# Matrix algebra

PSY544 – Introduction to Factor Analysis

Week 2



# Prologue

- Matrix algebra is a framework for manipulating collections of numbers or algebraic symbols.
- Factor model is an algebraic system. If you understand the way it is communicated, you gain a better appreciation of what is going on.
- We have already seen the common factor model representing the structure of score  $x_{ij}$  this model applies to every  $x_{ij}$  in the data matrix **X**. Matrix algebra will allow us to express that.

- **Scalar**: A single value, e.g., *k* = 3, *z* = 0.7
- Matrix: A rectangular table of *elements* (numbers, symbols...):

$$\mathbf{A} = \begin{bmatrix} & & \\ & & \end{bmatrix} \begin{bmatrix} & & \\ & & \end{bmatrix}$$

*a<sub>ii</sub>* = element in row *i* and column *j* of matrix *A* 

$$a_{11} = 1.0, a_{21} = 0.2$$

An uppercase letter (like A) names the matrix and stands for all the elements

• Data matrix: Each element is a score for an individual on a variable

$$p = 3$$
 manifest variables  
 $\mathbf{X} = \begin{bmatrix} N = 4 \text{ subjects} \end{bmatrix}$ 

•  $x_{ij}$  = score for the *i*-th individual on the *j*-th variable

- Order: The size of a matrix.
- A matrix with N rows and p columns is of order N x p
- Square matrix: A matrix with the same number of rows and columns
- Vector: A matrix with a single column (column vector) or a single row (row vector)

$$v = \begin{bmatrix} 1 \times m \text{ row vector} \\ m \times 1 \text{ column vector} & w = \begin{bmatrix} 1 \times m \text{ row vector} \\ 0 & 0 \end{bmatrix}$$

• **Transpose** of matrix **A** is a new matrix, **A'**, formed by writing the rows of **A** as the columns of **A'**:

If 
$$\mathbf{A} = \begin{bmatrix} \\ \end{bmatrix}$$
 then the transpose is  $\mathbf{A'} = \begin{bmatrix} \\ \end{bmatrix}$ 

- The transpose of a *P x M* matrix **A** is a *M x P* matrix **A'** (or **A**<sup>*T*</sup>)
- Equality of matrices: Two matrices are equal if and only if they are of the same order and all their corresponding elements are equal.

# Arithmetic operations

- Addition and subtraction: Only possible if matrices are of the same order (*conformable* for addition)
- Corresponding elements of **A** and **B** are summed to form **C**.

• **C** = **A** + **B**; 
$$c_{ij} = a_{ij} + b_{ij}$$
 for all *i* and *j*

Commutative law: **A** + **B** = **B** + **A** 

Associative law: (A + B) + C = A + (B + C)

The transpose of a sum is the sum of the transposes: (A + B)' = A' + B'

• Scalar multiplication:

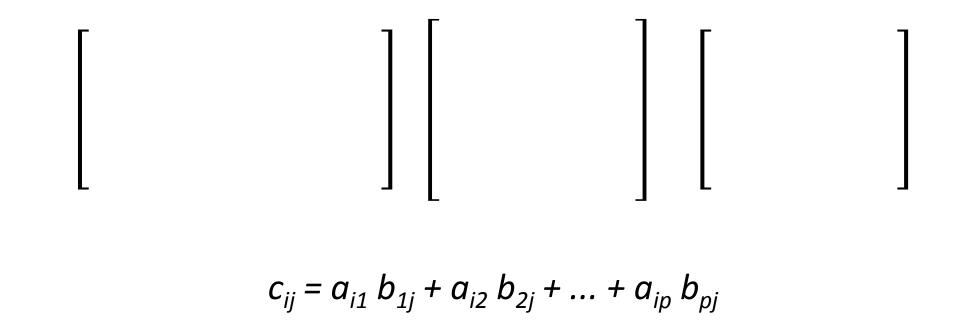
 $C = Ba = aB ; c_{ij} = a \cdot b_{ij}$   $2\begin{bmatrix} \\ \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix}$ 

- Matrix multiplication is not what you might think it is!
- Matrix multiplication: A and B have to be *conformable* for multiplication. Matrices are conformable if the number of columns in the first matrix equals the number of rows in the second.

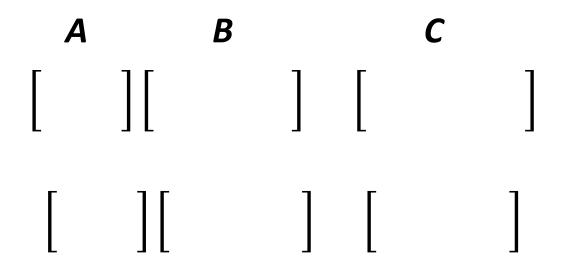
 $\begin{array}{ccc} A & B & = AB = & C \\ n x p & p x m & n x m \end{array}$ 

- The product matrix has as many rows as the first matrix and as many columns as the second matrix.
- In this case, **B** was being *pre-multiplied* by **A** (and **A** was being *post-multiplied* by **B**)

 Matrix multiplication: c<sub>ij</sub> equals the sum of products of elements in the *i*-th row of *A* and the *j*-th column of *B*.



For instance, if A is a 2x2 matrix and B is a 2x3 matrix, then AB = C is a 2x3 matrix:



• Note again that order matters here! **AB** = **C**, but **BA** is undefined.

- Matrix multiplication is associative: A(BC) = AB(C)
- Matrix multiplication is not commutative: **AB ≠ BA**
- Matrix multiplication is distributive: A(B+C) = AB + AC; (B+C)A = BA + CA
- The transpose of a product of matrices equals the product of the transposes in reverse order: (AB)' = B' A'

• Symmetric matrix: A square matrix S is symmetric if it's equal to its transpose

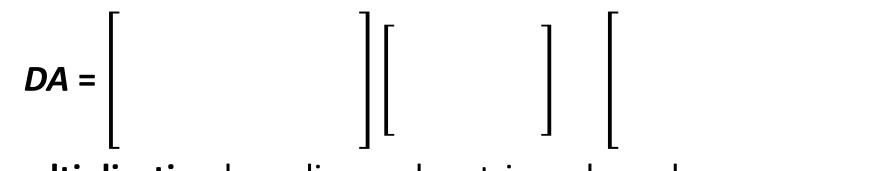
$$S = \begin{bmatrix} \\ \end{bmatrix} = S'$$

• **Triangular matrix**: A square matrix **S** is lower triangular if all the elements above the diagonal are zero. A square matrix **R** is upper triangular if all the elements below the diagonal are equal to zero.

• **Diagonal matrix**: A square matrix **D** is diagonal if all the off-diagonal elements are zero.

$$D = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

• **Pre-multiplication** by a diagonal matrix scales rows:



• **Post-multiplication** by a diagonal matrix scales columns:

$$BD = \begin{bmatrix} & & \\ & & \end{bmatrix} \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

• Identity matrix is a diagonal matrix with all diagonal elements = 1

• Multiplication of a matrix by an identity matrix does not change the matrix (it's like multiplying a scalar by 1)

- Orthogonal matrix: A square matrix T is orthogonal if TT' = I or T'T = I
- **Correlation matrix** is a square, symmetric matrix with unit diagonals and off-diagonal elements that satisfy  $-1 \le r_{ij} \le 1$ . Also, it has to be nonnegative definite (we will define that later)

- The **Determinant** of a square matrix **A** is a scalar function of the elements of **A**. It is denoted as |A| or det(**A**) and is a single number (scalar).
- The determinant has many functions which we will not cover here (neither will we cover the definition or computation)
- If a matrix has determinant equal to zero, the matrix is called *singular*. This is an indication that there is redundancy among the rows / columns of the matrix – if the determinant is zero, some columns (or rows) of the matrix can be expressed as linear combinations of other columns (rows). In other words, the columns (rows) are linearly dependent.

• A singular matrix:

(The last column is the sum of the first two columns)

- **Trace:** The trace of a square matrix **A**, tr(**A**), is the sum of its diagonal elements.
- **Rank:** The column rank of **A** is equal to the total number of linearly independent columns of **A**. The row rank of **A** is equal to the total number of linearly independent rows of **A**.

The rank of an N x K matrix is at most the minimum of N or K, min(N,K)

- A matrix whose rank is equal to min(N,K) is *full rank*
- A matrix whose rank is less than min(N,K) is rank deficient

• Inverse: If **A** is a square matrix and is not singular (i.e., its determinant is non-zero), then it has a unique inverse **A**<sup>-1</sup> such that:

 $AA^{-1} = A^{-1}A = I$ 

- The inverse of a matrix plays a role similar to that of a reciprocal in scalar algebra:  $x^* = 1$
- Post-multiplying **A** by the inverse of **B** is analogous to "dividing" **A** by **B** (assuming the matrices are conformable for multiplication)

• **Solving** equations:

Consider the equation Ax = b, where A is a N x N non-singular matrix, b is a N x 1 vector and x is a N x 1 vector. We know the elements of A and b and wish to solve for x:

$$Ax = b$$
$$A^{-1}Ax = A^{-1}b$$
$$Ix = A^{-1}b$$
$$x = A^{-1}b$$

• **Solving** equations:

4x + 5y = 43x + 1y = 3

- Eigenvalues and Eigenvectors
- Suppose that S is a square symmetric matrix of order p. If u is a column vector of order p and v is a scalar, such that:

#### *Su = vu*

...then v is said to be an *eigenvalue* (or characteristic root) of **S** and **u** is said to be an *eigenvector* (or characteristic vector) of **S**.

• **S** will have *p* eigenvalues and *p* associated eigenvectors.

- Eigenvalues and Eigenvectors
- If all *p* eigenvalues are positive, the matrix is *positive definite*. If one or more eigenvalues are zero and the rest is positive, the matrix is *nonnegative definite*. If one or more eigenvalues are negative, the matrix is *negative definite*.
- The determinant of *S*, det(*S*), equals the product of the eigenvalues of *S* Thus, if one or more eigenvalues are zero, the matrix is singular.

- Eigenvalues and Eigenvectors
- The eigenvalues can be arranged in descending order as the diagonal elements in a diagonal matrix **D**, and the corresponding eigenvectors can be arranged as columns of matrix **U**. Then:

*U* is orthogonal, that is, *U'U = I* The "eigenstructure" of *S* can be given in this form: *SU = UD* It also holds that *S = UDU* 

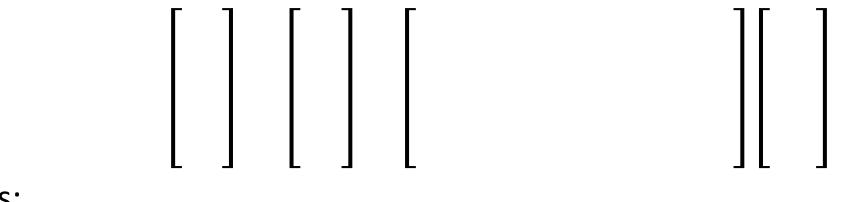
# Linear combinations of random variables

- Matrix equations are handy for representing linear combinations of random variables
- Let **x** be a column vector of order *p* containing scores for a random individual on variables *x*<sub>1</sub>, *x*<sub>2</sub>, ..., *x*<sub>p</sub>
- Let **z** be a column vector of order *m* containing scores for a random individual on variables  $z_1, z_2, ..., z_m$
- We will represent the variables in *x* as linear functions of the variables in *z*.
  Let *A* be a matrix of order *p* x *m* containing coefficients *a<sub>jk</sub>* representing the linear effects of *z<sub>k</sub>* on *x<sub>j</sub>*
- Let  $\mu$  be a column vector of order p containing fixed constants  $\mu_1, \mu_2, ..., \mu_p$

# Linear combinations of random variables

Then, we can represent the variables in *x* as linear functions of the variables in *z* and the constants in *μ* using the following matrix equation:

 $x = \mu + Az$ 



...thus:

• The matrix equation actually contains the whole set of linear equations

#### An intermezzo – expected values

• Wiki: "The *expected value* of random variable is the long-run average value of repetitions of the experiment it represents"

...so, the *expected value* is the variable's **mean**.

• 
$$E[X] = \mu$$

#### An intermezzo – expected values

• Now, consider the (scalar) formula for the **variance** of a random variable:

...which is the "mean squared deviation from the mean", right?

• As an expected value:  $E[(X - \mu)^2]$ 

#### An intermezzo – expected values

• Now consider the (scalar) formula for **covariance** 

...which is the "mean cross-product of deviations from the mean" (sorta)

• As an expected value:  $E[(X - \mu_x)(Y - \mu_y)]$ 

- Now suppose that x is a vector of order p containing scores on p variables for a random individual selected from some population, and µ is a vector of order p containing the population means of these p variables.
- Then, vector  $(x \mu)$  stands for the vector x with the population means subtracted (it represents deviations from the mean)
- Let's multiply this vector by its transpose:

 $(\boldsymbol{x}-\boldsymbol{\mu}) \ (\boldsymbol{x}-\boldsymbol{\mu})'$ 

• Let's multiply this vector by its transpose:

 $(\boldsymbol{x}-\boldsymbol{\mu}) \ (\boldsymbol{x}-\boldsymbol{\mu})'$ 

• ...and take the expectation:

$$\mathsf{E}[(\boldsymbol{x}-\boldsymbol{\mu}) \ (\boldsymbol{x}-\boldsymbol{\mu})']$$

 $\mathsf{E}[(\boldsymbol{x}-\boldsymbol{\mu}) \ (\boldsymbol{x}-\boldsymbol{\mu})']$ 

• Expanding, we get the expectation of:

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• ...which gives us the variance/covariance matrix of the manifest variables

$$\mathsf{E}[(\boldsymbol{x}-\boldsymbol{\mu}) \ (\boldsymbol{x}-\boldsymbol{\mu})']$$

• The variance-covariance matrix is a *p* x *p* symmetric matrix with variances on the diagonal and covariances off the diagonal