

Lesson 13

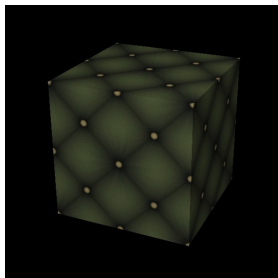
Parallax Occlusion Mapping

PV227 – GPU Rendering

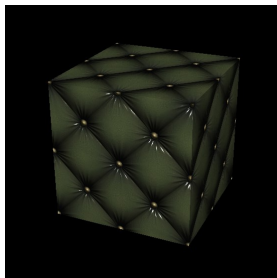
Jiří Chmelík, Jan Čejka
Fakulta informatiky Masarykovy univerzity

10. 12. 2019

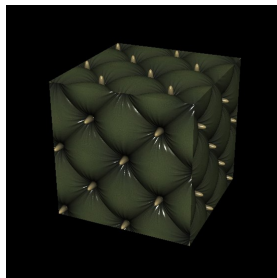
Parallax Occlusion Mapping



Nothing

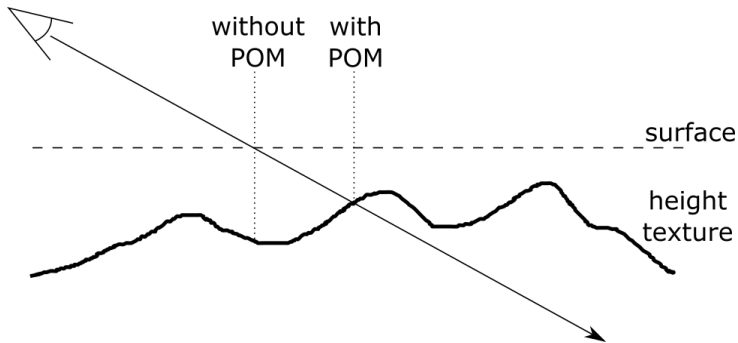


Normal mapping



Parallax Occlusion
Mapping

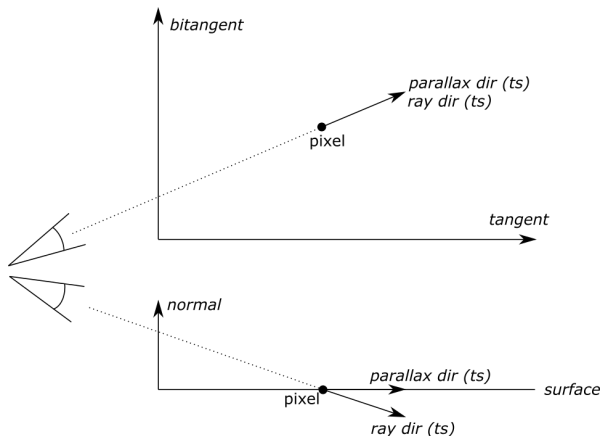
Basic principle



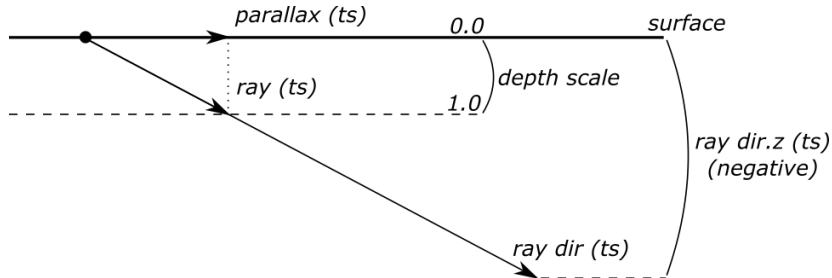
Basic principle

Parallax direction

- We work in the tangent space (ts) (on the surface of the object)
- $parallax\ dir(ts) = ray\ dir.xy(ts)$



Maximal parallax



$$\frac{\text{ray}(ts)}{\text{depth scale}} = \frac{\text{ray dir}(ts)}{-\text{ray dir.z}(ts)}$$

$$\frac{\text{ray}(ws)}{\text{depth scale}} = \frac{\text{ray dir}(ws)}{-\text{ray dir.z}(ts)}$$

$$\text{parallax}(ts) = \text{ray.xy}(ts)$$

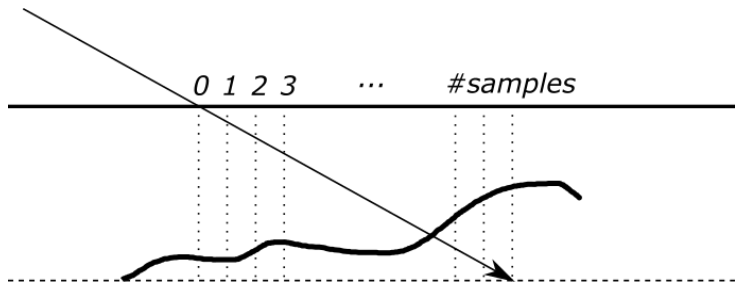
Texture space

- Our space with texture coordinates is a little different from the tangent space
- Directions of tangents and bitangents are the same as directions of s and t coordinates
- The sizes are different

$$\mathit{parallax}(t\mathit{ex}s) = \mathit{ts_to_t\mathit{ex}s} \cdot \mathit{parallax}(t\mathit{s})$$

Sampling

- Sample the height texture to find the first intersection



Algorithm

```
for sample i do  
  percentage  $\leftarrow i / \#samples$   
  sample_tex_coord  $\leftarrow tex\_coord_0 + parallax\_texs \cdot percentage$   
  tex_depth  $\leftarrow$   
    one_minus_sample(height_tex, sample_tex_coord)  
  ray_depth  $\leftarrow percentage$   
  if ray_depth > tex_depth then  
    | break  
  end  
end
```

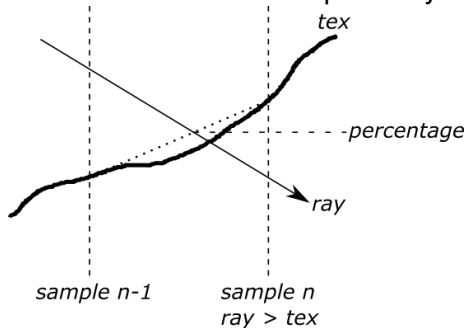
Use last *percentage* to compute the final texture coordinate and position.

Task: Implement POM

- **Task 1:** Implement this algorithm

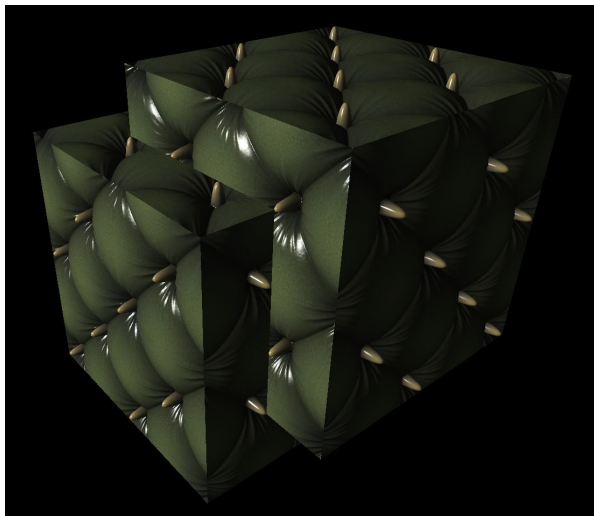
Task: Improve POM

- **Task 2:** Compute the intersection more precisely



- **Result:** Better result with less samples

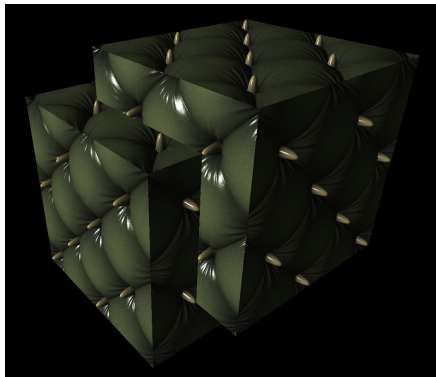
Interaction with other objects



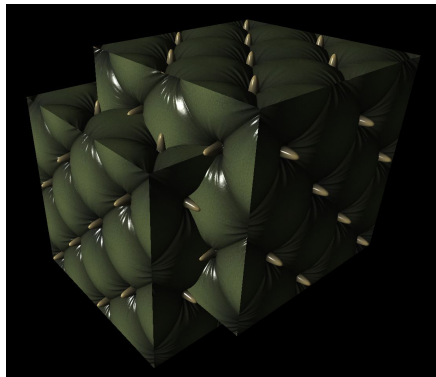
Task: Improve interaction with other objects

- **Task 3:** Adjust fragment's depth
 - ▶ Transform offseted position into clip space (transform in with *view* and *projection* matrices)
 - ▶ Transform it into normalized device coordinates (divide it with its *w*)
 - ▶ Transform it from $[-1, 1]$ to $[0, 1]$
 - ▶ Store its *z* into *gl_FragDepth*

Task: Improve interaction with other objects



Without depth adjustment

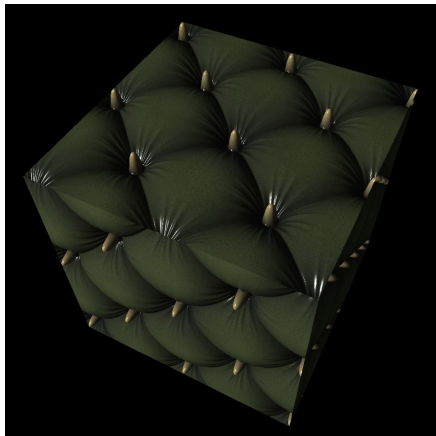


With depth adjustment

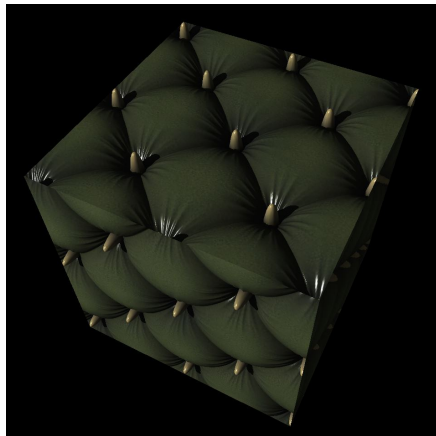
Task: Self-shadowing

- **Task 4:** Implement self-shadowing
 - ▶ Cast another ray from the offseted position to the light
 - ▶ Check whether there is an obstacle in the height map

Task: Self-shadowing



Without self-shadows



With self-shadows