

Relevance feedback and query expansion (Chapter 9)

Definition 1 (Rocchio relevance feedback)

Rocchio relevance feedback has the form

$$q_m = \alpha q_0 + \beta \frac{1}{|D_r|} \sum_{\vec{d}_r \in D_r} \vec{d}_r - \gamma \frac{1}{|D_{nr}|} \sum_{\vec{d}_{nr} \in D_{nr}} \vec{d}_{nr}$$

where q_0 is the original query vector, D_r is the set of relevant documents, D_{nr} is the set of non-relevant documents and the values α , β , γ depend on the system setting.

Exercise 9/1

What is the main purpose of Rocchio relevance feedback?

Answers can vary. For official definition refer to the Manning book.

Exercise 9/2

A user's primary query is *cheap CDs cheap DVDs extremely cheap CDs*. The user has a look on two documents: doc1 a doc2, marking doc1 *CDs cheap software cheap CDs* as relevant and doc2 *cheap thrills DVDs* as non-relevant. Assume that we use a simple *tf* scheme without vector length normalization. What would be the restructured query vector after considering the Rocchio relevance feedback with values $\alpha = 1$, $\beta = 0.75$, and $\gamma = 0.25$?

We rewrite the exercise to the table for an easier processing.

	relevant	non-relevant	
terms	doc1	doc2	query
CDs	2	0	2
cheap	2	1	3
software	1	0	0
thrills	0	1	0
DVDs	0	1	1
extremely	0	0	1

Table 1:

Now we mark the input of the algorithm by Definition 1.

$$d_r \in D_r = \begin{pmatrix} 2 \\ 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, d_{nr} \in D_{nr} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}, q = \begin{pmatrix} 2 \\ 3 \\ 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

By filling the values to the formula for q_m we get

$$\begin{aligned}
 q_m &= 1 \cdot \begin{pmatrix} 2 \\ 3 \\ 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} + 0.75 \cdot \frac{1}{1} \begin{pmatrix} 2 \\ 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} - 0.25 \cdot \frac{1}{1} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} \\
 &= \begin{pmatrix} 2 \\ 3 \\ 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1.5 \\ 1.5 \\ 0.75 \\ 0 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0.25 \\ 0 \\ 0.25 \\ 0.25 \\ 0 \end{pmatrix} \\
 &= \begin{pmatrix} 3.5 \\ 4.25 \\ 0.75 \\ -0.25 \\ 0.75 \\ 1 \end{pmatrix}
 \end{aligned}$$

Text classification and Naive Bayes (Chapter 13)

Definition 2 (Naive Bayes Classifier)

Naive Bayes (NB) Classifier assumes that the effect of the value of a predictor x on a given class c is class conditional independent. Bayes theorem provides a way of calculating the posterior probability $P(c|x)$ from class prior probability $P(c)$, predictor prior probability $P(x)$ and probability of the predictor given the class $P(x|c)$

$$P(c|x) = \frac{P(x|c)P(c)}{P(x)}$$

and for a vector of predictors $X = (x_1, \dots, x_n)$

$$P(c|X) = \frac{P(x_1|c) \dots P(x_n|c)P(c)}{P(x_1) \dots P(x_n)}.$$

The class with the highest posterior probability is the outcome of prediction.

Exercise 13/1

What is naive about Naive Bayes classifier? Briefly outline its major idea.

Answers can vary. For official definition refer to the Manning book.

Exercise 13/2

Considering the table of observations, use the Naive Bayes classifier to recommend whether to *Play Golf* given a day with *Outlook = Rainy*, *Temperature = Mild*, *Humidity = Normal* and *Windy = True*. Do not deal with the zero-frequency problem.

Outlook	Temperature	Humidity	Windy	Play Golf
Rainy	Hot	High	False	No
Rainy	Hot	High	True	No
Overcast	Hot	High	False	Yes
Sunny	Mild	High	False	Yes
Sunny	Cool	Normal	False	Yes
Sunny	Cool	Normal	True	No
Overcast	Cool	Normal	True	Yes
Rainy	Mild	High	False	No
Rainy	Cool	Normal	False	Yes
Sunny	Mild	Normal	False	Yes
Rainy	Mild	Normal	True	Yes
Overcast	Mild	High	True	Yes
Overcast	Hot	Normal	False	Yes
Sunny	Mild	High	True	No

Table 2: Exercise.

First build the likelihood tables for each predictor

		Play Golf				Play Golf			
		Yes	No			Yes	No		
Outlook	Sunny	3/9	2/5	5/14	Temperature	Hot	2/9	2/5	4/14
	Overcast	4/9	0/5	4/14		Mild	4/9	2/5	6/14
	Rainy	2/9	3/5	5/14		Cool	3/9	1/5	4/14
		9/14	5/14			9/14	5/14		

		Play Golf				Play Golf			
		Yes	No			Yes	No		
Humidity	High	3/9	4/5	7/14	Windy	True	3/9	2/5	5/14
	Normal	6/9	1/5	7/14		False	6/9	3/5	9/14
		9/14	5/14			9/14	5/14		

We see that probability of *Sunny* given *Yes* is $3/9 = 0.33$, probability of *Sunny* is $5/14 = 0.36$ and probability of *Yes* is $9/14 = 0.64$. Then we count the likelihoods of *Yes* and *No*

$$\begin{aligned}
P(\text{Yes}|\text{Rainy}, \text{Mild}, \text{Normal}, \text{True}) &\propto \\
&= P(\text{Rainy}|\text{Yes}) \cdot P(\text{Mild}|\text{Yes}) \cdot P(\text{Normal}|\text{Yes}) \cdot P(\text{True}|\text{Yes}) \cdot P(\text{Yes}) \\
&= \frac{2}{9} \cdot \frac{4}{9} \cdot \frac{6}{9} \cdot \frac{3}{9} \cdot \frac{9}{14} = 0.014109347 \\
P(\text{No}|\text{Rainy}, \text{Mild}, \text{Normal}, \text{True}) &\propto \\
&= P(\text{Rainy}|\text{No}) \cdot P(\text{Mild}|\text{No}) \cdot P(\text{Normal}|\text{No}) \cdot P(\text{True}|\text{No}) \cdot P(\text{No}) \\
&= \frac{3}{5} \cdot \frac{2}{5} \cdot \frac{1}{5} \cdot \frac{3}{5} \cdot \frac{5}{14} = 0.010285714
\end{aligned} \tag{1}$$

and suggest *Yes*. We can normalize the likelihoods to obtain the % confidence:

$$P(\text{Yes}|\text{Rainy}, \text{Mild}, \text{Normal}, \text{True}) = \frac{0.014109347}{0.014109347 + 0.010285714} = 57.84\%$$

$$P(\text{No}|\text{Rainy}, \text{Mild}, \text{Normal}, \text{True}) = \frac{0.010285714}{0.014109347 + 0.010285714} = 42.16\%$$

Definition 3 (A Linear Classifier)

Our linear classifier finds the hyperplane that bisects and is perpendicular to the connecting line of the closest points from the two classes. The separating (decision) hyperplane is defined in terms of a normal (weight) vector \mathbf{w} and a scalar intercept term b as

$$f(x) = \mathbf{w} \cdot \mathbf{x} + b$$

where \cdot is the dot product of vectors. Finally, the classifier becomes

$$\text{class}(x) = \text{sgn}(f(x)).$$

Exercise 13/3

Draw a sketch explaining the concept of our linear classifier. Include the equation of the separation hyperplane. Is our classifier equivalent to support vector machines (SVM)? What are limitations of our classifier?

Answers can vary. For official definition refer to the Manning book.

Exercise 13/4

Build a linear classifier for the training set $\{([1, 1], -1), ([2, 0], -1), ([2, 3], +1)\}$.

We first take the closest two points from the respective classes: $[1, 1]$ and $[2, 3]$. We have $\mathbf{w} = a \cdot ([1, 1] - [2, 3]) = [a, 2a]$. Now we calculate a and b

$$a + 2a + b = -1$$

$$2a + 6a + b = 1$$

for the points $[1, 1]$ and $[2, 3]$, respectively. The solution is

$$a = \frac{2}{5} \quad b = \frac{-11}{5}$$

building the weight vector

$$\mathbf{w} = \left[\frac{2}{5}, \frac{4}{5} \right]$$

and the final classifier becomes

$$\text{class}(x) = \text{sgn} \left(\frac{2}{5}x_1 + \frac{4}{5}x_2 - \frac{11}{5} \right).$$

Exercise 13/5

Explain the concept of classification based on neural networks. Draw a sketch and comment on all components.

Answers can vary. For official definition refer to the Manning book.

Exercise 13/6

What is the difference between supervised and unsupervised learning? Give examples.

Answers can vary. For official definition refer to the Manning book.