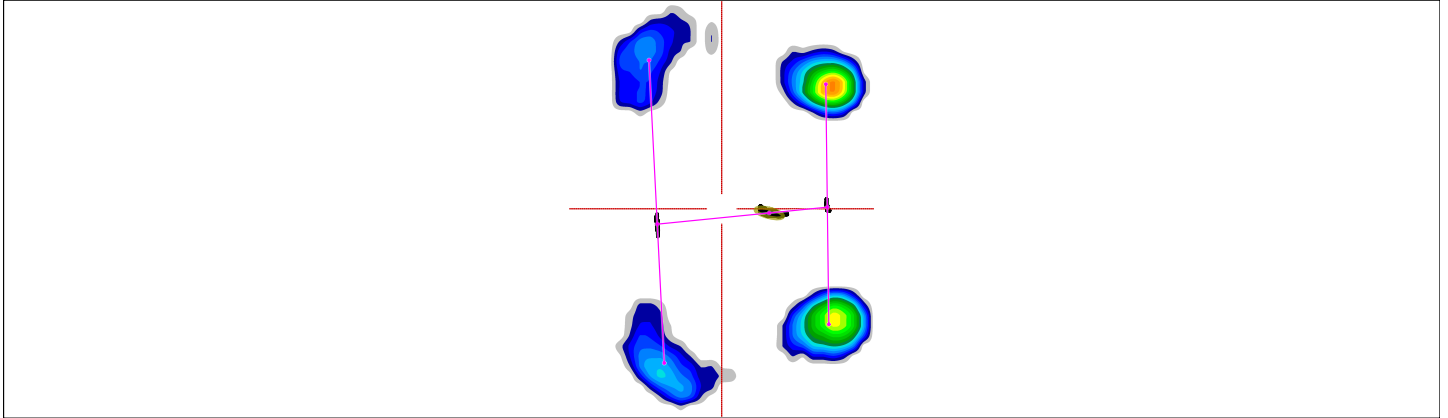


## Stance parameters

Stance, average



### Parameters

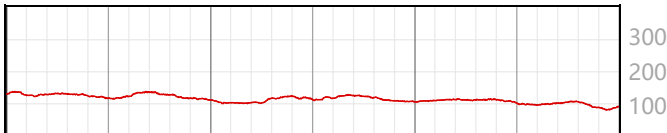
Analysis time, sec	30,0	<div style="width: 75%;"></div>	40 sec
95% confidence ellipse area, mm <sup>2</sup>	131	<div style="width: 33%;"></div>	140 mm <sup>2</sup>
COP path length, mm	113	<div style="width: 81%;"></div>	120 mm
COP average velocity, mm/sec	4	<div style="width: 3%;"></div>	4 mm/sec

### Parameters advanced

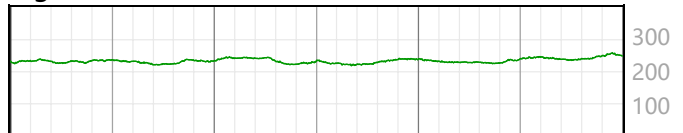
Length of minor axis, mm	7,1	<div style="width: 18%;"></div>	40 mm
Length of major axis, mm	23,6	<div style="width: 59%;"></div>	40 mm
Angle btw. Y and major axis, deg	75,9	<div style="width: 95%;"></div>	80 deg
Deviation X, mm	35,8	<div style="width: 89%;"></div>	40 mm
Deviation Y, mm	-7,4	<div style="width: 19%;"></div>	40 mm

### Force (N)

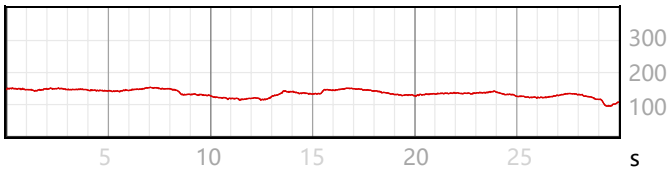
Left forefoot



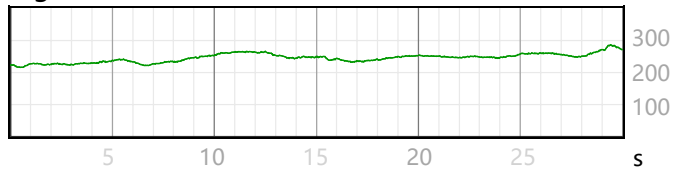
Right forefoot



Left backfoot



Right backfoot



### Average Forces (%)

#### Left

Forefoot	46	<div style="width: 46%;"></div>	100%
Backfoot	54	<div style="width: 54%;"></div>	
Total	34	<div style="width: 34%;"></div>	

#### Right

100%	<div style="width: 49%;"></div>	49	Forefoot
	<div style="width: 51%;"></div>	51	Backfoot
	<div style="width: 66%;"></div>	66	Total