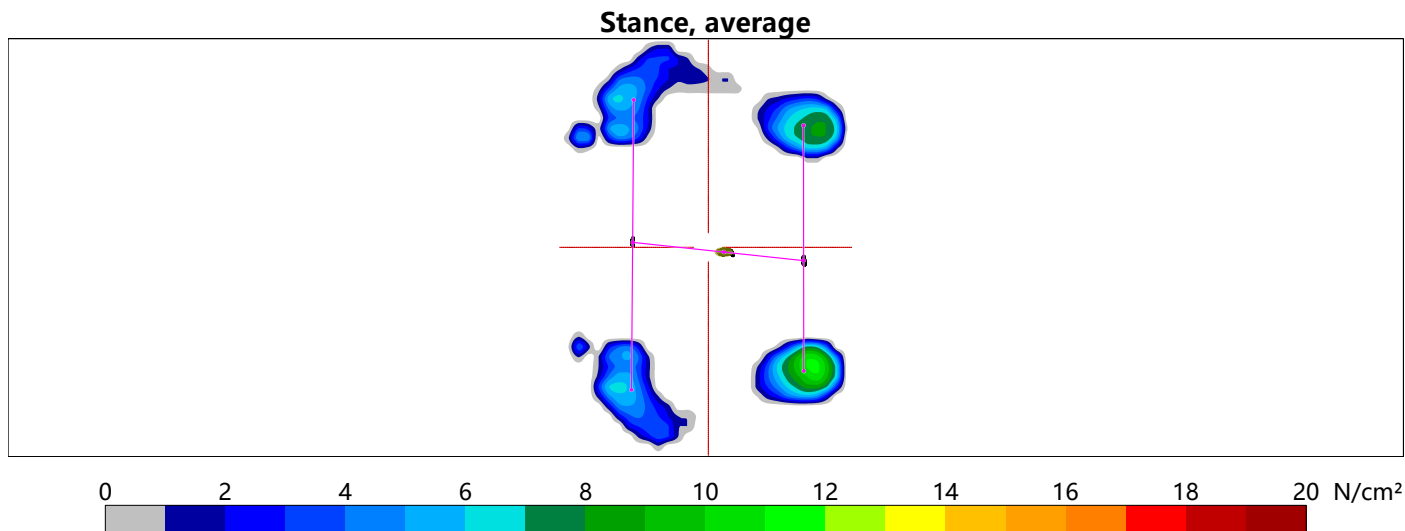


# zebris Stance Report

**Person:** Oliver Redli, 15.01.1996  
**Record:** 04.11.2019 11:19, Stance Analysis, oo

## Stance parameters



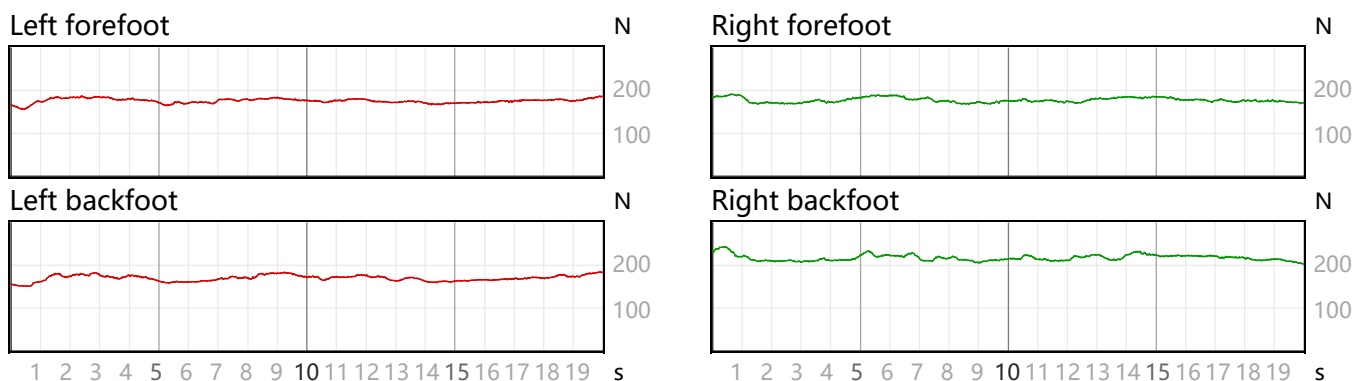
### Parameters

|                                  |      |          |
|----------------------------------|------|----------|
| Analysis time, sec               | 20,0 | 21 sec   |
| 95% confidence ellipse area, mm² | 47   | 50 mm²   |
| COP path length, mm              | 94   | 100 mm   |
| COP average velocity, mm/sec     | 5    | 5 mm/sec |

### Parameters advanced

|                                  |      |         |
|----------------------------------|------|---------|
| Length of minor axis, mm         | 4,9  | 13 mm   |
| Length of major axis, mm         | 12,3 | 13 mm   |
| Angle btw. Y and major axis, deg | 89,3 | 100 deg |
| Deviation X, mm                  | 9,2  | 13 mm   |
| Deviation Y, mm                  | -8,0 | 13 mm   |

### Force (N)



### Average Forces (%)

| Left     |    |                                 |      | Right                           |                                 |    |          |
|----------|----|---------------------------------|------|---------------------------------|---------------------------------|----|----------|
| Forefoot | 51 | <div style="width: 51%;"></div> | 100% | 100%                            | <div style="width: 45%;"></div> | 45 | Forefoot |
| Backfoot | 49 | <div style="width: 49%;"></div> |      | <div style="width: 55%;"></div> | 55                              |    | Backfoot |
| Total    | 47 | <div style="width: 47%;"></div> |      | <div style="width: 53%;"></div> | 53                              |    | Total    |