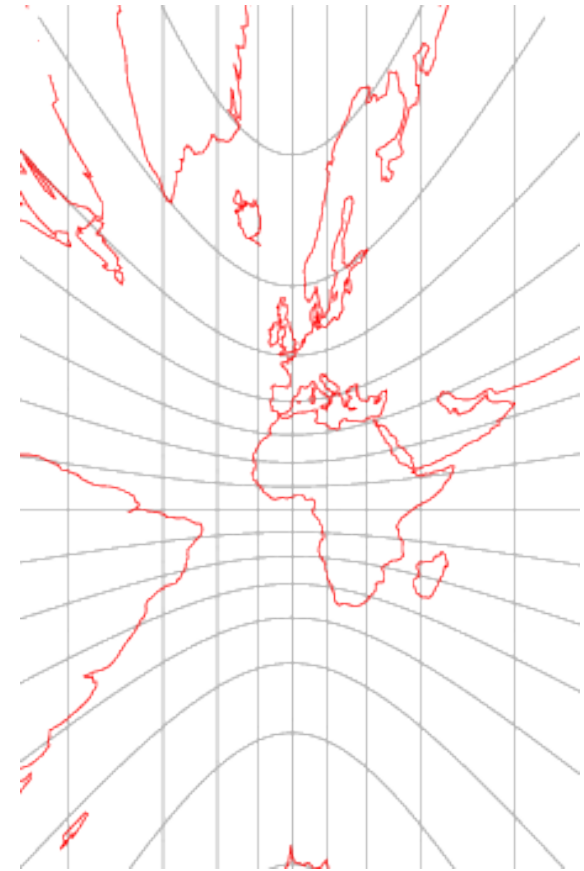
- Equidistant projections
  - Preserve distance from point or line





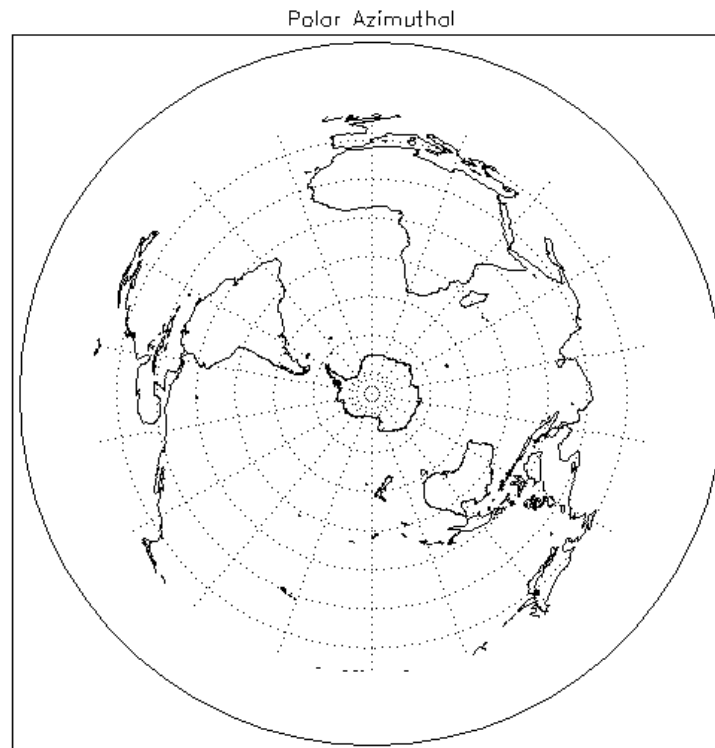
# Map projections

- Gnomonic projections
  - Show meridians and parallels of latitude as lines
  - Preserve the shortest path between two points
  - We cannot show the whole hemisphere (borders are heading to infinity)



# Map projections

- Azimuthal projections
  - Preserve the direction from the central point, radially symmetrical

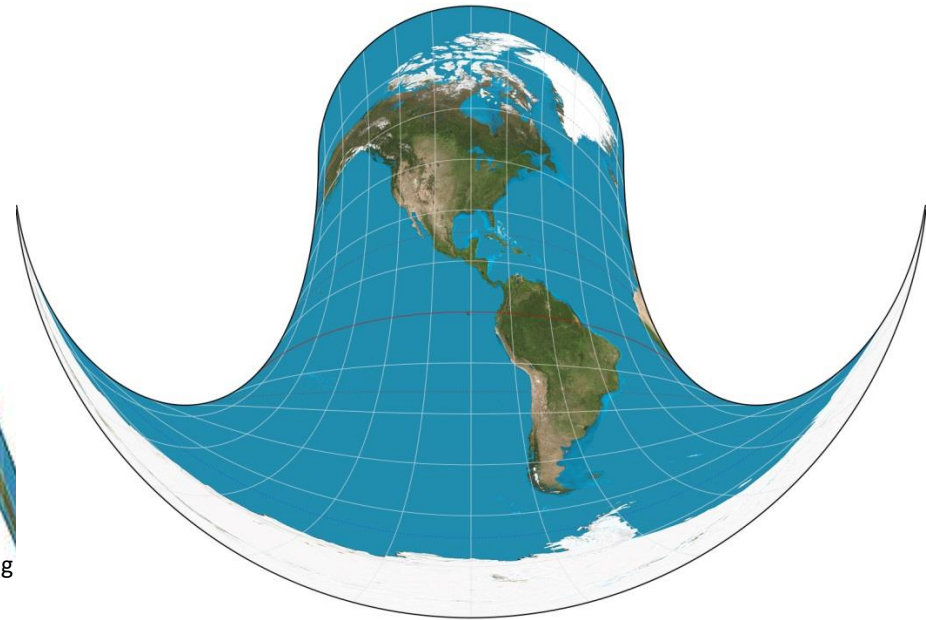


# Map projections

- Retroazimuthal projection
  - Direction from point S to point L corresponds to the direction from S to L on the map



[en.wikipedia.org](http://en.wikipedia.org)



[commons.wikimedia.org](http://commons.wikimedia.org)

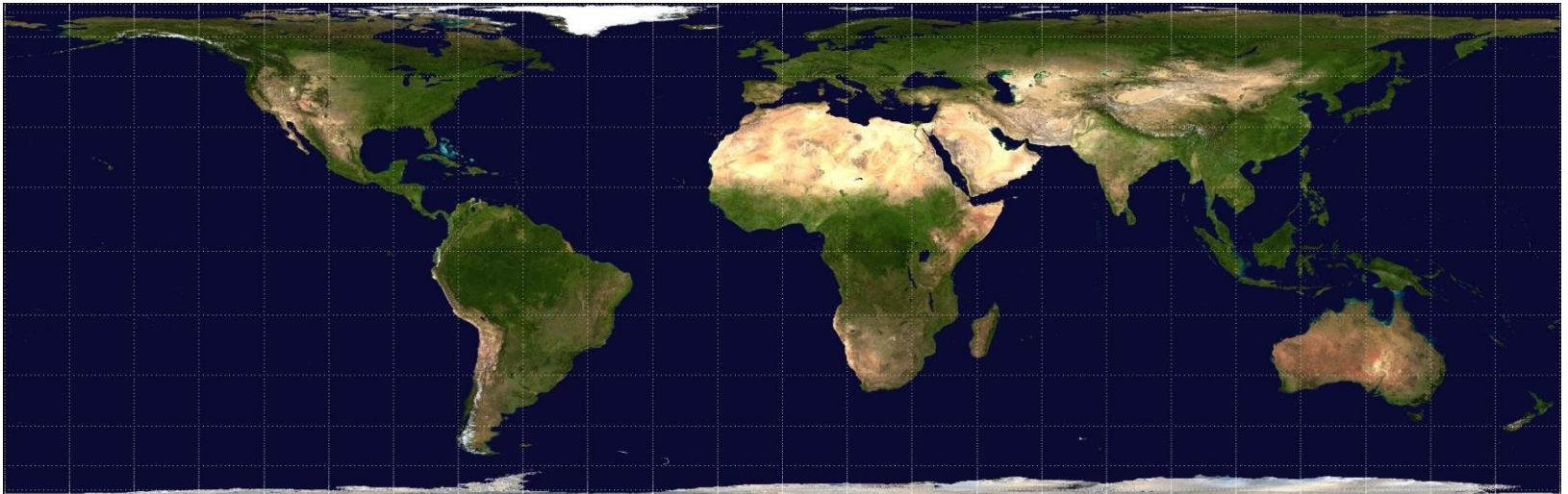
# Map projections – classification according to type of surface

- Sphere can be projected onto different surfaces:
  - Cylindrical projection
  - Planar projection
  - Cone projection



# Cylindrical projection

- Projecting the sphere surface onto cylinder positioned around the sphere
- Shows the whole spherical surface
- Conformal projection – preserves local angles



# Pseudo-cylindrical projection

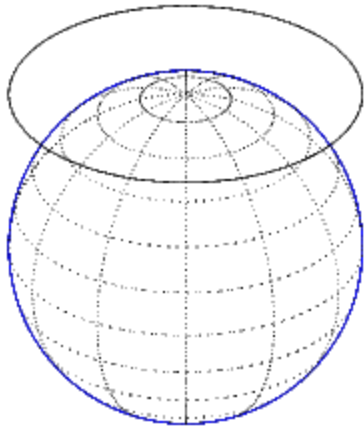
- Prime meridian and parallels are straight lines, other meridians are distorted

Mollweide projection  
(Other Names: Babinet, Elliptical, Homalographic, Homolographic)  
Pseudocylindrical; Equal-area;  
Carl B. Mollweide; 1805



# Planar projection

- Azimuthal projection mapping the sphere surface onto a plane tangential to the sphere
- Tangential point corresponds to the center of projection



# Cone projection

- Mapping of sphere surface on the tangential cone
- Latitude = spheres with centers in the center of projection
- Longitude = straight lines from the center of projection



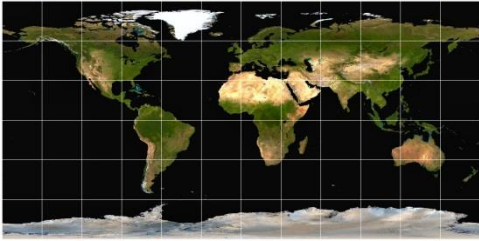


# Examples of commonly used map projections

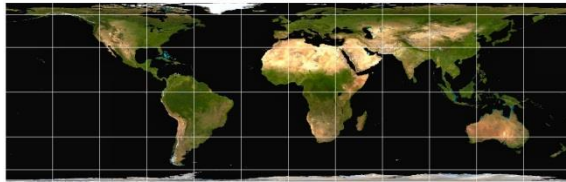
- Variables used in map projections:

$\varphi$	measured degrees of latitude in radians
$\lambda$	measured degrees of longitude in radians
$x$	horizontal axis of the two-dimensional map
$y$	vertical axis of the two-dimensional map
$\varphi_0; \lambda_0$	latitude of the standard parallel resp. meridian measured in radians

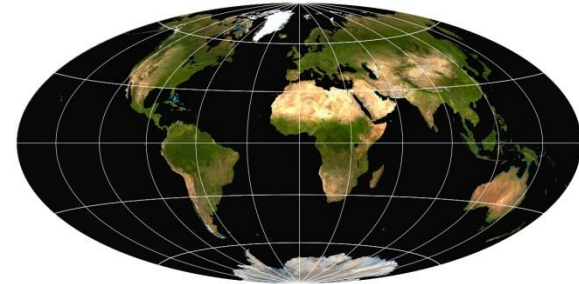
# Different map projections



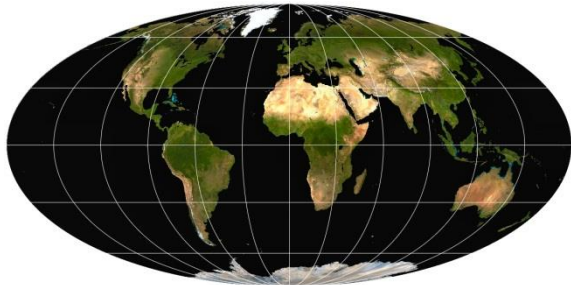
Equirectangular



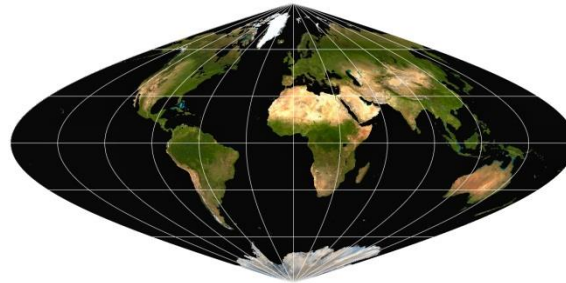
Lambert cylindrical



Hammer-Aitoff



Mollweide

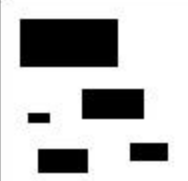
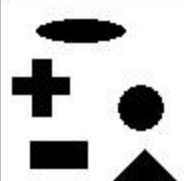
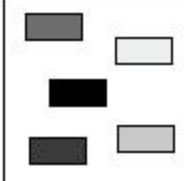
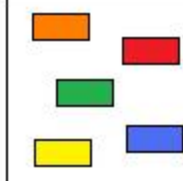

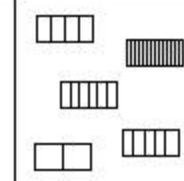
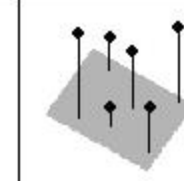
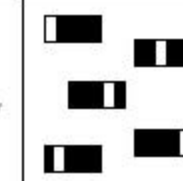














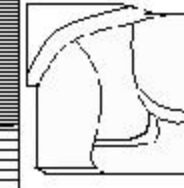
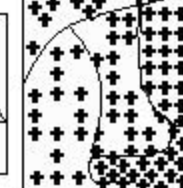


Cosinusodial



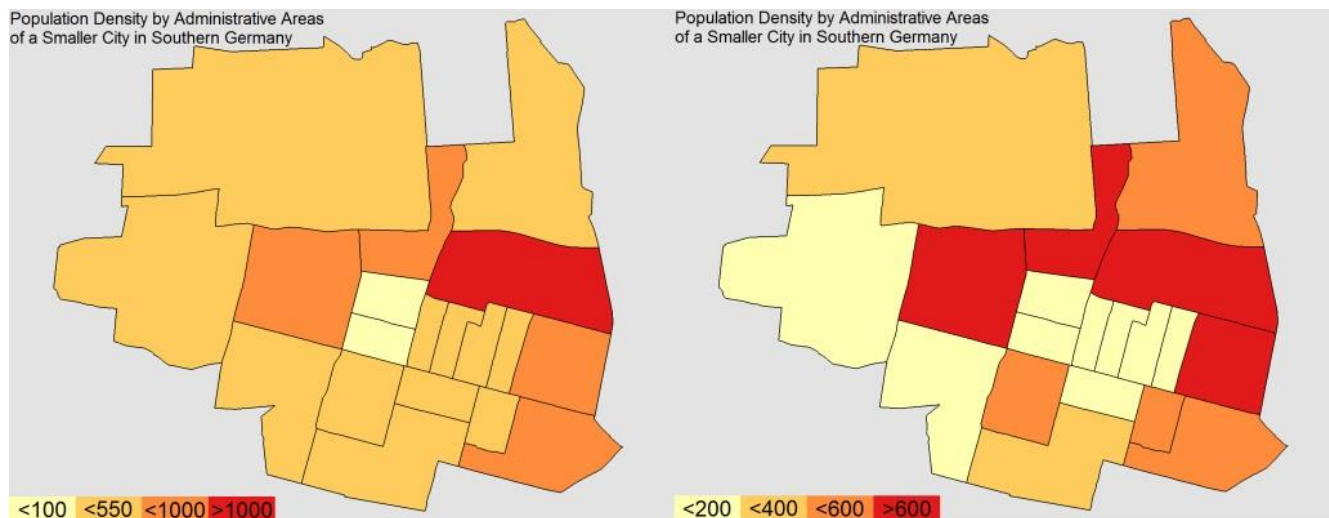
Albers equal-area conic

# Visual variables for spatial data

	Size	Shape	Brightness	Color	Orientation	Spacing	Perspective height	Arrangement
Point	 A collection of black rectangles of various sizes, illustrating the visual variable of size.	 A collection of black shapes including a cross, a circle, a triangle, and a rectangle, illustrating the visual variable of shape.	 A collection of black and gray rectangles of various shades, illustrating the visual variable of brightness.	 A collection of colored rectangles in orange, red, green, yellow, and blue, illustrating the visual variable of color.	 A collection of black rectangles rotated at various angles, illustrating the visual variable of orientation.	 A collection of white rectangles with varying spacing between them, illustrating the visual variable of spacing.	 A gray square with several black lines of varying heights extending upwards from its corners, illustrating the visual variable of perspective height.	 A collection of black rectangles arranged in different patterns, illustrating the visual variable of arrangement.
Linear	 A collection of black lines of varying thicknesses, illustrating the visual variable of size.	 A collection of black lines with different shapes at their ends, illustrating the visual variable of shape.	 A collection of black and gray lines of varying shades, illustrating the visual variable of brightness.	 A collection of colored lines in orange, red, green, yellow, and blue, illustrating the visual variable of color.	 A collection of black lines rotated at various angles, illustrating the visual variable of orientation.	 A collection of black lines with varying spacing between them, illustrating the visual variable of spacing.	 A collection of black lines of varying heights extending upwards from a common base, illustrating the visual variable of perspective height.	 A collection of black lines arranged in different patterns, illustrating the visual variable of arrangement.
Areal	 A collection of black crosses of varying sizes, illustrating the visual variable of size.	 A collection of black shapes including a cross, a circle, a triangle, and a rectangle, illustrating the visual variable of shape.	 A collection of black and gray shapes of various shades, illustrating the visual variable of brightness.	 A collection of colored shapes in red, green, yellow, and blue, illustrating the visual variable of color.	 A collection of black shapes rotated at various angles, illustrating the visual variable of orientation.	 A collection of black shapes with varying spacing between them, illustrating the visual variable of spacing.	 A collection of black shapes of varying heights extending upwards from a common base, illustrating the visual variable of perspective height.	 A collection of black shapes arranged in different patterns, illustrating the visual variable of arrangement.

# Influence of input data corrections onto the resulting map

- Sampling, segmentation, normalization, ... can influence the map a lot
- Different thresholds → different „borders“ → different results:



# Influence of input data corrections onto the resulting map

- Difference between absolute and relative (here according to population size) mapping

Absolute Population Density for Administrative Areas:



Area-Relative Population Density:



# Influence of input data corrections onto the resulting map

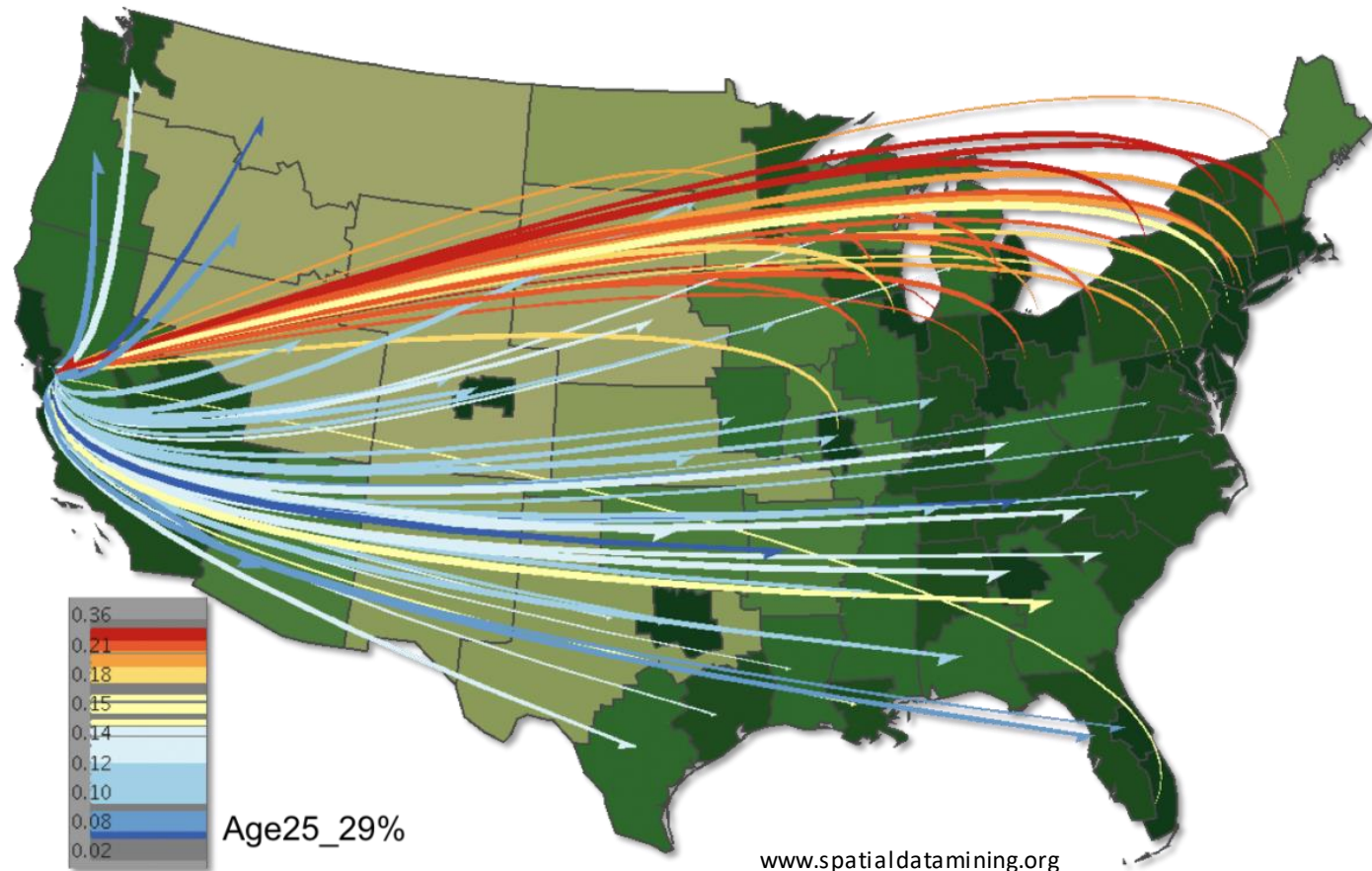
- Different clustering = different maps

Area Aggregation:



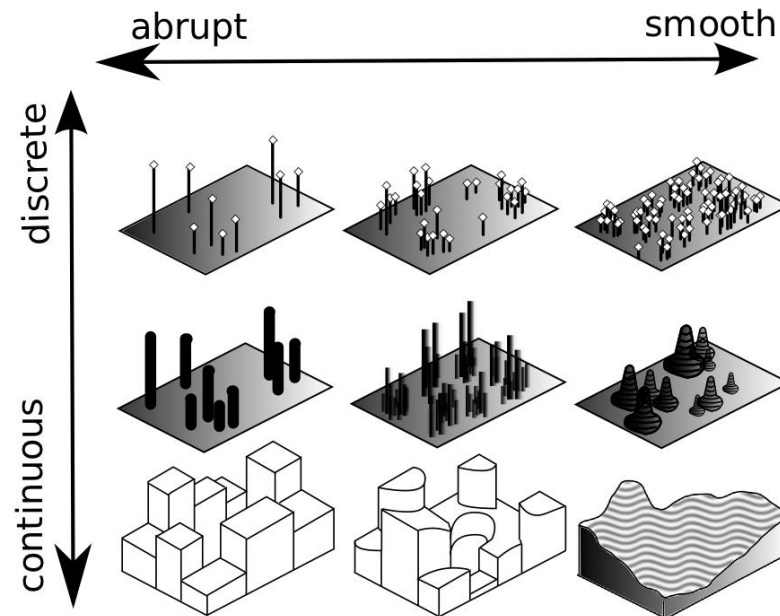
# Geovisualization

- Three basic types of objects:
  - Points
  - Lines
  - Areas



# Point data visualization

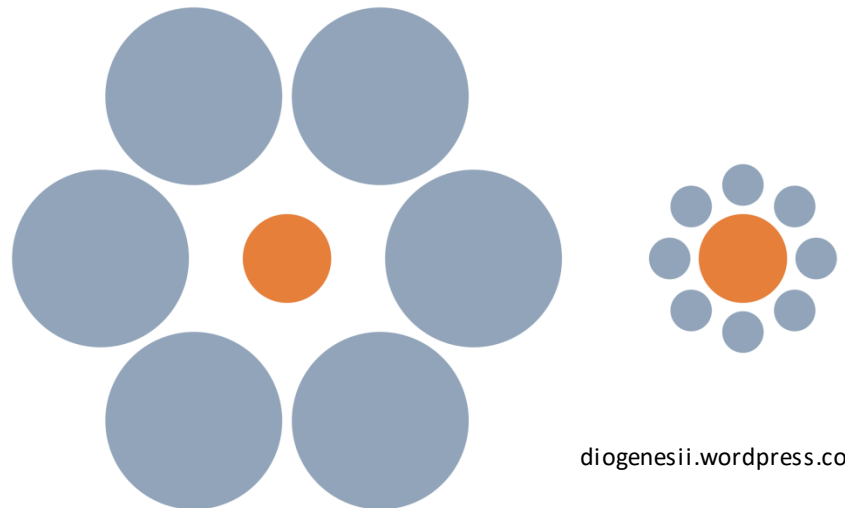
- Discrete, but can describe a continuous phenomenon (e.g., measuring of temperature in a given spot)
- From discrete to continuous, from smooth to abrupt





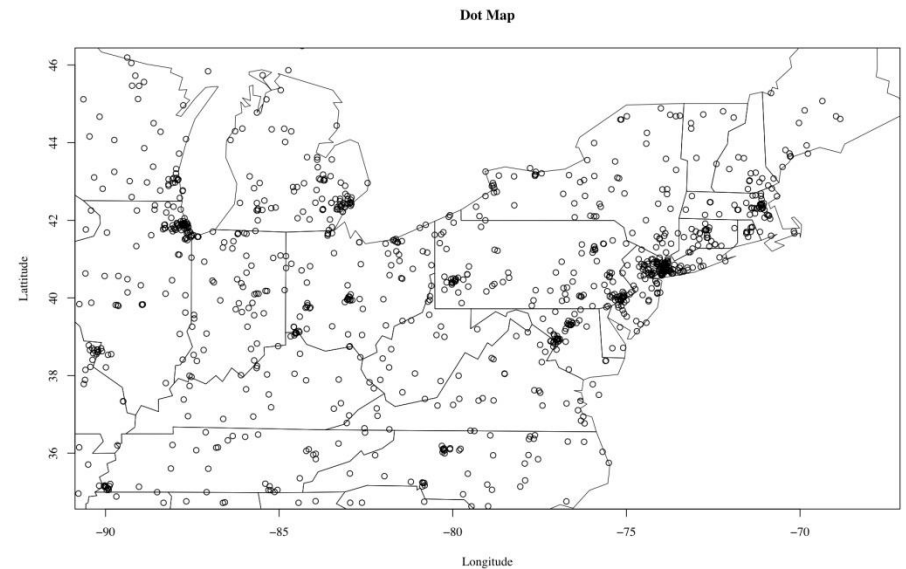
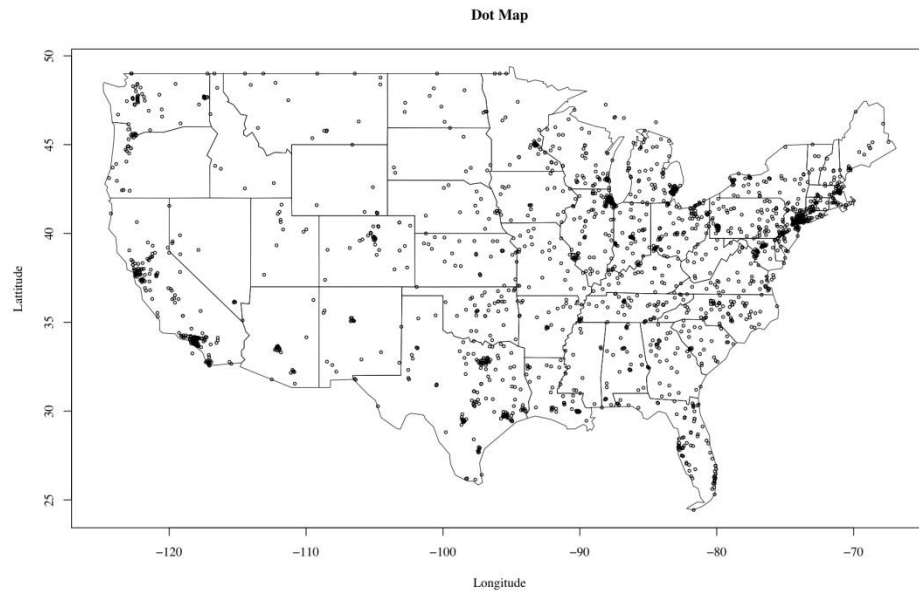
# Point maps

- Quantitative parameter can be mapped onto size or color
- Beware of size – correct values for symbol sizes does not mean that we are perceiving it correctly!!!
- Ebbinghaus illusion:



# Distribution of points

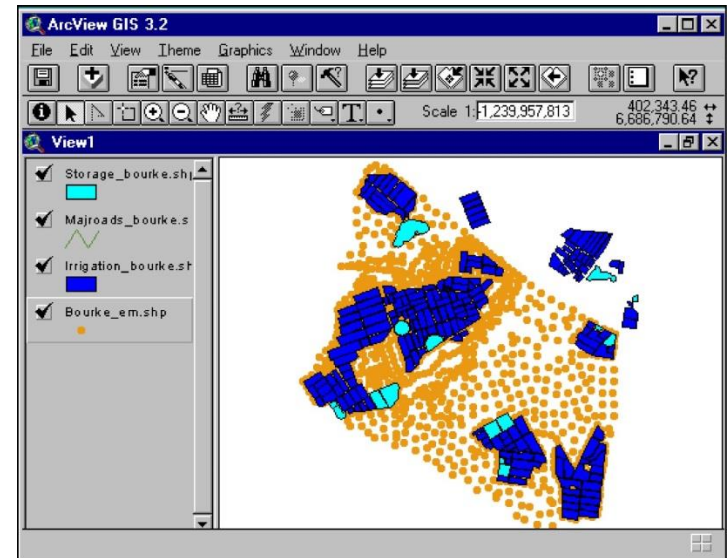
- Possible overlaps in areas with dense data



Daniel A. Keim, Christian Panse, and Mike Sips. "Visual Data Mining of Large Spatial Data Sets." In *Databases in Networked Information Systems, Lecture Notes in Computer Science, 2822, Lecture Notes in Computer Science, 2822*, pp. 201–215. Berlin: Springer, 2003.

# Methods for visualizing dense point maps

- 2.5D visualization aggregating data points to regions



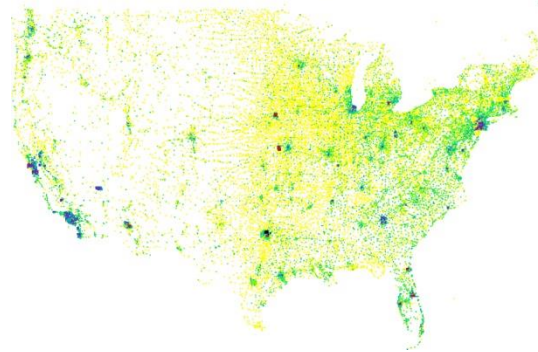
- Data points visualized as bars

# PixelMaps

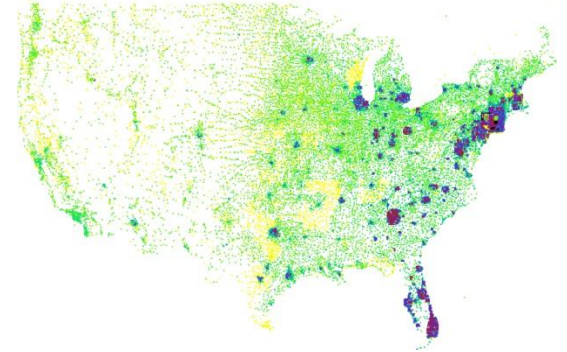
- Shifting the overlapping pixels
- Recursive algorithm utilizing quad-tree
  - Dividing into 4 subregions
  - We divide until the space in the subregion is bigger than the number of pixels in this subregion
  - Finally we perform the „pixel placement“ algorithm – it places the first data item to its correct position and the subsequent data items are placed to the nearest free positions

# PixelMaps

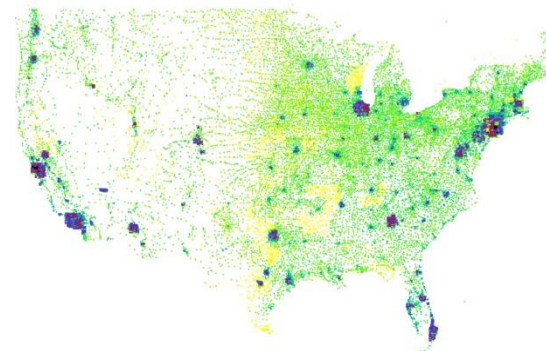
- Problem – in datasets with high overlaps the positioning depends on the order of the data stored in database



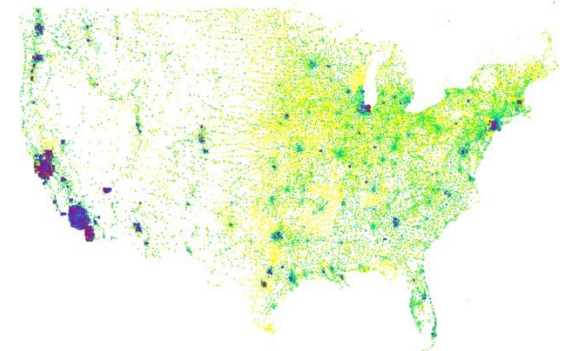
0:00 am (EST)



6:00 am (EST)



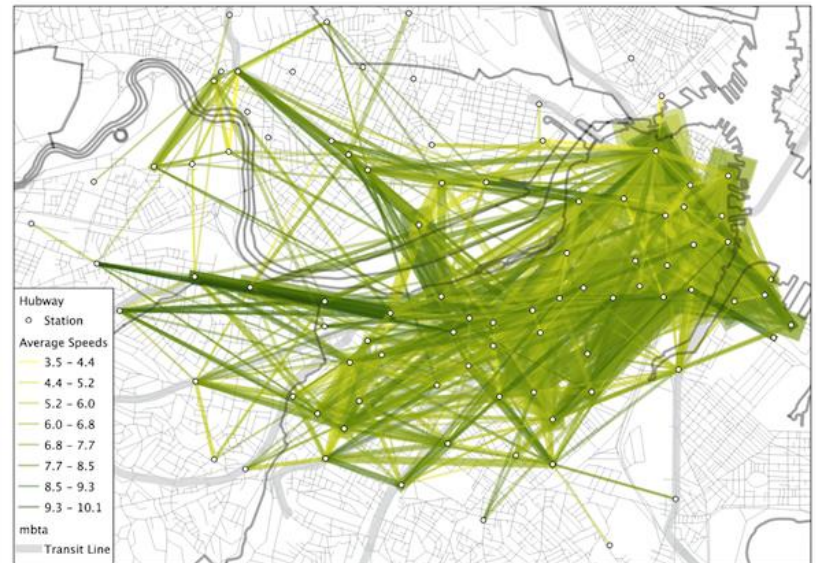
10:00 pm (EST)



6:00 pm (EST)

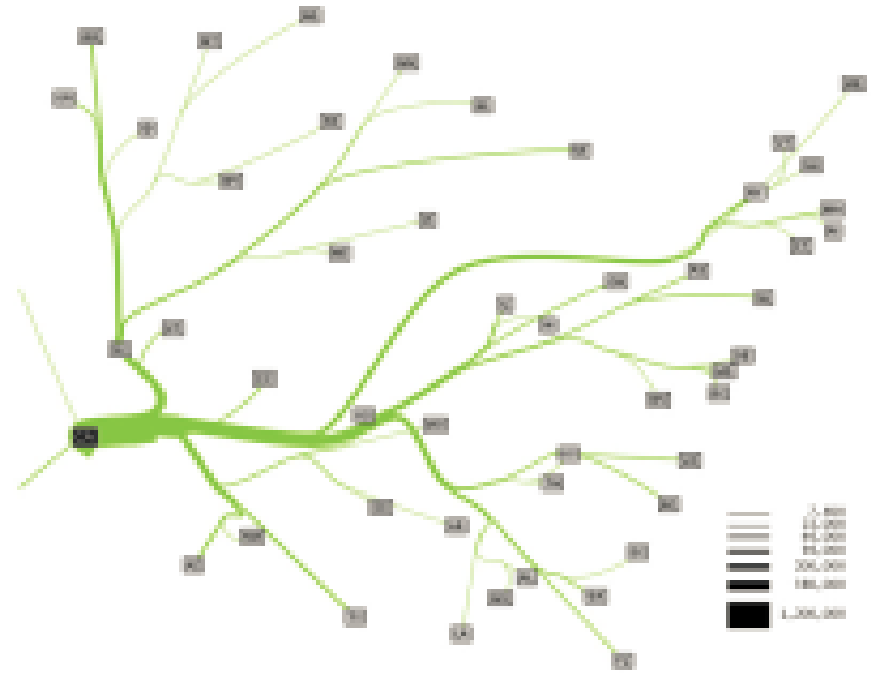
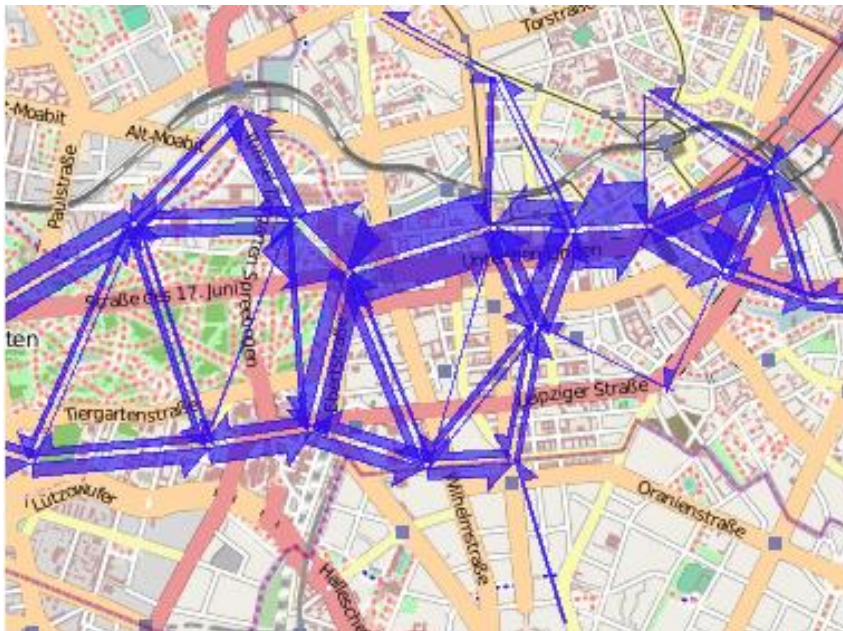
# Line data visualization

- Representation of linear phenomena using line segments between two endpoints defined by their longitude and latitude
- Other parameters of data mapped onto line width, pattern, color, labeling



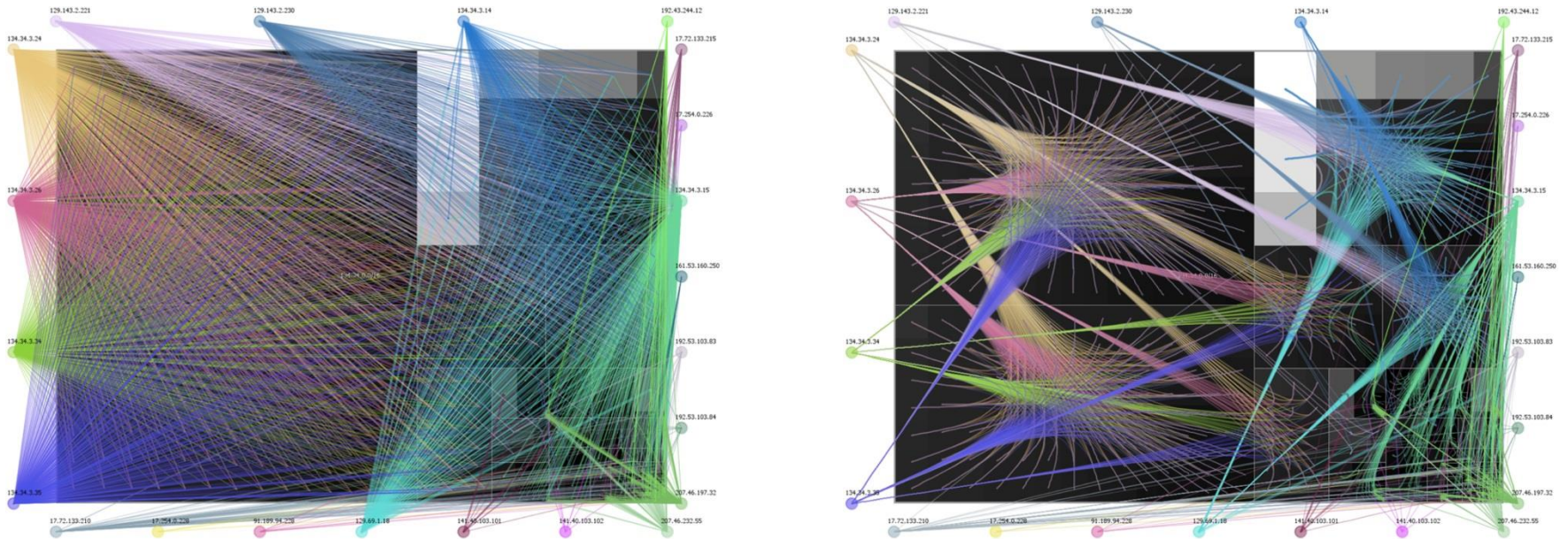
# Flow maps

- Eliminating line intersections and deformations of node positions while keeping their relative position
- Flow of tourists in Berlin vs. migration from California



# Flow maps

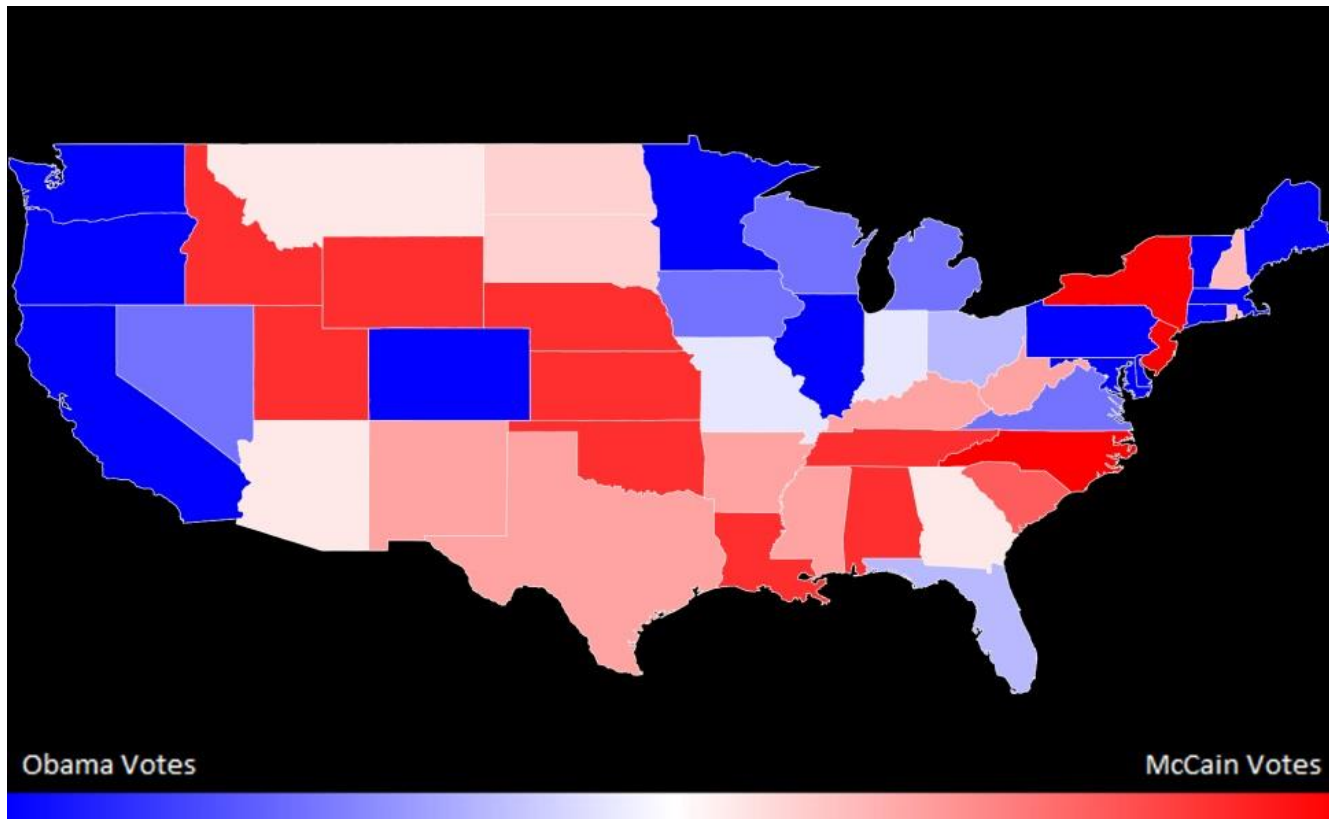
- Edge bundling – highlighting relations, bending of edges





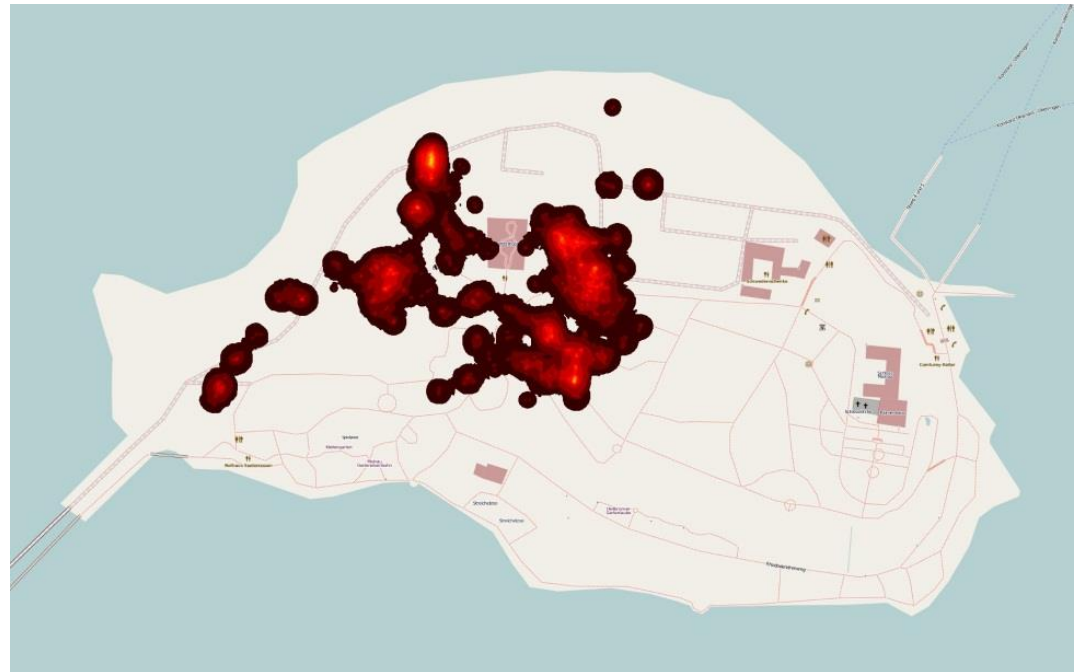
# Area data visualization

- **Thematic maps** are the most commonly used
- Most popular = **choropleth maps**



# Area data visualization

- Dasymetric maps – if we don't know the data distribution according to regions
- Isarithmic maps – contours of continuous phenomena

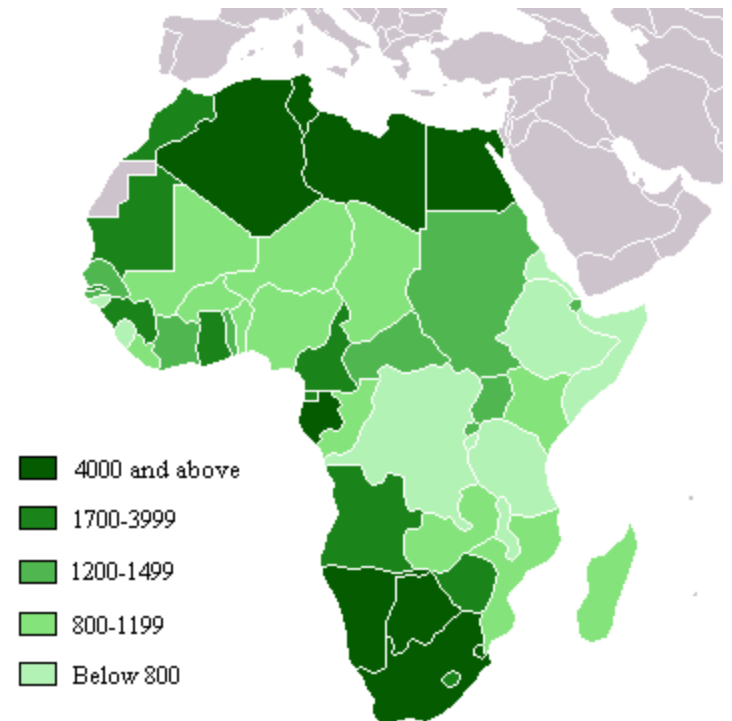


# Area data visualization

- Isometric maps – contours derived from real data points (e.g., temperature at a given spot)
- Isopleths – data point is considered to be the center of gravity in a given region
- Cartograms – scaling of region size in order to visualize statistical information

# Choropleth maps

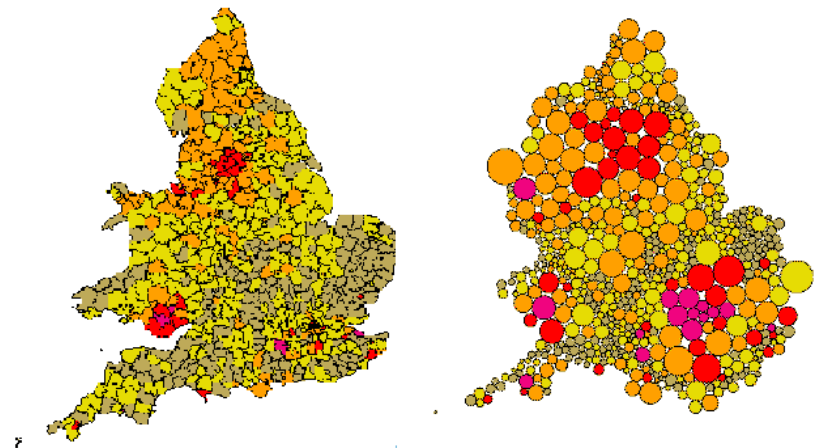
- Area phenomena visualized as shaded polygons enclosed by a contour
- Countries, parcs, ...
- Problem:
  - Interesting values in densely populated areas
  - mostly small polygons



# Cartograms

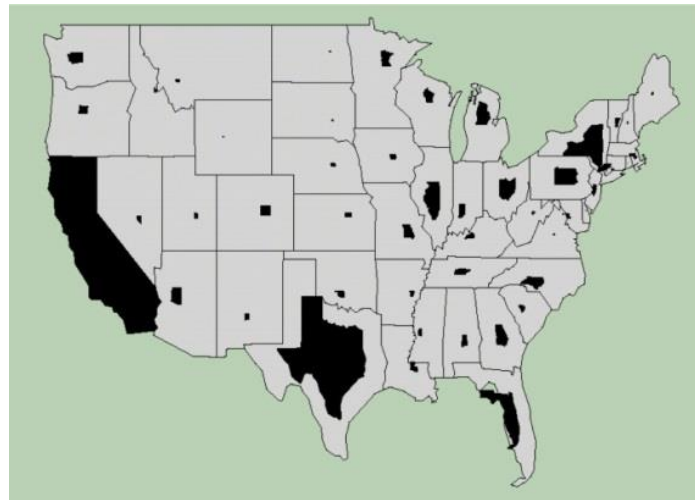
- Generalization of thematic maps, tries to avoid problems of choropleth maps
- Size of regions is changing according to given input variable associated with the geographic position of input data

COMPARISON OF A TRADITIONAL MAP AND CARTOGRAM REPRESENTATIONS OF THE PERCENTAGE OF THE MALE POPULATION OF WORKING AGE IN 1891



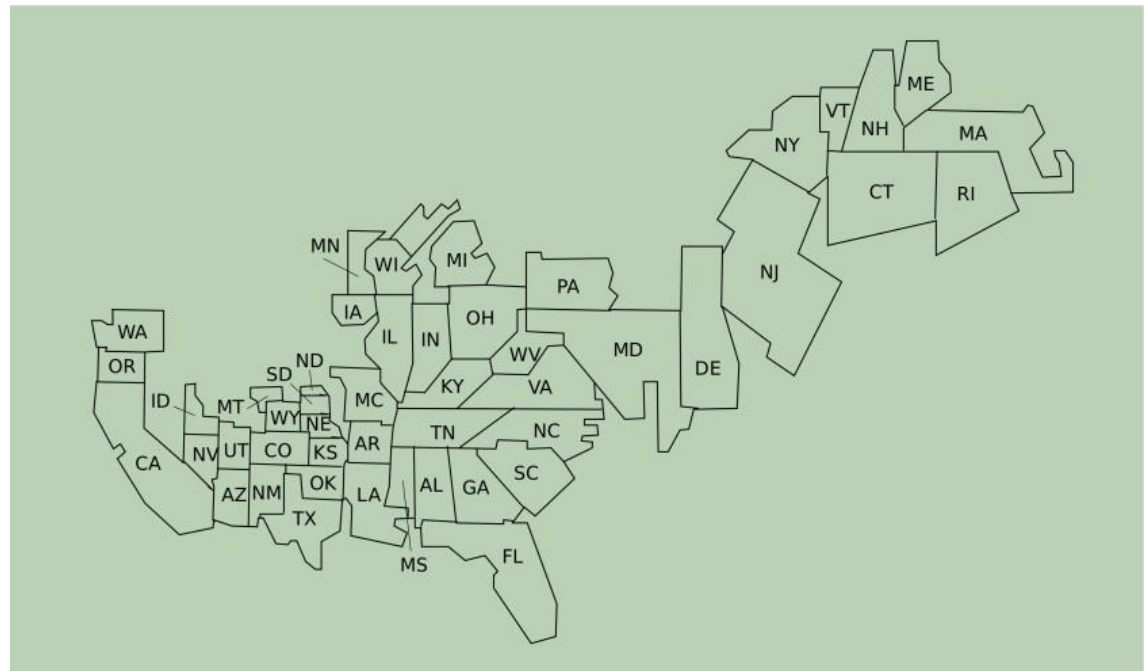
# Noncontinuous cartograms

- Do not preserve topology
- Scaled polygons are positioned inside the original polygons
- Original size of polygons limits the size of the resulting polygons (especially when enlarging them)



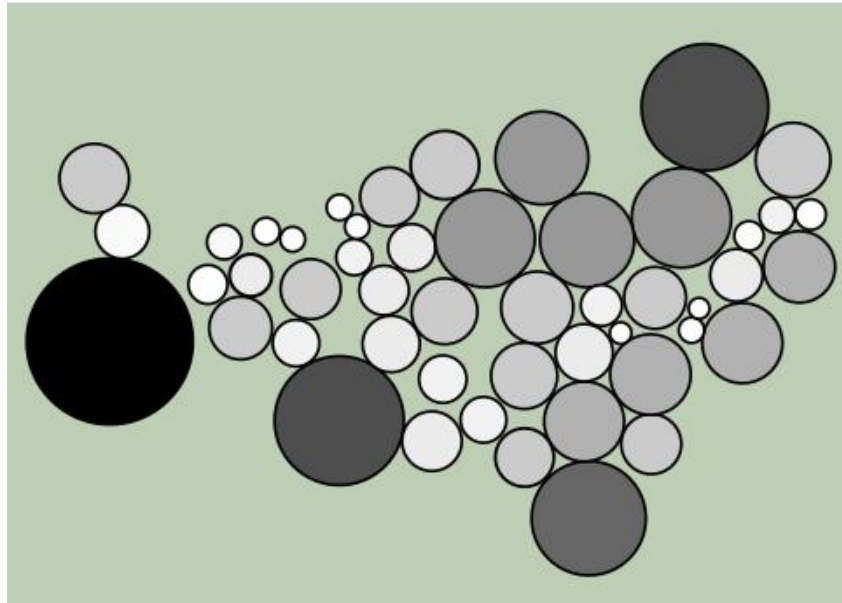
# Noncontiguous cartograms

- Scaling all polygons to their desired size
- Polygons do not preserve global topology and neighboring



# Circular cartograms

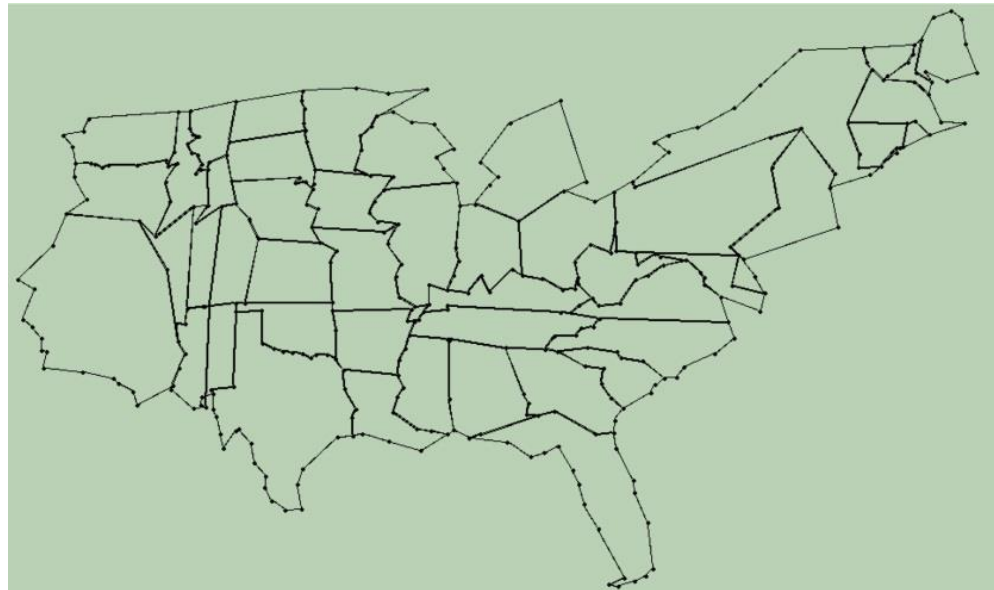
- Ignore the original shape of input polygons, they are represented by circles
- Relaxation of area and topological limitations = similar problems as the previous case





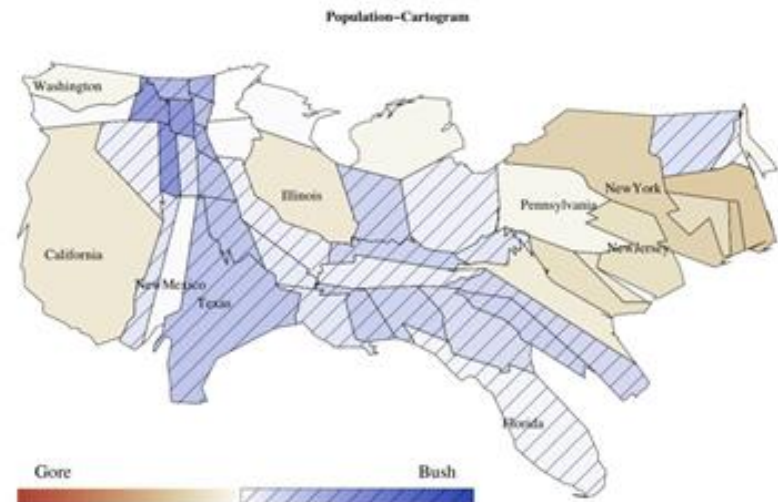
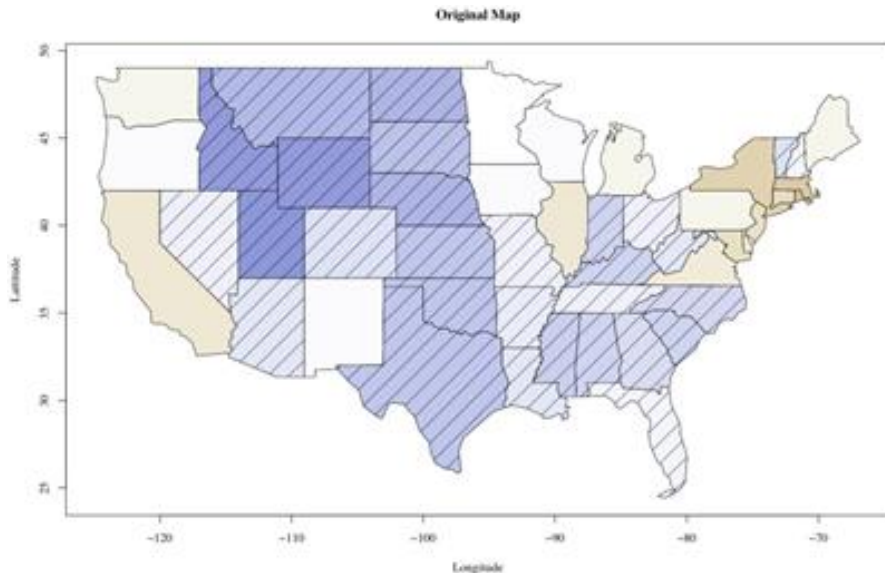
# Continuous cartograms

- Preserve the topology of the map
- Relaxation of area and shape limitations
- From all cartograms, this type preserves the best the topology of the original map



# Cartograms

- Manual creation is complicated, automatic techniques are therefore popular
- Preserve shape x preserve area



# Rectangular cartogram

- Approximation of regions by rectangles
- Division of the available screen space
- Rectangles are positioned as close as possible to the original positions and to the original neighbors
- **RecMap** algorithm



# Map labeling

- Positioning of text or image labels to the proximity of points, lines, and polygons
- Set of different algorithms solving this problem, with different efficiency and quality of results
- Mostly based on heuristic methods

# NASA Updates Eyes on Earth Visualization Site

- <https://eyes.nasa.gov/eyes-on-the-earth.html>

