NXP Semiconductors

User's Guide

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MCUXpresso SDK USB Stack User’s Guide

Contents

Chapter 1 Overview

This document describes the following:

- Steps to compile the USB examples, download a binary image, and run the examples.
- Steps to port the USB stack to a new platform.
- Steps to develop a new application based on the existing classes in the USB stack.

Chapter 2
Build the USB examples in MCUXpresso SDK

This section describes how to compile the USB stack and examples, download a binary image, and run the examples.

2.1 Requirements for building USB examples

The TWR-K22F120M Tower System module or FRDM-K64F Freedom platform is used as an example in this document. The process for compiling, downloading, and running examples is similar on all other boards. For a detailed version of the toolchain software, see the *MCUXpresso SDK Release Notes* (document MCUXSDKRN).

2.1.1 Hardware

- TWR-K22F120M Tower System module and (optional) TWR-SER Tower System module and Elevator
- MCUXpresso SDK Boards
- J-Link debugger (optional)
- USB cables

2.1.2 Software

- MCUXpresso SDK release package
- IAR Embedded Workbench for ARM® Version 8.11.3
- Keil µVision5 Integrated Development Environment Version 5.23 , available for ARM® Cortex®-M4 devices
- MCUXpresso IDE v10.1.0
- Makefiles support with GCC revision 6-2017-q2-update from ARM Embedded

2.2 USB code structure

The USB code is located in the folder:

<install_dir>/middleware/usb

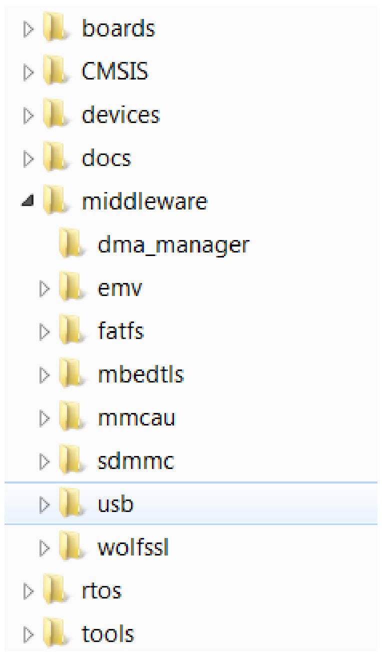


Figure 1. MCUXpresso SDK folder structure

The USB folder includes the source code for stack and examples. Note that the version number of the USB folder may vary.

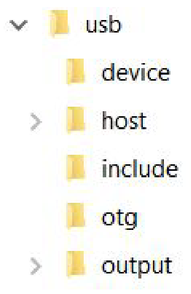


Figure 2. USB folder structure

The USB folder includes the following subfolders:

- device

  This subfolder includes the device controller driver and common device driver for the USB device.
- host

  This subfolder includes the host controller driver and common host driver for the USB host.
- include

  This subfolder includes the definitions and structures for the USB stack.
- otg

  This subfolder includes the OTG controller driver, common OTG driver and OTG peripheral driver for the USB OTG.
- output

  This subfolder includes the files that are specially used by the New Project wizard.

NOTE

For different USB stack versions, the folder structure may be a little different. See the folder structure in the release package to get the exact folder structure.

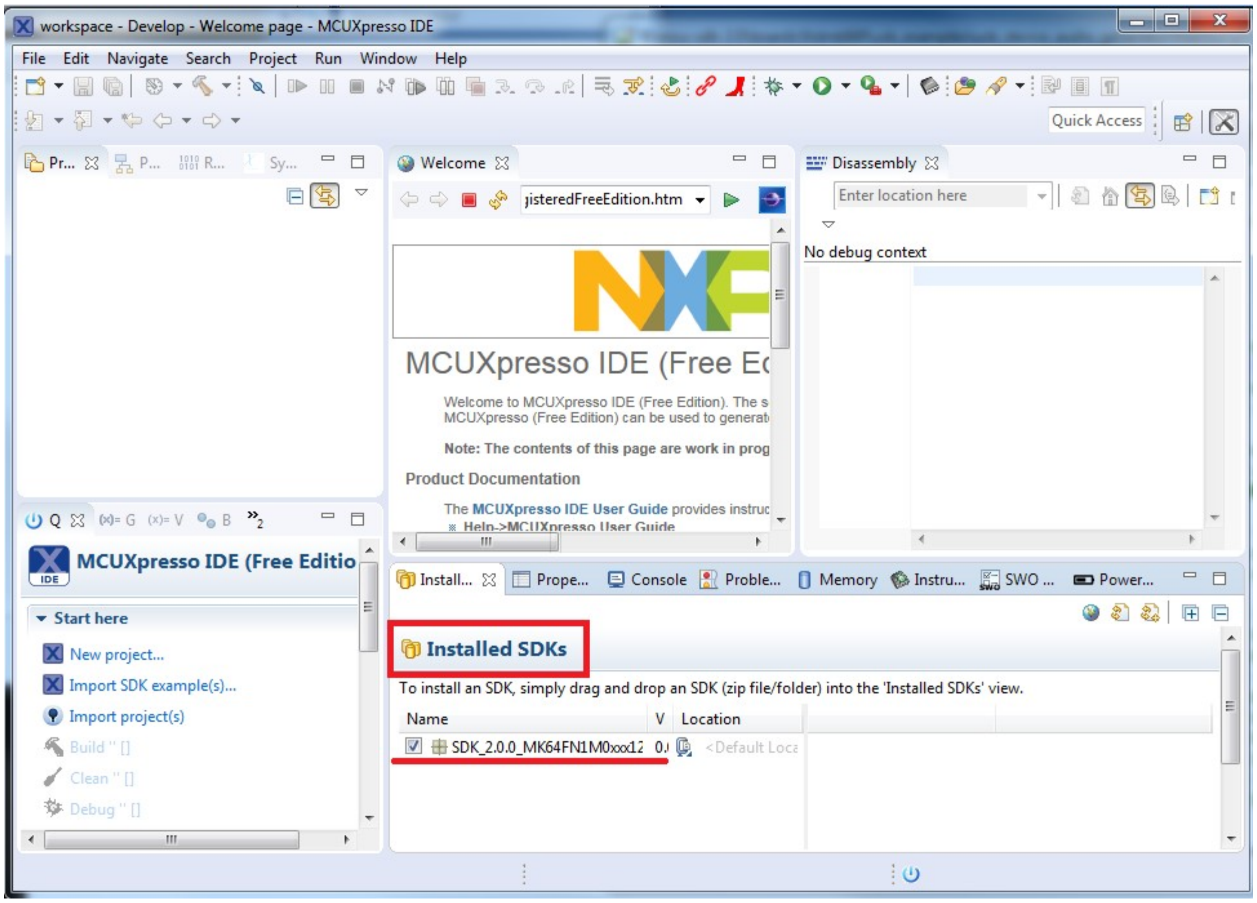
2.3 Compiling or running the USB stack and examples

NOTE

The USB example may not support all compilers. The steps below describes how to compile and run on all compilers. Check the specific MCUXpresso SDK documentation to know about the supported compilers for the USB example.

2.3.1 Step-by-step guide for MCUXpresso IDE

1. Prepare a compressed release package, such as SDK_2.0_FRDM-K64F.zip.
2. Open MCUXpresso IDE and drag and drop the MCUXpresso SDK (zip file/folder) into the "Installed SDKs". The MCUXpresso SDK should install.



To install an SDK, simply drag and drop an SDK (zip file/folder) into the 'Installed SDKs' view.

Figure 3. Installed SDK

3. To select an example, select the “Import SDK example(s)” button. Click the “Next” button after selecting the available board.

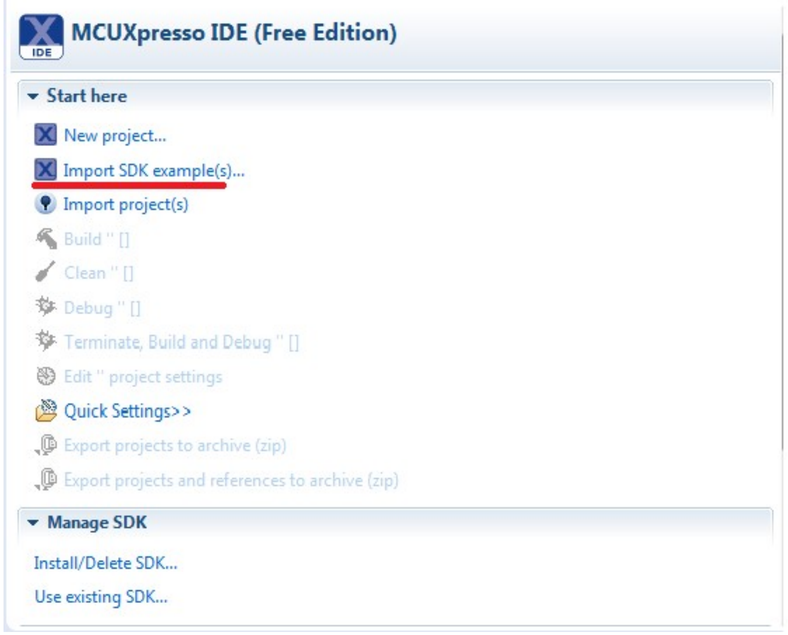
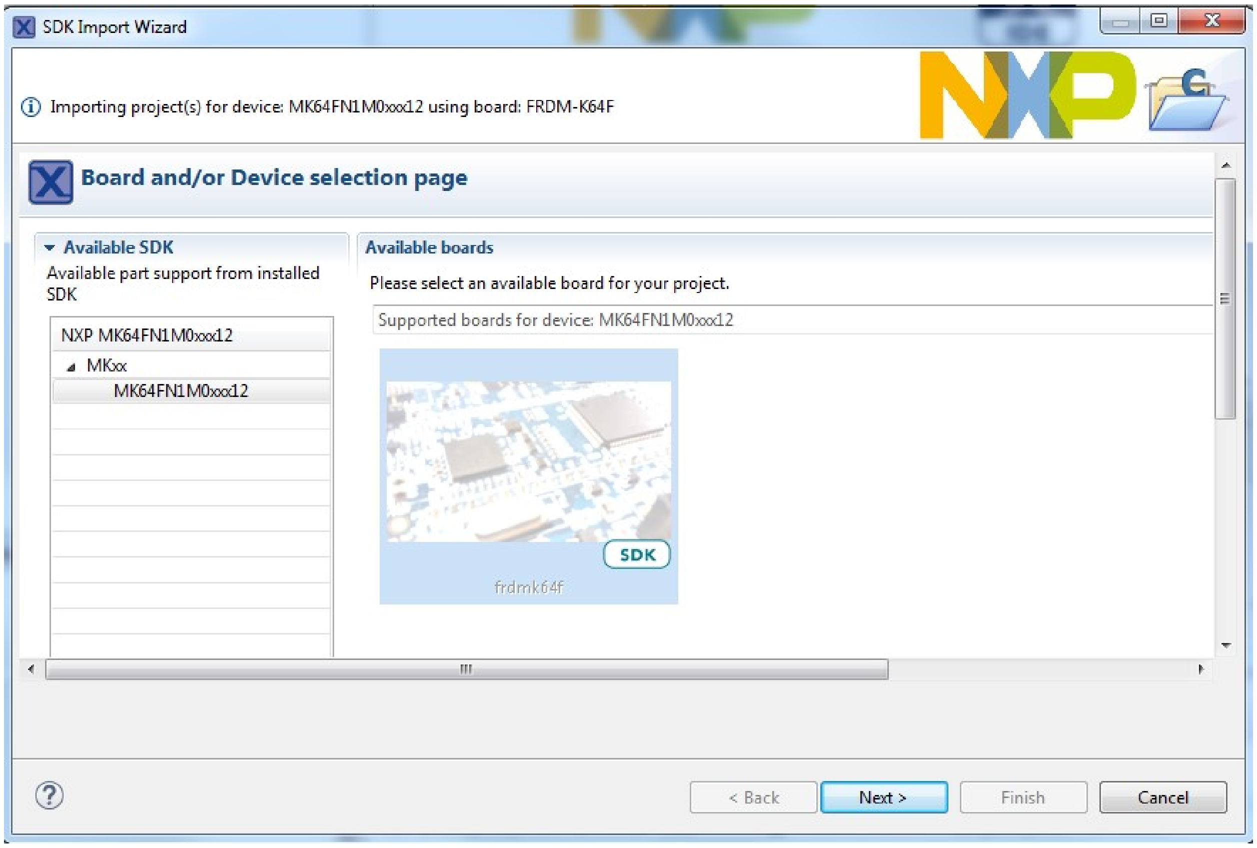


Figure 4. Import project button


SDK Import Wizard

Importing project(s) for device: MK64FN1M0xxx12 using board: FRDM-K64F

Board and/or Device selection page

Available SDK

Available part support from installed SDK

NXP MK64FN1M0xxx12
MKxx
MK64FN1M0xxx12

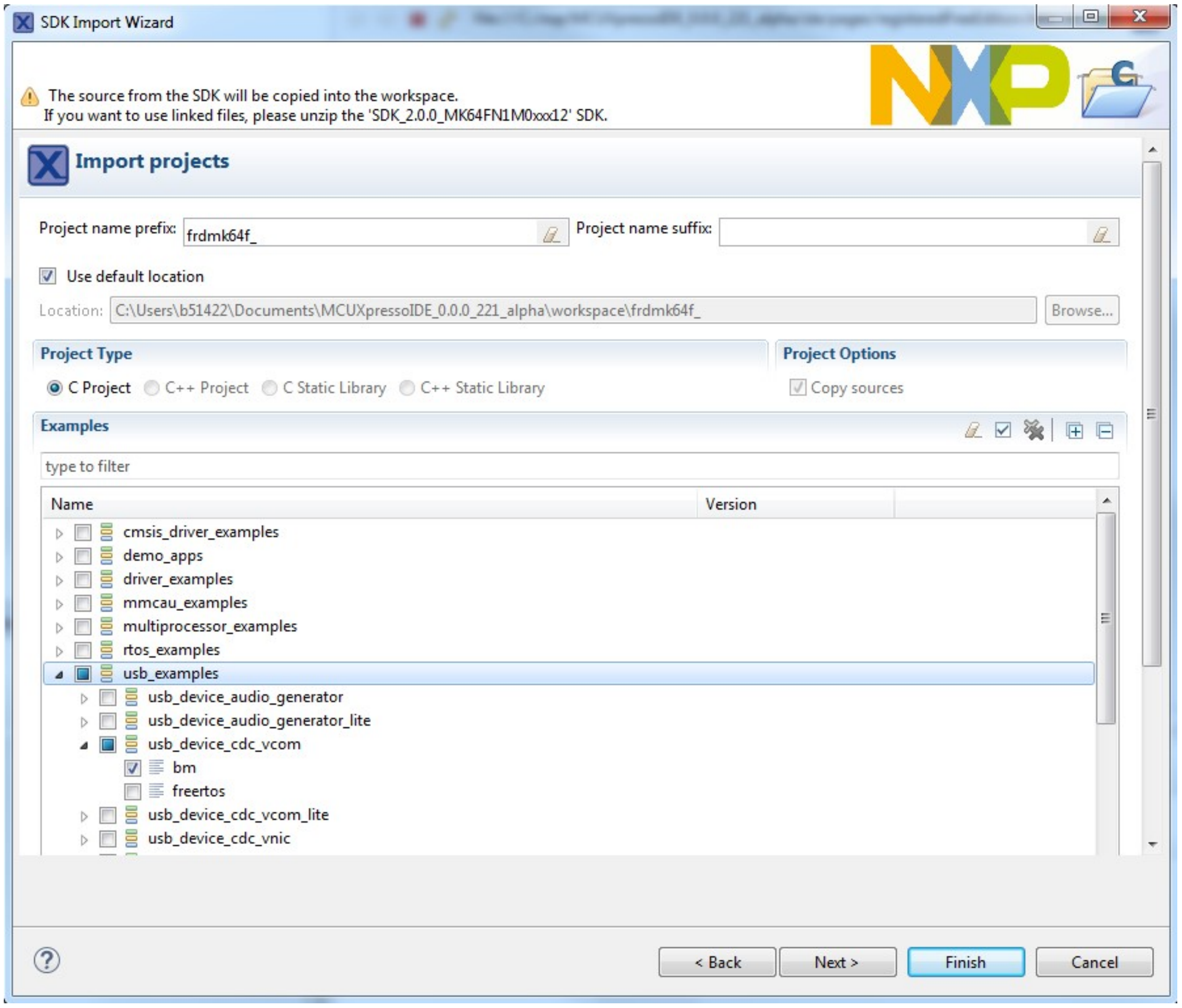
Available boards

Please select an available board for your project.

Supported boards for device: MK64FN1M0xxx12

Figure 5. Select boards

4. To import one example, click the “Finish” button after selecting the available example.



The source from the SDK will be copied into the workspace.
If you want to use linked files, please unzip the 'SDK_2.0.0_MK64FN1M0xxx12' SDK.

Import projects

Project name prefix: frdmk64f_
Project name suffix:

[✓] Use default location

Location: C:\Users\b51422\Documents\MCUXpressoIDE_0.0.0_221_alpha\workspace\frdmk64f_

Project Type: [● C Project] C++ Project C Static Library C++ Static Library

Project Options: [✓] Copy sources

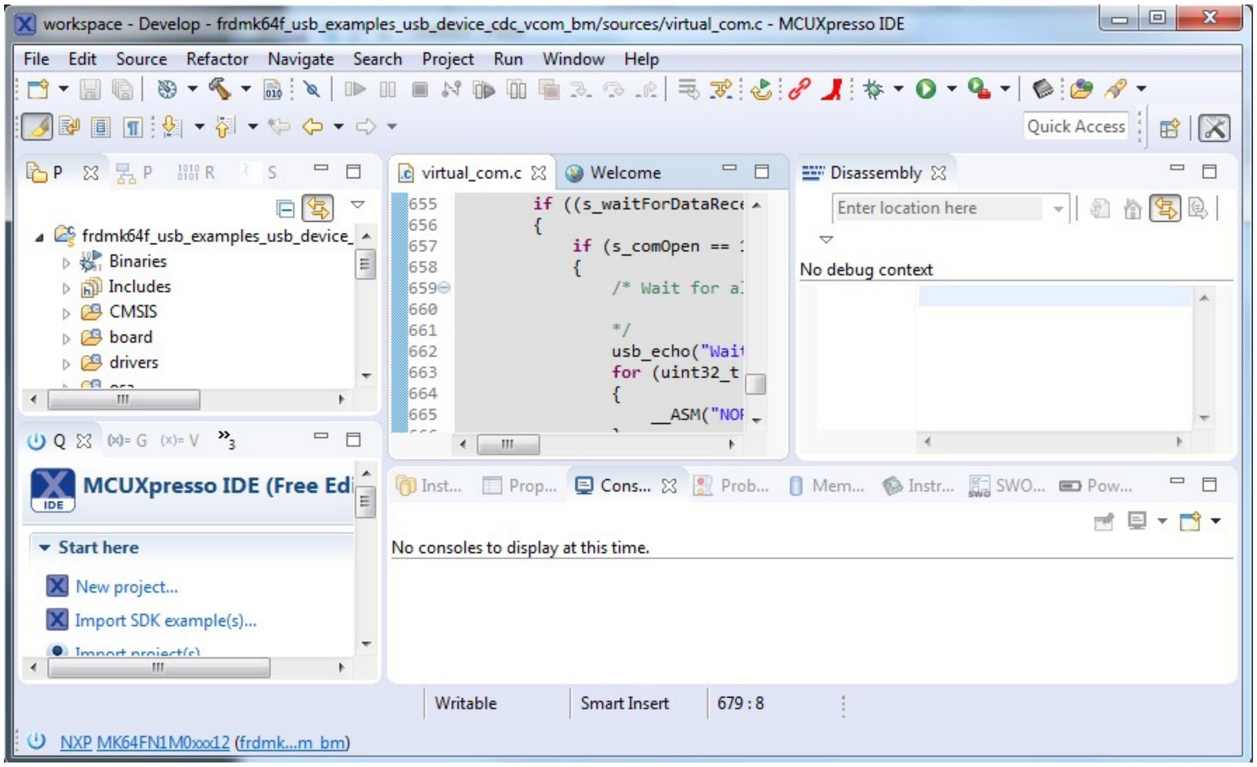
Examples

type to filter

Name	Version
cmsis_driver_examples	
demo_apps	
driver_examples	
mmcau_examples	
multiprocessor_examples	
rtos_examples	
usb_examples	
usb_device_audio_generator	
usb_device_audio_generator_lite	
usb_device_cdc_vcom	
[✓] bm	
freertos	
usb_device_cdc_vcom_lite	
usb_device_cdc_vnic	

Figure 6. Import project

5. After importing, the window should look like the below figure.


workspace - Develop - frdmk64f_usb_examples_usb_device_cdc_vcom_bm/sources/virtual_com.c - MCUXpresso IDE
File Edit Source Refactor Navigate Search Project Run Window Help
Quick Access
frdmk64f_usb_examples_usb_device_
Binaries
Includes
CMSIS
board
drivers
virtual_com.c
Welcome
Disassembly
Enter location here
No debug context
MCUXpresso IDE (Free Edi
Start here
New project...
Import SDK example(s)...
No consoles to display at this time.
Writable
Smart Insert
679 : 8
NXP MK64FN1M0xxx12 (frdmk...m_bm)

```
        if ((s_waitForDataRece
        {
            if (s_comOpen == 1
            {
                /* Wait for a
                */
                usb_echo("Wait
                for (uint32_t
                {
                    __ASM("NOP
```

Figure 7. The USB projects workspace

6. Choose the appropriate build target, “Debug” or “Release”, by left-clicking the build configuration icon as show in the below figure.

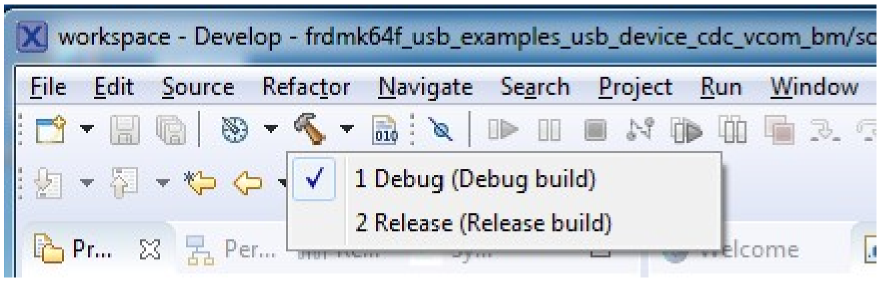

workspace - Develop - frdmk64f_usb_examples_usb_device_cdc_vcom_bm/sc
File Edit Source Refactor Navigate Search Project Run Window
1 Debug (Debug build)
2 Release (Release build)
Pr...
Per...
Welcome

Figure 8. Manage build configuration button

7. If the project build does not begin after selecting the desired target, left-click the build icon to start the build.

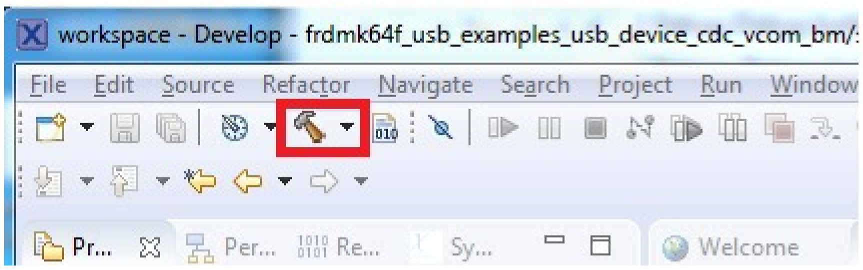

workspace - Develop - frdmk64f_usb_examples_usb_device_cdc_vcom_bm/:
File Edit Source Refactor Navigate Search Project Run Window
Pr...
Per...
Re...
Sy...
Welcome

Figure 9. Build project button

8. To check debugger configurations, click the down arrow next to the green debug button and select “Debug Configurations”.

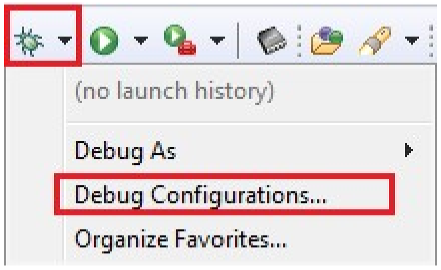
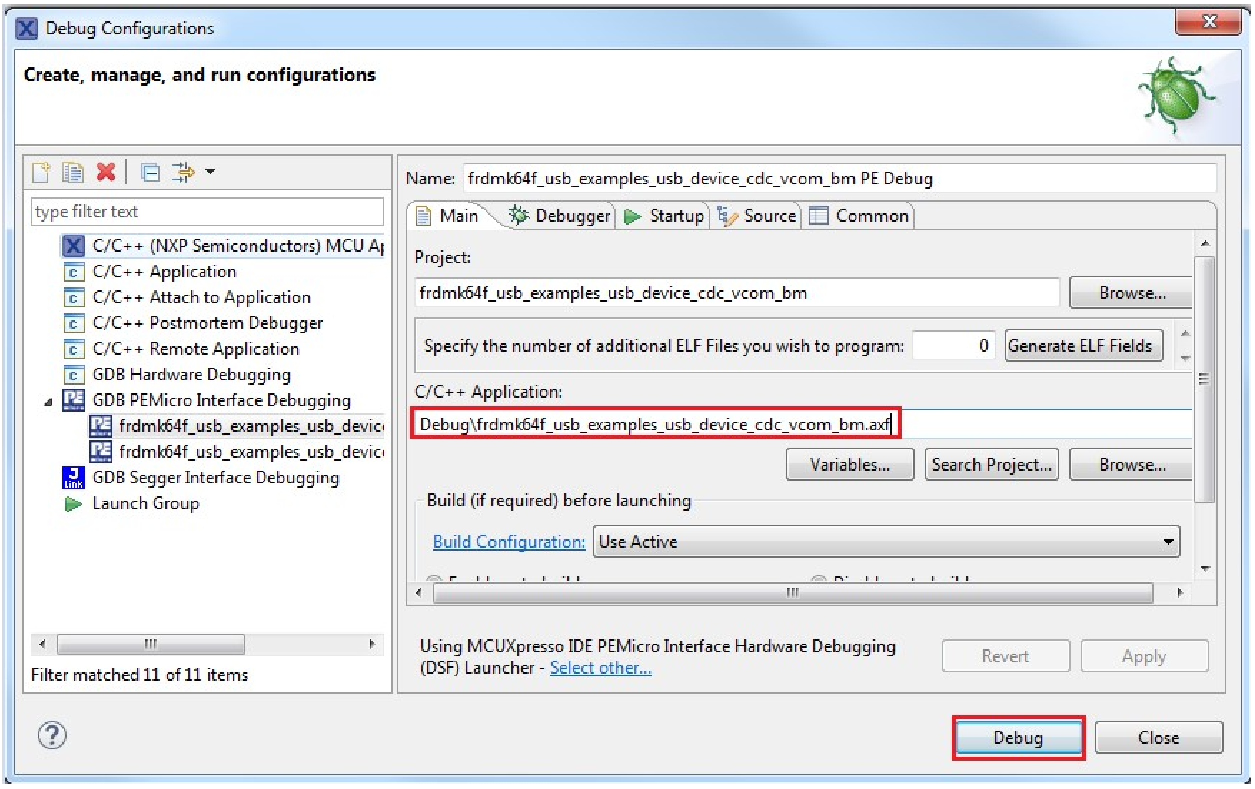


Figure 10. Configure debug button

9. After verifying the debugger configurations are correct, click the “Debug” button.



Debug Configurations

Create, manage, and run configurations

type filter text

- C/C++ (NXP Semiconductors) MCU Ap
- C/C++ Application
- C/C++ Attach to Application
- C/C++ Postmortem Debugger
- C/C++ Remote Application
- GDB Hardware Debugging
- GDB PEMicro Interface Debugging
  - frdmk64f_usb_examples_usb_devic
  - frdmk64f_usb_examples_usb_devic
- GDB Segger Interface Debugging
- Launch Group

Filter matched 11 of 11 items

Name: frdmk64f_usb_examples_usb_device_cdc_vcom_bm PE Debug

Main | Debugger | Startup | Source | Common

Project:
frdmk64f_usb_examples_usb_device_cdc_vcom_bm

Specify the number of additional ELF Files you wish to program: 0

C/C++ Application:
Debug\frdmk64f_usb_examples_usb_device_cdc_vcom_bm.axf

Build (if required) before launching

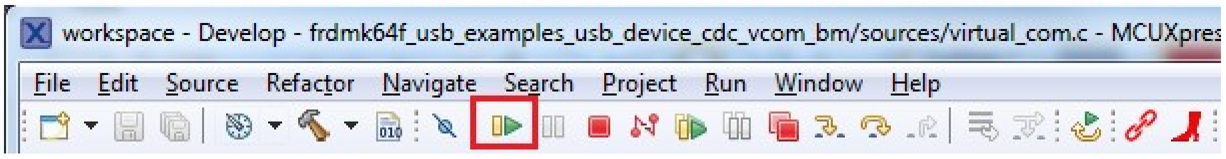
Build Configuration: Use Active

Using MCUXpresso IDE PEMicro Interface Hardware Debugging (DSF) Launcher - Select other...

Figure 11. MCUXpresso IDE debug configurations

10. The application is downloaded to the target and automatically runs to main():

11. Run the code by clicking the “Resume” button to start the application:



workspace - Develop - frdmk64f_usb_examples_usb_device_cdc_vcom_bm/sources/virtual_com.c - MCUXpres

Figure 12. Resume button

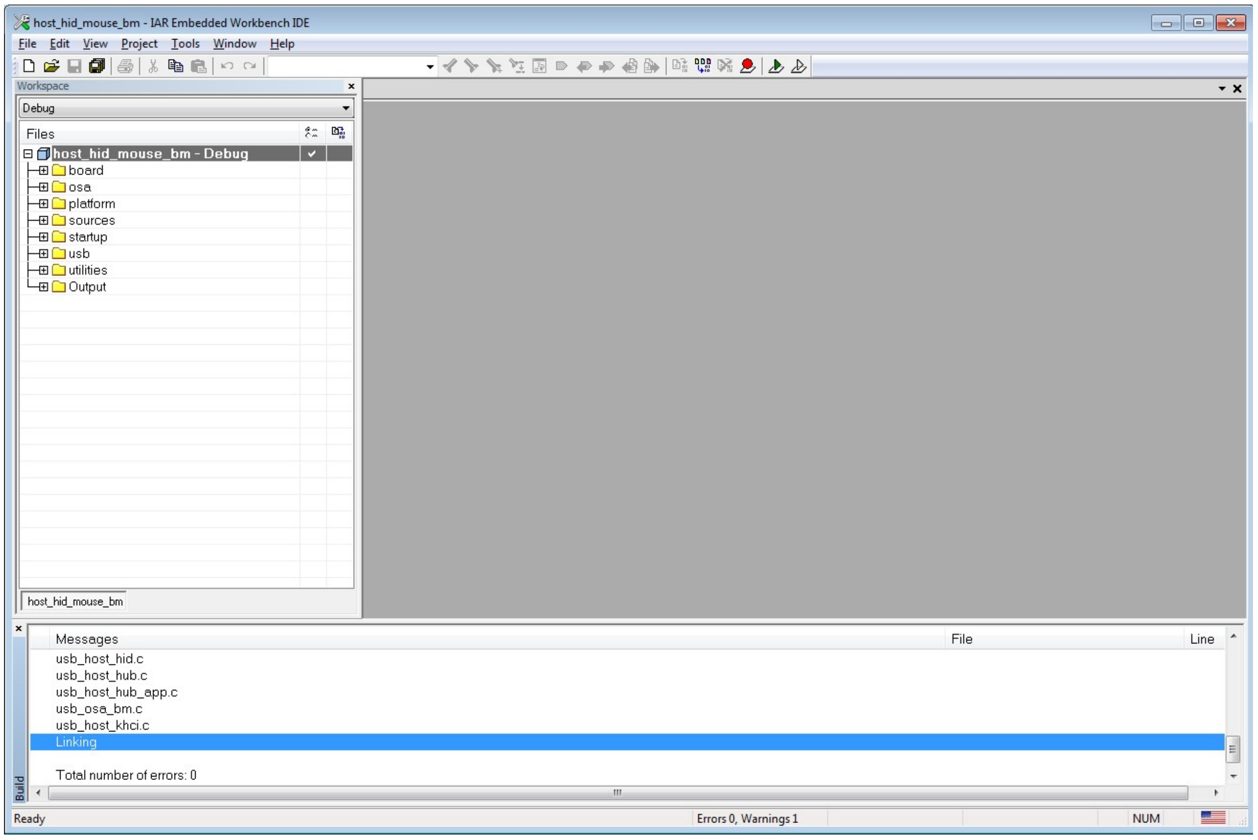
12. See the example-specific document for more test information.

2.3.2 Step-by-step guide for IAR

This section shows how to use IAR. Open IAR as shown in this figure:

1. Open the worksace corresponding to different examples.

   For example, the workspace file is located at: *<install_dir>/boards/twrk22f120m/usb_examples/usb_host_hid_mouse/bm/iar/host_hid_mouse_bm.eww*.



Messages	File	Line
usb_host_hid.c		
usb_host_hub.c		
usb_host_hub_app.c		
usb_osa_bm.c		
usb_host_khci.c		
Linking		
Total number of errors: 0		

Figure 13. IAR workspace

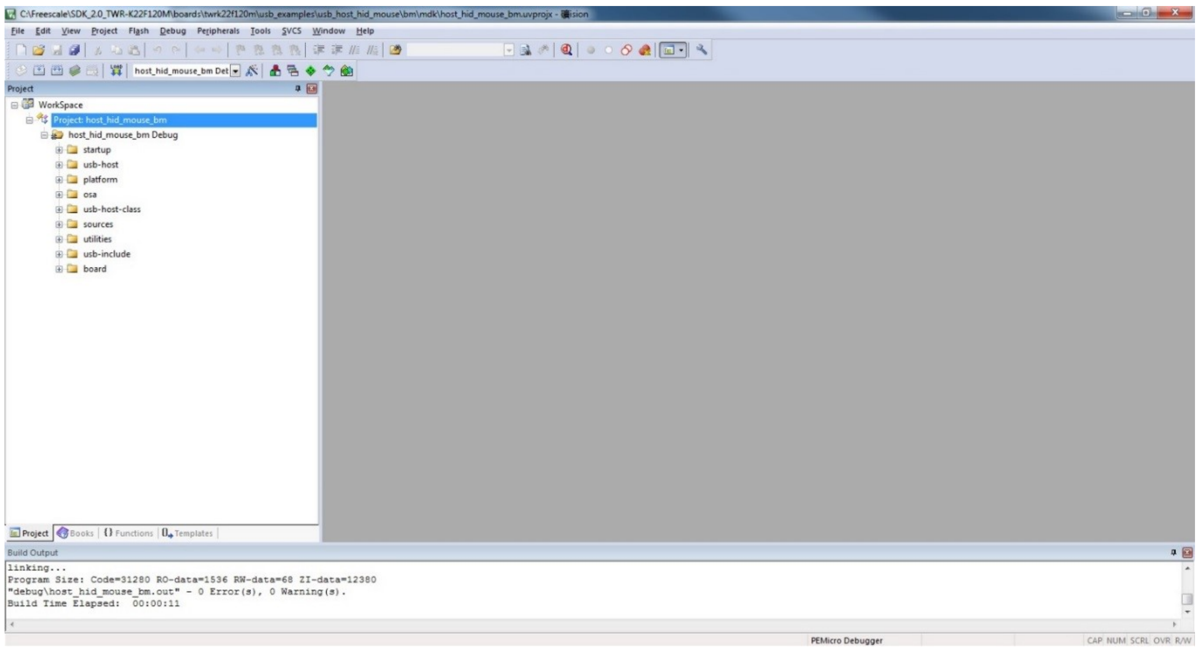
2. Build the host_hid_mouse_bm example.
3. Connect the micro USB cable from a PC to the J25 of the TWR-K22F120M Tower System module to power on the board.
4. Click the “Download and Debug” button. Wait for the download to complete.
5. Click the “Go” button to run the example.
6. See the example-specific readme.pdf for more test information.

2.3.3 Step-by-step guide for Keil µVision5

This section shows how to use Keil µVision5. Open Keil µVision5 as shown in this figure:

1. Open the workspace corresponding to different examples.

   For example, the workspace file is located in *<install_dir>/boards/twrk22f120m/usb_examples/usb_host_hid_mouse/bm/mdk/host_hid_mouse_bm.uvmpw.*


C:\Freescale\SDK_2.0_TWR-K22F120M\boards\twrk22f120m\usb_examples\usb_host_hid_mouse\bm\mdk\host_hid_mouse_bm.uvprojx - µVision
File Edit View Project Flash Debug Peripherals Tools SVCS Window Help
host_hid_mouse_bm Debug
Project
WorkSpace
Project: host_hid_mouse_bm
host_hid_mouse_bm Debug
startup
usb-host
platform
osa
usb-host-class
sources
utilities
usb-include
board
Project
Books
Functions
Templates
Build Output
PEMicro Debugger
CAP NUM SCRL OVR R/W

```
linking...
Program Size: Code=31280 RO-data=1536 RW-data=68 ZI-data=12380
"debug\host_hid_mouse_bm.out" - 0 Error(s), 0 Warning(s).
Build Time Elapsed:  00:00:11
```

Figure 14. Keil µVision5 workspace

2. Build the host_hid_mouse_bm example.
3. Click the “Start/Stop” debug session button. Wait for the download to complete.
4. Click the “Go” button to run the example.
5. See the example-specific readme.pdf for more test information.

2.3.4 Step-by-step guide for ARM GCC

2.3.4.1 Setup tool chains

2.3.4.2 Install GCC Arm embedded tool chain

Download and install the installer from www.launchpad.net/gcc-arm-embedded.

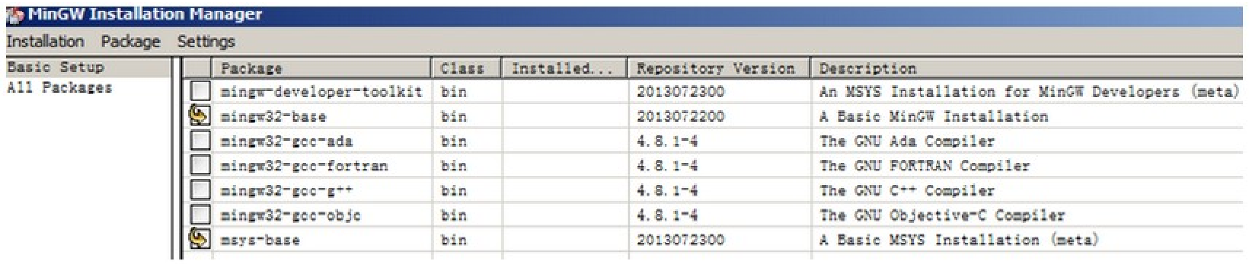
2.3.4.3 Install MinGW

1. Download the latest mingw-get-setup.exe.
2. Install the GCC Arm Embedded toolchain. The recommended path is C:/MINGW.

NOTE

The installation path should not contain a space.

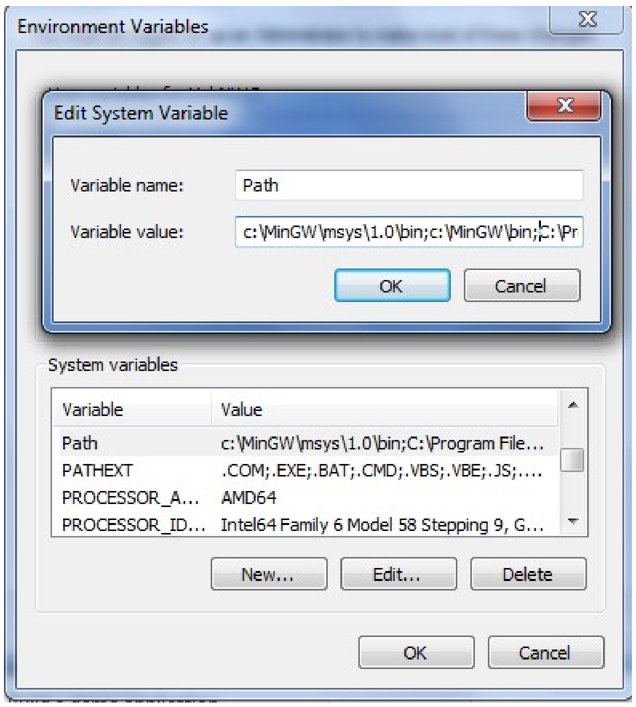
3. Ensure that the mingw32-base and msys-base are selected under basic setup.
4. Click “Installation” and “Apply changes”.



Package	Class	Installed...	Repository Version	Description
mingw-developer-toolkit	bin		2013072300	An MSYS Installation for MinGW Developers (meta)
mingw32-base	bin		2013072200	A Basic MinGW Installation
mingw32-gcc-ada	bin		4.8.1-4	The GNU Ada Compiler
mingw32-gcc-fortran	bin		4.8.1-4	The GNU FORTRAN Compiler
mingw32-gcc-g++	bin		4.8.1-4	The GNU C++ Compiler
mingw32-gcc-objc	bin		4.8.1-4	The GNU Objective-C Compiler
msys-base	bin		2013072300	A Basic MSYS Installation (meta)

Figure 15. Setup MinGW and MSYS

5. Add paths C:/MINGW/msys/1.0/bin;C:/MINGW/bin to the system environment. If the GCC Arm Embedded tool chain was not installed at the recommended location, the system paths added should reflect this change else the tool chain will not work. An example using the recommended installation locations is shown below.



Variable name: Path

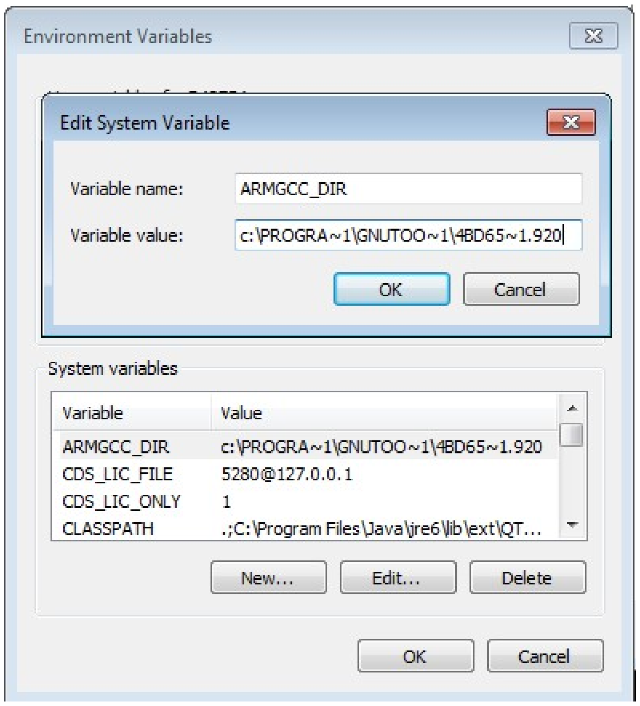
Variable value: c:\MinGW\msys\1.0\bin;c:\MinGW\bin;C:\Pr

Variable	Value
Path	c:\MinGW\msys\1.0\bin;C:\Program File...
PATHEXT	.COM;.EXE;.BAT;.CMD;.VBS;.VBE;.JS;....
PROCESSOR_A...	AMD64
PROCESSOR_ID...	Intel64 Family 6 Model 58 Stepping 9, G...

Figure 16. Add Path to systems environment

2.3.4.4 Add new system environment variable ARMGCC_DIR

Create a new system environment variable ARMGCC_DIR. The value of this variable should be the short name of the Arm GCC Embedded tool chain installation path.


Environment Variables

Edit System Variable

Variable name: ARMGCC_DIR

Variable value: c:\PROGRA~1\GNUTOO~1\4BD65~1.920

OK Cancel

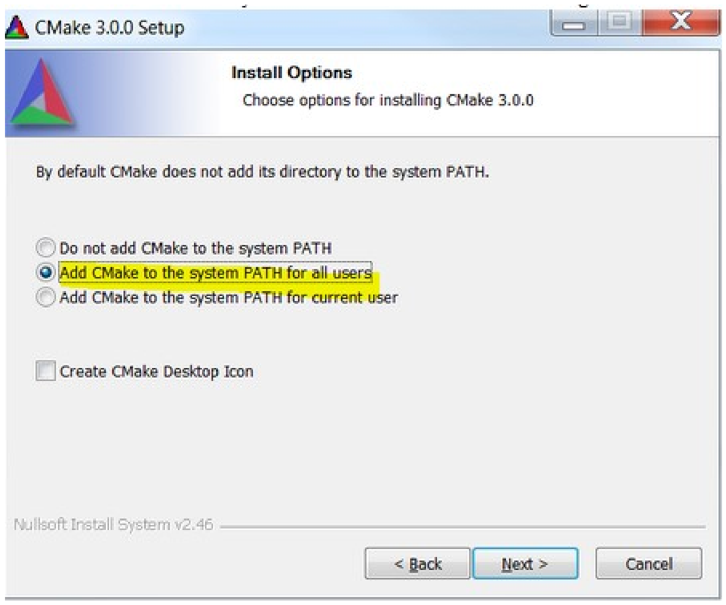
System variables

Variable	Value
ARMGCC_DIR	c:\PROGRA~1\GNUTOO~1\4BD65~1.920
CDS_LIC_FILE	5280@127.0.0.1
CDS_LIC_ONLY	1
CLASSPATH	.;C:\Program Files\Java\jre6\lib\ext\QT...

Figure 17. Add ARMGCC_DIR system variable

2.3.4.5 Install CMake

1. Download CMake 3.0.1 from www.cmake.org/cmake/resources/software.html.
2. Install CMake 3.0.1 and ensure that the option "Add CMake to system PATH" is selected.


CMake 3.0.0 Setup

Install Options

Choose options for installing CMake 3.0.0

By default CMake does not add its directory to the system PATH.

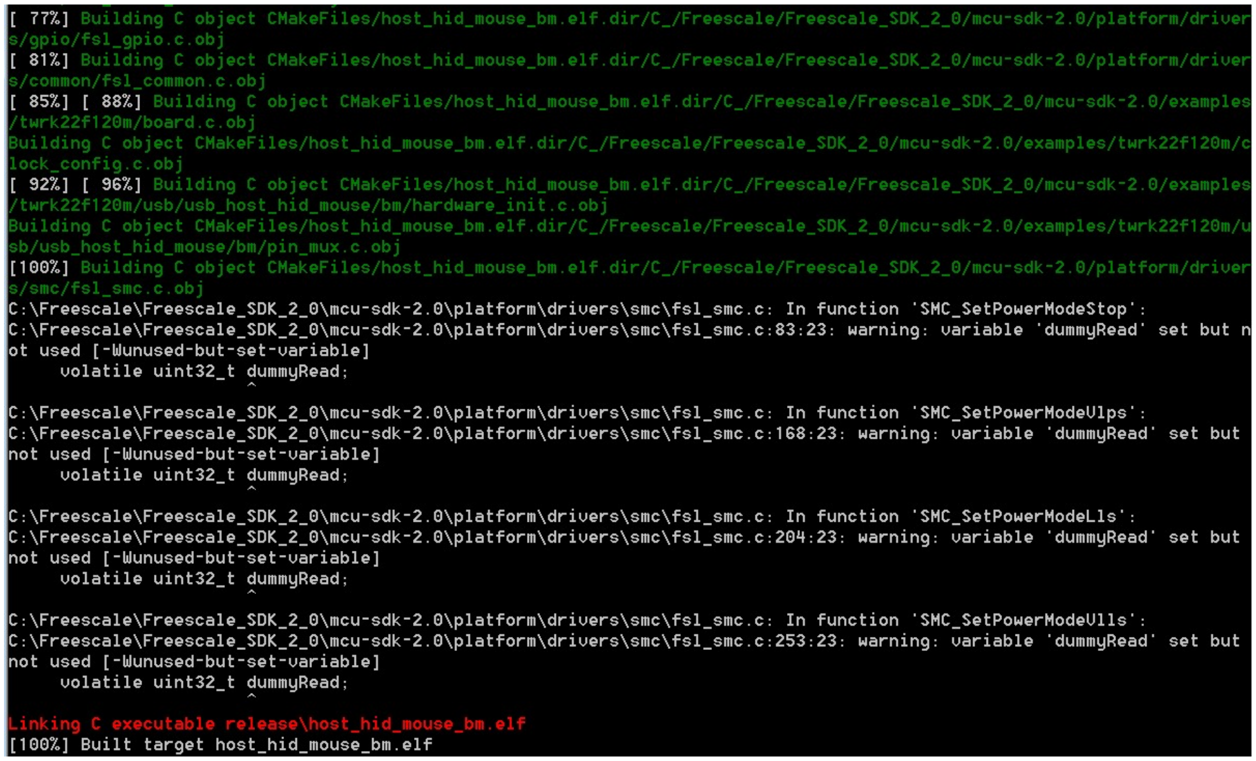
Do not add CMake to the system PATH [✓ Add CMake to the system PATH for all users] Add CMake to the system PATH for current user

Create CMake Desktop Icon

Figure 18. Install CMake

2.3.4.6 Build the USB demo

1. Change the directory to the project directory: *<install_dir>/boards/twrk22f120m/usb_examples/usb_host_hid_mouse/bm/armgcc.*
2. Run the build_all.bat. The build output is shown in this figure:



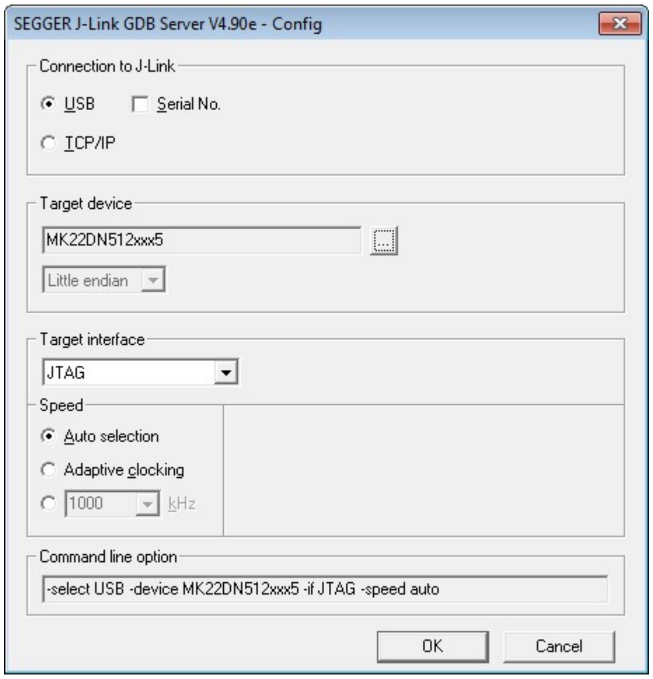
```
[ 77%] Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/platform/driver
s/gpio/fsl_gpio.c.obj
[ 81%] Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/platform/driver
s/common/fsl_common.c.obj
[ 85%] [ 88%] Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/examples
/twrk22f120m/board.c.obj
Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/examples/twrk22f120m/c
lock_config.c.obj
[ 92%] [ 96%] Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/examples
/twrk22f120m/usb/usb_host_hid_mouse/bm/hardware_init.c.obj
Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/examples/twrk22f120m/u
sb/usb_host_hid_mouse/bm/pin_mux.c.obj
[100%] Building C object CMakeFiles/host_hid_mouse_bm.elf.dir/C_/Freescale/Freescale_SDK_2_0/mcu-sdk-2.0/platform/driver
s/smc/fsl_smc.c.obj
C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c: In function 'SMC_SetPowerModeStop':
C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c:83:23: warning: variable 'dummyRead' set but n
ot used [-Wunused-but-set-variable]
     volatile uint32_t dummyRead;
                       ^

C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c: In function 'SMC_SetPowerModeVlps':
C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c:168:23: warning: variable 'dummyRead' set but
not used [-Wunused-but-set-variable]
     volatile uint32_t dummyRead;
                       ^

C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c: In function 'SMC_SetPowerModeLls':
C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c:204:23: warning: variable 'dummyRead' set but
not used [-Wunused-but-set-variable]
     volatile uint32_t dummyRead;
                       ^

C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c: In function 'SMC_SetPowerModeVlls':
C:\Freescale\Freescale_SDK_2_0\mcu-sdk-2.0\platform\drivers\smc\fsl_smc.c:253:23: warning: variable 'dummyRead' set but
not used [-Wunused-but-set-variable]
     volatile uint32_t dummyRead;
                       ^

Linking C executable release\host_hid_mouse_bm.elf
[100%] Built target host_hid_mouse_bm.elf
```

Figure 19. USB host demo built successfully

2.3.4.7 Run a demo application

This section describes steps to run a demo application using J-Link GDB Server application.

1. Connect the J-Link debug port to the SWD/JTAG connector of the board.
2. Open the J-Link GDB Server application and modify your connection settings as shown in this figure.

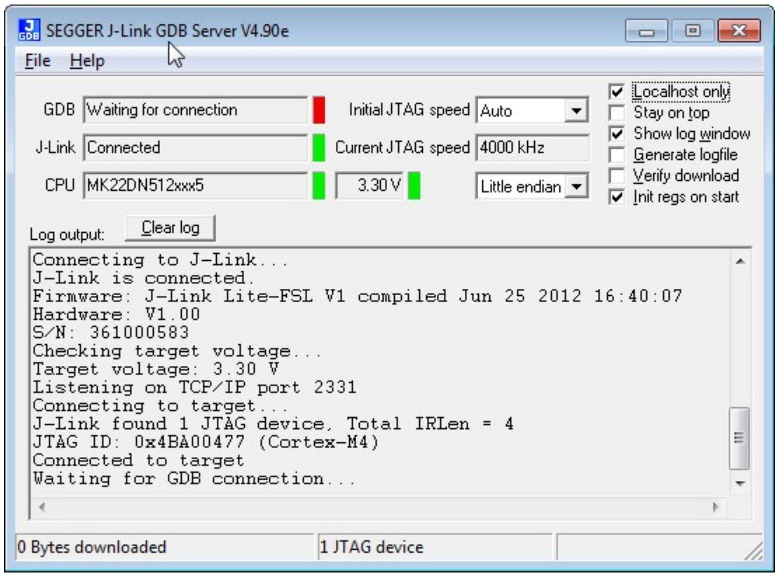


Connection to J-Link: USB
Target device: MK22DN512xxx5
Little endian
Target interface: JTAG
Speed: Auto selection
1000 kHz
Command line option: -select USB -device MK22DN512xxx5 -if JTAG -speed auto

Figure 20. SEGGER J-Link GDB Server configuration

NOTE
The target device selection should be MK22FN512xxx12. The target interface should be SWD.

3. After the connection is estabilished, the screen would resemble the figure below:



GDB: Waiting for connection
J-Link: Connected
CPU: MK22DN512xxx5
Initial JTAG speed: Auto
Current JTAG speed: 4000 kHz
3.30 V
Little endian

```
Connecting to J-Link...
J-Link is connected.
Firmware: J-Link Lite-FSL V1 compiled Jun 25 2012 16:40:07
Hardware: V1.00
S/N: 361000583
Checking target voltage...
Target voltage: 3.30 V
Listening on TCP/IP port 2331
Connecting to target...
J-Link found 1 JTAG device, Total IRLen = 4
JTAG ID: 0x4BA00477 (Cortex-M4)
Connected to target
Waiting for GDB connection...
```

0 Bytes downloaded
1 JTAG device

Figure 21. SEGGER J-Link GDB Server screen after successful connection

NOTE
The CPU selection should be CPU to: MK22FN512xxx12.

4. Open the Arm GCC command prompt and change the directory to the output directory of the desired demo. For this example, the directory is:

<install_dir>/boards/twrk22f120m/usb_examples/usb_host_hid_mouse/bm/armgcc/debug.

5. Run the command “arm-none-eabi-gdb.exe <DEMO_NAME>.elf”. Run these commands:
   - “target remote localhost: 2331”
   - “monitor reset”
   - “monitor halt”
   - “load”
   - “monitor reset”
6. The application is downloaded and connected. Execute the “monitor go” command to start the demo application.
7. See the example-specific document for more test information.

2.4 USB stack configuration

2.4.1 Device configuration

A device configuration file is set up for each example, such as:

<install_dir>/boards/twrk22f120m/usb_examples/usb_device_hid_mouse/bm/usb_device_config.h

This file is used to either enable or disable the USB class driver and to configure the interface type (high-speed or full speed). The object number is configurable either to decrease the memory usage or to meet specific requirements.

If the device stack configuration is changed, rebuild the example projects. For each device, follow these steps.

If the board is a Tower or Freedom platform, enable the following macros:

1. Enable *#define USB_DEVICE_CONFIG_KHCI (0U)* macro for full speed.
2. Enable *#define USB_DEVICE_CONFIG_EHCI (0U)* macro if the board supports high-speed.

If board is part of the LPC series, enable the following macros:

1. Enable *#define USB_DEVICE_CONFIG_LPCIP3511FS (0U)* macro for full speed.
2. Enable *#define USB_DEVICE_CONFIG_LPCIP3511HS (0U)* macro if the board supports high-speed.

2.4.2 Host configuration

A host configuration file is set up for each example, such as:

<install_dir>/boards/twrk22f120m/usb_examples/usb_host_hid_mouse/bm/usb_host_config.h

This file is used to either enable or disable the USB class driver. The object number is configurable either to decrease the memory usage or to meet specific requirements.

If the Host stack configuration is changed, rebuild the example projects.

For each Host, follow these steps.

If the board is a Tower for Freedom platform, enable the following macros:

Enable this macro for full speed.

#define USB_HOST_CONFIG_KHCI (0U)

Enable this macro if the board supports high-speed.

#define USB_HOST_CONFIG_EHCI (0U)

If board is part of the LPC series, enable the following macros:

Enable this macro for full speed.

#define USB_HOST_CONFIG_OHCI (0U)

Enable this macro if the board supports high-speed.

#define USB_HOST_CONFIG_IP3516HS (0U)

2.4.3 USB cache-related MACROs definitions

There are few MACROs in the USB stack to define USB data attributes.

- USB_STACK_USE_DEDICATED_RAM

  The following values are used to configure the USB stack to use dedicated RAM or not.

  1. USB_STACK_DEDICATED_RAM_TYPE_BDT_GLOBAL - The USB device global variables (controller data and device stack data) are put into the USB-dedicated RAM.

  2. USB_STACK_DEDICATED_RAM_TYPE_BDT - The USB device controller global variables (BDT data) are put into the USB-dedicated RAM.

  3. 0 - There is no USB-dedicated RAM.
- USB_DEVICE_CONFIG_BUFFER_PROPERTY_CACHEABLE

  The following values are used to configure the device stack cache to be enabled or not.

  0: disabled

  1: enable

  This macro is not supported in the Cortex-M7 platforms.
- USB_HOST_CONFIG_BUFFER_PROPERTY_CACHEABLE

  The following values are used to configure host stack cache to be enabled or not.

  0: disable

  1: enable

  This macro is not supported in the Cortex-M7 platforms.

Based on the above MACROs, the following cache-related MACROs are defined in the USB stack.

Table 1. Cache and global variable attribute relation

	USB_DEVICE_CONFIG_BUFFER_PROPERTY_CACHEABLE || USB_HOST_CONFIG_BUFFER_PROPERTY_CACHEABLE is true		USB_DEVICE_CONFIG_BUFFER_PROPERTY_CACHEABLE || USB_HOST_CONFIG_BUFFER_PROPERTY_CACHEABLE is false			
USB_STACK_USE_DEDICATED_RAM's Value			DATA_SECTION_IS_CACHEABLE is true		DATA_SECTION_IS_CACHEABLE is false	
USB_STACK_DEDICATED_RAM_TYPE_BDT_GLOBAL	USB_GLOBAL	dedicated ram, stack use only	USB_GLOBAL	dedicated ram, stack use only	USB_GLOBAL	dedicated ram, stack use only
	USB_BDT	dedicated ram, stack use only	USB_BDT	dedicated ram, stack use only	USB_BDT	dedicated ram, stack use only

	USB_CONTROLLER_DATA	NonCachable, stack use only	USB_CONTROLLER_DATA	NonCachable, stack use only	USB_CONTROLLER_DATA	dedicated ram, stack use only
	USB_DMA_NONINIT_DATA_ALIGN(n)	cachable ram and alignment	USB_DMA_NONINIT_DATA_ALIGN(n)	noncachable ram and alignment	USB_DMA_NONINIT_DATA_ALIGN(n)	alignment
	USB_DMA_INIT_DATA_ALIGN(n)	cachable ram and alignment	USB_DMA_INIT_DATA_ALIGN(n)	noncachable ram and alignment	USB_DMA_INIT_DATA_ALIGN(n)	alignment
USB_STACK_DEDICATED_RAM_TYPE_BDT	USB_GLOBAL	cachable ram and alignment, stack use only	USB_GLOBAL	NonCachable, stack use only	USB_GLOBAL	NULL, stack use only
	USB_BDT	dedicated ram, stack use only	USB_BDT	dedicated ram, stack use only	USB_BDT	dedicated ram, stack use only
	USB_CONTROLLER_DATA	NonCachable, stack use only	USB_CONTROLLER_DATA	NonCachable, stack use only	USB_CONTROLLER_DATA	NULL, stack use only
	USB_DMA_NONINIT_DATA_ALIGN(n)	cachable ram and alignment	USB_DMA_NONINIT_DATA_ALIGN(n)	NonCachable and alignment	USB_DMA_NONINIT_DATA_ALIGN(n)	alignment
	USB_DMA_INIT_DATA_ALIGN(n)	cachable ram and alignment	USB_DMA_INIT_DATA_ALIGN(n)	NonCachable and alignment	USB_DMA_INIT_DATA_ALIGN(n)	alignment
0	USB_GLOBAL	cachable ram and alignment, stack use only	USB_GLOBAL	NonCachable, stack use only	USB_GLOBAL	NULL, stack use only
	USB_BDT	NonCachable, stack use only	USB_BDT	NonCachable, stack use only	USB_BDT	NULL, stack use only
	USB_CONTROLLER_DATA	NonCachable, stack use only	USB_CONTROLLER_DATA	NonCachable, stack use only	USB_CONTROLLER_DATA	NULL, stack use only
	USB_DMA_NONINIT_DATA_ALIGN(n)	cachable ram and alignment	USB_DMA_NONINIT_DATA_ALIGN(n)	NonCachable and alignment	USB_DMA_NONINIT_DATA_ALIGN(n)	alignment
					USB_DMA_INIT_DATA_ALIGN(n)	alignment

Table continues on the next page...

Table 1. Cache and global variable attribute relation (continued)

	USB_DMA_INIT_DATA_ALIGN(n)	cachable ram and alignment	USB_DMA_INIT_DATA_ALIGN(n)	NonCachable and alignment	

NOTE

“NULL” means that the MACRO is empty and has no influence.

There are four assistant MACROs:

USB_DATA_ALIGN_SIZE	Used in USB stack and application, defines the default align size for USB data.
USB_DATA_ALIGN_SIZE_MULTIPLE(n)	Used in USB stack and application, calculates the value that is multiple of the data align size.
USB_DMA_DATA_NONCACHEABLE	Used in USB stack and application, puts data in the noncacheable region if the cache is enabled.
USB_GLOBAL_DEDICATED_RAM	Used in USB stack and application, puts data in the dedicated RAM if dedicated RAM is enabled.

Chapter 3
Porting to a new platform

To port the USB stack to a new platform in the MCUXpresso SDK, the SoC-related files, board-related files, and a linker file for a specified compiler are required.

Assume that the new platform's name is “xxxk22f120m” based on the MK22F51212 SoC.

3.1 System-on-Chip (SoC) files

SoC source/header files are in the following directory, which are available by default from MCUXpresso SDK.

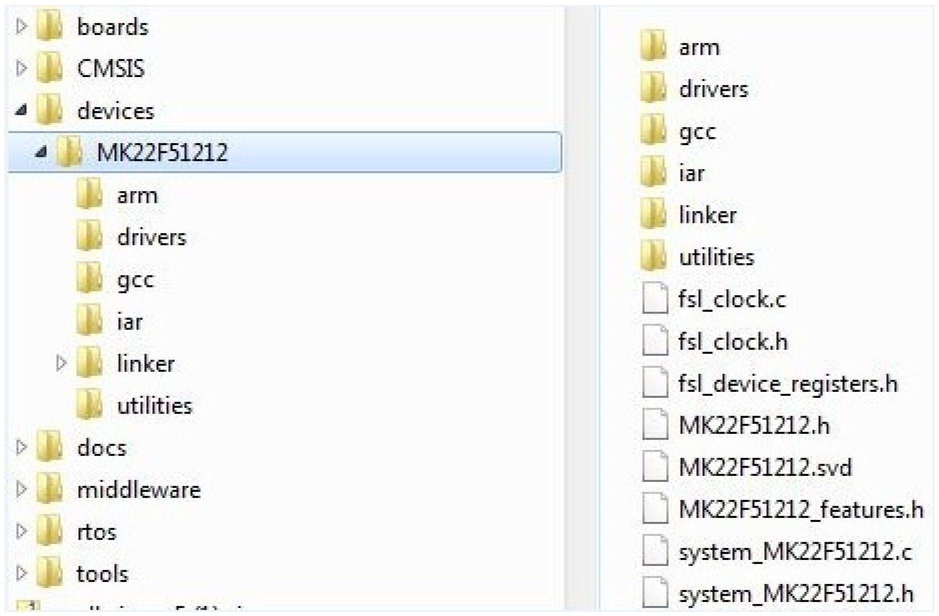


Figure 22. SoC header file directory

NOTE

Linker files for each toolchain are in the linker directory.

Different toolchains' SoC startup assembler files are in the Arm, GCC, and IAR directories.

3.2 Board files

The files for the board configuration and the clock configuration on a specific platform are needed to enable the USB stack.

The clock configuration files are shown in the following image.

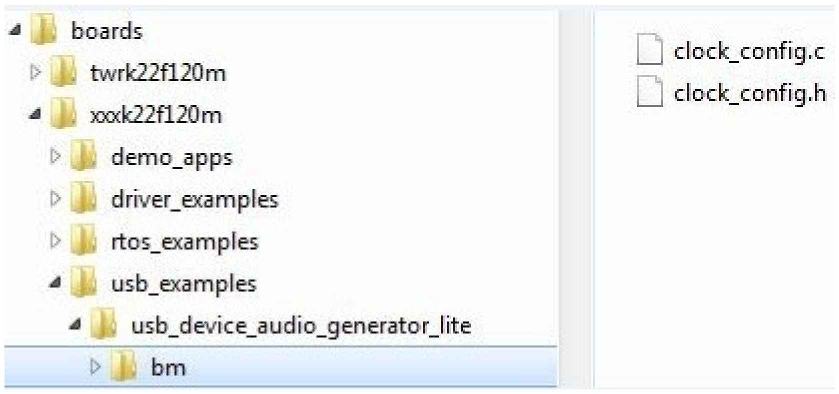


Figure 23. Clock configuration files

1. Create a folder "xxxk22f120m" under the examples directory.
2. Copy the clock_config.c and clock_config.h file from the similar platform. For example, the TWR-K22F120M Tower System module.
3. Ensure that `BOARD_BootClockxxx` is implemented in the clock_config.c file. For example, `BOARD_BootClockRUN` and `BOARD_BootClockHSRUN`. The user can change the function name. However, the `BOARD_InitHardware` must call the function. `BOARD_InitHardware` is introduced later.

   The board clock initialization is based on the board crystal oscillator. Ensure that the following two MACROs are defined in the clock_config.h file:

   ```
   #define BOARD_XTAL0_CLK_HZ    8000000U
   #define BOARD_XTAL32K_CLK_HZ  32768U
   ```

   The user can updatethe MACROs according to the board design. For example, if the XTAL0 crystal oscillator is 16000000U and the XTAL32K is 32768U, change the following MACROs as follows:

   ```
   #define BOARD_XTAL0_CLK_HZ    16000000U
   #define BOARD_XTAL32K_CLK_HZ  32768U
   ```

   The board configuration files are shown in the following image:

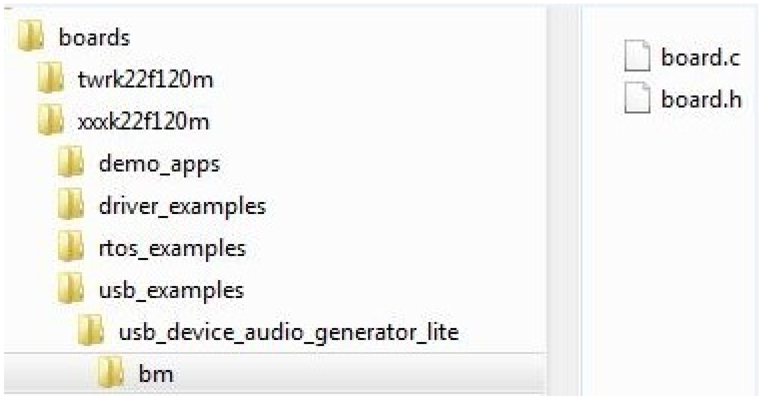


Figure 24. Board configuration files

4. Copy board.c and board.h from the similar platform. For example, the TWR-K22F120M platform. Ensure that the `BOARD_InitDebugConsole` is implemented in board.c file and that the `BOARD_InitHardware` calls the function. The `BOARD_InitHardware` function is introduced later.

The Debug console-related MACROS are needed in the board.h file, as follows:

```
#define BOARD_DEBUG_UART_TYPE DEBUG_CONSOLE_DEVICE_TYPE_UART
#define BOARD_DEBUG_UART_BASEADDR (uint32_t) UART2
#define BOARD_DEBUG_UART_CLKSRC BUS_CLK
#define BOARD_DEBUG_UART_BAUDRATE 115200
```

Update the MACROs according to the board design. For example, the default UART instance on the board is LPUART1, the type of default UART instance on one specific platform is LPUART, and the LPUART clock source is the external clock. In this case, change the above MACROs as follows:

```
#define BOARD_DEBUG_UART_TYPE DEBUG_CONSOLE_DEVICE_TYPE_LPUART
#define BOARD_DEBUG_UART_BASEADDR (uint32_t) LPUART1
#define BOARD_DEBUG_UART_CLKSRC kCLOCK_Osc0ErClk
#define BOARD_DEBUG_UART_BAUDRATE 115200
```

Note that there are three kinds of UART instances provided in MCUXpresso SDK devices, UART, LPUART, and LPSCI. The interfaces of the UART instance are different. To provide a uniform UART interface to a USB Host example in which the UART function is used, a UART instance wrapper is provided. The wrapper is implemented in the usb_uart_drv.c, usb_lpuart_drv.c, or usb_lpsci_drv.c file and has a common header file usb_uart_drv.h. For a different UART instance, use the corresponding UART instance wrapper file in the project.

3.3 Porting examples

3.3.1 Copy a new platform example

The platform USB examples directory is shown in the following figure.

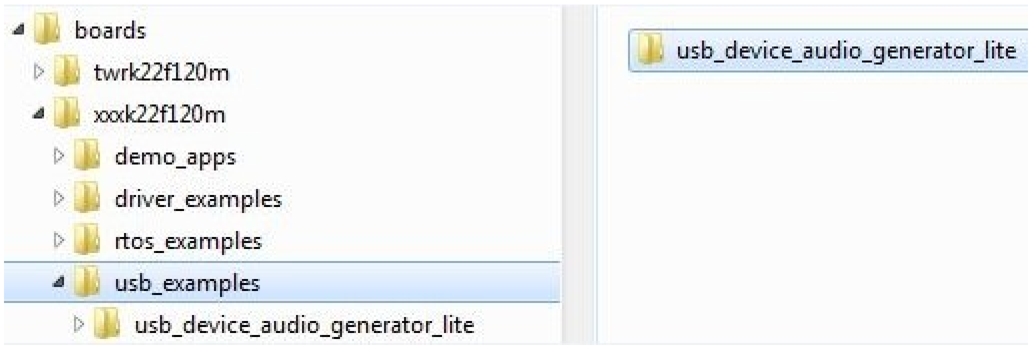


Figure 25. USB examples directory

Copy the existed example's whole directory from the similar platform, which ensures that all example source files and project files are copied.

For example, copy the *twrk22f120m/usb/usb_device_audio_generator_lite* to the *twrkxx/usb* location, which ensures that sources files and project files for usb_device_audio_generator_lite example are copied.

3.3.2 Porting the example

For different examples, different pins are used. As a result, the pin_mux.c/h files are needed to assign different pins to a specific functionality. Check the board schematic for correct pin settings.

Example-related port pin configurations are required in the following files:

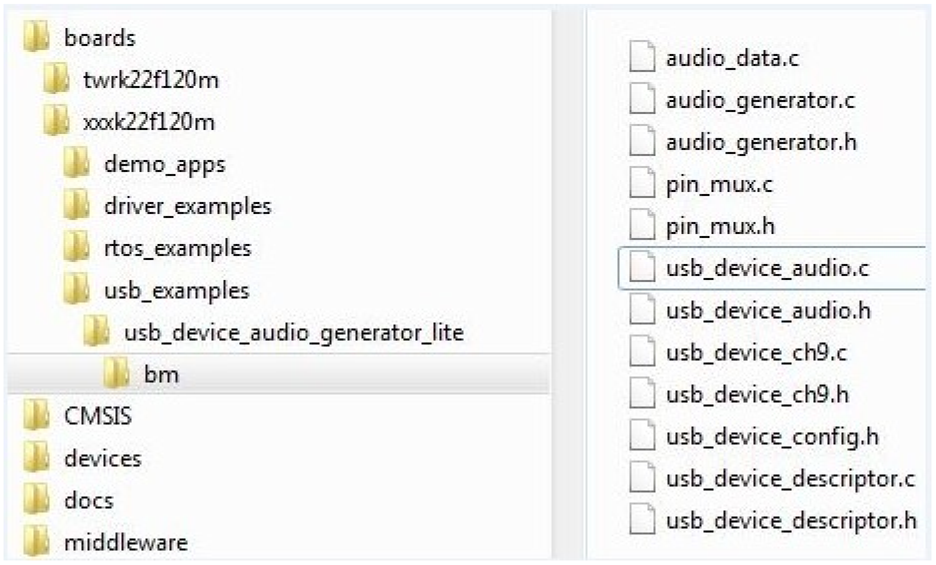


Figure 26. Example-related port pin configuration files

Ensure the `BOARD_InitPins` function is implemented in the pin_mux.c file. In this function, the port clock and pin mux are initialized. Ensure that the `BOARD_InitHardware` calls the function. The `BOARD_InitHardware` function will be introduced later.

For example, on the TWR-K65F180M board, the VBUS of the USB Host is controlled by the PORTD_8 as a GPIO. Therefore, the PORTD clock needs to be enabled first and then the PORTD_8 configured to GPIO functionality. The debug console uses UART2. The TX/RX pins are PORTE_16 and PORTE_17. As a result, the clock of PORTE needs to be enabled first and then the PORTE_16 and PORTE_17 configured to alternative 3.

This is example code for TWR-K65F180M:

```
void BOARD_InitPins(void)
{
/* Initialize UART2 pins below */
CLOCK_EnableClock(kCLOCK_PortE);
    PORT_SetPinMux(PORTE, 16u, kPORT_MuxAlt3);
    PORT_SetPinMux(PORTE, 17u, kPORT_MuxAlt3);

    /* Initialize usb vbus pin */
    CLOCK_EnableClock(kCLOCK_PortD);
    PORT_SetPinMux(PORTD, 8u, kPORT_MuxAsGpio);
}
```

Check the specific board design to find out which port is used to control the USB VBUS and which port is used for the debug console. For example, in the customer’s board design, the PORTC_15 is used to control the USB VBUS, and PORTD_1 and PORTD_2 is used for debug console. The following shows the example code:

```
void BOARD_InitPins(void)
{
/* Initialize UART2 pins below */
CLOCK_EnableClock(kCLOCK_PortD);
    PORT_SetPinMux(PORTD, 1u, kPORT_MuxAlt3);
    PORT_SetPinMux(PORTD, 2u, kPORT_MuxAlt3);

    /* Initialize usb vbus pin */
    CLOCK_EnableClock(kCLOCK_PortC);
    PORT_SetPinMux(PORTC, 15u, kPORT_MuxAsGpio);
}
```

The VBUS must output high. The following is example code for TWR-K65F180M:

```
void BOARD_InitHardware(void)
{
gpio_pin_config_t pinConfig;
BOARD_InitPins();
BOARD_BootClockRUN();
BOARD_InitDebugConsole();
/* vbus gpio output high */
pinConfig.pinDirection = kGPIO_DigitalOutput;
pinConfig.outputLogic = 1U;
GPIO_PinInit(PTD, 8U, &pinConfig);
}
```

The user can change the function as follows:

```
void BOARD_InitHardware(void)
{
gpio_pin_config_t pinConfig;
BOARD_InitPins();
BOARD_BootClockxxx();
BOARD_InitDebugConsole();
/* vbus gpio output high */
pinConfig.pinDirection = kGPIO_DigitalOutput;
pinConfig.outputLogic = 1U;
GPIO_PinInit(PTC, 15U, &pinConfig);
}
```

3.3.3 Modify the example project

USB example project files are kept in the example directory, as shown in the following figure.

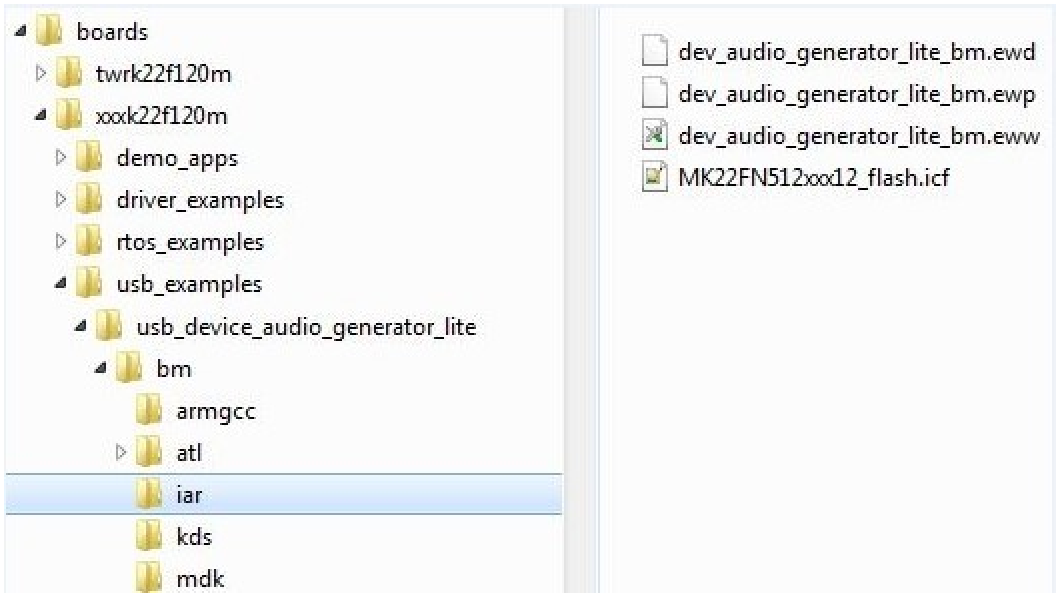

boards
twrk22f120m
xxxk22f120m
demo_apps
driver_examples
rtos_examples
usb_examples
usb_device_audio_generator_lite
bm
armgcc
atl
iar
kds
mdk
dev_audio_generator_lite_bm.ewd
dev_audio_generator_lite_bm.ewp
dev_audio_generator_lite_bm.eww
MK22FN512xxx12_flash.icf

Figure 27. Modify the example project

1. Open the project and change the SoC.

NOTE

a. Check the project SoC and update to the porting platform SoC.

b. Update the SoC full name, platform name, and board type name macros if the SoC is updated. For example, for TWR-K22F120M, update the CPU_MK22FN512VDC12, TWR_K22F120M, and TOWER macros.

2. Check the files in startup group, for example (IAR):

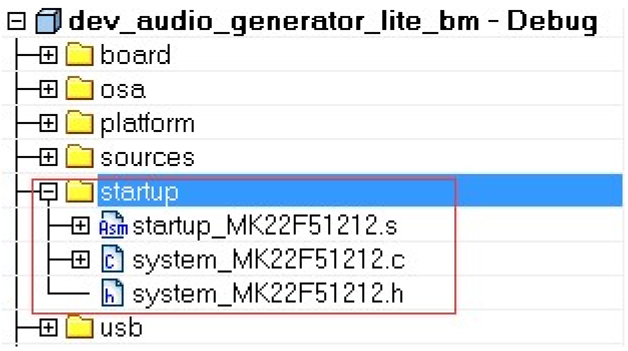


Figure 28. Check files in startup group

Ensure that the system_MK22F51212.c, system_MK22F51212.h, and strtup_MK22F51212.s are the porting SoC files. Also change the include path.

3. Check the files in the platform/clock group, for example (IAR):

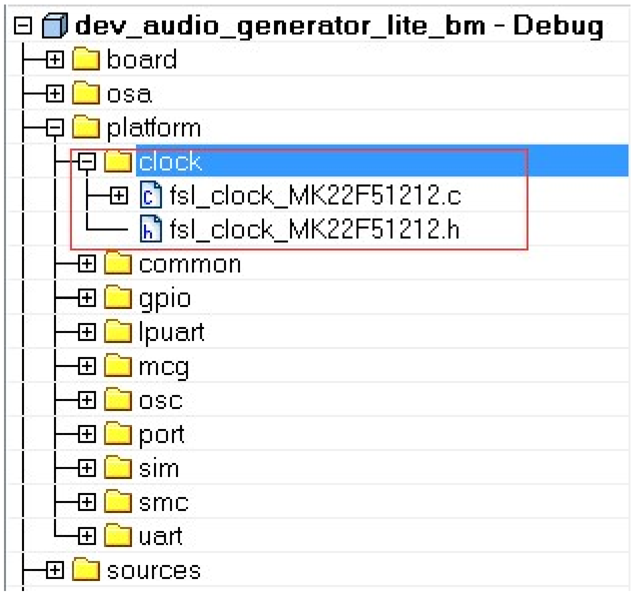


Figure 29. Check files in platform/clock group

Ensure that the fsl_clock_MK22F51212.c, and fsl_clock_MK22F51212.h are porting SoC files. Additionally, change the include path.

4. Change the files in board group, for example (IAR):

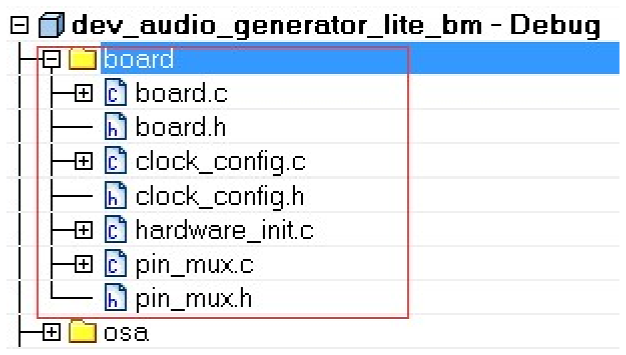


Figure 30. Change files in board group

Ensure that board.c, board.h, clock_config.c, and clock_config.h are porting platform files. Additionally, change the include path.

5. Check the files in the sources group, for example (IAR):

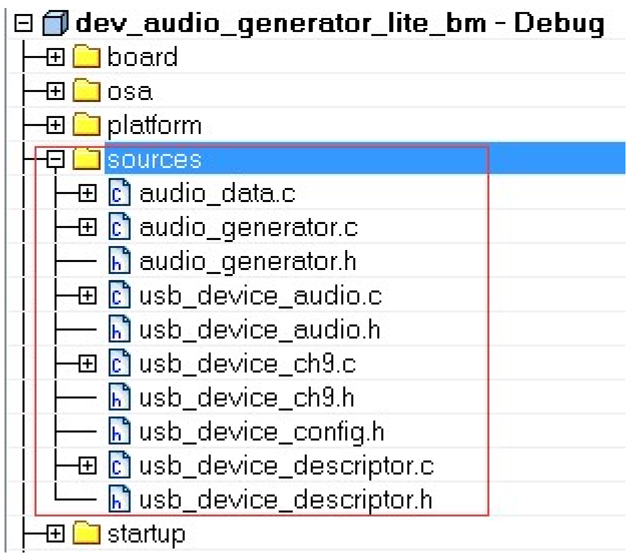


Figure 31. Check files in source group

The example application source files are copied when copying the example directory. Change the include path.

6. Change the linker file to the new platform. Ensure that the linker file is the porting SoC file.
7. Debug console may use UART, LPUART, or LPSCI according to the platform. As a result, the example project needs to contain UART, LPUART, or LPSCI driver files according to the platform.

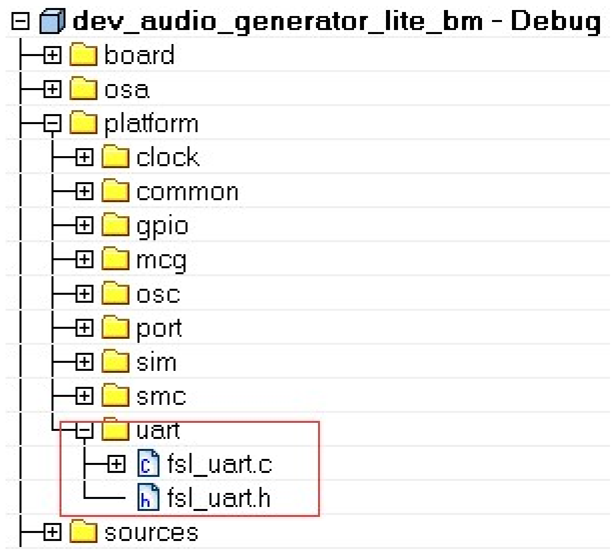


Figure 32. UART, LPUART, and LPSCI files

For example, for TWR-K22F120M all UART files are all in the project. In another example, TWR-K80F150M, all LPUART files are in the project.

3.3.4 USB host CDC example

The MCUXpresso SDK debug console can be based on The MCUXpresso SDK UART, LPUART, or LPSCI driver. Because different platforms may use different drivers, the CDC has a wrapper code. The files, which call the corresponding driver API according to the debug console use UART, LPUART, or LPSCI. The utility uses the BOARD_DEBUG_UART_TYPE toidentify the UART type. To use a different UART instance, use the corresponding UART instance wrapper file.

The MCUXpresso SDK debug console only enables send. The Host CDC example needs the receive function. Therefore, configuration MACROs need to be defined in the board.h file. The debug console and the Host CDC share the same configuration. This is an example:

```
#define BOARD_DEBUG_UART_TYPE       kSerialPort_Uart
#define BOARD_DEBUG_UART_BASEADDR   (uint32_t)UART1
#define BOARD_DEBUG_UART_CLKSRC     kCLOCK_CoreSysClk
#define BOARD_DEBUG_UART_BAUDRATE   115200
```

Update MACROs according to board design. For example, the default UART instance on the board is LPUART1, the type of default UART instance on one specific platform is LPUART, and the LPUART clock source is the external clock. In this case, change the above MACROs as follows:

```
#define BOARD_DEBUG_UART_TYPE kSerialPort_Uart
#define BOARD_DEBUG_UART_BASEADDR (uint32_t) LPUART1
#define BOARD_DEBUG_UART_CLKSRC kCLOCK_Osc0ErClk
#define BOARD_DEBUG_UART_BAUDRATE 115200
```

3.3.5 USB device MSC SD card example

USB device MSC SD card example needs SDHC driver support and SD card support. The example works only if the platform supports both SD card and the SDHC. To enable this example using the same code, the following MACROs are defined in the board.h file:

```
#define BOARD_SDHC_BASEADDR             SDHC
#define BOARD_SDHC_CLKSRC               kCLOCK_CoreSysClk
```

```
#define BOARD_SDHC_CD_GPIO_BASE         GPIOB
#define BOARD_SDHC_CD_GPIO_PIN          20U
#define BOARD_SDHC_CD_PORT_BASE         PORTB
#define BOARD_SDHC_CD_PORT_IRQ          PORTB_IRQn
#define BOARD_SDHC_CD_PORT_IRQ_HANDLER  PORTB_IRQHandler
```

Update the MACROs according to the board design. For example, the SD card detection GPIO on the board is PORTD_1. In this case, change the above MACROs as follows:

```
#define BOARD_SDHC_BASEADDR             SDHC
#define BOARD_SDHC_CLKSRC               kCLOCK_CoreSysClk
#define BOARD_SDHC_CD_GPIO_BASE         GPIOD
#define BOARD_SDHC_CD_GPIO_PIN          1U
#define BOARD_SDHC_CD_PORT_BASE         PORTD
#define BOARD_SDHC_CD_PORT_IRQ          PORTD_IRQn
#define BOARD_SDHC_CD_PORT_IRQ_HANDLER  PORTD_IRQHandler
```

3.3.6 USB device audio speaker example

USB device audio speaker example needs the I2C, SAI, and DMA driver support.

The instance of SAI (I2S) and I2C are defined in the app.h file in the example directory as follows:

```
#define DEMO_SAI I2S0
#define DEMO_I2C I2C0
#define DEMO_SAI_CLKSRC kCLOCK_CoreSysClk
```

Update the MACROs according to board design. For example, the I2S instance on the board is I2S2. In this case, change the above MACROs as follows:

```
#define DEMO_SAI I2S2
#define DEMO_I2C I2C2
#define DEMO_SAI_CLKSRC kCLOCK_CoreSysClk
```

3.3.7 USB device CCID Smart card example

The example is based on the EMVL1 stack, which works on the EMV protocol. As a result, the example can only be ported to the platform that supports both the EMVL1 stack and the EMV protocol.

Chapter 4 Developing a new USB application

The following sections provide information regarding how to develop a new USB application.

4.1 Developing a new USB device application

This chapter introduces how to develop a new USB device application. The user needs to use the application interface and the following steps to develop a new application.

4.1.1 Application interfaces

The interface definition between the application and the classes includes the calls shown in the following table:

Table 2. Application and classes interface definition

API Call	Description
Class Initialization	This API is used to initialize the class.
Receive Data	This API is used by the application to receive data from the host system.
Send Data	This API is used by the application to send data to the host system.
USB descriptor-related callback	Handles the callback to get the descriptor.
USB Device call back function	Handles the callback by the class driver to inform the application about various USB bus events.
USB Class-specific call back function	Handles the specific callback of the class.

4.1.2 How to develop a new device application

Perform these steps to develop a new device application:

1. Create a new application directory under `<install_dir>/boards/<board>/usb_examples/usb_device_<class>_<application>` to locate the application source files and header files. For example, `<install_dir>/boards/<board>/usb_examples/usb_device_hid_test`.
2. Copy the following files from the similar existing applications to the application directory that is created in Step 1.

   ```
   usb_device_descriptor.c
   usb_device_descriptor.h
   ```

   The `usb_device_descriptor.c` and `usb_device_descriptor.h` files contain the USB descriptors that are dependent on the application and the class driver.
3. Copy the bm directory from the similar existing application directory to the new application directory. Remove the unused project directory from the bm directory. Modify the project directory name to the new application project name. For example, to create `toolchain-IAR, board-frdmk64 class-hid related application`, create the new application `hid_test` based on a similar existing application `hid_mouse`.

   Change `<install_dir>/boards/<board>/usb_examples/usb_device_hid_mouse` to `<install_dir>/boards/<board>/usb_examples/usb_device_hid_test`
4. Modify the project file name to the new application project file name, for example, from `dev_hid_mouse_bm.ewp` to `dev_hid_test_bm.ewp`. Globally replace the existing name to the new project name by editing the project files. The `dev_hid_test_bm.ewp` file includes the new application project setting.

5. Create a new source file to implement the main application functions and callback functions. The name of this file is similar to the new application name, such as `mouse.c` and `keyboard.c`.

The following sections describe the steps to change application files created in the steps above to match the new application.

4.1.2.1 Changing the usb_device_descriptor.c file

This file contains the class driver interface. It also contains USB standard descriptors such as device descriptor, configuration descriptor, string descriptor, and the other class-specific descriptors that are provided to class driver when required.

The lists below show user-modifiable variable types for an already implemented class driver. The user should also modify the corresponding MACROs defined in the usb_device_descriptor.h file. See the *MCUXpresso SDK API Reference Manual* (document MCUXSDKAPIRM) for details.

- usb_device_endpoint_struct_t;
- usb_device_endpoint_list_t;
- usb_device_interface_struct_t;
- usb_device_interfaces_struct_t;
- usb_device_interface_list_t;
- usb_device_class_struct_t;
- usb_device_class_config_struct_t;
- usb_device_class_config_list_struct_t;

This diagram shows the relationship between these items:

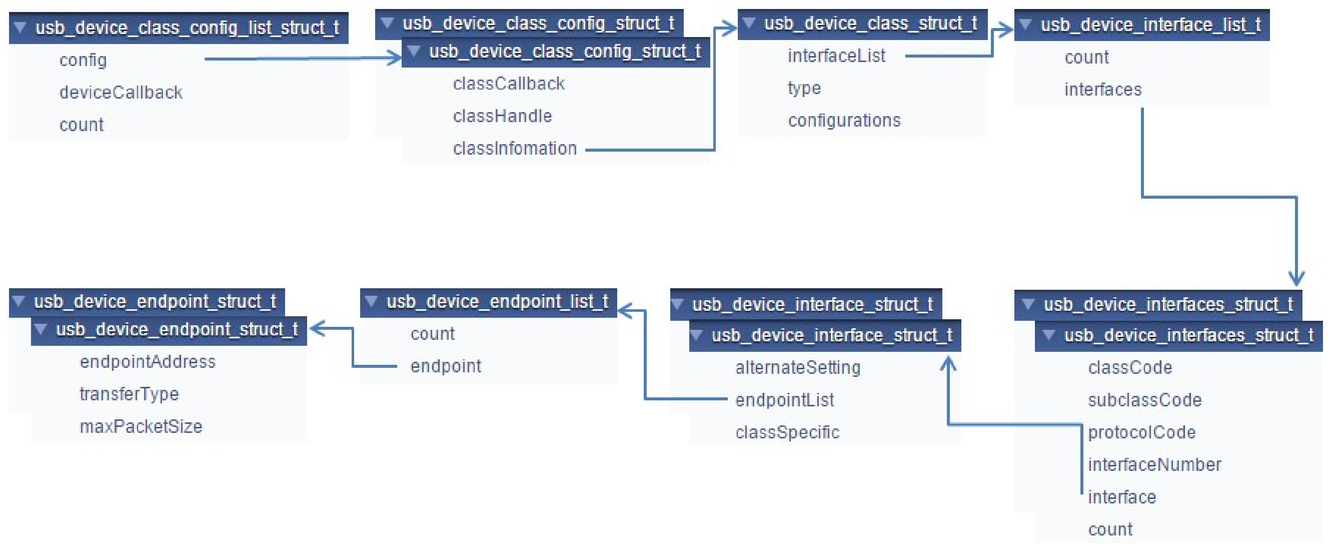

usb_device_class_config_list_struct_t
config
deviceCallback
count
usb_device_class_config_struct_t
usb_device_class_config_struct_t
classCallback
classHandle
classInfomation
usb_device_class_struct_t
interfaceList
type
configurations
usb_device_interface_list_t
count
interfaces
usb_device_endpoint_struct_t
usb_device_endpoint_struct_t
endpointAddress
transferType
maxPacketSize
usb_device_endpoint_list_t
count
endpoint
usb_device_interface_struct_t
usb_device_interface_struct_t
alternateSetting
endpointList
classSpecific
usb_device_interfaces_struct_t
usb_device_interfaces_struct_t
classCode
subclassCode
protocolCode
interfaceNumber
interface
count

Figure 33. Relationship diagram

This is the sample code implementation of the endpoint descriptor for the HID class:

```
/* HID mouse endpoint information */
usb_device_endpoint_struct_t g_UsbDeviceHidMouseEndpoints[USB_HID_MOUSE_ENDPOINT_COUNT] =
{
    /* HID mouse interrupt IN pipe */
    {
        USB_HID_MOUSE_ENDPOINT_IN | (USB_IN << USB_DESCRIPTOR_ENDPOINT_ADDRESS_DIRECTION_SHIFT),
        USB_ENDPOINT_INTERRUPT,
        FS_HID_MOUSE_INTERRUPT_IN_PACKET_SIZE,
    },
};
```

The endpoint address, transfer type, and max packet size in this variable are defined in the usb_device_descriptor.h file. The user may change these value as required. For example, to implement a CDC class application:

```
/* Define endpoint for a communication class */
usb_device_endpoint_struct_t g_UsbDeviceCdcVcomCicEndpoints[USB_CDC_VCOM_ENDPOINT_CIC_COUNT] = {
    {
        USB_CDC_VCOM_INTERRUPT_IN_ENDPOINT | (USB_IN << 7U), USB_ENDPOINT_INTERRUPT,
        FS_CDC_VCOM_INTERRUPT_IN_PACKET_SIZE,
    },
};

/* Define endpoint for data class */
usb_device_endpoint_struct_t g_UsbDeviceCdcVcomDicEndpoints[USB_CDC_VCOM_ENDPOINT_DIC_COUNT] = {
    {
        USB_CDC_VCOM_BULK_IN_ENDPOINT | (USB_IN << 7U),
USB_ENDPOINT_BULK, FS_CDC_VCOM_BULK_IN_PACKET_SIZE,
    },
    {
        USB_CDC_VCOM_BULK_OUT_ENDPOINT | (USB_OUT << 7U),
USB_ENDPOINT_BULK, FS_CDC_VCOM_BULK_OUT_PACKET_SIZE,
    }
};
```

The endpoint count and alternate setting of the interface may differ in various applications. The user may change these values as required. For example, the interface structure of a CDC class application is as follows:

```
/* Define interface for communication class */
usb_device_interface_struct_t g_UsbDeviceCdcVcomCommunicationInterface[] = {{
    1U,
    {
        USB_CDC_VCOM_ENDPOINT_CIC_COUNT, g_UsbDeviceCdcVcomCicEndpoints,
    },
}};
/* Define interface for data class */
usb_device_interface_struct_t g_UsbDeviceCdcVcomDataInterface[] =
{
    {
        0,
        {
            USB_CDC_VCOM_ENDPOINT_DIC_COUNT,
            g_UsbDeviceCdcVcomDicEndpoints,
        },
        NULL
    }
};
```

The class code, subclass code, and protocol code may differ in various classes. For example, the usb_device_interfaces_struct of a CDC class is as follows:

```
/* Define interfaces for the virtual com */
usb_device_interfaces_struct_t g_UsbDeviceCdcVcomInterfaces[USB_CDC_VCOM_INTERFACE_COUNT] = {
    {USB_CDC_VCOM_CIC_CLASS, USB_CDC_VCOM_CIC_SUBCLASS,
USB_CDC_VCOM_CIC_PROTOCOL, USB_CDC_VCOM_COMM_INTERFACE_INDEX,
     g_UsbDeviceCdcVcomCommunicationInterface,
     sizeof(g_UsbDeviceCdcVcomCommunicationInterface) / sizeof(usb_device_interfaces_struct_t)},
    {USB_CDC_VCOM_DIC_CLASS, USB_CDC_VCOM_DIC_SUBCLASS,
USB_CDC_VCOM_DIC_PROTOCOL, USB_CDC_VCOM_DATA_INTERFACE_INDEX,
     g_UsbDeviceCdcVcomDataInterface,
sizeof(g_UsbDeviceCdcVcomDataInterface) / sizeof(usb_device_interfaces_struct_t)},
};
```

The interface count may differ in various applications. For example, the usb_device_interface_list of a CDC class application is as follows:

```
/* Define configurations for virtual com */
usb_device_interface_list_t g_UsbDeviceCdcVcomInterfaceList[USB_DEVICE_CONFIGURATION_COUNT] = {
    {
        USB_CDC_VCOM_INTERFACE_COUNT, g_UsbDeviceCdcVcomInterfaces,
    },
};
```

The interface list, class type and configuration count may differ in various applications. For example, the usb_device_class_struct of a CDC class application is as follows:

```
/* Define class information for virtual com */
usb_device_class_struct_t g_UsbDeviceCdcVcomConfig = {
    g_UsbDeviceCdcVcomInterfaceList, kUSB_DeviceClassTypeCdc, USB_DEVICE_CONFIGURATION_COUNT,
};
```

- g_UsbDeviceDescriptor

  This variable contains the USB Device Descriptor.

  Sample code implementation of the device descriptor for the HID class is shown as follows:

  ```
  uint8_t g_UsbDeviceDescriptor[USB_DESCRIPTOR_LENGTH_DEVICE] =
  {
      USB_DESCRIPTOR_LENGTH_DEVICE,    /* Size of this descriptor in bytes */
      USB_DESCRIPTOR_TYPE_DEVICE,      /* DEVICE Descriptor Type */
      USB_SHORT_GET_LOW(USB_DEVICE_SPECIFIC_BCD_VERSION),
      USB_SHORT_GET_HIGH(USB_DEVICE_SPECIFIC_BCD_VERSION),/* USB Specification Release Number in
                                                             Binary-Coded Decimal (i.e., 2.10 is
  210H). */
      USB_DEVICE_CLASS,                /* Class code (assigned by the USB-IF). */
      USB_DEVICE_SUBCLASS,             /* Subclass code (assigned by the USB-IF). */
      USB_DEVICE_PROTOCOL,             /* Protocol code (assigned by the USB-IF). */
      USB_CONTROL_MAX_PACKET_SIZE,     /* Maximum packet size for endpoint zero
                                          (only 8, 16, 32, or 64 are valid) */
      0xA2U, 0x15U,                    /* Vendor ID (assigned by the USB-IF) */
      0x7CU, 0x00U,                    /* Product ID (assigned by the manufacturer) */
      USB_SHORT_GET_LOW(USB_DEVICE_DEMO_BCD_VERSION),
      USB_SHORT_GET_HIGH(USB_DEVICE_DEMO_BCD_VERSION),/* Device release number in binary-coded
  decimal */
      0x01U,                           /* Index of string descriptor describing manufacturer */
      0x02U,                           /* Index of string descriptor describing product */
      0x00U,                           /* Index of string descriptor describing the
                                          device serial number */
      USB_DEVICE_CONFIGURATION_COUNT,  /* Number of possible configurations */
  };
  ```

The macros in the variable above are defined in the usb_device_descriptor.h file, such as the USB_DEVICE_CLASS, USB_DEVICE_SUBCLASS, and USB_DEVICE_PROTOCOL. Those values may need to be modified as required. The vendor ID and product ID can also be modified.

- g_UsbDeviceConfigurationDescriptor

  This variable contains the USB Configuration Descriptor.

Sample code implementation of the configuration descriptor for the HID class is providing in the following:

```
uint8_t g_UsbDeviceConfigurationDescriptor[USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL] =
{
   USB_DESCRIPTOR_LENGTH_CONFIGURE,  /* Size of this descriptor in bytes */
   USB_DESCRIPTOR_TYPE_CONFIGURE,    /* CONFIGURATION Descriptor Type */
   USB_SHORT_GET_LOW(USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL),
   USB_SHORT_GET_HIGH(USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL),/* Total length of data returned
for this configuration. */
   USB_HID_MOUSE_INTERFACE_COUNT,  /* Number of interfaces supported by this configuration */
   USB_HID_MOUSE_CONFIGURE_INDEX,  /* Value to use as an argument to the
                                       SetConfiguration() request to select this configuration */
   0x00U,                            /* Index of string descriptor describing this
configuration */
   (USB_DESCRIPTOR_CONFIGURE_ATTRIBUTE_D7_MASK) |
   (USB_DEVICE_CONFIG_SELF_POWER << USB_DESCRIPTOR_CONFIGURE_ATTRIBUTE_SELF_POWERED_SHIFT) |
   (USB_DEVICE_CONFIG_REMOTE_WAKEUP << USB_DESCRIPTOR_CONFIGURE_ATTRIBUTE_REMOTE_WAKEUP_SHIFT),
                                     /* Configuration characteristics
                                          D7: Reserved (set to one)
                                          D6: Self-powered
                                          D5: Remote Wakeup
                                          D4...0: Reserved (reset to zero)
                                     */
   USB_DEVICE_MAX_POWER,             /* Maximum power consumption of the USB
                                      * device from the bus in this specific
                                      * configuration when the device is fully
                                      * operational. Expressed in 2 mA units
                                      *  (i.e., 50 = 100 mA).
                                      */
```

The macro USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL, which is defined in the usb_device_descriptor.h, needs to be modified to equal the size of this variable. The interface count and configuration index may differ in various applications. For example, this part of a CDC class application is as shown below:

```
    /* Size of this descriptor in bytes */
    USB_DESCRIPTOR_LENGTH_CONFIGURE,
    /* CONFIGURATION Descriptor Type */
    USB_DESCRIPTOR_TYPE_CONFIGURE,
    /* Total length of data returned for this configuration. */
    USB_SHORT_GET_LOW(USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL),
    USB_SHORT_GET_HIGH(USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL),
    /* Number of interfaces supported by this configuration */
    USB_CDC_VCOM_INTERFACE_COUNT,
    /* Value to use as an argument to the SetConfiguration() request to select this configuration */
    USB_CDC_VCOM_CONFIGURE_INDEX,
    /* Index of string descriptor describing this configuration */
    0,
    /* Configuration characteristics D7: Reserved (set to one) D6: Self-powered D5: Remote Wakeup
D4...0: Reserved
       (reset to zero) */
    (USB_DESCRIPTOR_CONFIGURE_ATTRIBUTE_D7_MASK) |
        (USB_DEVICE_CONFIG_SELF_POWER << USB_DESCRIPTOR_CONFIGURE_ATTRIBUTE_SELF_POWERED_SHIFT) |
        (USB_DEVICE_CONFIG_REMOTE_WAKEUP << USB_DESCRIPTOR_CONFIGURE_ATTRIBUTE_REMOTE_WAKEUP_SHIFT),
    /* Maximum power consumption of the USB * device from the bus in this specific * configuration
when the device is
       fully * operational. Expressed in 2 mA units *  (i.e., 50 = 100 mA).  */
USB_DEVICE_MAX_POWER,
```

The interface descriptor may differ from various applications. For example, the interface descriptor of a CDC class application would be as shown below.

```
    /* Communication Interface Descriptor */
    USB_DESCRIPTOR_LENGTH_INTERFACE, USB_DESCRIPTOR_TYPE_INTERFACE,
USB_CDC_VCOM_COMM_INTERFACE_INDEX, 0x00,
    USB_CDC_VCOM_ENDPOINT_CIC_COUNT, USB_CDC_VCOM_CIC_CLASS,
USB_CDC_VCOM_CIC_SUBCLASS, USB_CDC_VCOM_CIC_PROTOCOL,
0x00, /* Interface Description String Index*/
```

The class specific descriptor may differ from various applications. For example, the class specific descriptor of a CDC class application would be as shown below.

```
    /* CDC Class-Specific descriptor */
    USB_DESCRIPTOR_LENGTH_CDC_HEADER_FUNC, /* Size of this descriptor in bytes */
    USB_DESCRIPTOR_TYPE_CDC_CS_INTERFACE,  /* CS_INTERFACE Descriptor Type */
    HEADER_FUNC_DESC, 0x10,
    0x01, /* USB Class Definitions for Communications the Communication specification version 1.10 */

    USB_DESCRIPTOR_LENGTH_CDC_CALL_MANAG, /* Size of this descriptor in bytes */
    USB_DESCRIPTOR_TYPE_CDC_CS_INTERFACE, /* CS_INTERFACE Descriptor Type */
    CALL_MANAGEMENT_FUNC_DESC,
    0x01, /*Bit 0: Whether device handle call management itself 1, Bit 1: Whether device can send/
receive call
             management information over a Data Class Interface 0 */
    0x01, /* Indicates multiplexed commands are handled via data interface */
       USB_DESCRIPTOR_LENGTH_CDC_ABSTRACT,   /* Size of this descriptor in bytes */
    USB_DESCRIPTOR_TYPE_CDC_CS_INTERFACE, /* CS_INTERFACE Descriptor Type */
    USB_CDC_ABSTRACT_CONTROL_FUNC_DESC,
    0x06, /* Bit 0: Whether device supports the request combination of Set_Comm_Feature,
Clear_Comm_Feature, and
             Get_Comm_Feature 0, Bit 1: Whether device supports the request combination
of Set_Line_Coding,
             Set_Control_Line_State, Get_Line_Coding, and the notification Serial_State 1, Bit ...  */

    USB_DESCRIPTOR_LENGTH_CDC_UNION_FUNC, /* Size of this descriptor in bytes */
    USB_DESCRIPTOR_TYPE_CDC_CS_INTERFACE, /* CS_INTERFACE Descriptor Type */
    USB_CDC_UNION_FUNC_DESC, 0x00,        /* The interface number of the Communications or Data Class
interface  */
    0x01,                                 /* Interface number of subordinate interface in the
Union  */
```

The endpoint descriptor may differ from various applications. For example, the endpoint descriptor of a CDC class application is as follows:

```
/*Notification Endpoint descriptor */
    USB_DESCRIPTOR_LENGTH_ENDPOINT, USB_DESCRIPTOR_TYPE_ENDPOINT, USB_CDC_VCOM_INTERRUPT_IN_ENDPOINT
| (USB_IN << 7U),
    USB_ENDPOINT_INTERRUPT, USB_SHORT_GET_LOW(FS_CDC_VCOM_INTERRUPT_IN_PACKET_SIZE),
    USB_SHORT_GET_HIGH(FS_CDC_VCOM_INTERRUPT_IN_PACKET_SIZE), FS_CDC_VCOM_INTERRUPT_IN_INTERVAL,
}
```

- String Descriptors

  Users can modify string descriptors to customize their product. String descriptors are written in the UNICODE format. An appropriate language identification number is specified in the USB_STR_0. Multiple language support can also be added.

- USB_DeviceGetDeviceDescriptor

This interface function is invoked by the application. This call is made when the application receives the kUSB_DeviceEventGetDeviceDescriptor event from the Host. Mandatory descriptors that an application is required to implement are as follows:

— Device Descriptor

— Configuration Descriptor

— Class-Specific Descriptors (For example, for HID class implementation, Report Descriptor, and HID Descriptor)

Apart from the mandatory descriptors, an application should also implement various string descriptors as specified by the Device Descriptor and other configuration descriptors.

Sample code for HID class application is as follows:

```
/* Get device descriptor request */
usb_status_t USB_DeviceGetDeviceDescriptor(usb_device_handle handle,

usb_device_get_device_descriptor_struct_t *deviceDescriptor)
{
    deviceDescriptor->buffer = g_UsbDeviceDescriptor;
    deviceDescriptor->length = USB_DESCRIPTOR_LENGTH_DEVICE;
    return kStatus_USB_Success;
}
```

The user may assign the appropriate variable of the device descriptor. For example, if the device descriptor variable name is g_UsbDeviceDescriptorUser, the sample code is as follows:

```
/* Get device descriptor request */
usb_status_t USB_DeviceGetDeviceDescriptor(usb_device_handle handle,

usb_device_get_device_descriptor_struct_t *deviceDescriptor)
{
    deviceDescriptor->buffer = g_UsbDeviceDescriptorUser;
    deviceDescriptor->length = USB_DESCRIPTOR_LENGTH_DEVICE;
    return kStatus_USB_Success;
}
```

- USB_DeviceGetConfigurationDescriptor

  This interface function is invoked by the application. This call is made when the application receives the kUSB_DeviceEventGetConfigurationDescriptor event from the Host.

```
/* Get device configuration descriptor request */
usb_status_t USB_DeviceGetConfigurationDescriptor(
    usb_device_handle handle,
usb_device_get_configuration_descriptor_struct_t *configurationDescriptor)
{
    if (USB_HID_MOUSE_CONFIGURE_INDEX > configurationDescriptor->configuration)
    {
        configurationDescriptor->buffer = g_UsbDeviceConfigurationDescriptor;
        configurationDescriptor->length = USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL;
        return kStatus_USB_Success;
    }
    return kStatus_USB_InvalidRequest;
}
```

The macro HID_MOUSE_CONFIGURE_INDEX may differ from various applications. For example, the implementation of a CDC class application would be as follows:

```
usb_status_t USB_DeviceGetConfigurationDescriptor(
    usb_device_handle handle,
usb_device_get_configuration_descriptor_struct_t *configurationDescriptor)
{
    if (USB_CDC_VCOM_CONFIGURE_INDEX > configurationDescriptor->configuration)
    {
        configurationDescriptor->buffer = g_UsbDeviceConfigurationDescriptor;
        configurationDescriptor->length = USB_DESCRIPTOR_LENGTH_CONFIGURATION_ALL;
        return kStatus_USB_Success;
    }
    return kStatus_USB_InvalidRequest;
}
```

- USB_DeviceGetStringDescriptor

  This interface function is invoked by the application. This call is made when the application receives the kUSB_DeviceEventGetStringDescriptor event from the Host.

  See the usb_device_hid_mouse example for sample code.

- USB_DeviceGetHidReportDescriptor

  This interface function is invoked by the application. This call is made when the application receives the kUSB_DeviceEventGetHidReportDescriptor event from the Host.

  See the usb_device_hid_mouse example for sample code.

- USB_DeviceSetSpeed

  Because HS and FS descriptors are different, the device descriptors and configurations need to be updated to match the current speed. By default, the device descriptors and configurations are configured using FS parameters for EHCI, KHCI, and other controllers, such as LPC IP3511. When the EHCI is enabled, the application needs to call this function to update the device by using the current speed. The updated information includes the endpoint max packet size, endpoint interval, and so on.

4.1.2.2 Changing the usb_device_descriptor.h file

This file is mandatory for the application to implement. The usb_device_descriptor.c file includes this file for function prototype definitions. When the user modifies the usb_device_descriptor.c, MACROs in this file should also be modified.

4.1.2.3 Changing the application file

- Main application function

  The main application function is provided by two functions: USB_DeviceApplicationInit and APP_task (optional).

  The USB_DeviceApplicationInit enables the clock and the USB interrupt and also initialize the specific USB class. See the usb_device_hid_mouse example for the sample code.

- USB device call back function

  The device callback function handles the USB device-specific requests. See the usb_device_hid_mouse example for the sample code.

- USB Class-specific call back function

  The class callback function handles the USB class-specific requests. See the usb_device_hid_mouse example for the sample code.

4.2 Developing a new USB host application

4.2.1 Background

In the USB system, the host software controls the bus and talks to the target devices following the rules defined by the specification. A device is represented by a configuration that is a collection of one or more interfaces. Each interface comprises one or more endpoints. Each endpoint is represented as a logical pipe from the application software perspective.

The host application software registers a callback with the USB host stack, which notifies the application about the device attach/detach events and determines whether the device is supported or not. The following figure shows the enumeration and detachment flow.

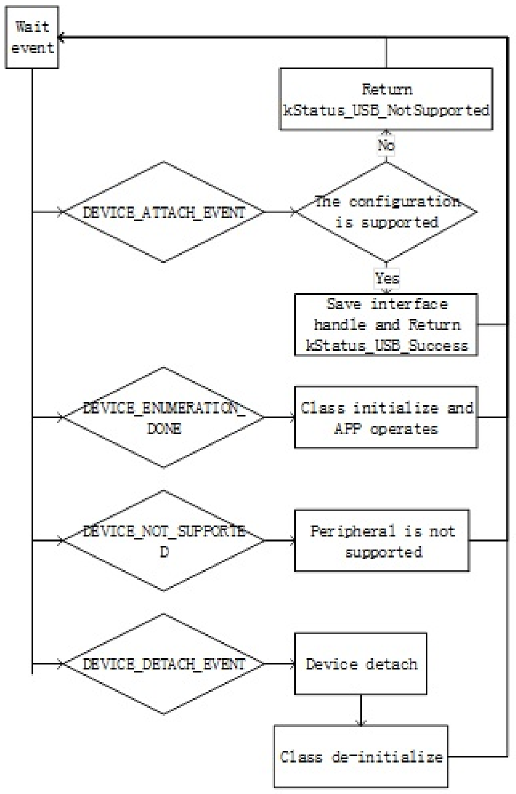

Wait event
Return kStatus_USB_NotSupported
No
DEVICE_ATTACH_EVENT
The configuration is supported
Yes
Save interface handle and Return kStatus_USB_Success
DEVICE_ENUMERATION_DONE
Class initialize and APP operates
DEVICE_NOT_SUPPORTED
Peripheral is not supported
DEVICE_DETACH_EVENT
Device detach
Class de-initialize

Figure 34. Enumeration and detachment flow

The USB host stack is a few lines of code executed before starting communication with the USB device. The examples on the USB stack are written with class driver APIs. Class drivers work with the host API as a supplement to the functionality. They make it easy to achieve the target functionality (see example sources for details) without dealing with the implementation of standard routines. The following code steps are taken inside a host application driver for any specific device.

4.2.2 How to develop a new host application

4.2.2.1 Creating a project

Perform the following steps to create a project.

- Create a new application directory under `<install_dir>/boards/<board>/usb_examples/usb_host_<class>_<application>` to locate the application source files and header files. For example, `<install_dir>/boards/<board>/usb_examples/usb_host_hid_mouse`.
- Copy the following files from the similar existing applications to the application directory that is created in step 1.

  app.c

  usb_host_config.h

The app.c file contains the common initialization code for USB host and the usb_host_config.h file contains the configuration MACROs for the USB host.

- Copy the bm directory from the similar existing application directory to the new application directory. Remove the unused project directory from the bm directory. Modify the project directory name to the new application project name. For example, `to create toolchain-IAR, board-frdmk64 class-hid related application` , create the new application `hid_test` based on a similar existing application `hid_mouse`.

  Copy `<install_dir>/boards/frdmk64f/usb_examples/usb_host_hid_mouse/bm`

  to `<install_dir>/boards/frdmk64f/usb_examples/usb_host_hid_test/bm`
- Modify the project file name to the new application project file name, for example, from `host_hid_mouse_bm.ewp` to `host_hid_test_bm.ewp` . Globally replace the existing name to the new project name by editing the project files. The `host_hid_test_bm.ewp` file includes the new application project setting.
- Create a new source file to implement the main application function, application task function, and the callback function. The name of this file is similar to the new application name, such as `host_mouse.c` and `host_keyboard.c`.

The following sections describe the steps to modify application files created in the steps above to match the new application.

4.2.2.2 Main application function flow

In the main application function, follow these steps:

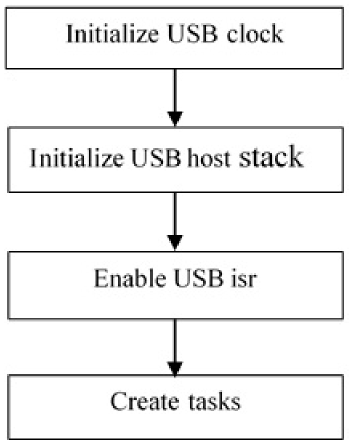


Figure 35. Main application function flow

- Initialize the USB clock.

  Call the MCUXpresso SDK API to initialize the KHCI, the EHCI USB clock, or other controller.
- Initialize the host controller.

  This allows the stack to initialize the necessary memory required to run the stack and register the callback function to the stack.

  For example:`status = USB_HostInit(CONTROLLER_ID, &g_HostHandle, USB_HostEvent);`
- Enable the USB ISR.

  Set the USB interrupt priority and enable the USB interrupt.
- Initialize the host stack task and application task.

  For example (Bare metal):

```
while (1)
{
USB_HostTaskFn(g_HostHandle);
```

```
USB_HostMsdTask(&g_MsdCommandInstance);
```

Note that in this code, the g_MsdCommandInstance variable contains all states and pointers used by the application to control or operate the device. If implementing the application task as USB_HostHidTestTask and use g_HidTestInstance to maintain the application states, modify the code as follows:

```
while (1)
{
USB_HostTaskFn(g_HostHandle);
    USB_HostHidTestTask(&g_HidTestInstance);
}
```

4.2.2.3 Event callback function

In the app.c file, there is one `USB_HostEvent` function. By default, the function is registered to the host stack when calling the `USB_HostInit`. In the USB Host stack, customers do not have to write any enumeration code. When the device is connected to the host controller, the USB Host stack enumerates the device. The device attach/detach events are notified by this callback function.

Application needs to implement one or more functions to correspond to one class process. These application functions are called in the `USB_HostEvent`. The device's configuration handle and interface list are passed to the application through the function so that the application can determine whether the device is supported by this application.

There are four events in the callback: `kUSB_HostEventAttach, kUSB_HostEventNotSupported, kUSB_HostEventEnumerationDone, and kUSB_HostEventDetach`.

The events occur as follows:

- When one device is attached, host stack notifies `kUSB_HostEventAttach`.
- The application returns `kStatus_USB_Success` to notify the host stack that the device configuration is supported by this class application, or return the `kStatus_USB_NotSupported` to notify the host stack that the device configuration is not supported by this class application.
- The Host stack continues for enumeration if the device is supported by the application and notifies `kUSB_HostEventEnumerationDone` when the enumeration is done.
- The Host stack checks the next device's configuration if the current configuration is not supported by the application.
- When the Host stack checks all configurations and all are not supported by the application, it notifies the `kUSB_HostEventNotSupported`.
- When the device detaches, the Host stack notifies the `kUSB_HostEventDetach`.

This is the sample code for the HID mouse application. The `USB_HostHidMouseEvent` function should be called bythe `USB_HostEvent`. In this code, the `g_HostHidMouse` variable contains all states and pointers used by the application to control or operate the device:

```
usb_status_t USB_HostHidMouseEvent
(
usb_device_handle deviceHandle,
   usb_host_configuration_handle configurationHandle,
   uint32_t eventCode
)
{
    /* Process the same and supported device's configuration handle */
    static usb_host_configuration_handle s_ConfigHandle = NULL;
    usb_status_t status = kStatus_USB_Success;
    uint8_t id;
    usb_host_configuration_t *configuration;
    uint8_t interfaceIndex;
    usb_host_interface_t *interface;
    switch (eventCode)
    {
        case kUSB_HostEventAttach:
            /* judge whether is configurationHandle supported */
            configuration = (usb_host_configuration_t *)configurationHandle;
            for (interfaceIndex = 0; interfaceIndex < configuration->interfaceCount; ++interfaceIndex)
            {
                interface = &configuration->interfaceList[interfaceIndex];
                id = interface->interfaceDesc->bInterfaceClass;
                if (id != USB_HOST_HID_CLASS_CODE)
                {
                    continue;
                }
                id = interface->interfaceDesc->bInterfaceSubClass;
                if ((id != USB_HOST_HID_SUBCLASS_CODE_NONE) && (id !
= USB_HOST_HID_SUBCLASS_CODE_BOOT))
                {
                    continue;
                }
                id = interface->interfaceDesc->bInterfaceProtocol;
                if (id != USB_HOST_HID_PROTOCOL_MOUSE)
                {
                    continue;
                }
                else
                {
                    /* the interface is supported by the application */
                    g_HostHidMouse.deviceHandle = deviceHandle;
                    g_HostHidMouse.interfaceHandle = interface;
                    s_ConfigHandle = configurationHandle;
                    return kStatus_USB_Success;
                }
            }
            status = kStatus_USB_NotSupported;
            break;
        case kUSB_HostEventNotSupported:
            break;
        case kUSB_HostEventEnumerationDone:
            if (s_ConfigHandle == configurationHandle)
            {
                if ((g_HostHidMouse.deviceHandle != NULL) && (g_HostHidMouse.interfaceHandle != NULL))
                {
                    /* the device enumeration is done */
                    if (g_HostHidMouse.deviceState == kStatus_DEV_Idle)
                    {
                        g_HostHidMouse.deviceState = kStatus_DEV_Attached;
                    }
                    else
                    {
                        usb_echo("not idle mouse instance\r\n");
                    }
                }
            }
            break;
        case kUSB_HostEventDetach:
            if (s_ConfigHandle == configurationHandle)
            {
                /* the device is detached */
                s_ConfigHandle = NULL;
                if (g_HostHidMouse.deviceState != kStatus_DEV_Idle)
                {
                    g_HostHidMouse.deviceState = kStatus_DEV_Detached;
                }
            }
            break;
        default:
            break;
    }
    return status;
}
```

If implementing the callback as `USB_HostHidTestEvent`, use `g_HidTestInstance`, and support the device that the class code is USB_HOST_HID_TEST_CLASS_CODE, sub-class code is USB_HOST_HID_TEST_SUBCLASS_CODE, and the protocol is USB_HOST_HID_TEST_PROTOCOL. The code can be modified as follows:

```
usb_status_t USB_HostHidMouseEvent
(
usb_device_handle deviceHandle,
   usb_host_configuration_handle configurationHandle,
   uint32_t eventCode
)
{
    /* Process the same and supported device's configuration handle */
    static usb_host_configuration_handle s_ConfigHandle = NULL;
    usb_status_t status = kStatus_USB_Success;
    uint8_t id;
    usb_host_configuration_t *configuration;
    uint8_t interfaceIndex;
    usb_host_interface_t *interface;

    switch (eventCode)
    {
        case kUSB_HostEventAttach:
            /* judge whether is configurationHandle supported */
            configuration = (usb_host_configuration_t *)configurationHandle;
            for (interfaceIndex = 0; interfaceIndex < configuration->interfaceCount; ++interfaceIndex)
            {
                interface = &configuration->interfaceList[interfaceIndex];
                id = interface->interfaceDesc->bInterfaceClass;
                if (id != USB_HOST_HID_TEST_CLASS_CODE)
                {
                    continue;
                }
                id = interface->interfaceDesc->bInterfaceSubClass;
                if (id != USB_HOST_HID_TEST_SUBCLASS_CODE)
                {
                    continue;
                }
                id = interface->interfaceDesc->bInterfaceProtocol;
                if (id != USB_HOST_HID_TEST_PROTOCOL)
                {
                    continue;
                }
                else
                {
                    /* the interface is supported by the application */
                    g_HidTestInstance.deviceHandle = deviceHandle;
                    g_HidTestInstance.interfaceHandle = interface;
```

```
                     s_ConfigHandle = configurationHandle;
                     return kStatus_USB_Success;
                 }
             }
             status = kStatus_USB_NotSupported;
             break;
         case kUSB_HostEventNotSupported:
             break;
         case kUSB_HostEventEnumerationDone:
             if (s_ConfigHandle == configurationHandle)
             {
                 if ((g_HidTestInstance.deviceHandle != NULL) && (g_HidTestInstance.interfaceHandle !
= NULL))
                 {
                     /* the device enumeration is done */
                     if (g_HidTestInstance.deviceState == kStatus_DEV_Idle)
                     {
                         g_HidTestInstance.deviceState = kStatus_DEV_Attached;
                     }
                     else
                     {
                         usb_echo("not idle mouse instance\r\n");
                     }
                 }
             }
             break;
         case kUSB_HostEventDetach:
             if (s_ConfigHandle == configurationHandle)
             {
                 /* the device is detached */
                 s_ConfigHandle = NULL;
                 if (g_HidTestInstance.deviceState != kStatus_DEV_Idle)
                 {
                     g_HidTestInstance.deviceState = kStatus_DEV_Detached;
                 }
             }
             break;
         default:
             break;
     }
     return status;
}
```

Note that the `kStatus_DEV_Attached`, `kStatus_DEV_Detached` MACROs are defined in the example.

4.2.2.4 Class initialization

When the supported device is attached, the device’s class needs to be initialized.

For example, the HID mouse initialization flow is as follows:

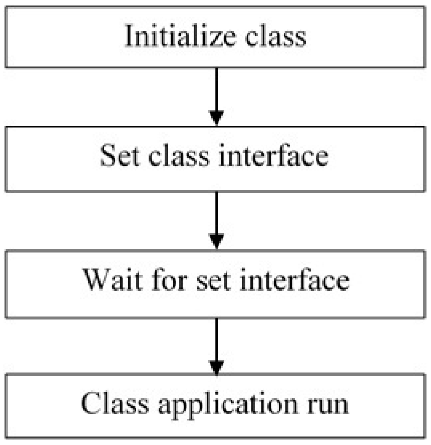


Figure 36. HID mouse initialization flow

- Call class initialization function to initialize the class instance.
- Call class set interface function to set the class interface
- When the set interface callback returns successfully, the application can run.

4.2.2.5 Sending/Receiving data to/from the device

The transfer flow is as follows:

1. Call the `USB_hostClassxxx` API to begin the transfer.
2. The transfer result is notified by the callback function that is passed as a parameter.
3. The HID mouse host uses the following code to receive data from the device:`USB_HostHidRecv(classHandle, mouseBuffer, bufferLength, callbackFunction, callbackParameter);`

Chapter 5 USB compliance tests

For the device, this is enabled on "dev_hid_mouse_bm" as an example.

```
enable USB_DEVICE_CONFIG_COMPLIANCE_TEST (0U)
```

The macro is defined in `usb_device_config.h`. Use the TWR-K65F180M Tower System module as an example. The file path is

<install_dir>/boards/twrk65f180m/usb_examples/usb_device_hid_mouse/bm/usb_device_config.h.

Both CV test and USB test mode are enabled.

For the host, this is enabled on "host_mad_fatfs_bm" as an example.

```
enable USB_HOST_CONFIG_COMPLIANCE_TEST (0U)
```

The macro is defined in the usb_host_config.h file.

For example, for the TWR-K65F180M Tower System module, the file path is

<install_dir>/boards/twrk65f180m/usb_examples/usb_host_msd_fatfs/bm/usb_host_config.h

Chapter 6 USB host FatFs throughput

The following test is based on usb_host_msd_fatfs, bm, IAR, release target.

Table 3. USB host FatFs throughput

	Test device - Sandisk extreme USB3.0 64G SDCZ80 - 64G	
Controller	**Write speed**	**Read speed**
RT1050 EHCI	~32163 KB/s	~38509 KB/s
K28FA KHCI	~913 KB/s	~932 KB/s
LPCXpresso54628 IP3516	~22034 KB/s	~22489 KB/s
LPCXpresso54628 OHCI	~860 KB/s	~970 KB/s

Chapter 7 USB device ramdisk throughput

Table 4. USB device ramdisk throughput

Controller	Write speed	Read speed
RT1050 EHCI (System clock 600 MHz)	~29051 KB/s	~32338 KB/s
K28FA KHCI (System clock 150 MHz)	~1007 KB/s	~1106 KB/s
LPCXpresso54628 IP3511FS (System clock 220 MHz)	~972 KB/s	~1140 KB/s
LPCXpresso54628 IP3511HS (System clock 220 MHz)	~17438 KB/s	~31496 KB/s

Chapter 8 Precautions

For USB host, if using USB HUB, the external power supply of the USB HUB must be provided before it is used.

The development board power is not enough to supply multi-level USB HUBs and connected devices.

Therefore, the external USB HUB connected to the development board should have its own power supply.

Chapter 9
Revision history

This table summarizes revisions to this document since the release of the previous version.

Table 5. Revision history

Revision number	Date	Substantive changes
1	01/2016	KSDK 2.0.0 release
2	08/2016	Added LPC content for release
3	09/2016	Updated for KSDK 2.0.0 release 5
4	11/2016	Updated IAR version and USB code structure version, Section 2.4.1 and Section 2.4.2
5	03/2017	Updated for MCUXpresso SDK
6	04/2017	Added note in Section 2.3
7	11/2017	MCUXpresso SDK 2.3.0 release
8	05/2018	• Updated Section 4.1.2.1., "Changing the usb_device_descriptor.c file" • Removed Section 2.3.4, "Step-by-step guide for Kinetis Design Studio (KDS) IDE", Updated for MCUXpresso SDK 2.4.0 release
9	12/2018	• Updated Chapter 5, "USB compliance tests" • Add a bullet for 'Chapter 6 for MCUXpresso SDK 2.5.0'
10	06/2019	• Updated Section 4.2, "Developing a new USB host application" for MCUXpresso SDK 2.6.0 • Added Chapter 7, "USB device ramdisk throughput" for MCUXpresso SDK 2.6.0
11	06/2020	Updated for MCUXpresso SDK v2.8.0
12	11/2020	Updated for MCUXpresso SDK v2.9.0

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