Filters in Image Processing Image Transforms (II) – Wavelets

David Svoboda

email: svoboda@fi.muni.cz Centre for Biomedical Image Analysis Faculty of Informatics, Masaryk University, Brno, CZ

CBIA

October 11, 2019

Outline

- Motivation
- New basis
- 1D Discrete Wavelet Transform
- Subband coding
 - Signal Analysis
 - From Filter Banks to Wavelets
- 1D Fast Discrete Wavelet Transform
- 6 2D Discrete Wavelet Transform
- Wavelet Packets

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Motivation

Fourier transform and its derivatives have nice properties

- reversible
- linear operator
- easy to construct (data independent)
- decorrelation property

Fourier transform has some drawbacks

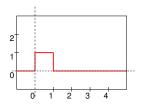
- localization is very expensive
- complexity cannot be lower than $O(n \log n)$

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- Fourier basis originates from sin and cos functions.
- Let us introduce so called scaling function φ and wavelet function ϕ .
- ullet φ and ψ should be strictly localized.
- ullet A new basis should originate from φ and ψ .

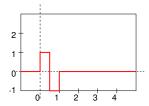
Scaling function φ

$$\varphi(x) = \begin{cases} 1 & \text{iff} \quad 0 \le x < 1 \\ 0 & \text{otherwise} \end{cases}$$



Wavelet function ψ

$$\psi(x) = \begin{cases} 1 & \text{iff} \quad 0 \le x < 0.5 \\ -1 & \text{iff} \quad 0.5 \le x < 1 \\ 0 & \text{elsewhere} \end{cases}$$



Scaling function

Let $\varphi(x)$ be a scaling function. We will modify it as follows:

$$\varphi_{j,k}(x) = 2^{j/2} \varphi \left(2^j \frac{x}{M} - k \right)$$

where $j, k \in \mathbb{Z}$ then

- $j \dots \varphi_{j,k}(x)$'s width controls broadness and height of the function along x and y axis, respectively.
- $k \dots$ shift of $\varphi_{j,k}(x)$ along x-axis
- M ... length of the processed signal

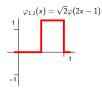
Notice: The function is orthogonal to its integer shifts

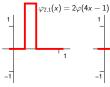
Scaling function (M = 1) – examples

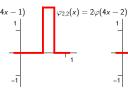


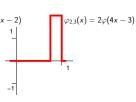










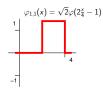


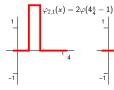
Scaling function (M = 4) – examples

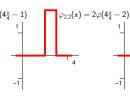


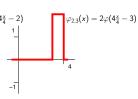












Wavelet function

Let $\psi(x)$ be a wavelet function. We will modify it as follows:

$$\psi_{j,k}(x) = 2^{j/2}\psi\left(2^j\frac{x}{M} - k\right)$$

where $j, k \in \mathbb{Z}$ then

- $j \dots \varphi_{j,k}(x)$'s width controls broadness and height of the function along x and y axis, respectively.
- $k \dots$ shift of $\varphi_{j,k}(x)$ along x-axis
- M ... length of the processed signal

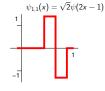
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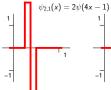
Wavelet function (M = 1) – examples



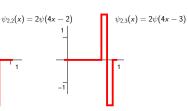










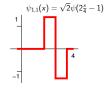


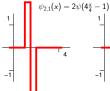
Wavelet function (M = 4) – examples



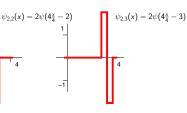












Support of basis functions

Fourier basis

- The domain of sin and cos is (0; 1).
- The domain is periodic.
- When applying the Fourier basis function $\varphi_m(k)$ to a transformed function f of length N, this basis function $\varphi_m(k)$ (its period) is stretched to the length N.

New basis

- The domain of $\varphi(x)$ and $\psi(x)$ is $\langle 0; 1 \rangle$.
- Each function has limited compact support.
- When applying the scaling or wavelet function to a transformed function f of length M, both scaling and wavelet function are appropriately stretched to the required length.

Design of transform matrix

Let us recall that the basis forms the rows of transform matrix!

Sample matrix for signal of length M = 4

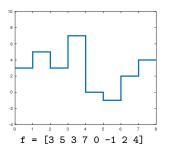
$$HT_4 = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ \sqrt{2} & -\sqrt{2} & 0 & 0 \\ 0 & 0 & \sqrt{2} & -\sqrt{2} \end{pmatrix} = \begin{array}{c} \varphi_{0,0} \\ = & \psi_{0,0} \\ = & \psi_{1,0} \\ = & \psi_{1,1} \end{array}$$

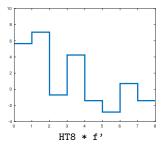
- Notice the structure of individual rows.
- Explain the value $\frac{1}{2}$.

Design of transform matrix

Matrices for signal of length M = 8

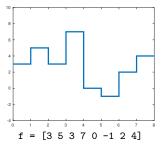
$$HT_8 = \frac{1}{\sqrt{8}} \begin{pmatrix} 2 & 2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 2 & 2 & 0 & 0 \\ 2 & -2 & 0 & 0 & 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 2 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 & -2 \end{pmatrix} = \frac{\varphi_{2,0}}{\psi_{2,1}}$$

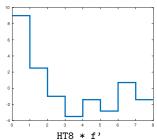




Design of transform matrix

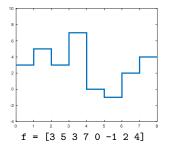
Matrices for signal of length M = 8

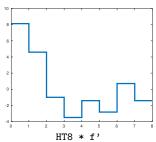




Design of transform matrix

Matrices for signal of length M = 8





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Forward

$$A_{j_0}(k) = \frac{1}{\sqrt{M}} \sum_{m=0}^{M-1} f(m) \varphi_{j_0,k}(m)$$

$$D_{j}(k) = \frac{1}{\sqrt{M}} \sum_{m=0}^{M-1} f(m) \psi_{j,k}(m)$$

Inverse

$$f(m) = \frac{1}{\sqrt{M}} \sum_{k=0}^{2^{j_0}-1} A_{j_0}(k) \varphi_{j_0,k}(m) + \frac{1}{\sqrt{M}} \sum_{j=j_0}^{J-1} \sum_{k=0}^{2^{j}-1} D_j(k) \psi_{j,k}(m)$$

- ullet φ, ψ ...orthogonal scaling and wavelet function, respectively
- A_{j0}(k) ... scaling coefficients (approximations)
- $D_i(k)$... wavelet coefficients (details)

- M = 2^J ... number of samples in function f
- $j \in \{j_0, ..., J-1\}$... level of detail, where $j_0 \ge 0$
- $k \in \{0, 1, \dots, 2^j 1\}$

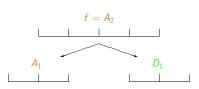
An example

Input:

•
$$f = [1, 4, -3, 0]$$

•
$$|f| = M = 4$$
 \Rightarrow $J = 2$

• decomposition level: $j_0 = 1$



$$A_{1}(0) = \frac{1}{2} \sum_{m=0}^{3} f(m) \varphi_{1,0}(m) = \frac{1}{2} [1 \cdot \sqrt{2} + 4 \cdot \sqrt{2} + (-3) \cdot 0 + 0 \cdot 0] = \frac{5}{\sqrt{2}}$$

$$A_{1}(1) = \frac{1}{2} \sum_{m=0}^{3} f(m) \varphi_{1,1}(m) = \frac{1}{2} [1 \cdot 0 + 4 \cdot 0 + (-3) \cdot \sqrt{2} + 0 \cdot \sqrt{2}] = \frac{-3}{\sqrt{2}}$$

$$D_{1}(0) = \frac{1}{2} \sum_{m=0}^{3} f(m) \psi_{1,0}(m) = \frac{1}{2} [1 \cdot \sqrt{2} + 4 \cdot (-\sqrt{2}) - 3 \cdot 0 + 0 \cdot 0] = -\frac{3}{\sqrt{2}}$$

$$D_{1}(1) = \frac{1}{2} \sum_{m=0}^{3} f(m) \psi_{1,1}(m) = \frac{1}{2} [1 \cdot 0 + 4 \cdot 0 - 3 \cdot \sqrt{2} + 0 \cdot (-\sqrt{2})] = -\frac{3}{\sqrt{2}}$$

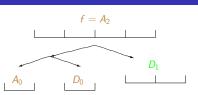
An example

Input:

•
$$f = [1, 4, -3, 0]$$

•
$$|f| = M = 4 \Rightarrow J = 2$$

• decomposition level: $j_0 = 0$



$$A_{0}(0) = \frac{1}{2} \sum_{m=0}^{3} f(m) \varphi_{0,0}(m) = \frac{1}{2} [1 \cdot 1 + 4 \cdot 1 - 3 \cdot 1 + 0 \cdot 1] = 1$$

$$D_{0}(0) = \frac{1}{2} \sum_{m=0}^{3} f(m) \psi_{0,0}(m) = \frac{1}{2} [1 \cdot 1 + 4 \cdot 1 - 3 \cdot (-1) + 0 \cdot (-1)] = 4$$

$$D_{1}(0) = \frac{1}{2} \sum_{m=0}^{3} f(m) \psi_{1,0}(m) = \frac{1}{2} [1 \cdot \sqrt{2} + 4 \cdot (-\sqrt{2}) - 3 \cdot 0 + 0 \cdot 0] = -\frac{3}{2} \sqrt{2}$$

$$D_{1}(1) = \frac{1}{2} \sum_{m=0}^{3} f(m) \psi_{1,1}(m) = \frac{1}{2} [1 \cdot 0 + 4 \cdot 0 - 3 \cdot \sqrt{2} + 0 \cdot (-\sqrt{2})] = -\frac{3}{2} \sqrt{2}$$

An example

DWT
$$(f) = [1, 4, -\frac{3}{2}\sqrt{2}, -\frac{3}{2}\sqrt{2}], \text{ i.e.}$$

$$f(m) = IDWT([1, 4, -\frac{3}{2}\sqrt{2}, -\frac{3}{2}\sqrt{2}])$$

$$= \frac{1}{2}A_0(0) \cdot \varphi_{0,0}(m) + \frac{1}{2}(D_0(0) \cdot \psi_{0,0}(m) + D_1(0) \cdot \psi_{1,0}(m) + D_1(1) \cdot \psi_{1,1}(m))$$

$$= \frac{1}{2} \cdot 1 \cdot \varphi_{0,0}(m) + \frac{1}{2}\left(4 \cdot \psi_{0,0}(m) - \frac{3}{2}\sqrt{2} \cdot \psi_{1,0}(m) - \frac{3}{2}\sqrt{2} \cdot \psi_{1,1}(m)\right)$$

Utilization of the same basis functions in forward and inverse transforms is conditioned to orthonormality of selected functions.

An example

After submitting signal

$$f = \boxed{f(0)} \boxed{f(1)} \boxed{f(2)} \boxed{f(3)}$$

to 1D-DWT, we obtain separately approximations and details of the signal:

- for $j_0 = 2$: no decomposition
- for $j_0 = 1$: DWT(f) = $A_1(0) | A_1(1) | D_1(0) | D_1(1)$
- for $j_0 = 0$: DWT(f) = $A_0(0)$ $D_0(0)$ $D_1(0)$ $D_1(1)$

Notice: The output signal is always of the same length as the input signal.

Variability & Issues

The common families of scaling (father) and wavelet (mother) functions

- Haar (already introduced)
- Daubechies: db1, db2, db3, db4, ...
- Meyer
- Coiflets: coif1, coif2, coif3, ...
- Symlets: sym2, sym3, sym4, ...
- Biorthogonal: bior1, bior2, bior3, . . .

Complexity of 1D-DWT

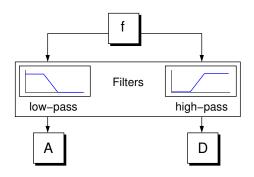
- matrix multiplication $O(n^2)$
- the whole transform matrix typically built only for Haar wavelets
- other wavelets computed iteratively (one matrix per one level of decomposition) \Rightarrow iterations \times $O(n^2)$
- can we speed it up?

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Signal Analysis

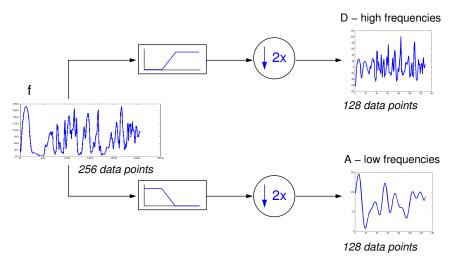
Any signal f can be decomposed into two parts:

- approximation (A) ... obtained by low-pass filtering of the original signal
- detail (D) ... obtained by high-pass filtering of the original signal



Signal Analysis

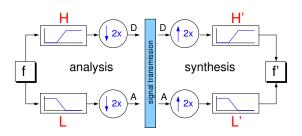
The filtered signal must be downsampled $(\downarrow 2\times)$ to avoid data redundancy.



Signal Analysis and Synthesis

The decomposed signal may be reconstructed:

- detail (D) is upsampled ($\uparrow 2 \times$) and then high-pass filtered
- approximation (A) is upsampled ($\uparrow 2 \times$) and then low-pass filtered
- results are added $\rightarrow f'$

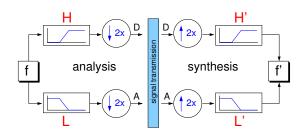


Notice: We would like to have f = f'

Signal Analysis and Synthesis

Filter banks

- H ... high-pass analysis filter (FIR)
- L ... low-pass analysis filter (FIR)
- H' ... high-pass synthesis filter (FIR)
- L' ... low-pass synthesis filter (FIR)



Signal Analysis and Synthesis

Filter banks

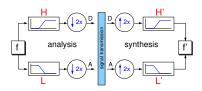
If f = f' then the filters L, L', H, H' are called perfect reconstruction filters and they must fulfill one of the following conditions:

$$H'(n) = (-1)^n L(n)$$

 $L'(n) = (-1)^{n+1} H(n)$

$$H'(n) = (-1)^{n+1}L(n)$$

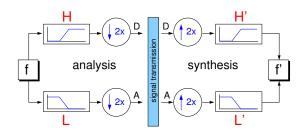
 $L'(n) = (-1)^nH(n)$



Signal Analysis and Synthesis

Filter banks

- \bullet H and L' are mutually cross-modulated
- H' and L are mutually cross-modulated
- H, H', L, L' are called quadrature mirror filters (QMF)

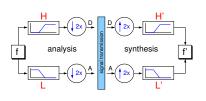


Signal Analysis and Synthesis

Filter banks

Biorthogonal filters

We need to define two filters H and L. The remaining H' and L' are derived by cross-modulation.



Orthogonal filters

We define only one filter H'. The remaining filters fulfill:

$$L'(n) = (-1)^n H'(length - 1 - n)$$

$$H(n) = H'(length - 1 - n)$$

$$L(n) = L'(length - 1 - n)$$

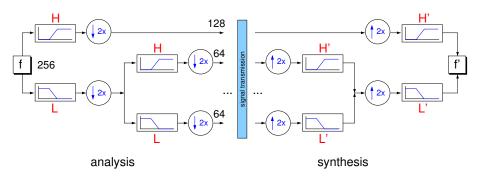
where

length = size(H') &
is_even(length) = true

Notice: We will focus namely on the orthogonal filters.

Recursive Signal Analysis

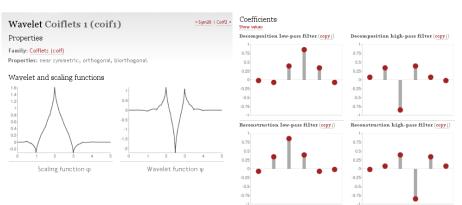
Once the input signal is decomposed into two parts (A and D), its approximation (A) can be further decomposed. In the reverse order, the same is valid for reconstruction.



Notice: Let us assume we have already employed (bi)orthogonal filters.

The most common orthogonal filters

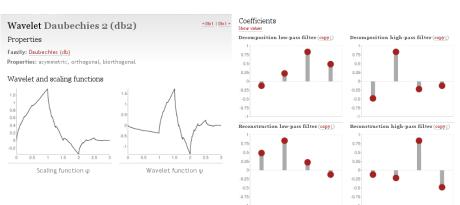
... and their scaling and wavelet functions



Notice: Useful web-pages: http://wavelets.pybytes.com/

The most common orthogonal filters

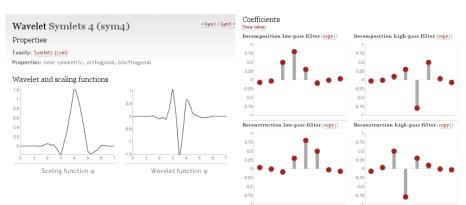
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The most common orthogonal filters

...and their scaling and wavelet functions

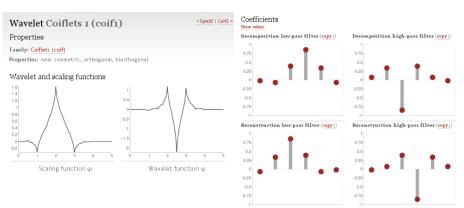


Notice: Useful web-pages: http://wavelets.pybytes.com/

Subband Coding

The most common orthogonal filters

... and their scaling and wavelet functions



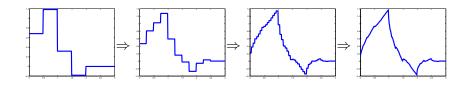
Notice: Useful web-pages: http://wavelets.pybytes.com/

From Filter Banks to Wavelets

Cascade algorithm for φ function (numerical solution)

Algorithm

- 1: $L' \leftarrow$ fetch low-pass synthesis filter from the selected filter bank
- 2: $h_{\varphi} = fliplr(L')$
- 3: $\varphi \leftarrow \mathsf{Dirac} \; \mathsf{delta} \; \mathsf{impulse}$
- 4: **while** (φ is converging) **do**
- 5: $\varphi \leftarrow \operatorname{conv}(\varphi, h_{\varphi})$
- 6: $\varphi \leftarrow \text{upsample}(\varphi, 2 \times)$
- 7: end while
- 8: OUTPUT $\leftarrow \varphi$

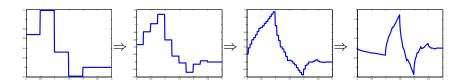


From Filter Banks to Wavelets

Cascade algorithm for ψ function (numerical solution)

Algorithm

- 1: $\varphi \leftarrow \text{call Cascade algorithm to get } \varphi \text{ function}$
- 2: $H' \leftarrow$ fetch high-pass synthesis filter from the selected filter bank
- 3: $h_{\psi} = \text{fliplr}(H')$
- 4: $\psi \leftarrow \text{conv}(\varphi, h_{\psi})$
- 5: $\psi \leftarrow \mathtt{upsample}(\psi, 2 \times)$
- 6: OUTPUT $\leftarrow \psi$



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Definition

$$D_{j}(k) = \sum_{r=0}^{|A_{j+1}|-1} H'(2k+1-r)A_{j+1}(r)$$

$$A_{j}(k) = \sum_{r=0}^{|A_{j+1}|-1} L'(2k+1-r)A_{j+1}(r)$$

$$A_{J}(k) = f(k)$$

Each step in FWT corresponds to convolution with high-pass and low-pass analysis filter followed by down-sampling $(\downarrow 2\times)$.

 $1D-DWT \equiv Subband coding$

Basic scheme

 $D_0(0)$

 $A_0(0)$

Fast Wavelet Transform

An example

Given f(k) = [1, 4, -3, 0] and Haar scaling and wavelet coefficients

$$L'(k) = \left\{ \begin{array}{ll} 1/\sqrt{2} & k = 0, 1 \\ 0 & \text{otherwise} \end{array} \right. \ \, \text{and/} \quad H'(k) = \left\{ \begin{array}{ll} -1/\sqrt{2} & k = 0 \\ 1/\sqrt{2} & k = 1 \\ 0 & \text{otherwise} \end{array} \right.$$

we can evaluate the following:

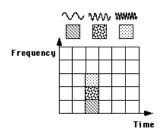
level 2:
$$A_2(k) = f(k) = [1, 4, -3, 0]$$

level 1: $A_1(k) = \sum_{r=0}^{3} L'(2k+1-r)A_2(r) = [5/\sqrt{2}, -3/\sqrt{2}]$
 $D_1(k) = \sum_{r=0}^{3} H'(2k+1-r)A_2(r) = [-3/\sqrt{2}, -3/\sqrt{2}]$
level 0: $A_0(k) = \sum_{r=0}^{1} L'(2k+1-r)A_1(r) = [1]$
 $D_0(k) = \sum_{r=0}^{1} H'(2k+1-r)A_1(r) = [4]$

Comparison of FWT and FFT

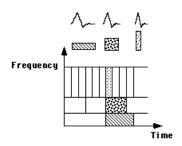
Fast Fourier Transform

- complexity: $O(n \log n)$
- existence: at any time
- time versus frequency domain



Fast Wavelet Transform

- complexity O(cn)
 c . . . support of L' filter (typically small)
- existence: depends upon the availability of scaling function and the orthogonality of the scaling function
- time & frequency changes simultaneously



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- Wavelet Packets

An extension of scaling function and wavelets to 2D in straightforward:

$$\varphi(x) \rightarrow \varphi(x,y)
\psi(x) \rightarrow \psi^{H}(x,y), \psi^{V}(x,y), \psi^{D}(x,y)$$

where all the 2D functions are separable in the following manner:

$$\varphi(x,y) = \varphi(x)\varphi(y)
\psi^{H}(x,y) = \psi(x)\varphi(y)
\psi^{V}(x,y) = \varphi(x)\psi(y)
\psi^{D}(x,y) = \psi(x)\psi(y)$$

What is the meaning of new wavelets?

- $\psi^H(x,y)$... intensity variations for image columns
- $\psi^{V}(x,y)$... intensity variations along rows
- $\psi^D(x,y)$... intensity variations along diagonals

Corollary:

$$\begin{array}{lcl} \varphi_{j,m,n}(x,y) & = & 2^{j/2} \varphi \left(2^{j} \frac{x}{M} - m, 2^{j} \frac{y}{N} - n \right) \\ \psi^{i}_{j,m,n}(x,y) & = & 2^{j/2} \psi^{i} \left(2^{j} \frac{x}{M} - m, 2^{j} \frac{y}{N} - n \right), \quad i = \{H, V, D\} \end{array}$$

Definition

Forward

$$A_{j_0}(m,n) = \frac{1}{\sqrt{MN}} \sum_{k=0}^{M-1} \sum_{l=0}^{N-1} f(k,l) \varphi_{j_0,m,n}(k,l)$$

$$D_j^i(m,n) = \frac{1}{\sqrt{MN}} \sum_{k=0}^{M-1} \sum_{l=0}^{N-1} f(k,l) \psi_{j,m,n}^i(k,l)$$

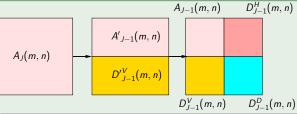
Inverse

$$f(k,l) = \frac{1}{\sqrt{MN}} \sum_{m} \sum_{n} A_{j_0}(m,n) \varphi_{j_0,m,n}(k,l) + \frac{1}{\sqrt{MN}} \sum_{i=H,V} \sum_{D} \sum_{j=i_0}^{J-1} \sum_{m} \sum_{n} D_j^i(m,n) \psi_{j,m,n}^i(k,l)$$

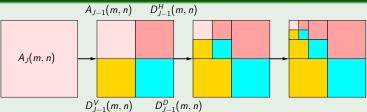
where $i = \{H, V, D\}$

Practical implementation

1-level decomposition as a 2-step process



n-th level decomposition as a iterative process



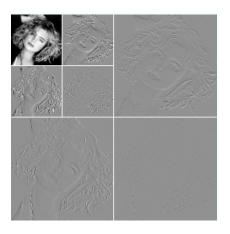
An example - DWT using Haar wavelets



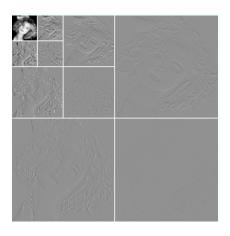
An example – DWT using Haar wavelets



An example – DWT using Haar wavelets



An example - DWT using Haar wavelets



An example - DWT using Haar wavelets



An example

$DWT \rightarrow modification \rightarrow IDWT$





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- 6 2D Discrete Wavelet Transform
- Wavelet Packets

Wavelet Packets

Problem to solve:

Traditional wavelet transform decomposes the (image) data always in the same manner.

Solution:

Decompose those parts of the data which need it.

An example:

The lowest entropy lead to better compression. Let us split those parts of the image (not only $A_j(m, n)$) which need it \rightarrow which division causes entropy reduction.

Bibliography

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You should know the answers . . .

- Explain the difference between Fourier basis functions and scaling and wavelet functions.
- Given a signal of fixed length and given a particular scaling a wavelet function we can perform discrete wavelet transform. The result is however not unique. Which parameter controls the behaviour of DWT? Demonstrate on some sample data.
- Explain the meaning of A and D coefficients.
- Derive the complexity for DWT and separately for FWT.
- What would happen if the quadrature mirror filters are not perfect reconstruction filters.
- Describe the Cascade algorithm.
- Design an algorithm for computing 2D-FWT.