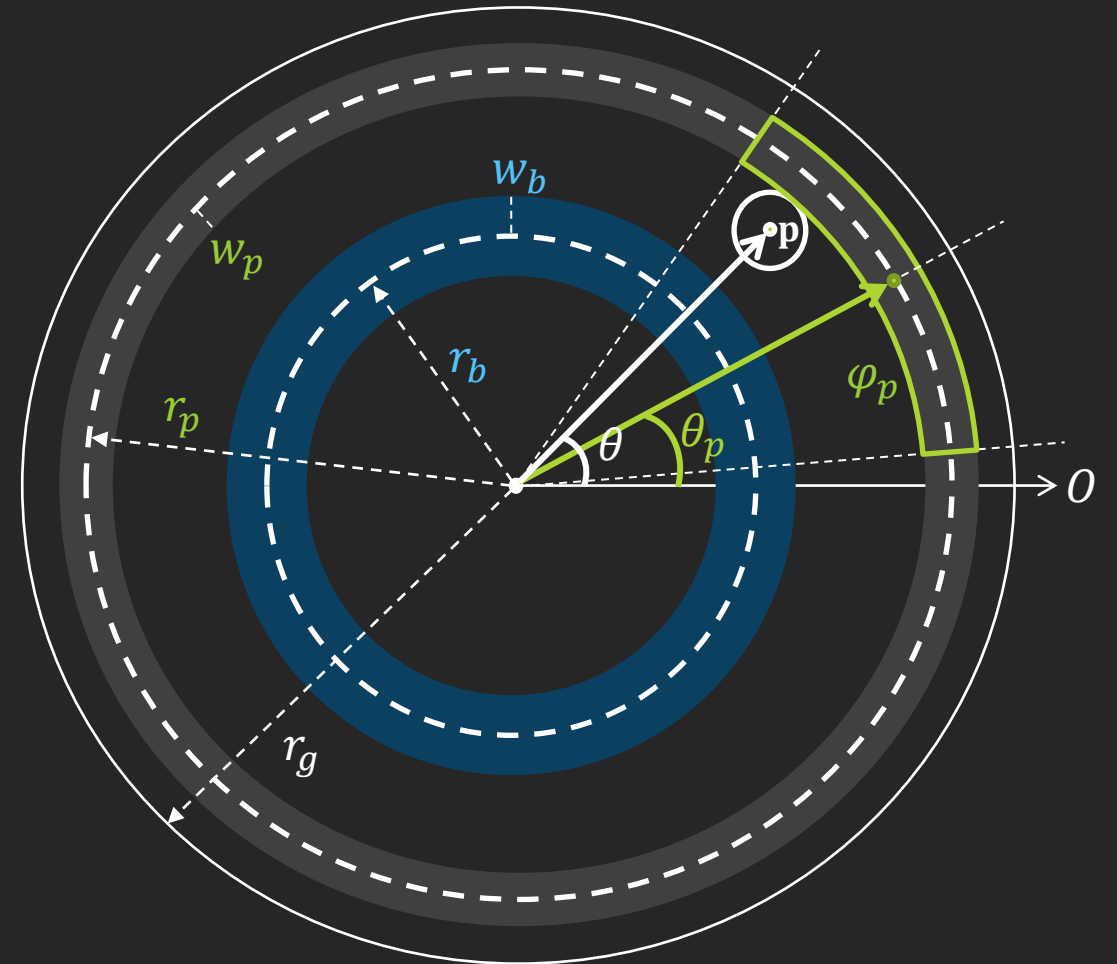


Collision detection and response in the assignment

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PA199

Collision detection: Broad phase

- ▶ Position of the ball: $\mathbf{p} = (\mathbf{p}_x, \mathbf{p}_y, r)^\top$, where r is the radius of the sphere.
- ▶ If $|\mathbf{p}| - r > r_g$ then **GAME OVER**.
- ▶ If $|\mathbf{p}| + r \geq r_p - w_p \wedge |\mathbf{p}| - r \leq r_p + w_p$ then “broad phase with **paddles**”.
- ▶ If $|\mathbf{p}| + r \geq r_b - w_b \wedge |\mathbf{p}| - r \leq r_b + w_b$ then “broad phase with **bricks**”.
- ▶ Otherwise, **no collision**.



Collision detection: Broad phase

Colliding with Paddles (brick wall case is similar)

```
def broad_phase(positions,  $w_p, \varphi_p$ ):
```

```
     $r_p, \theta_p = \text{positions}[0]$ 
```

```
    for  $r'_p, \theta'_p$  in positions[1:]:
```

```
        if min_difference( $\theta, \theta'_p$ )  
           < min_difference( $\theta, \theta_p$ ):
```

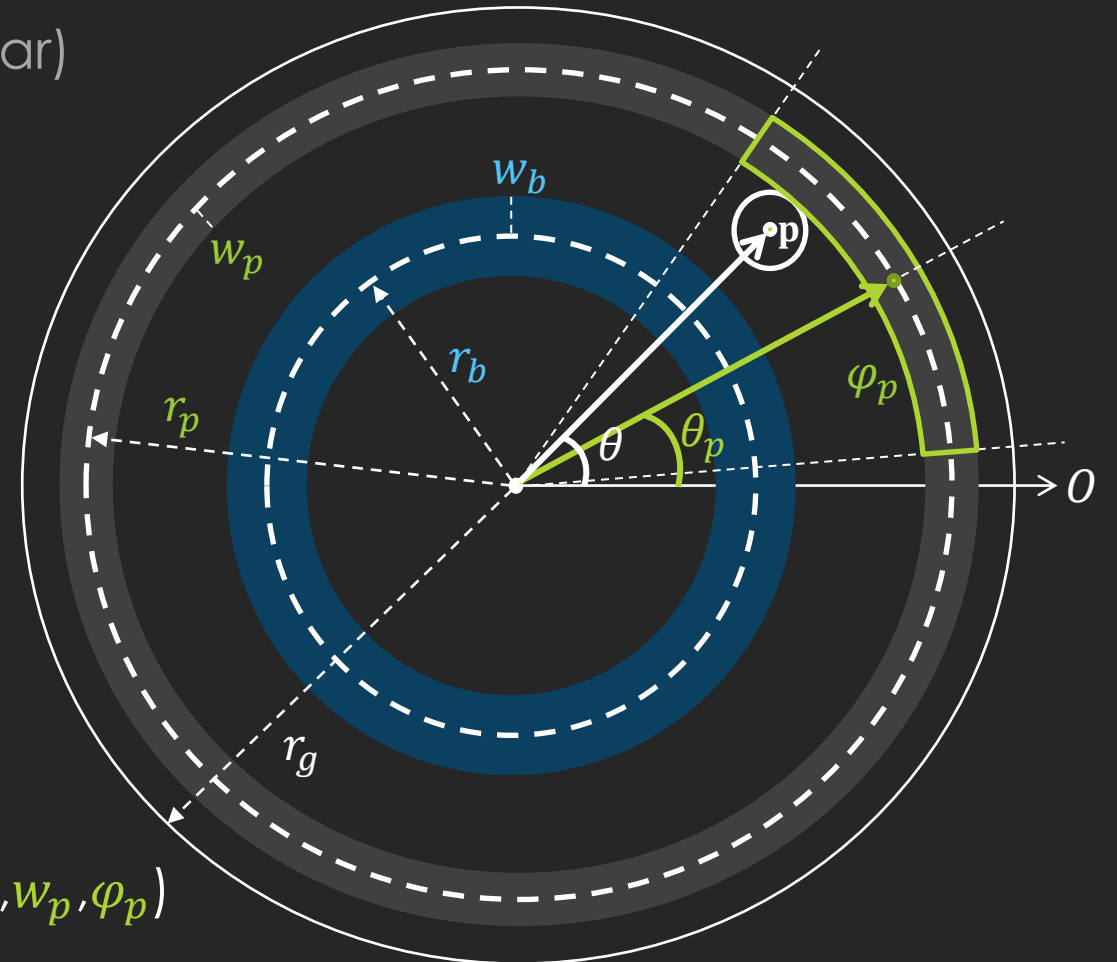
```
             $r_p, \theta_p = r'_p, \theta'_p$ 
```

```
    if min_difference( $\theta, \theta_p$ )  $\leq \varphi_p$ :
```

```
        return narrow_phase_case_1( $\mathbf{p}, r_p$ )
```

```
    else
```

```
        return narrow_phase_case_2( $\mathbf{p}, r, \theta, r_p, \theta_p, w_p, \varphi_p$ )
```



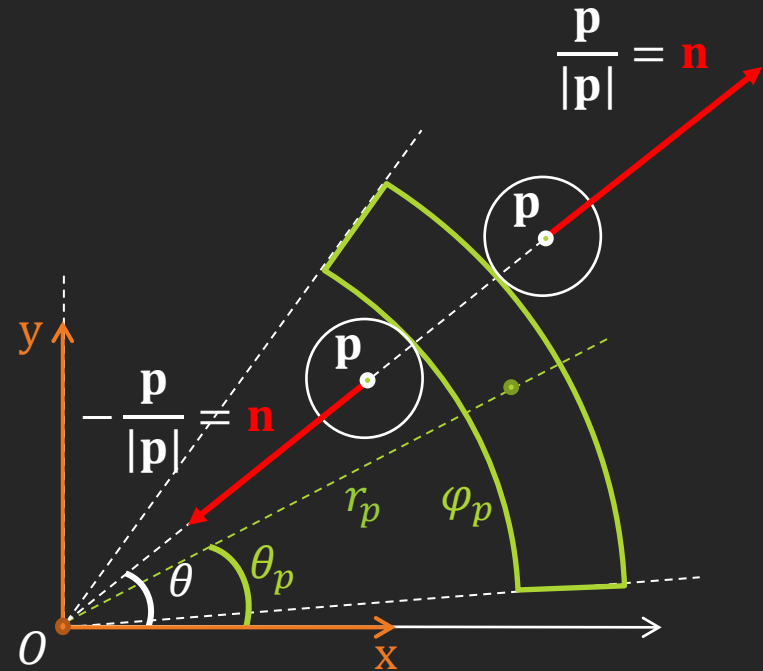
Collision detection: Narrow phase

- ▶ Case 1: “ $\min_difference(\theta, \theta_p) \leq \varphi_p$ ”.

```
def narrow_phase_case_1(p,  $r_p$ ):
```

```
    n = p / |p|
```

```
    return -n if |p| <  $r_p$  else n
```



Collision detection: Narrow phase

► Case 2: “ $\min_difference(\theta, \theta_p) > \varphi_p$ ”.

```
def narrow_phase_case_2(p,  $r$ ,  $\theta$ ,  $r_p$ ,  $\theta_p$ ,  $w_p$ ,  $\varphi_p$ ):
```

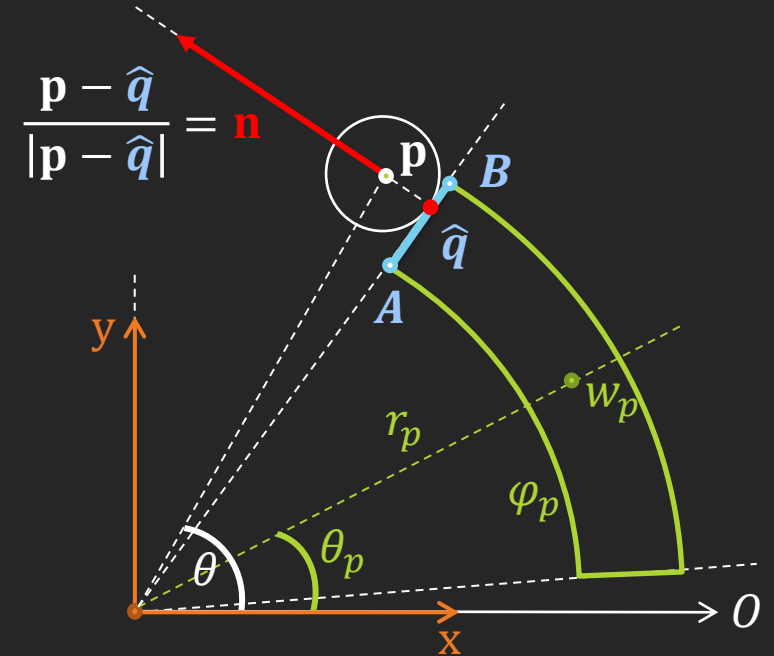
```
    sign = 1 if on_left( $\theta$ ,  $\theta_p + \varphi_p$ ) else -1
```

```
    A = to_cartesian( $r_p - w_p$ ,  $\theta_p + \text{sign} * \varphi_p$ )
```

```
    B = to_cartesian( $r_p + w_p$ ,  $\theta_p + \text{sign} * \varphi_p$ )
```

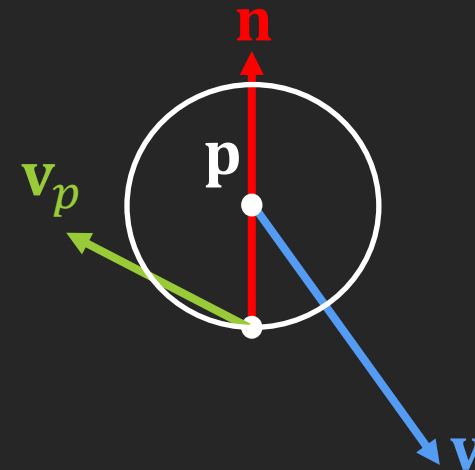
```
     $\hat{q}$  = closest_point_on_line(AB, p)
```

```
    return (p -  $\hat{q}$ ) / |p -  $\hat{q}$ | if |p -  $\hat{q}$ |  $\in$  (0,  $r$ ) else None
```

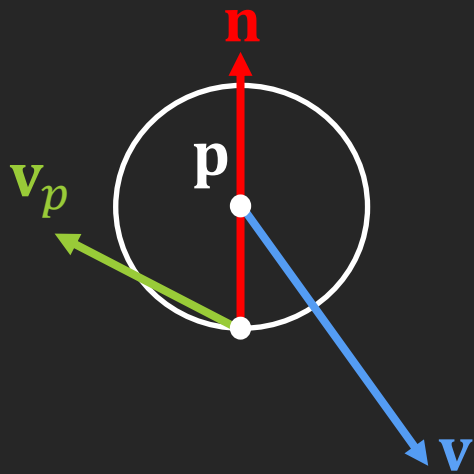


Collision response

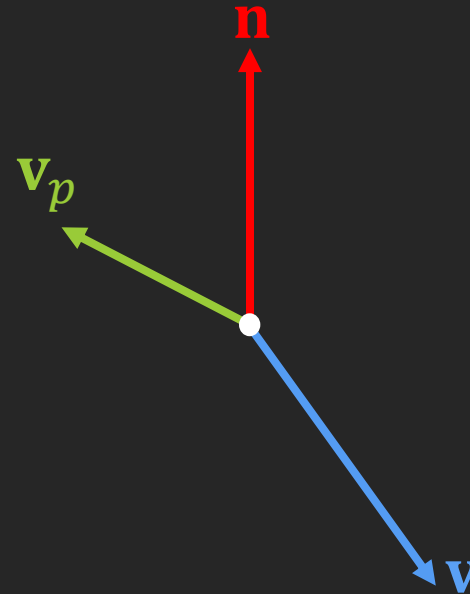
- ▶ Ball's velocity: $\mathbf{v} = (v_x, 0, v_z)^T$, $|\mathbf{v}| = v_0$, where v_0 is the fixed speed.
- ▶ We have the **unit collision normal** $\mathbf{n} = (n_x, n_y, 0)$, $|\mathbf{n}| = 1$ from the collision detection.
- ▶ Velocity of a paddle is \mathbf{v}_p .



Collision response



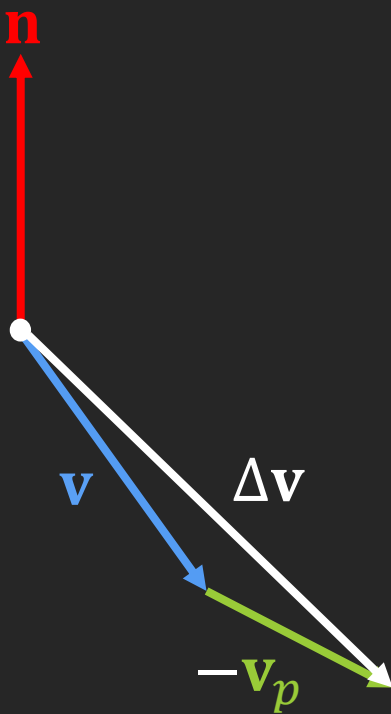
We can model the situation as



Compute the relative velocity



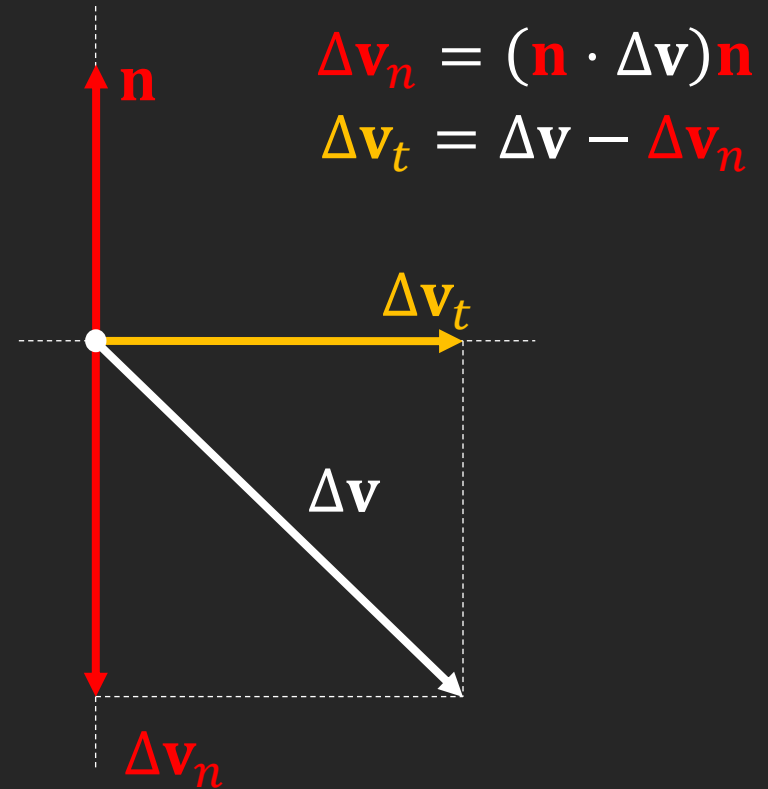
Collision response



Decompose $\Delta\mathbf{v}$



IMPORTANT
Continue only if
 $\Delta\mathbf{v} \cdot \mathbf{n} < 0$



Collision response

- ▶ “Bounce of the paddle” velocity change:

$$\Delta \mathbf{v}'_n = -2\Delta \mathbf{v}_n$$

- ▶ “Match paddle’s velocity” velocity change:

$$\Delta \mathbf{v}'_t = -\mu_p \min\{|\Delta \mathbf{v}_n|, |\Delta \mathbf{v}_t|\} \frac{\Delta \mathbf{v}_t}{|\Delta \mathbf{v}_t|}, \quad \text{if } |\Delta \mathbf{v}_t| > 0,$$

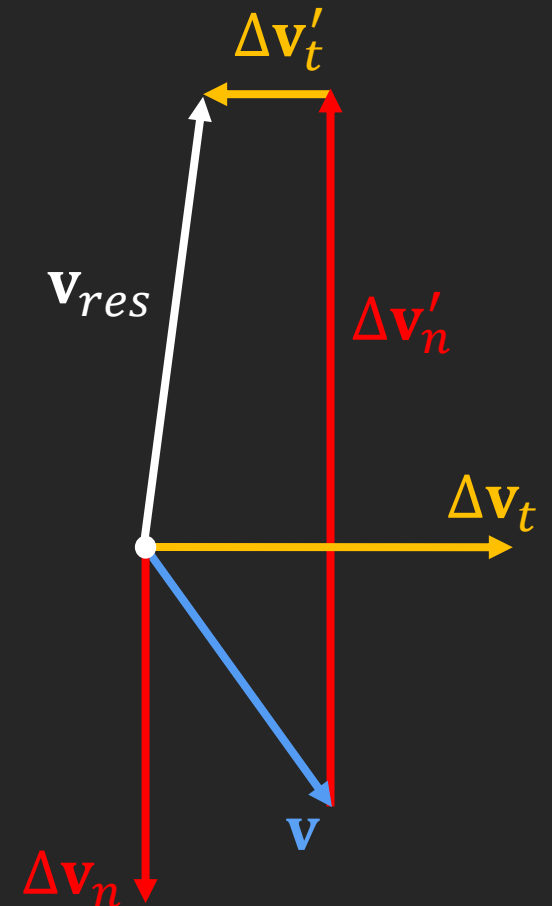
where $0 \leq \mu_p \leq 1$ is a “friction” coefficient.

- ▶ So, the collision response velocity is:

$$\mathbf{v}_{res} = \mathbf{v} + \Delta \mathbf{v}'_n + \Delta \mathbf{v}'_t$$

- ▶ The final velocity is then:

$$\mathbf{v} := v_0 \frac{\mathbf{v}_{res}}{|\mathbf{v}_{res}|}, \quad \text{NOTE: } |\mathbf{v}_{res}| > 0.$$



Implementation notes

- ▶ Polar coordinates:
 - ▶ Always normalize the angles to the range $(0, 2\pi)$ before comparison.
 - ▶ Consider using normalization directly in:
 - ▶ Conversion from the Cartesian to polar coordinates.
 - ▶ Operators for addition and subtraction of angles.
 - ▶ Alternatively, in comparison operators.
 - ▶ Otherwise, assert angles are normalized before comparisons.
 - ▶ When implementing angle comparison algorithm, keep in mind the case of passing the polar axis (in CW or CCW direction).

Implementation notes

► Recommendations:

- Build **tests** and **test scenes** for collision detection and response algorithms.

=> Do **not** build the complete scene of the game (all paddles all wall bricks).

=> Test function “closest_point_on_line” in different situations (configurations of line’s points and the reference point).

=> Test all phases of the collision detection in separate test scenes.

=> Test collision response in separate test scenes (for different velocities of the ball and the paddle).