

Related topics

Longitudinal waves, velocity of sound in liquids, wavelength, frequency, piezoelectric effect, piezoelectric ultrasonics transformer.

Principle and task

The sound waves transmitted to a liquid by the ultrasonic generator are picked up by a piezoelectric ultrasonic pick-up and the signal from transmitter and receiver compared on an oscilloscope.

The wavelength is determined and the phase velocity calculated from the relative phase position of the signals. The group velocity is determined from measurements of the sound pulse delay time.

Equipment

Ultrasonic pickup	11744.00	1
Ultrasonic generator	11744.93	1
Glass cell, 150×55×100 mm	03504.00	1
Insulating support	07924.00	1
Optical profile bench l = 60 cm	08283.00	1
Base f. opt. profile-bench, adjust.	08284.00	2
Slide mount f. opt. pr.-bench, h 30 mm	08286.01	2
Slide mount f. opt. pr.-bench, h 80 mm	08286.02	1
Table top on rod	08060.00	1
Swinging arm	08256.00	1

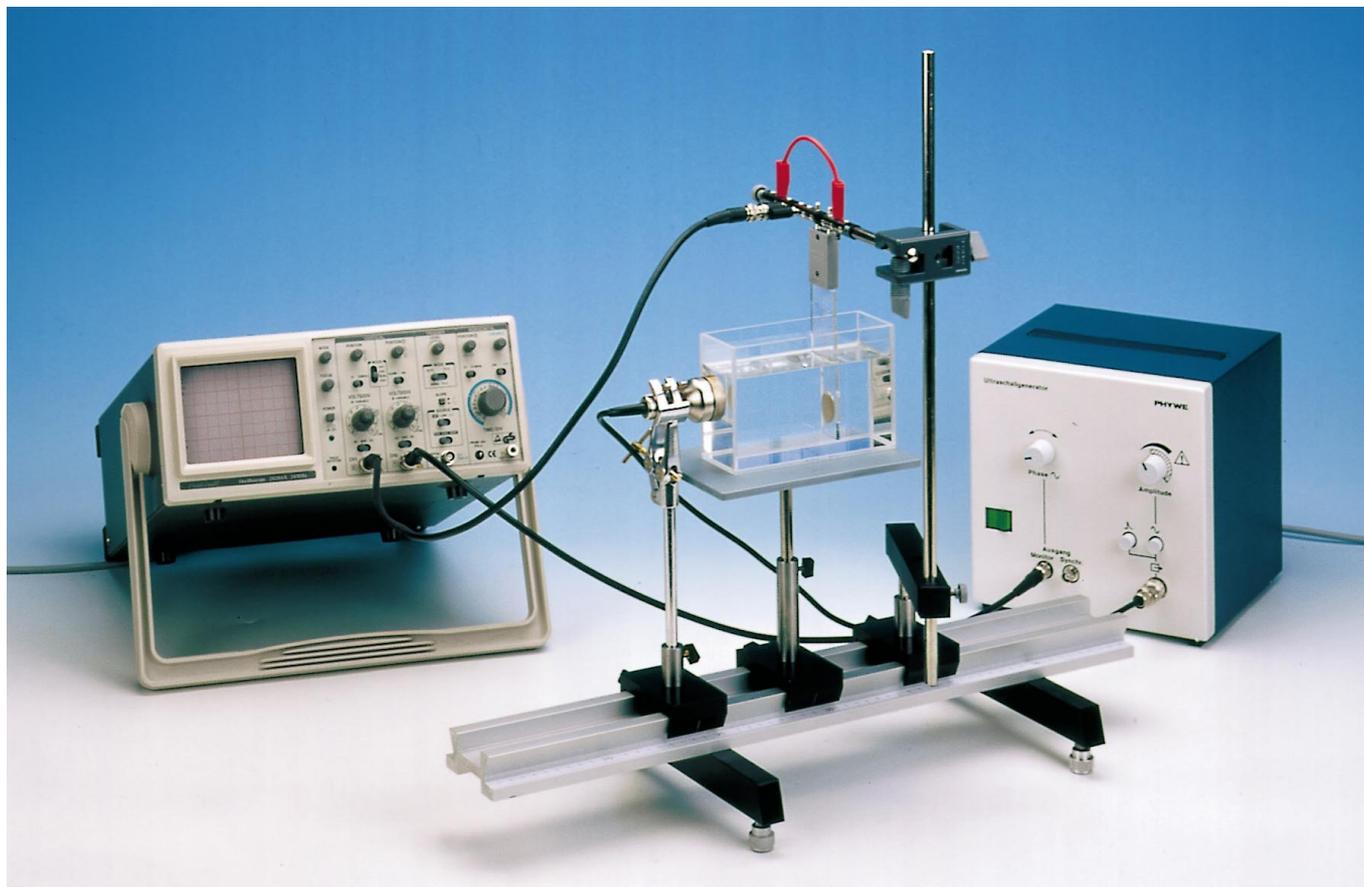
Right angle clamp -PASS-	02040.55	1
Support rod, stainl.steel, 500 mm	02032.00	1
Universal clamp	37715.00	1
Oscilloscope, 20 MHz, 2 channels	11454.93	1
Connecting cord, 100 mm, red	07359.01	1
Screened cable, BNC, l 750 mm	07542.11	2
Adapter, BNC-socket/4 mm plug pair	07542.27	1
Thermometer -10...+30 C	05949.00	1
Glycerol 250 ml	30084.25	3
Sodium chloride 500 g	30155.50	1
Water, distilled 5 l	31246.81	1

Problems

The signals from the ultrasonic generator and the ultrasonic pick-up are recorded on the oscilloscope.

1. To measure the relative phase position of the signal from the ultrasonic pick-up as a function of its distance from the ultrasonic generator (which is in the sine mode), and to determine the ultrasonic wavelength and the phase velocity when the frequency is known.
 - 2.1. To determine the oscilloscope's coefficient of sweep with the aid of the ultrasonic frequency.
 - 2.2. With the generator in the pulsed mode, to record the delay time of the sound pulses as a function of the distance between a generator and the pick-up, and to determine the group velocity.

Fig. 1: Experimental set-up for investigating the velocity of propagation of ultrasonics in liquids.



Set-up and procedure

The experiment is set up as shown in Fig. 1. The sound-radiating surface of the generator is wetted with glycerol or water in order to improve the connecting and rests against the wall of the glass cell.

In order to avoid stationary waves and multiple echoes through sound reflection, the cell wall opposite the generator is covered with sound-absorbing material such as foam or crumpled paper.

1. The oscilloscope is triggered internally via channel 2 by the monitor signal from the ultrasonic generator. The pick-up and monitor signals are set in phase on the screen by moving the pick-up and the phase setting on the generator. The pick-up is moved from this setting and the wavelength determined from the distance Δl by which it was moved and the number n of passages in the same phase that were covered thereby.
- 2.1. The time base is calibrated with the known generator frequency when the oscilloscope time base best suited to the delay time has been estimated.
- 2.2. The oscilloscope is triggered externally by the synchronous signal of the generator which is set to the pulsed mode. The ultrasonic pick-up is moved from its initial position close to the generator, and the change in the pulse delay time determined from the displacement of the pulse edge on the oscillogram. The temperature of the liquid is measured. The measurement is made for water, glycerol and sodium chloride solution.

Theory and evaluation

Problem 1:

With a change Δl in the distance between generator and pick-up, from its initial position (relative phase $\Delta\phi = 0$), the receiver signal phase moves in relation to the transmitter signal by

$$\Delta\phi = \frac{\Delta l}{\lambda} \cdot 2\pi \quad (1)$$

When the distance changes further, the signal overlap again for:

$$\Delta\phi = n \cdot 2\pi \quad n = 1, 2 \dots \quad (2)$$

The wavelength λ can be determined as

$$\lambda = \frac{\Delta l}{\Delta\phi} \cdot 2\pi = \frac{\Delta l}{n} \quad (3)$$

from equations (1) and (2).

When the sound frequency f is known, the phase velocity is

$$c_p = \lambda \cdot f \quad (4)$$

The wavelength λ is obtained from (3) as a slope of the regression line.

Table 1 shows the wavelengths λ with the standard errors $\Delta\lambda$ and the phase velocities calculated at a frequency $f = 800$ kHz in accordance with (4). The error for the phase velocity Δc_p is given by $\Delta\lambda$ and the error for the frequency $\delta f = +5$ kHz.

Table 1

Liquid	ϑ °C	λ mm	$\Delta\lambda$ mm	c_p m/s	Δc_p m/s
Distilled water	25	1.873	0.003	1500	12
Sodium chloride solution (saturated)	25	2.255	0.007	1800	20
Glycerol ⁺	25	2.353	0.004	1880	15

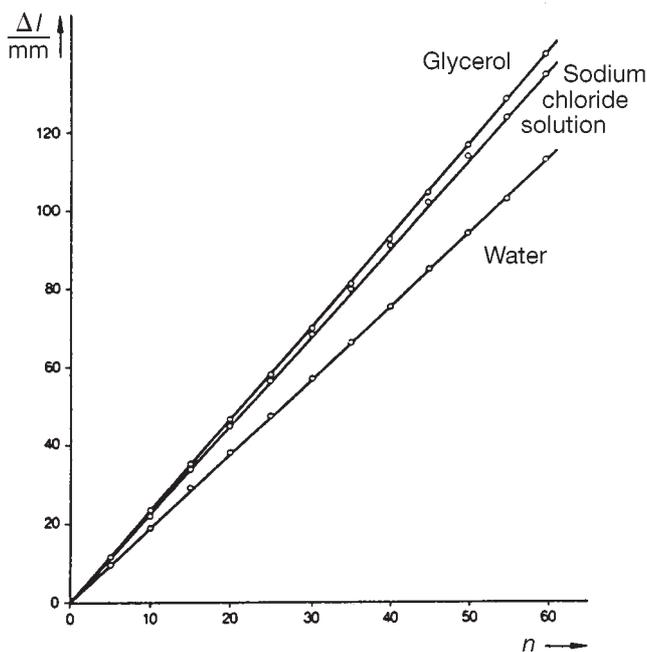


Fig. 2: Detector displacement Δl as a function of the number n of wavelengths covered, for water, glycerol and sodium chloride solution (temperature $\vartheta = 25^\circ\text{C}$).

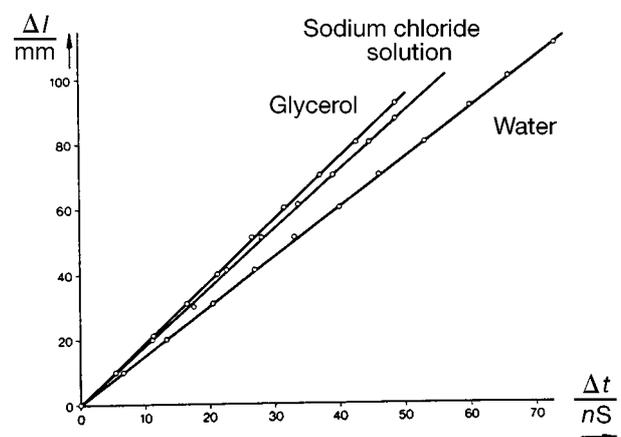


Fig. 3: Change in sound path Δl as a function of the change in delay time Δt , for water, glycerol and sodium chloride solution (temperature $\vartheta = 25^\circ\text{C}$).

2.1. The coefficient of sweep is obtained as:

$$t^* = \frac{N \cdot T}{x} \quad (5)$$

where:

N = number of vibration periods shown.

$T = \frac{1}{f}$ = duration of the period

($T = 1.25 \mu\text{s}$ when
 $f = 800 \text{ kHz}$)

x = length of the vibration periods shown on the oscillogram.

2.2. The group velocity c_G is obtained from the changes in the sound path Δl and in the delay time Δt as:

$$c_G = \frac{\Delta l}{\Delta t} \quad (6)$$

Table 2 shows the group velocities obtained as a slope of the regression line in accordance with equation (6) and with the standard error Δc_G .

Table 2

Liquid	ϑ °C	$\frac{c_G}{m/s}$	$\frac{\Delta c_G}{m/s}$	$\frac{\Delta_M c_G}{m/s}$
Distilled water	25	1506	7	12
Sodium chloride solution (saturated)	25	1800	9	14
Glycerol [†]	25	1900	9	15

The last column contains the standard mean error $\Delta_M c_G$ obtained from the statistical and systematic errors occurring in the determination of the sweep coefficient at the generator frequency.

Group and phase velocity are interlinked in accordance with:

$$c_G = c_p - \lambda \frac{dc_p}{d\lambda}$$

The fact that the results $c_G = c_p$ agree within the limits of measurement error indicate that

$$\frac{dc_p}{d\lambda} = 0$$

and that there is no dispersion.

Table 3

Liquid	ϑ °C	$\frac{c}{m/s}$	$\frac{\Delta c / \Delta T}{m/s \cdot ^\circ C}$	Source
Glycerol [†]	20	1923	-1.8	*
	25	1904	-2.2	**
Water (distilled)	25	1497	+2.5	*
	25	1498	+2.4	**
($0 < \vartheta < 40 \text{ }^\circ\text{C}$)				

Bibliography

* L. Bergmann, Der Ultraschall (Ultrasonics), Hirzel-Verlag

** Handbook of Chemistry and Physics, The Chemical Rubber Co.

Note

1. As glycerol is hygroscopic, a slower sound velocity is often measured for glycerol which has been allowed to stand.

2. Oscilloscope: relative sweep error $\pm 5\%$.

Ultrasonic generator: relative error for a frequency of 800 kHz: $\pm 0.6\%$.

3. According to L. Bergmann, the velocity of sound in a sodium chloride solution increases linearly with concentration. The change in velocity which takes place as the temperature changes is the same as that of water.

Sound velocity are a function of temperature (see Bibliography).