

# GPU Hardware Performance

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# Atomic operations

- performs read-modify-write operations on shared or global memory
- no interference with other threads
- for 32-bit and 64-bit integers (c. c.  $\geq 1.2$ ), float addition (c. c.  $\geq 2.0$ ), double addition (c.c.  $\geq 6.0$ )
- using global memory for c. c.  $\geq 1.1$  and shared memory for c. c.  $\geq 1.2$
- arithmetic (Add, Sub, Exch, Min, Max, Inc, Dec, CAS) a bitwise (And, Or, Xor) operations

# Warp Voting

All threads in one warp evaluate the same condition and perform its comparison. Available in c. c.  $\geq 1.2$ .

```
int __all(int predicate);
```

Result is non-zero iff the predicate is non-zero for all the threads in the warp.

```
int __any(int predicate);
```

Result is non-zero iff the predicate is non-zero for at least one thread in the warp.

```
unsigned int __ballot(int predicate);
```

Contains voting bit mask of individual threads.

# Shuffle Functions

Threads within a warp can efficiently communicate using warp shuffle functions (from c.c.  $\geq 3.0$ ).

```
float __shfl_sync(float var, int srcLane, int width=warpSize);
```

Copy value from srcLane.

```
float __shfl_up_sync(float var, unsigned int delta, int width=warpSize);
```

Copy value from threads with lower ID relative to caller. Analogically `__shfl_down`.

```
float __shfl_xor_sync(float var, int laneMask, int width=warpSize);
```

Copy from a thread based on bitwise XOR of own ID and laneMask.

Parameter `width` defines the number of participating threads. It must be power of two, indexing starts at 0.

# Synchronization of Memory Operations

Compiler can optimize operations on shared/global memory (intermediate results may be kept in registers) and can reorder them

- if we need to ensure that the data are visible for others, we use `__threadfence()` or `__threadfence_block()`
- if a variable is declared as `volatile`, all load/store operations are implemented in shared/global memory
  - very important if we assume implicit warp synchronization (c.c. 6.0 or lower)

# Global Synchronization using Atomic Operations

Alternative implementation of a vector reduction

- each thread block sums elements in its part of a vector
- barrier (weak global barrier)
- one thread block sums results of all the blocks

```
__device__ unsigned int count = 0;
__shared__ bool isLastBlockDone;
__global__ void sum(const float* array, unsigned int N,
float* result) {
    float partialSum = calculatePartialSum(array, N);
    if (threadIdx.x == 0) {
        result[blockIdx.x] = partialSum;
        __threadfence();
        unsigned int value = atomicInc(&count, gridDim.x);
        isLastBlockDone = (value == (gridDim.x - 1));
    }
    __syncthreads();
    if (isLastBlockDone) {
        float totalSum = calculateTotalSum(result);
        if (threadIdx.x == 0) {
            result[0] = totalSum;
            count = 0;
        }
    }
}
```

# Global Memory Access Optimization

Performance of global memory becomes a bottleneck easily

- global memory bandwidth is low relatively to arithmetic performance of GPU (GT200  $\geq$  24 FLOPS/float, GF100  $\geq$  30, GK110  $\geq$  62, GM200  $\geq$  73, GP100  $\geq$  53, GV100  $\geq$  67, TU102  $\geq$  76, GA100  $\geq$  50)
- 400–600 cycles latency

The throughput can be significantly worse with bad parallel access pattern

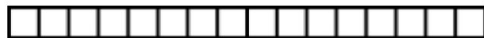
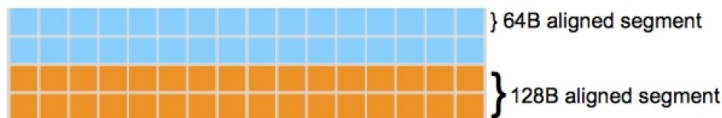
- the memory has to be accessed *coalesced*
- use of just certain subset of memory regions should be avoided (*partition camping*)



# Coalesced Memory Access (C. C. < 2.0)

GPU memory needs to be accessed in larger blocks for efficiency

- global memory is split into 64 B segments
- two of these segments are aggregated into 128 B segments



Half warp of threads

## Coalesced Memory Access (C. C. < 2.0)

A half of a warp can transfer data using single transaction or one to two transactions when transferring a 128 B word

- it is necessary to use large words
- one memory transaction can transfer 32 B, 64 B, or 128 B words
- GPUs with c. c.  $\leq 1.2$ 
  - the accessed block has to begin at an address divisible by  $16 \times$  data size
  - $k$ -th thread has to access  $k$ -th block element
  - some threads may not participate
- if these rules are not obeyed, each element is retrieved using a separate memory transaction

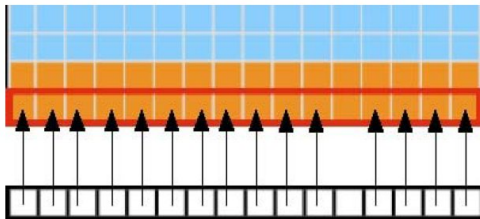
# Coalesced Memory Access (C. C. < 2.0)

GPUs with c. c.  $\geq 1.2$  are less restrictive

- each transfer is split into 32 B, 64 B, or 128 B transactions in a way to serve all requests with the least number of transactions
- order of threads can be arbitrarily permuted w.r.t. transferred elements

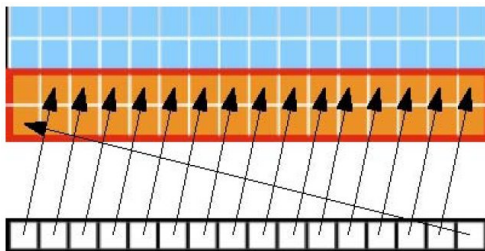
# Coalesced Memory Access (C. C. < 2.0)

Threads are aligned, element block is contiguous, order is not permuted – coalesced access on all GPUs



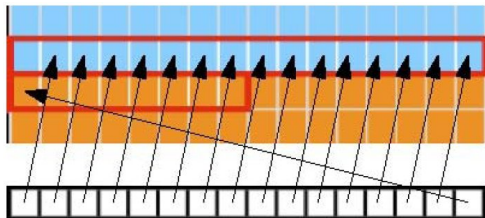
# Unaligned Memory Access (C. C. < 2.0)

Threads **are not** aligned, contiguous elements accessed, order is not permuted – one transaction on GPUs with c. c.  $\geq 1.2$



# Unaligned Memory Access (C. C. < 2.0)

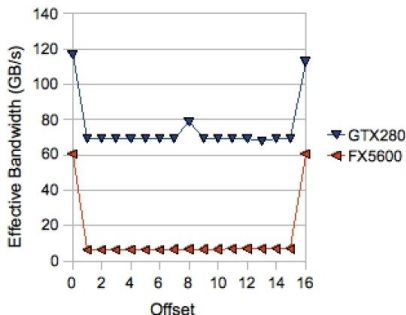
Similar case may result in a need for two transactions



# Unaligned Memory Access Performance (C. C. < 2.0)

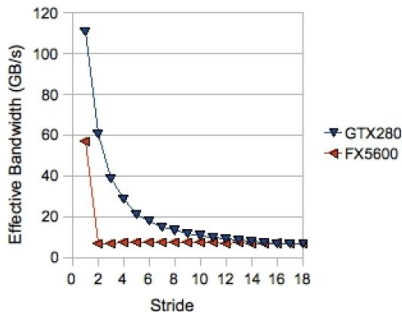
Older GPUs perform smallest possible transfer (32 B) for each element, thus reducing performance to 1/8

Newer GPUs perform (c. c.  $\geq 1.2$ ) two transfers



# Interleaved Memory Access Performance (C. C. < 2.0)

The bigger the spaces between elements, the bigger performance drop on GPUs with c. c.  $\geq 1.2$  – the effect is rather dramatic





# Global Memory Access with Fermi (C. C. = 2.x)

Fermi has L1 and L2 cache

- L1: 256 B per row, 16 kB or 48 kB per multiprocessor in total
- L2: 32 B per row, 768 kB on GPU in total

What are the advantages?

- more efficient programs with unpredictable data locality
- more efficient when shared memory is not used from some reason
- unaligned access – no slowdown in principle
- interleaved access – data needs to be used before it is flushed from the cache, otherwise the same or bigger problem as with c. c. < 2.0 (L1 cache may be turned of to avoid overfetching)

# Global Memory Access with "gaming" Kepler (C. C. = 3.0)

There is only L2 cache for read/write global memory access

- L2: 32 B per row, up to 1.5 MB per GPU
- L1: for local memory, 16 KB, 32 KB or 48 KB in total

# Global Memory Access with fully-featured Kepler and newer (C. C. $\geq 3.5$ )

## Read-only data cache

- shared with textures
- compiler tries to use, we can help with `__restrict__` and `__ldg()`
- slower than Fermi's L1

Maxwell and Pascal does not have L1 cache for local memory

- inefficient for programs heavily using local memory

# Partition camping

- relevant for c. c. 1.x (and AMD GPUs)
- processors based on G80 have 6 regions, G200 have 8 regions of global memory
- the memory is split into regions in 256 B chunks
- even access among the regions is needed for maximum performance
  - among individual blocks
  - block are usually run in order given by their position in the grid
- if only part of regions is used, the resulting condition is called *partition camping*
- generally not as critical as the coalesced access
- more tricky, problem size dependent, not visible from fine-grained perspective

# HW Organization of Shared Memory

Shared memory is organized into memory banks, which can be accessed in parallel

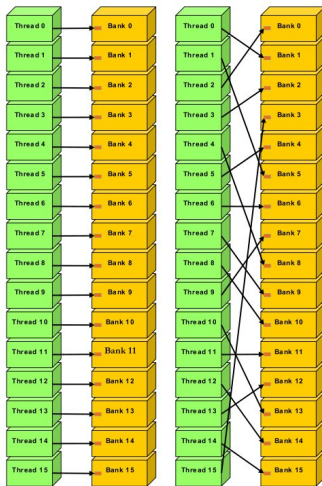
- c. c. 1.x 16 banks, c. c.  $\geq 2.0$  32 banks
- memory space mapped in an interleaved way with 32 b shift or 64 b shift (c.c. 3.x)
- to use full memory performance, we have to access data in different banks
- broadcast implemented – if all threads access the same data

# Bank Conflict

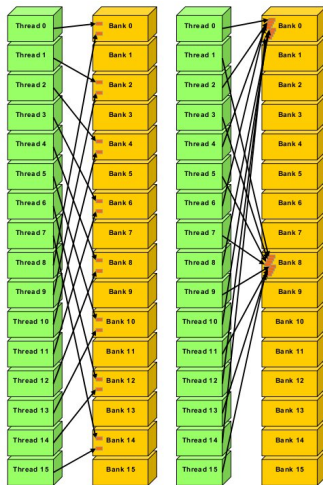
## Bank conflict

- occurs when some threads in warp/half-warp access data in the same memory bank with several exceptions
  - threads access exactly the same data
  - threads access different half-words of 64 b word (c.c. 3.x)
- when occurs, memory access gets serialized
- performance drop is proportional to number of parallel operations that the memory has to perform to serve a request

# Access without Conflicts

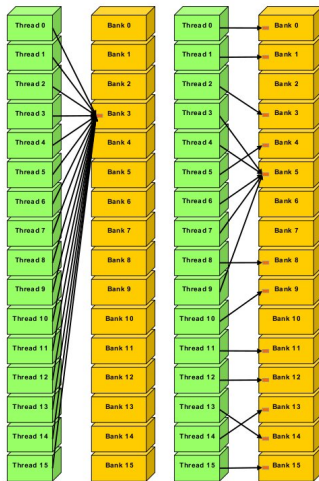


# n-Way Conflicts





# Broadcast



# Access Patterns

Alignment is not needed, bank conflicts not generated

```
int x = s[threadIdx.x + offset];
```

Interleaving does not create conflicts if  $c$  is odd, for  $c.c. \geq 3.0$  no conflict if  $c = 2$  and 32 b numbers are accessed

```
int x = s[threadIdx.x * c];
```

Access to the same variable never generates conflicts on  $c.c. 2.x$ , while on  $1.x$  only if thread count accessing the variable is multiple of 16

```
int x = s[threadIdx.x / c];
```

# Other Memory Types

## Transfers between host and GPU memory

- need to be minimized (often at cost of decreasing efficiency of computation on GPU)
- may be accelerated using page-locked memory
- it is more efficient to transfer large blocks at once
- computations and memory transfers should be overlapped

## Texture memory

- designed to reduce number of transfers from the global memory
- does not help if latency is the bottleneck
- may simplify addressing or add filtering

# Other Memory Types

## Constant memory

- as fast as registers if the same value is read by all threads within a warp
- performance decreases linearly with number of different values read

## Registers

- read-after-write latency, hidden if at least 192 threads are running for c. c. 1.x or at least 768 threads are running for c. c. 2.x (approximation)
- possible bank conflicts even in registers
  - compiler tries to avoid them
  - we can make life easier for the compiler if we set block size to multiple of 64