Matrix algebra

PSY544 – Introduction to Factor Analysis

Week 2

Prologue

- Matrix algebra is a framework for manipulating collections of numbers or algebraic symbols.
- Factor model is an algebraic system. If you understand the way it is communicated, you gain a better appreciation of what is going on.
- We have already seen the common factor model representing the structure of score x_{ij} – this model applies to every x_{ij} in the data matrix *X*. Matrix algebra will allow us to express that.

- **Scalar**: A single value, e.g., *k = 3, z = 0.7*
- **Matrix:** A rectangular table of *elements* (numbers, symbols…):

$$
A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}
$$

 a_{ii} = element in row *i* and column *j* of matrix **A**

$$
a_{11} = 1.0, a_{21} = 0.2
$$

An uppercase letter (like *A*) names the matrix and stands for all the elements

• **Data matrix:** Each element is a score for an individual on a variable

$$
p = 3
$$
 manifest variables

$$
\mathbf{X} = \begin{bmatrix} & & \\ & & \\ & & \\ & & \end{bmatrix}
$$
 N = 4 subjects

• x_{ij} = score for the *i*-th individual on the *j*-th variable

- **Order**: The size of a matrix.
- A matrix with *N* rows and *p* columns is of order *N x p*
- **Square matrix**: A matrix with the same number of rows and columns
- **Vector**: A matrix with a single column (column vector) or a single row (row vector) $\mathbf \mathbf T$

$$
V = \begin{bmatrix} 1 & x & x & y \\ 0 & 1 & y & z \\ 0 & 0 & 1 & z \\ 0 & 0 & 1 & z \end{bmatrix}
$$

• **Transpose** of matrix *A* is a new matrix, *A'*, formed by writing the rows of *A* as the columns of *A'*:

If
$$
A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}
$$
 then the transpose is $A' = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

- The transpose of a *P x M* matrix *A* is a *M x P* matrix *A'* (or *A^T*)
- **Equality of matrices:** Two matrices are equal if and only if they are of the same order and all their corresponding elements are equal.

Arithmetic operations

- **Addition and subtraction:** Only possible if matrices are of the same order (*conformable* for addition)
- Corresponding elements of *A* and *B* are summed to form *C*.

•
$$
C = A + B
$$
;
$$
c_{ij} = a_{ij} + b_{ij}
$$
 for all i and j

$$
\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}
$$

Commutative law: *A + B = B + A*

Associative law: *(A + B) + C = A + (B + C)*

The transpose of a sum is the sum of the transposes: $(A + B)' = A' + B'$

• **Scalar multiplication**:

C = *Ba* = *aB* ; c_{ij} = *a∙b*_{*ij*} $2 \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

- **Matrix multiplication** is **not** what you might think it is!
- **Matrix multiplication**: *A* and *B* have to be *conformable* for multiplication. Matrices are conformable if the number of columns in the first matrix equals the number of rows in the second.

A B = AB = C n x p p x m n x m

- The product matrix has as many rows as the first matrix and as many columns as the second matrix.
- In this case, *B* was being *pre-multiplied* by *A* (and *A* was being *postmultiplied by B*)

• **Matrix multiplication**: *cij* equals the sum of products of elements in the *i-*th row of *A* and the *j-*th column of *B*.

• For instance, if *A* is a 2x2 matrix and *B* is a 2x3 matrix, then *AB = C* is a 2x3 matrix:

• Note again that order matters here! *AB = C*, but *BA* is undefined.

- Matrix multiplication is associative: *A*(*BC*) = *AB*(*C*)
- Matrix multiplication is not commutative: *AB ≠ BA*
- Matrix multiplication is distributive: *A*(*B+C*) = *AB + AC*; (*B+C*)*A = BA + CA*
- The transpose of a product of matrices equals the product of the transposes in reverse order: (*AB*)' = *B' A'*

• **Symmetric matrix**: A square matrix *S* is symmetric if it's equal to its transpose

$$
S = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = S'
$$

• **Triangular matrix**: A square matrix *S* is lower triangular if all the elements above the diagonal are zero. A square matrix *R* is upper triangular if all the elements below the diagonal are equal to zero.

$$
S = \begin{bmatrix} & & \\ & & \end{bmatrix}
$$

• **Diagonal matrix**: A square matrix *D* is diagonal if all the off-diagonal elements are zero.

D **=**

• **Pre-multiplication** by a diagonal matrix scales rows:

• **Post-multiplication** by a diagonal matrix scales columns:

$$
BD = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}
$$

• **Identity matrix** is a diagonal matrix with all diagonal elements = 1

$$
I = \begin{bmatrix} & & \\ & & \end{bmatrix}
$$

• Multiplication of a matrix by an identity matrix does not change the matrix (it's like multiplying a scalar by 1)

- **Orthogonal matrix**: A square matrix *T* is orthogonal if *TT' = I* or *T'T = I*
- **Correlation matrix** is a square, symmetric matrix with unit diagonals and off-diagonal elements that satisfy $-1 \le r_{ii} \le 1$. Also, it has to be nonnegative definite (we will define that later)

- The **Determinant** of a square matrix *A* is a scalar function of the elements of *A*. It is denoted as |*A*| or det(*A*) and is a single number (scalar).
- The determinant has many functions which we will not cover here (neither will we cover the definition or computation)
- If a matrix has determinant equal to zero, the matrix is called *singular*. This is an indication that there is redundancy among the rows / columns of the matrix – if the determinant is zero, some columns (or rows) of the matrix can be expressed as linear combinations of other columns (rows). In other words, the columns (rows) are linearly dependent.

• A singular matrix:

$$
A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}
$$

(The last column is the sum of the first two columns)

- **Trace:** The trace of a square matrix *A*, tr(*A*), is the sum of its diagonal elements.
- **Rank:** The column rank of *A* is equal to the total number of linearly independent columns of *A*. The row rank of *A* is equal to the total number of linearly independent rows of *A*.

The rank of an N x K matrix is at most the minimum of N or K, min(N,K)

- A matrix whose rank is equal to min(N,K) is *full rank*
- A matrix whose rank is less than min(N,K) is *rank deficient*

• **Inverse:** If *A* is a square matrix and is not singular (i.e., its determinant is non-zero), then it has a unique inverse *A-1* such that:

AA-1 = A-1A = I

- The inverse of a matrix plays a role similar to that of a reciprocal in scalar algebra: *x * =* 1
- Post-multiplying A by the inverse of B is analogous to "dividing" A by B (assuming the matrices are conformable for multiplication)

• **Solving** equations:

Consider the equation *Ax = b*, where *A* is a N x N non-singular matrix, *b* is a N x 1 vector and *x* is a N x 1 vector. We know the elements of *A* and *b* and wish to solve for *x*:

$$
Ax = b
$$

$$
A^{-1}Ax = A^{-1}b
$$

$$
Ix = A^{-1}b
$$

$$
x = A^{-1}b
$$

• **Solving** equations:

4x + 5y = 4 3x + 1y = 3

• In matrix form: solving:

- **Eigenvalues** and **Eigenvectors**
- Suppose that *S* is a square symmetric matrix of order *p*. If *u* is a column vector of order *p* and *v* is a scalar, such that:

Su = vu

...then *v* is said to be an *eigenvalue* (or characteristic root) of *S* and *u* is said to be an *eigenvector* (or characteristic vector) of *S*.

• *S* will have *p* eigenvalues and *p* associated eigenvectors.

- **Eigenvalues** and **Eigenvectors**
- If all *p* eigenvalues are positive, the matrix is *positive definite*. If one or more eigenvalues are zero and the rest is positive, the matrix is *nonnegative definite*. If one or more eigenvalues are negative, the matrix is *negative definite*.
- The determinant of *S*, det(*S*), equals the product of the eigenvalues of *S* Thus, if one or more eigenvalues are zero, the matrix is singular.

- **Eigenvalues** and **Eigenvectors**
- The eigenvalues can be arranged in descending order as the diagonal elements in a diagonal matrix *D*, and the corresponding eigenvectors can be arranged as columns of matrix *U*. Then:

U is orthogonal, that is, *U'U = I* The "eigenstructure" of *S* can be given in this form: *SU = UD* It also holds that *S = UDU'*

Linear combinations of random variables

- Matrix equations are handy for representing linear combinations of random variables
- Let *x* be a column vector of order *p* containing scores for a random individual on variables x_1 , x_2 , ..., x_p
- Let *z* be a column vector of order *m* containing scores for a random individual on variables z_1 , z_2 , ..., z_m
- We will represent the variables in *x* as linear functions of the variables in *z.* Let A be a matrix of order $p \times m$ containing coefficients a_{ik} representing the linear effects of z_k on x_j
- Let *μ* be a column vector of order *p* containing fixed constants $μ_1$, $μ_2$, ..., $μ_p$

Linear combinations of random variables

• Then, we can represent the variables in *x* as linear functions of the variables in *z* and the constants in *μ* using the following matrix equation:

 $x = \mu + Az$

…thus:

• The matrix equation actually contains the whole set of linear equations

An intermezzo – expected values

• Wiki: "The *expected value* of random variable is the long-run average value of repetitions of the experiment it represents"

...so, the *expected value* is the variable's **mean**.

•
$$
E[X] = \mu
$$

An intermezzo – expected values

• Now, consider the (scalar) formula for the **variance** of a random variable:

…which is the "mean squared deviation from the mean", right?

• As an expected value: $E[(X - \mu)^2]$

An intermezzo – expected values

• Now consider the (scalar) formula for **covariance**

…which is the "mean cross-product of deviations from the mean" (sorta)

• As an expected value: $E[(X - \mu_X)(Y - \mu_Y)]$

- Now suppose that *x* is a vector of order *p* containing scores on *p* variables for a random individual selected from some population, and *μ* is a vector of order *p* containing the population means of these *p* variables.
- Then, vector (*x – μ*) stands for the vector *x* with the population means subtracted (it represents deviations from the mean)
- Let's multiply this vector by its transpose:

 $(x - \mu)(x - \mu)'$

• Let's multiply this vector by its transpose:

 $(x - \mu)(x - \mu)'$

• …and take the expectation:

$$
E[(x-\mu)(x-\mu)']
$$

 $E[(x - \mu)(x - \mu)']$

• Expanding, we get the expectation of:

• ... which gives us the variance/covariance matrix of the manifest variables

$$
E[(x-\mu)(x-\mu)']
$$

• The variance-covariance matrix is a *p* x *p* symmetric matrix with variances on the diagonal and covariances off the diagonal