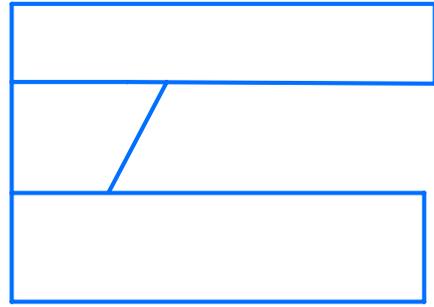
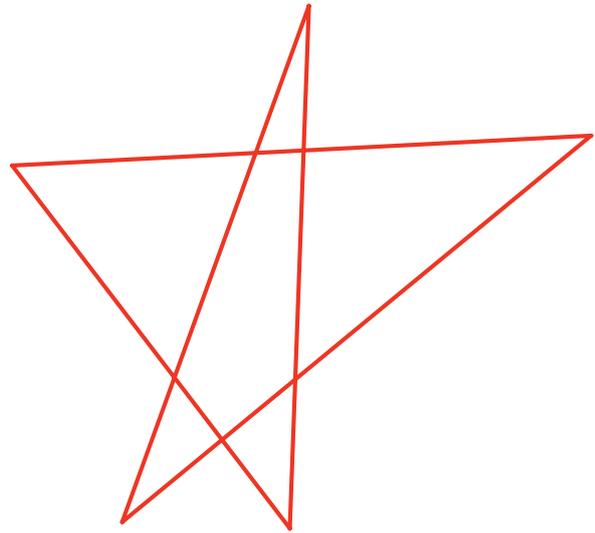


L3 - Map overlay

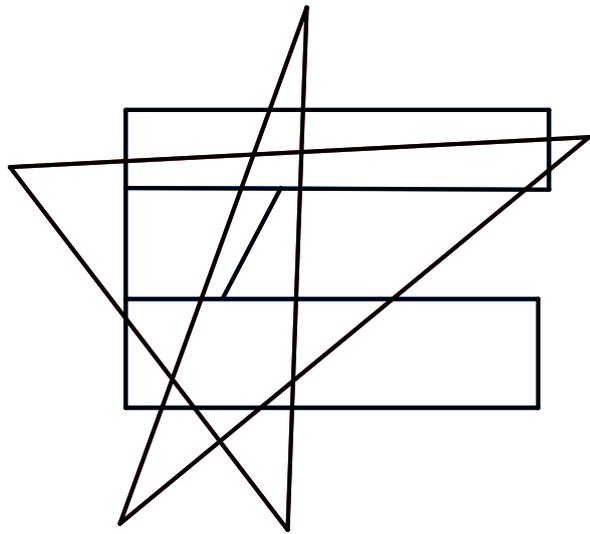
Given blue map



& red map

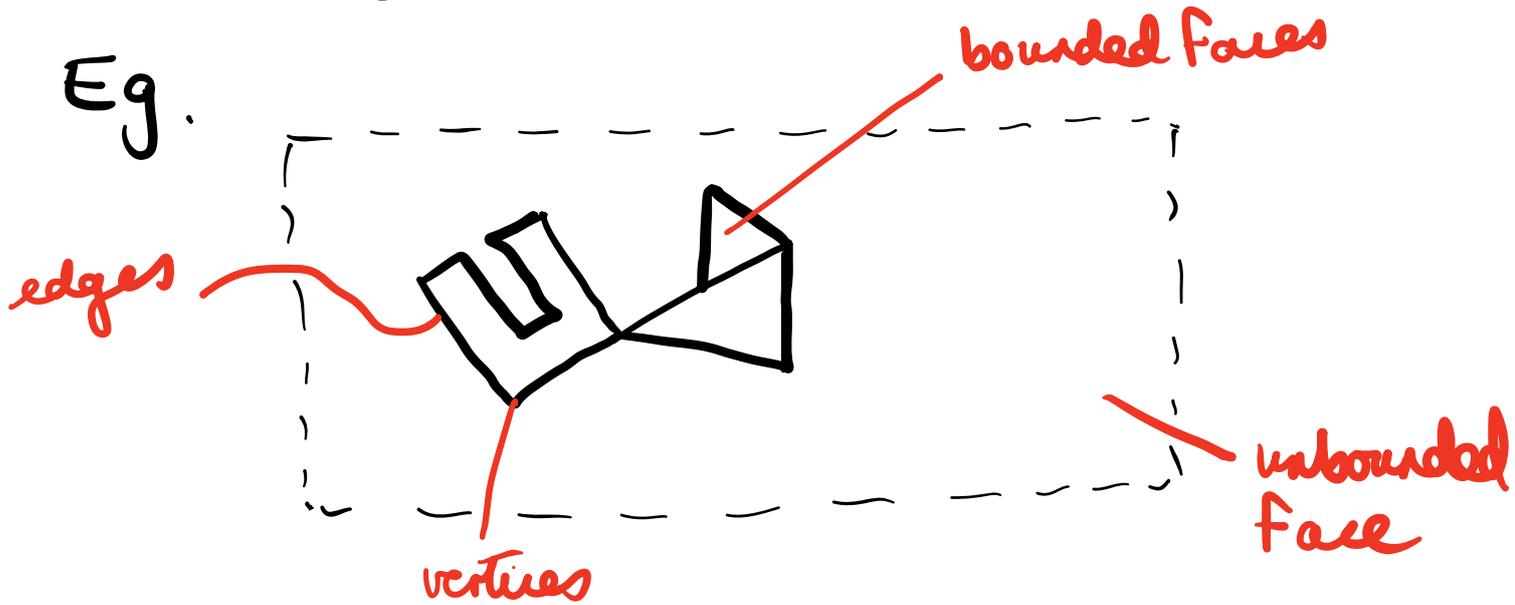


create overlay map



Maps

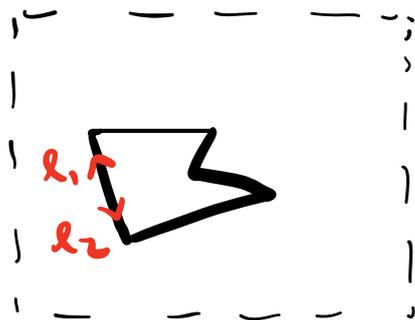
Maps are planar subdivisions - embedding of a graph into plane \mathbb{R}^2 .



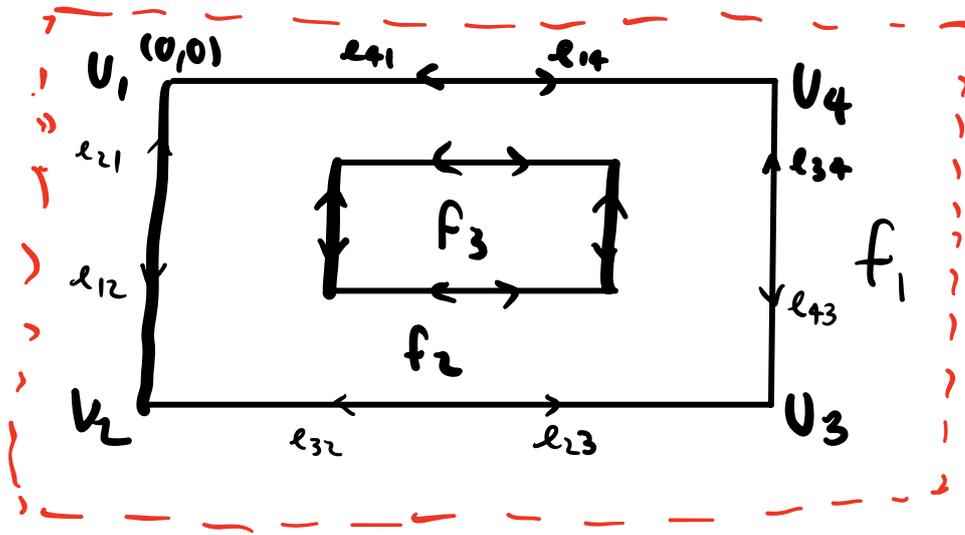
- Store planar subdivision in a DCEL: doubly connected edge list.

- In this approach, orientation of edges is important.

Eg.



DCELs



- 3 tables (vertices, edges, faces)

Table for vertices

Name of vertex	Co-ordinate	Edge originating @ vertex
v_1	(0,0)	l_{12}

DCELs

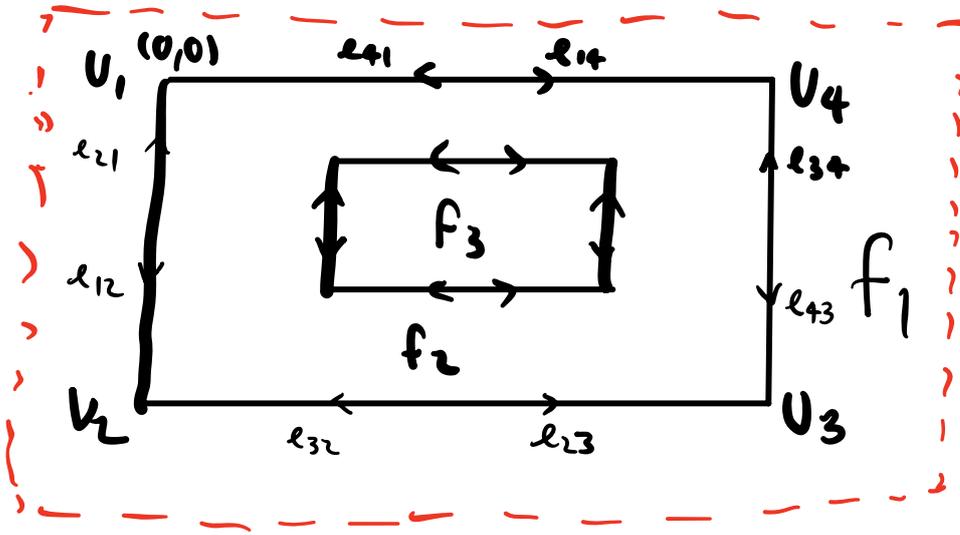
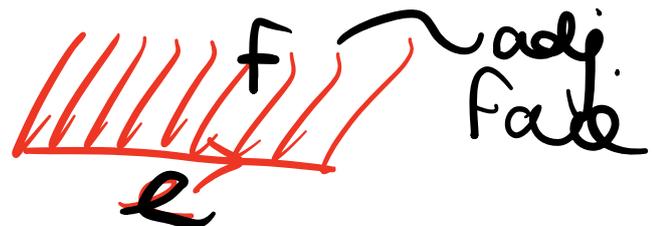


Table for edges

Name	Origin (vertex)	Twin	Next edge	Previous edge	Adjacent Face
e_{21}	U_2	e_{12}	e_{14}		f_1

• Adjacent face : face to left of oriented edge



DCELs

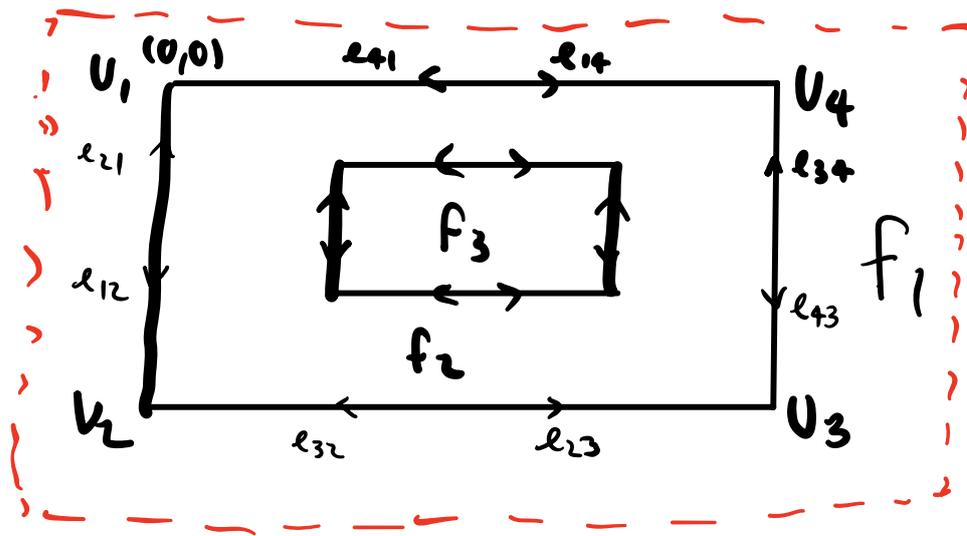


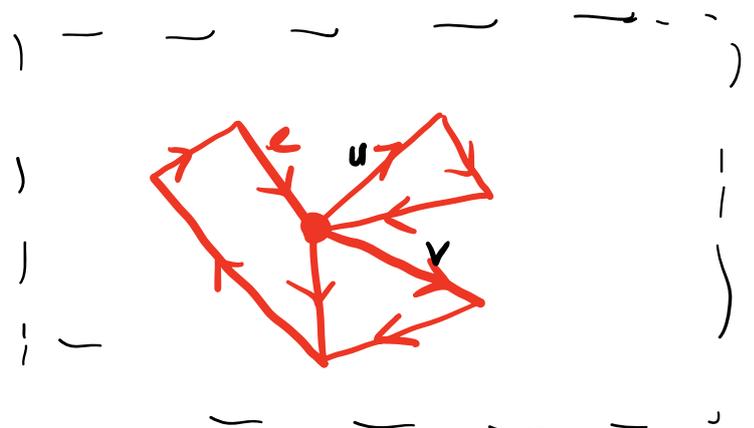
Table for edges

Name	Origin (vertex)	Twin	Next edge	Previous edge	Adjacent face
e_{21}	u_2	e_{12}	e_{14}		f_1

- Next edge $next(e)$: ① Origin = endpoint of e
② same adjacent face as e

There is no edge between e & $next(e)$ with these two properties.

Eq. in picture to right,
 u, v satisfy ①, ②
relative to e ,
but $u = next(e)$.



DCELS

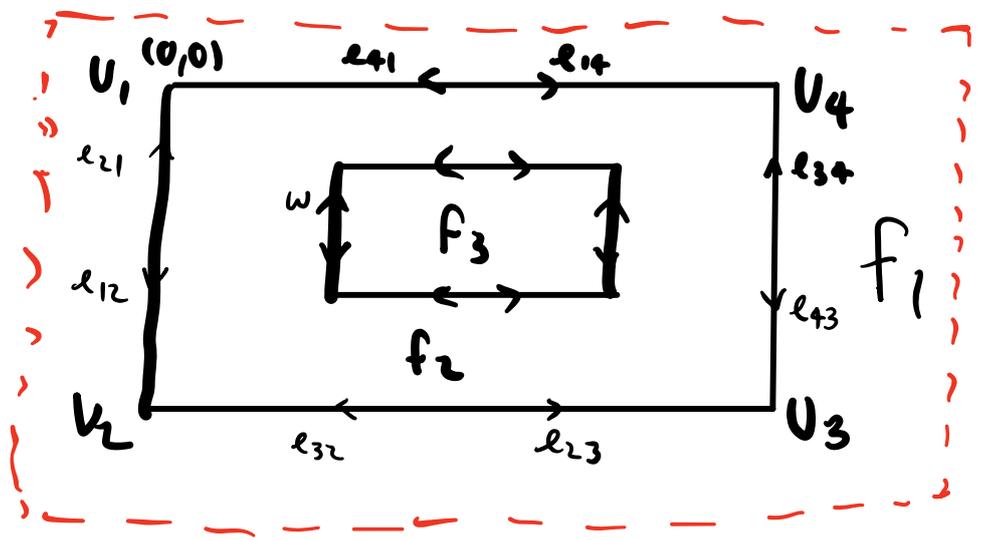


Table for faces

Name	1 edge on outer cycle	1 edge on each inner cycle
f_2	e_{12}	w
f_1	none	e_{21}

Cycle = sequence (e_1, \dots, e_n) of edges with $\text{next}(e_i) = e_{i+1}$ & $\text{next}(e_n) = e_1$, & no element repeated.

- Cycle of f if $f = \text{adj}(e_i)$ each e_i
- Outer cycle of f if e_i lies on outer boundary of f .
- Inner cycle of f otherwise.

Complexity of planar subdivision/DCEL is no. of vertices + no. of edges + no. of faces

Exercise : using DCEL,
calculate all edges with
vertex u in clockwise order .

Algorithm for map overlay

S_1 red map ----- D_1 DCEL

S_2 blue map ----- D_2 DCEL

$S = \text{Overlay}(S_1, S_2)$ - calculate DCEL D

For overlay S .

Algorithm has 3 steps:

① Put Tables for vertices & edges of D_1 & D_2 into single Table D (record colour of edges)

② At this point D is incorrect:
update using segment intersection algorithm,

③ Finally create table for faces.

For each face $f \in D$, find

blue face $f_1 \in D_1$ & red face $f_2 \in D_2$
in which f lies?

(Detailed version in Tanku's Thesis -
see E-learning)

Algorithm involves :

- event queue Q (balanced binary tree)
- balanced bin tree T of line segments (coloured)
- For each $p \in Q$, sets $L(p)$, $U(p)$ & $C(p)$ of coloured line segments on which p lies (like last week)

• Step ① of algorithm is straightforward

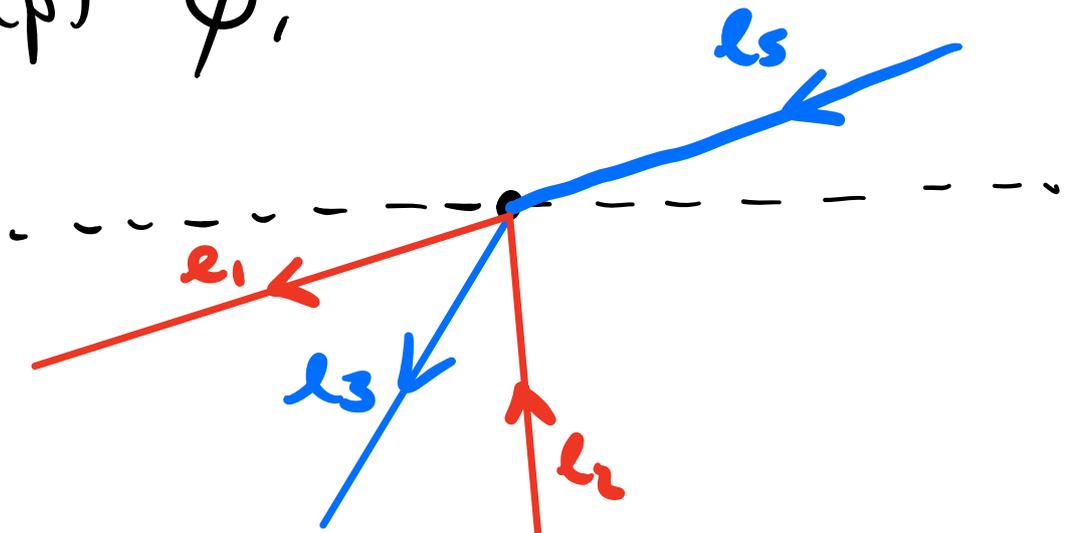
Here we describe steps ② & ③.

• For Step ②, we begin by adding all endpoints of segments to Q .

• Several cases to consider

@ event point $p \in Q$.

- At $p \in Q$, update Q&T as in segment intersection alg but keeping track of colours of segs.
- If $C(p) = \emptyset$,



do not add new edges or vertices,
only update next & previous.

Original table

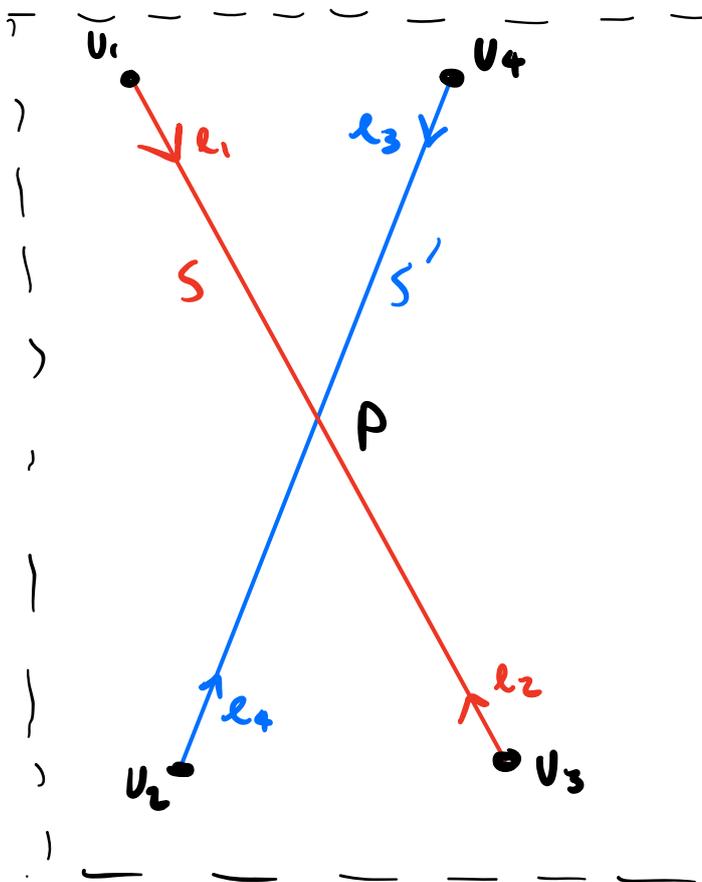
$$\text{next}(e_2) = e_1$$

New table

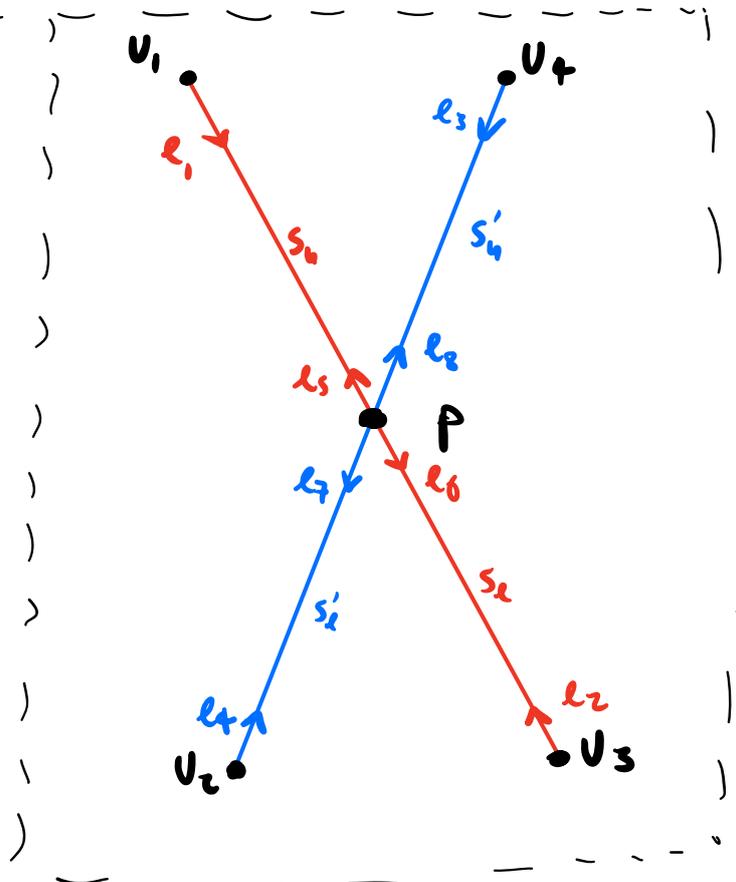
$$\text{next}(e_2) = e_3$$

- If $C(p) \neq \emptyset$,

Before



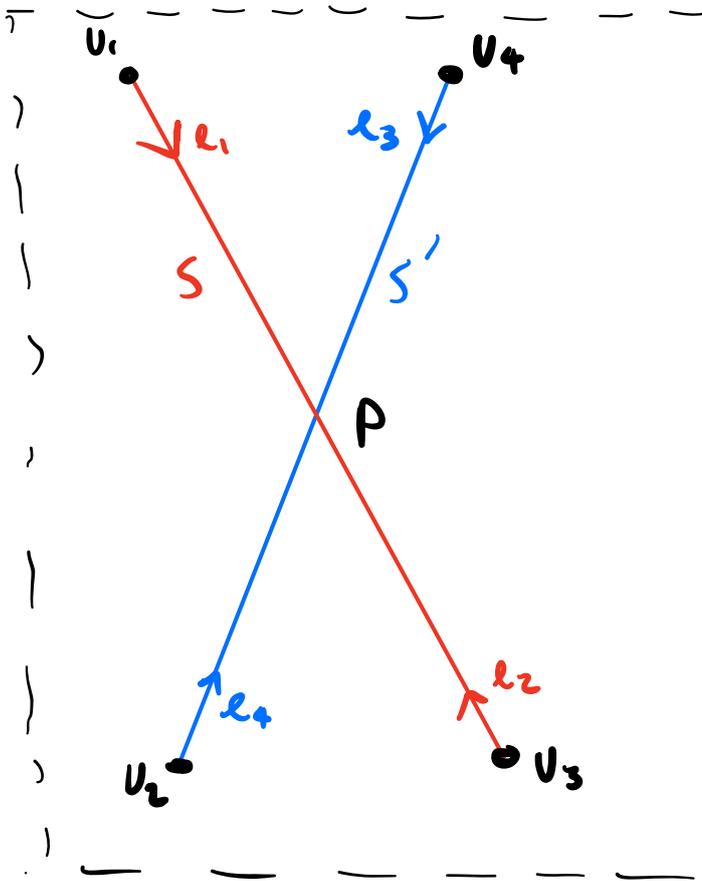
After



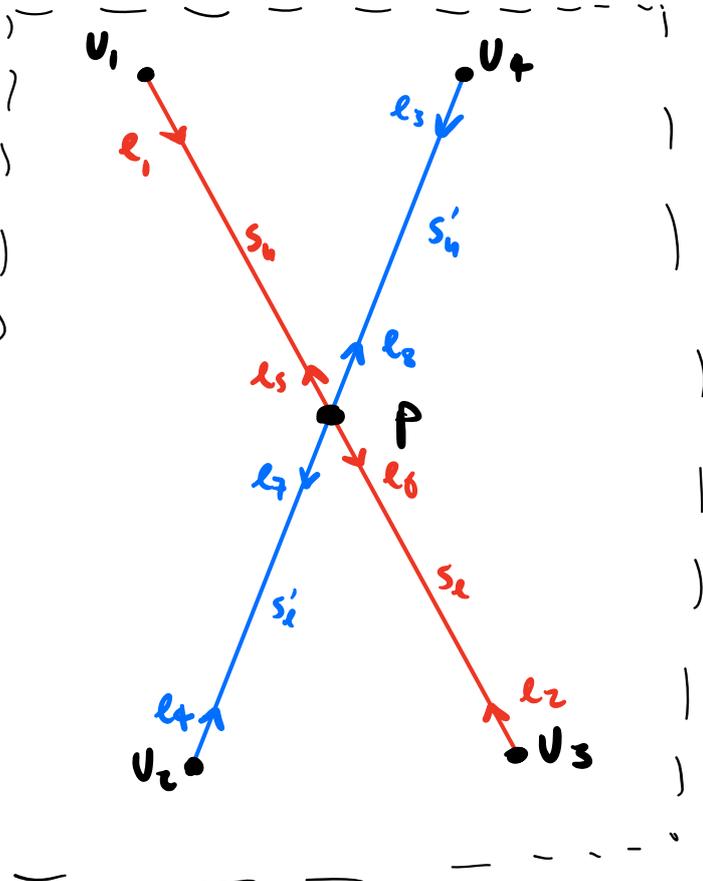
- split segments in $C(p)$ into 2 parts - upper & lower. Add lower parts to T .
- add new vertex p to D .
- Edges associated to these segments are split in 2 as in example above: add new rows for these edges & update origin, next, prev., adj. face (see \tilde{E} -Learning for more detail)

- If $C(p) \neq \emptyset$,

Before



After



Name of vertex	Co-ordinate	Edge originating @ vertex
P	intersection co-ord	l_5

Name	Origin (vertex)	Twin	Next edge	Previous edge	Adjacent Face
l_1	v_1	l_5	l_8	leave orig.	
l_5	P	l_1	same as for l_2	l_3	

- For Step ③, need to calculate Faces.

Idea

- Each bounded Face has unique outer cycle
Outer Face has no outer cycle
- So can define Faces of D to be
 $\text{OuterCycles}(D) \cup \{C_\infty\}$

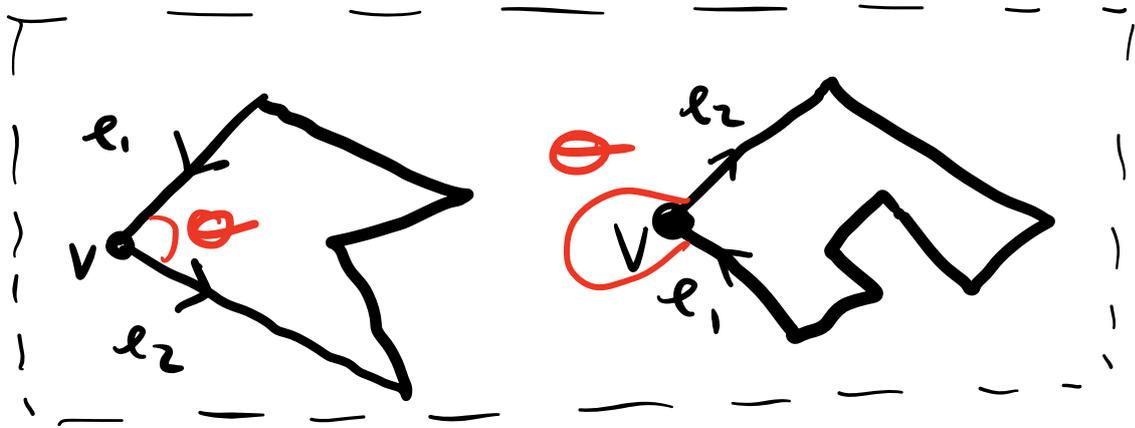
imaginary outer
cycle for unbounded
region.

- Now we can calculate all of
the cycles of D using the
vertices & next pointers, which are
already correct,

but which of these cycles are
outer & which are inner?

Outer or inner?

- At a cycle c , choose leftmost vertex v .



- Let e_1, e_2 be edges going into & out of v .
 - Now measure angle θ between e_1, e_2 measured over adjacent region
 - $\theta < 180^\circ \sim$ outer cycle
 - $\theta > 180^\circ \sim$ inner cycle
- $$\theta < 180^\circ \Leftrightarrow \det \begin{pmatrix} e_{1x} & e_{1y} \\ e_{2x} & e_{2y} \end{pmatrix} > 0$$

- Hence can determine outer cycles & Fill Faces in D
 (*outer cycles* \cup C_{∞})
 but need to complete tables

Name	Origin (vertex)	Twin	Next edge	Previous edge	Adjacent Face
✓	✓	✓	✓	✓	<i>Some outer cycle?</i>

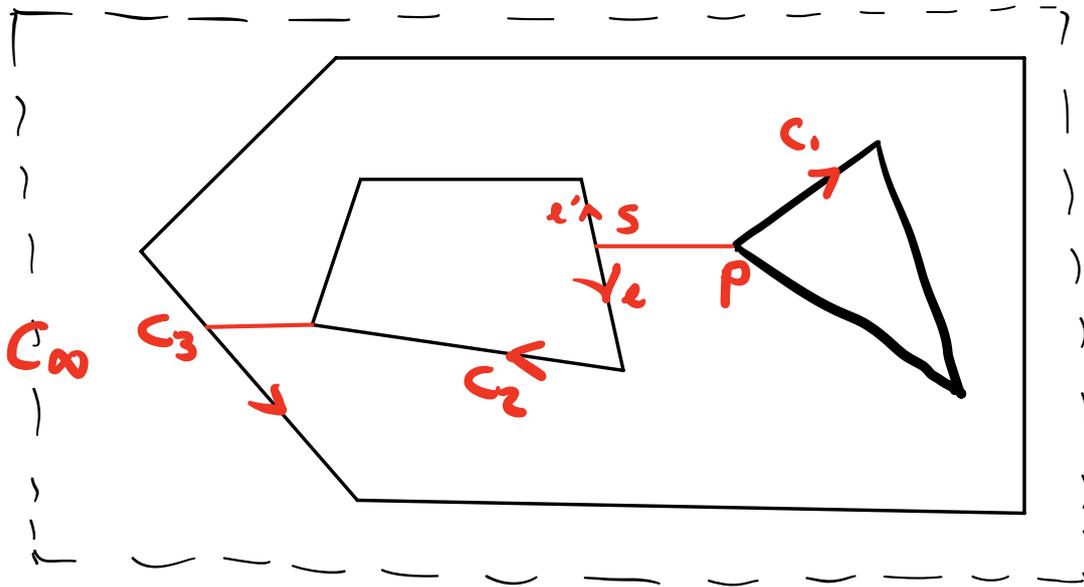
Table for faces

Faces	1 edge on outer cycle	1 edge on each inner cycle
(e_1, \dots, e_n)	?	?
C_{∞}	none	?

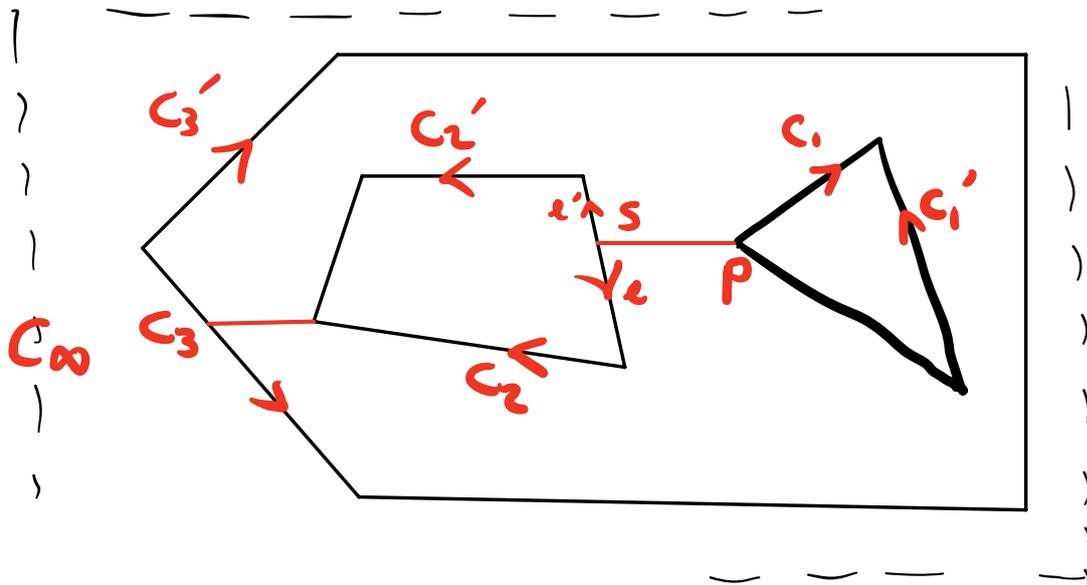
How to do it?

Make a graph G_f

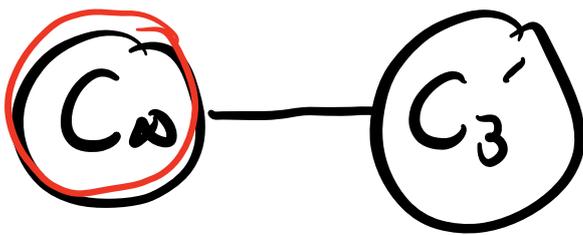
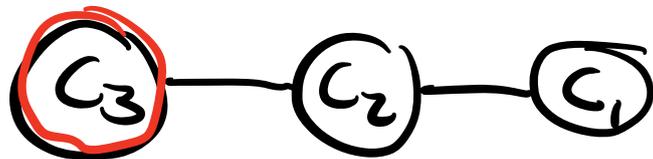
- Vertices = cycles
- Take inner cycle c_1 with leftmost vertex p .
- Find closest segment s to its left, if it exists.



- It determines 2 edges e, e' , one with p to its left, which we call c_2 .
- Draw edge $(c_2) \text{---} (c_1)$
- If c_2 outer, stop; else repeat.
- If no edge to left, connect to c_0 .



Red = outer



• Each connected comp has exactly one face \rightsquigarrow outer cycle & specifies all its inner & outer cycles.

Identification of faces

- For each face $f \in D$, find faces $f_1 \in D_1$, $f_2 \in D_2$ in which f lies

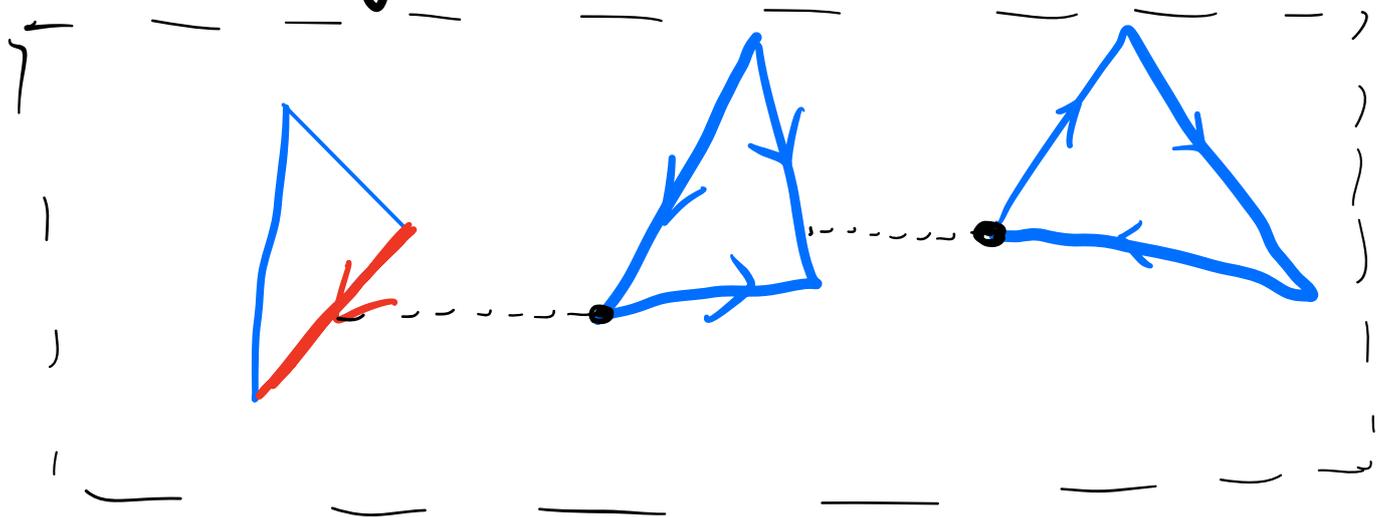
Two cases

- ① Cycle F contains blue & red edges - take their adjacent faces in D_1 & D_2 .

② - - - - - only blue \rightarrow
determines blue face in D_1 .

What about red face?

- If f is unbounded, take unbounded face in D_2 .
- Else f is bounded.



- Search to left, much as before, until we find cycle with red edge \rightarrow take adj face in D_2 .
- Else take unbounded face in D_2 .
- See E-learning for more detail.

Complexity

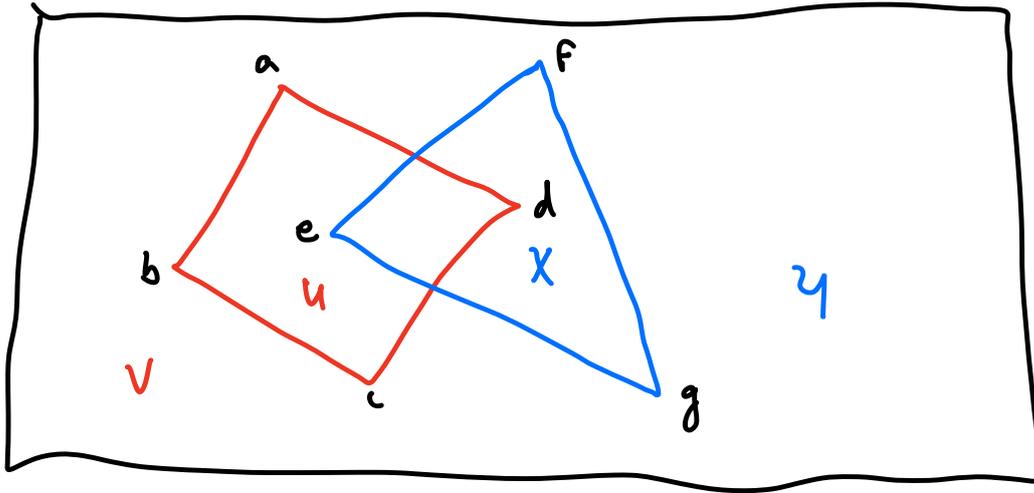
- S_1 complexity n_1
- S_2 — — — — n_2
- $n = n_1 + n_2$

The alg for building
DCEL for overlay has
complexity

$$O((n + k) \log n)$$

k
no of intersections
found

Exercise in class



Vertex	Co	Edge ov
a		ab
b		bc
c		cd
d		da
e		de
f		ef
g		fg

Edge	Or	T	Ne	Pv	AF
ab	a	ba	bc		u
ba	b	ab	ad		v
bc	b	cb	cd		u
cb	c	bc	ba		v
cd	c	dc	da		u
dc	d	cd	cb		v
da	d	ad	ab		u
ad	a	da	dc		v
ef	e	fe	fg		u
fe	f	ef	fd		x
fg	f	gf	fg		u
gf	g	fg	fd		x
fd	d	df	de		u
de	e	ed	eb		x
ed	d	de	eb		x
eb	b	be	ba		u
be	e	eb	ed		x

$$Q = (f, a, d, e, b, c, g)$$