

MUNI



Università  
di Catania

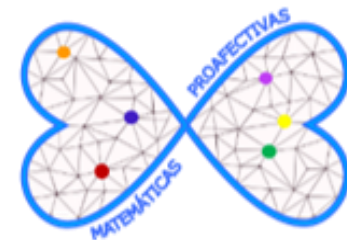


Instituto Politécnico  
de Viana do Castelo

Erasmus+ BIP: Supporting curriculum through integrated STEAM Education practices

# Robotics in STEAM Education: A Hands-On Journey with Graph Theory Challenges

Teresa Fernández Blanco  
Antía Fernández López  
Cristina Lois Prados



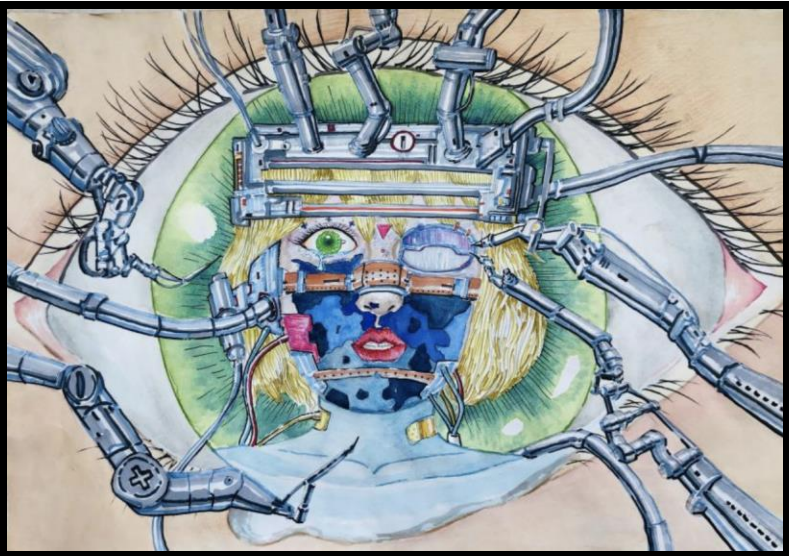
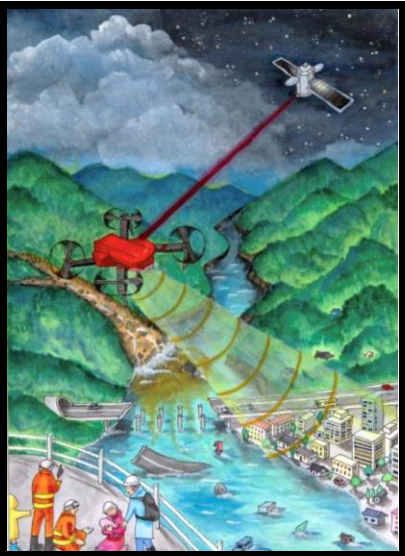
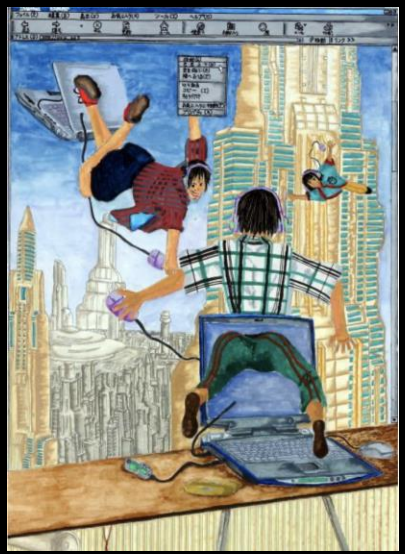
PID2021-122326OB-I00

# INITIAL QUESTIONNAIRE BIP





# HOW DO KIDS SEE THE FUTURE?







# HOW DO "ADULTS" SEE THE FUTURE?

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<https://youtu.be/G2emilxcHm8>

**WHAT TECHNOLOGIES HAVE THESE  
MOVIES PREDICTED?**



# WHAT TECHNOLOGIES HAVE THESE MOVIES PREDICTED?



Hologram



Fingerprint reader



Robot + mechanical arm



Android



VW



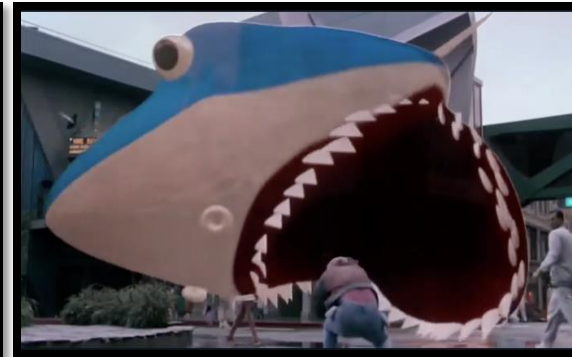
Exoskeleton



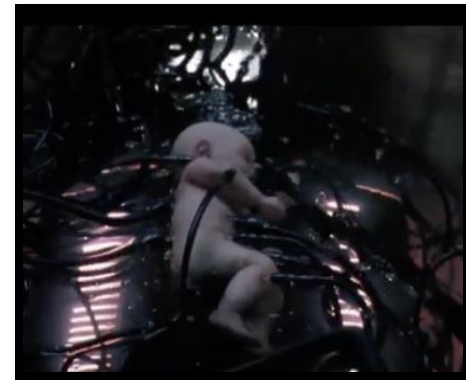
3D Printing



Rocket



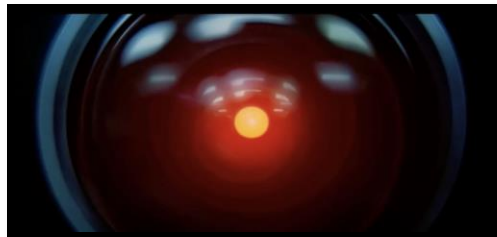
AR



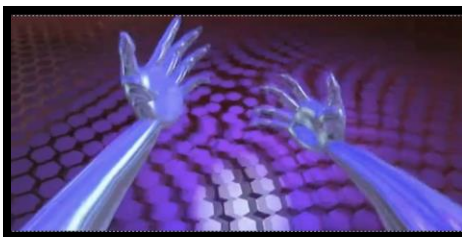
Cyber-pregnancy



Holographic screen



AI



VR

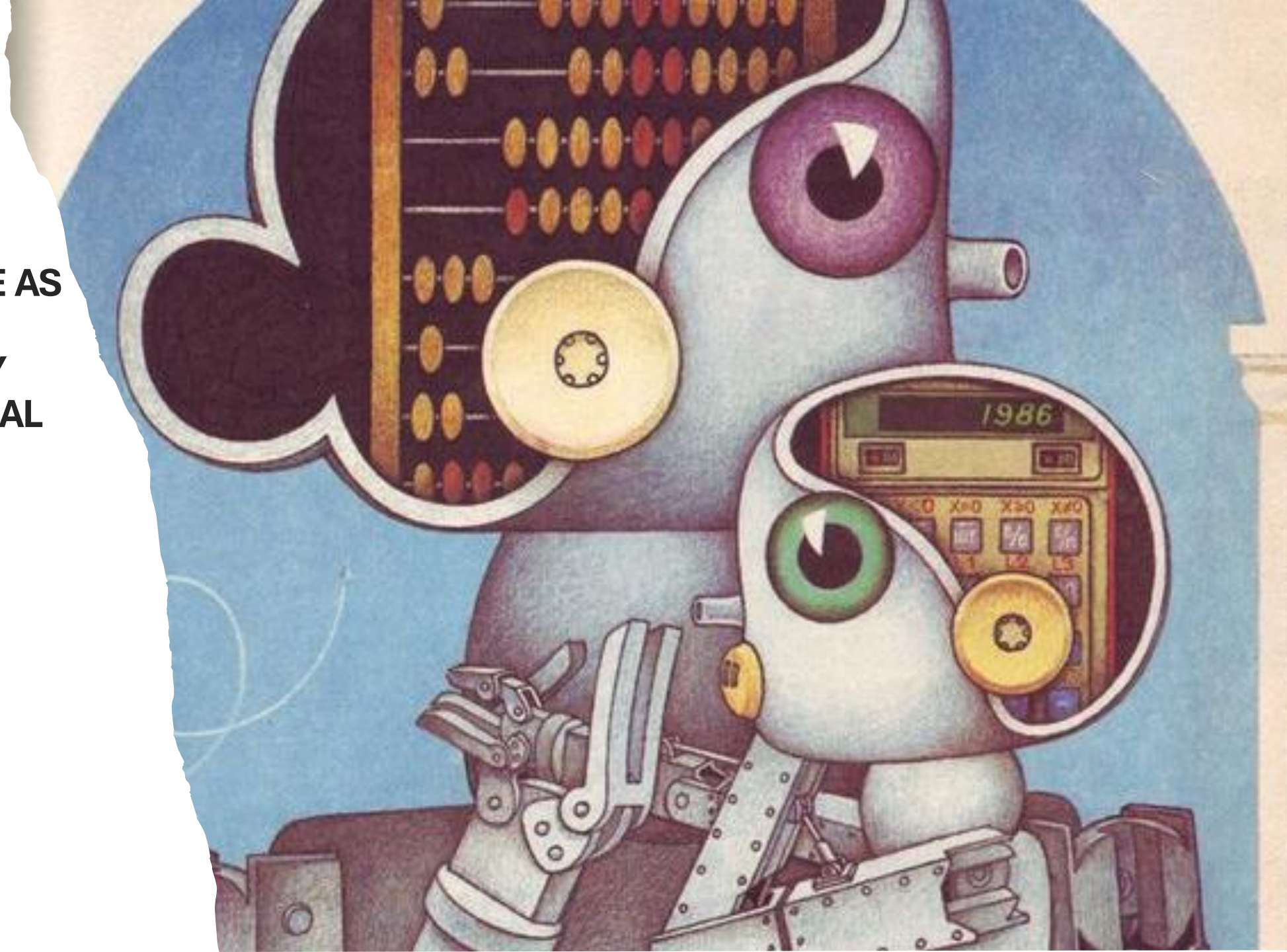


AI Android



**WHICH IS OUR ROLE AS  
TEACHERS IN THE  
FUTURE OF SOCIETY  
AND TECHNOLOGICAL  
DEVELOPMENT?**

**CAN WE IGNORE AS  
TEACHERS THE  
TECHNOLOGICAL  
INCLUSION IN  
CLASSROOM?**

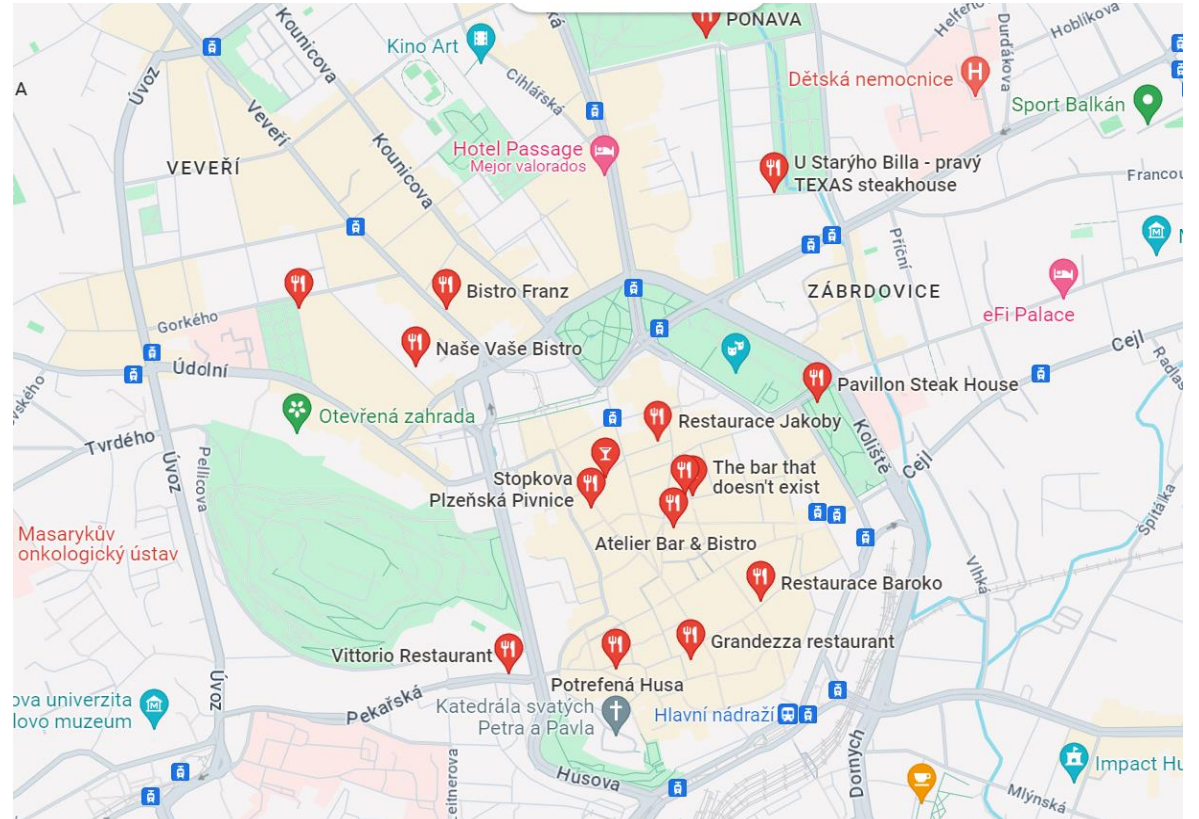




# CHALLENGE PRESENTATION

Is it possible nowadays to program an **intelligent home delivery car**?

In the following pictures we can see the city of Brno and an street map of an small part of it  
We can find an **area full of restaurants** besides an **urban area**



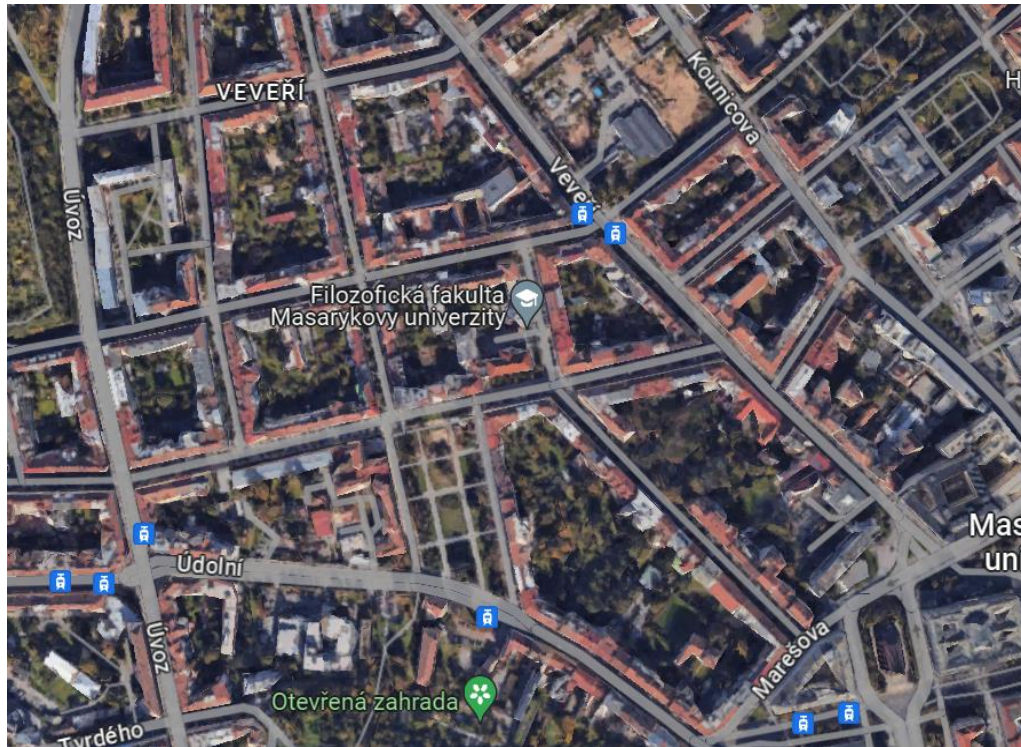


# CHALLENGE PRESENTATION

Is it possible nowadays to program an intelligent home delivery car?

Do you have any idea about **how to model this situation**?

Urban area

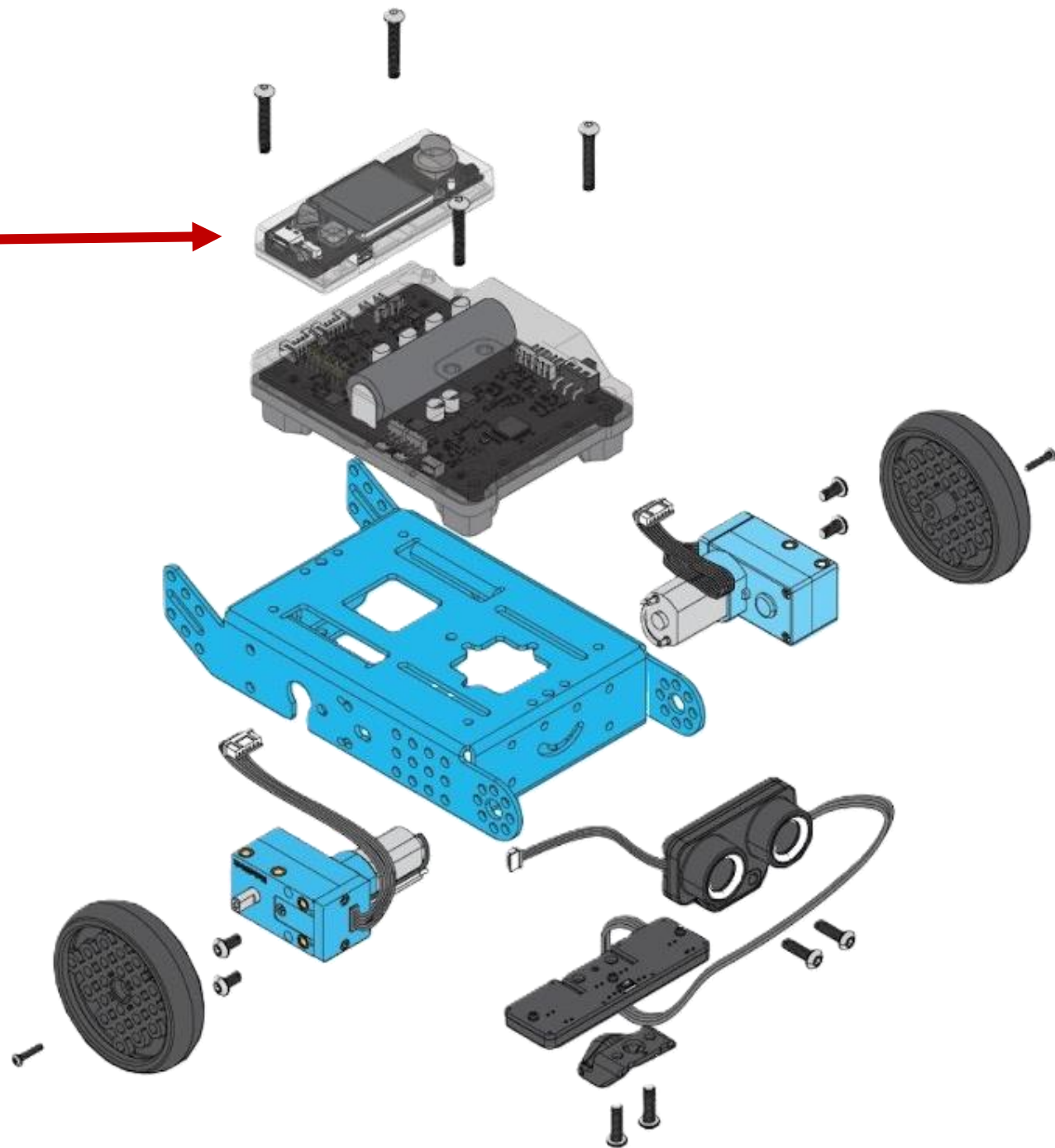


Restaurants zone



# MBOT2

**CYBERPI**



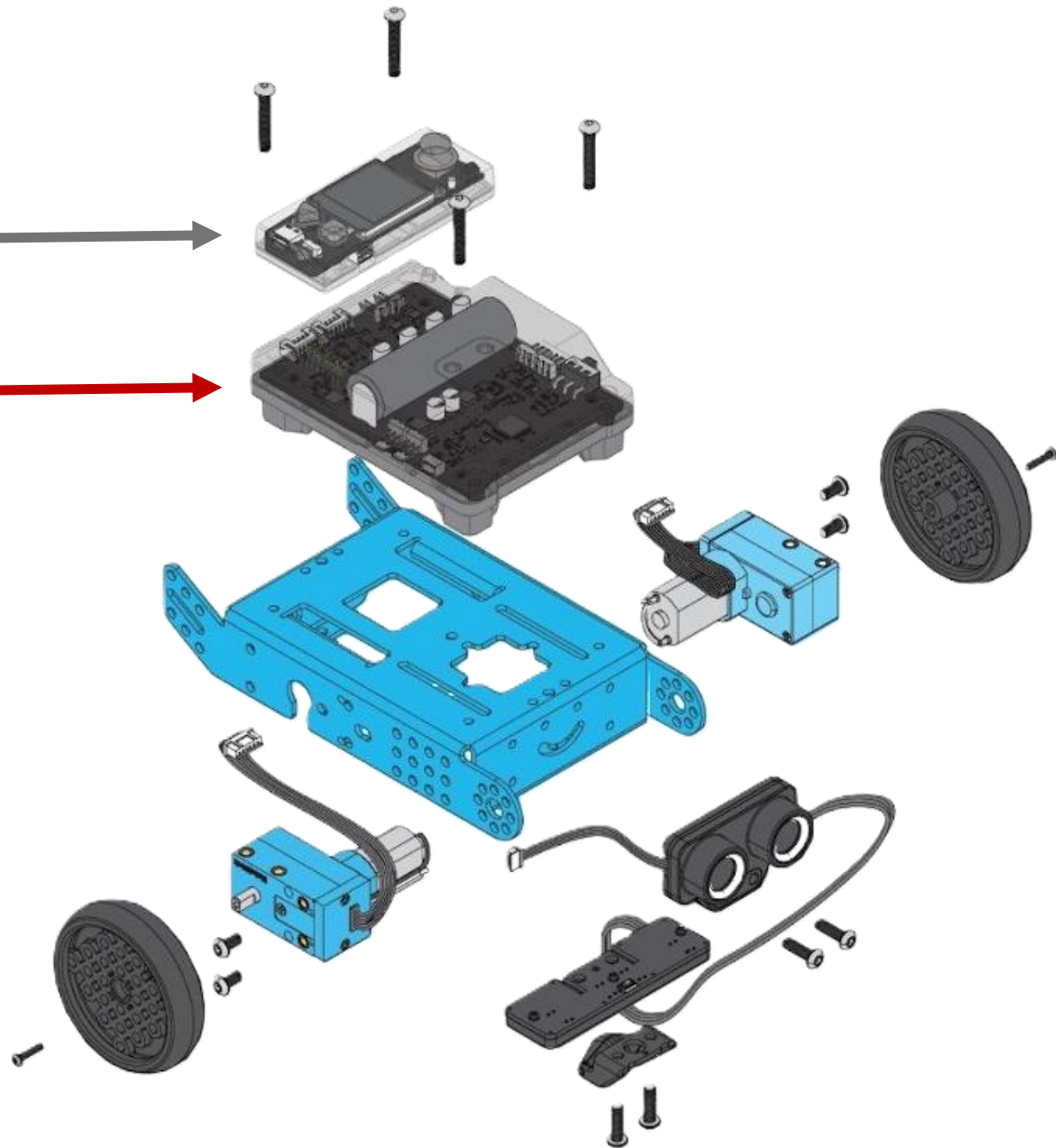
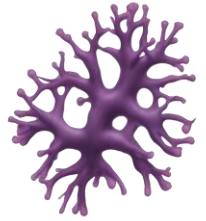


# MBOT2

CYBERPI



MOTHERBOARD

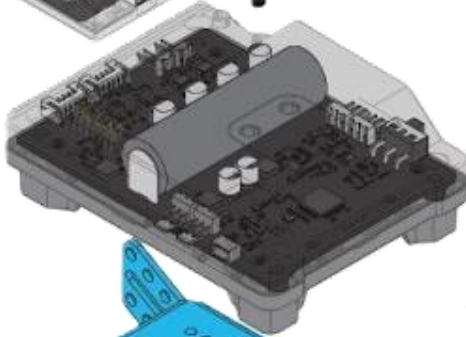


# MBOT2

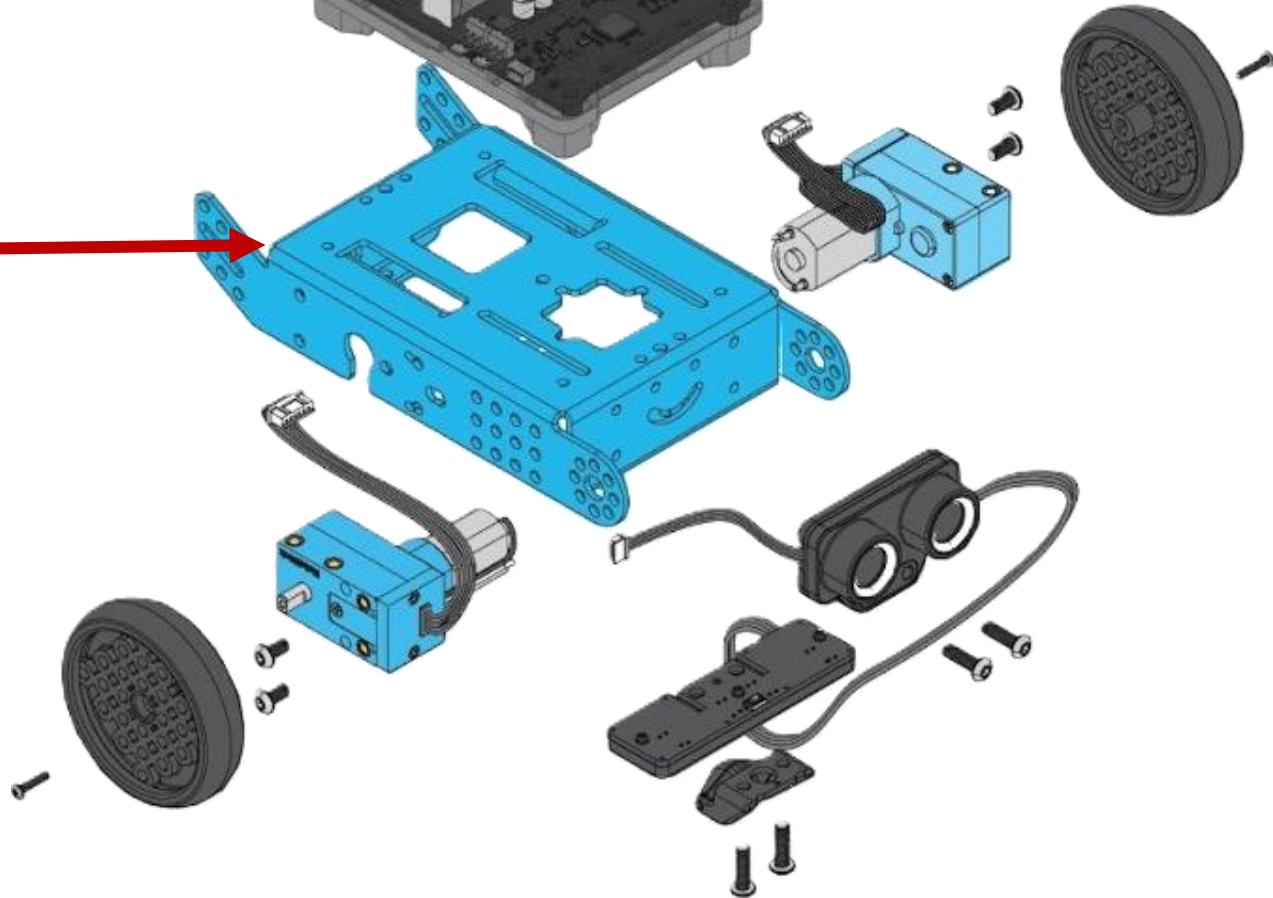
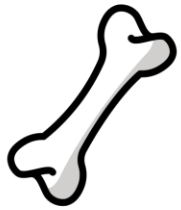
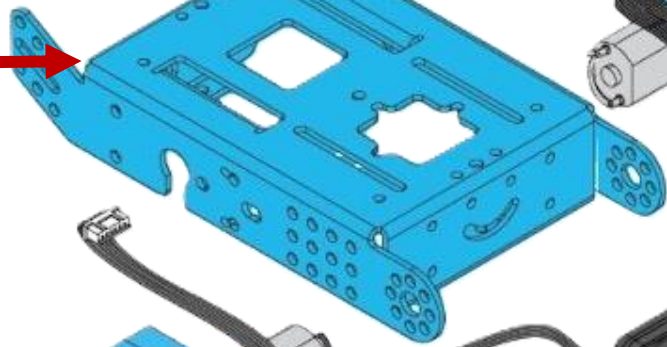
CYBERPI



MOTHERBOARD



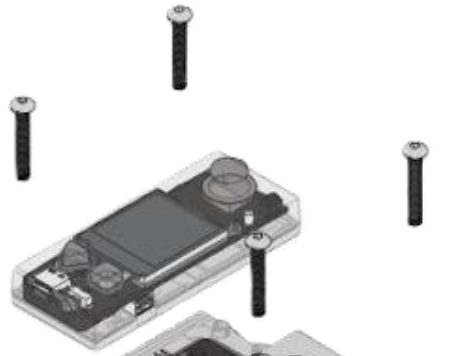
CHASIS



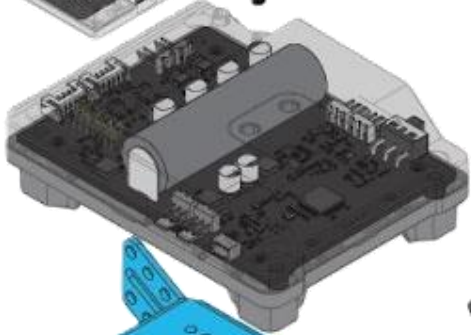


# MBOT2

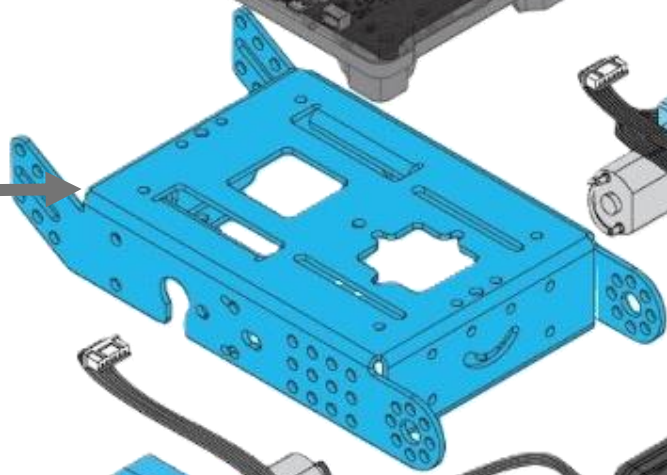
CYBERPI



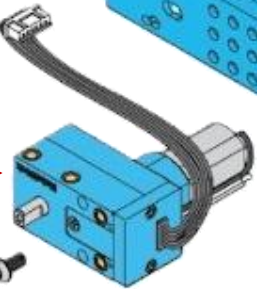
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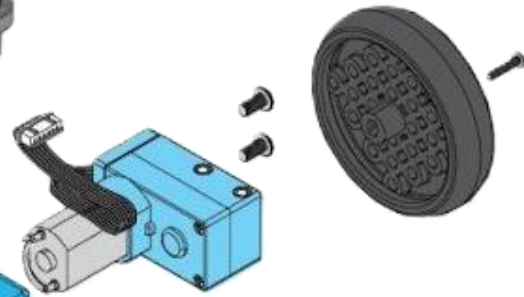
CHASIS



MOTORS



WHEELS

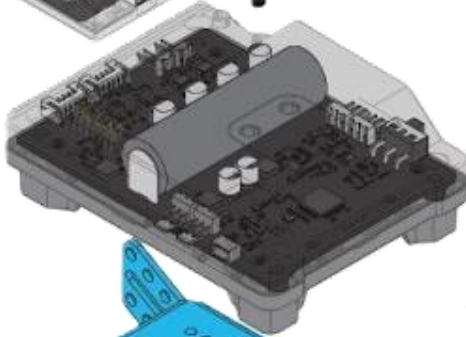


# MBOT2

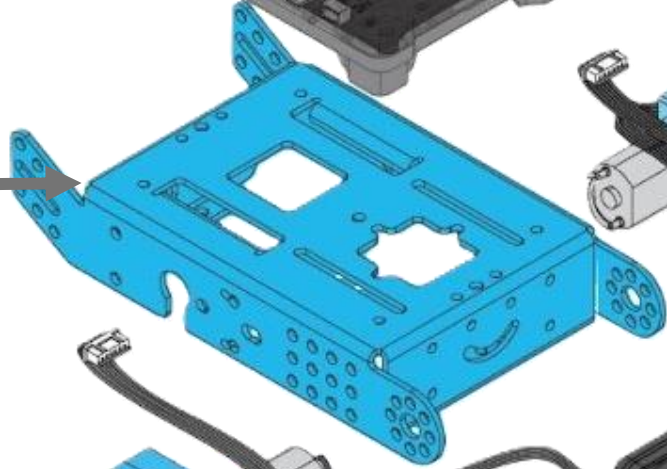
CYBERPI



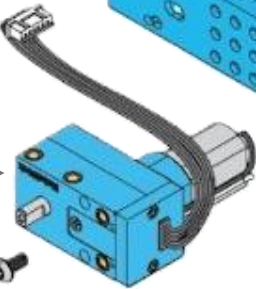
MOTHERBOARD



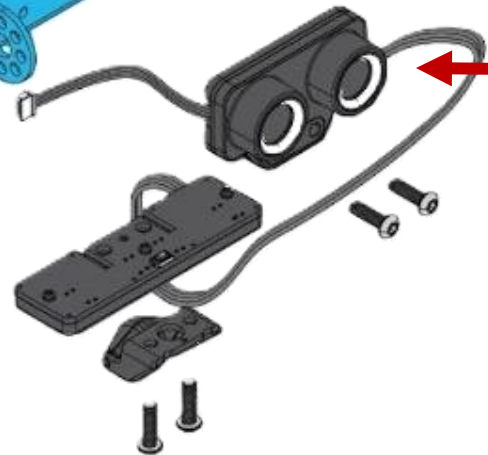
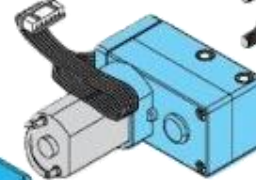
CHASIS



MOTORS



WHEELS



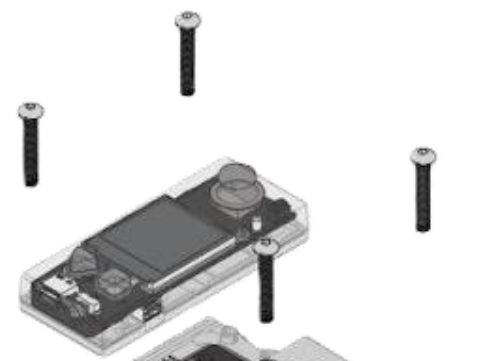
**ULTRASONIC SENSOR**



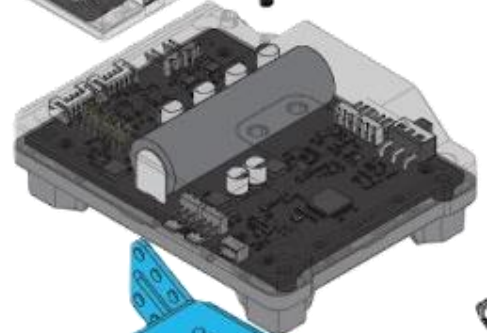


# MBOT2

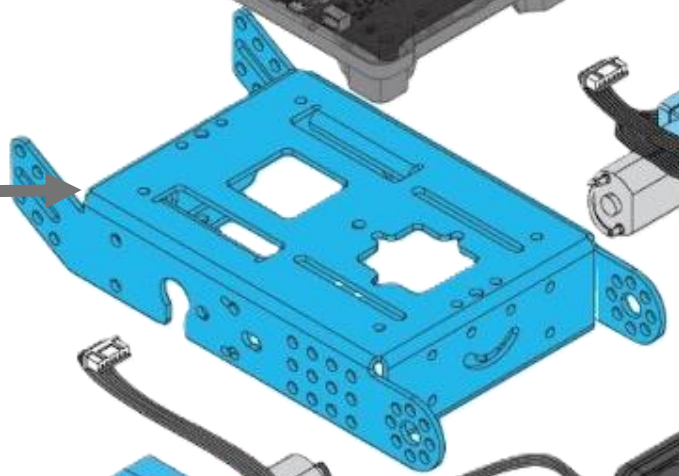
CYBERPI



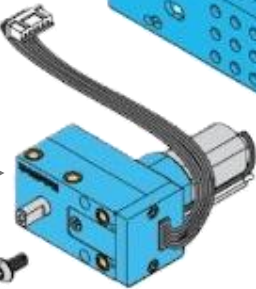
MOTHERBOARD



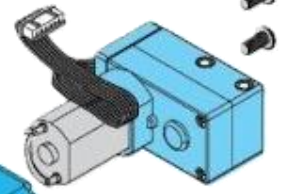
CHASIS



MOTORS



WHEELS



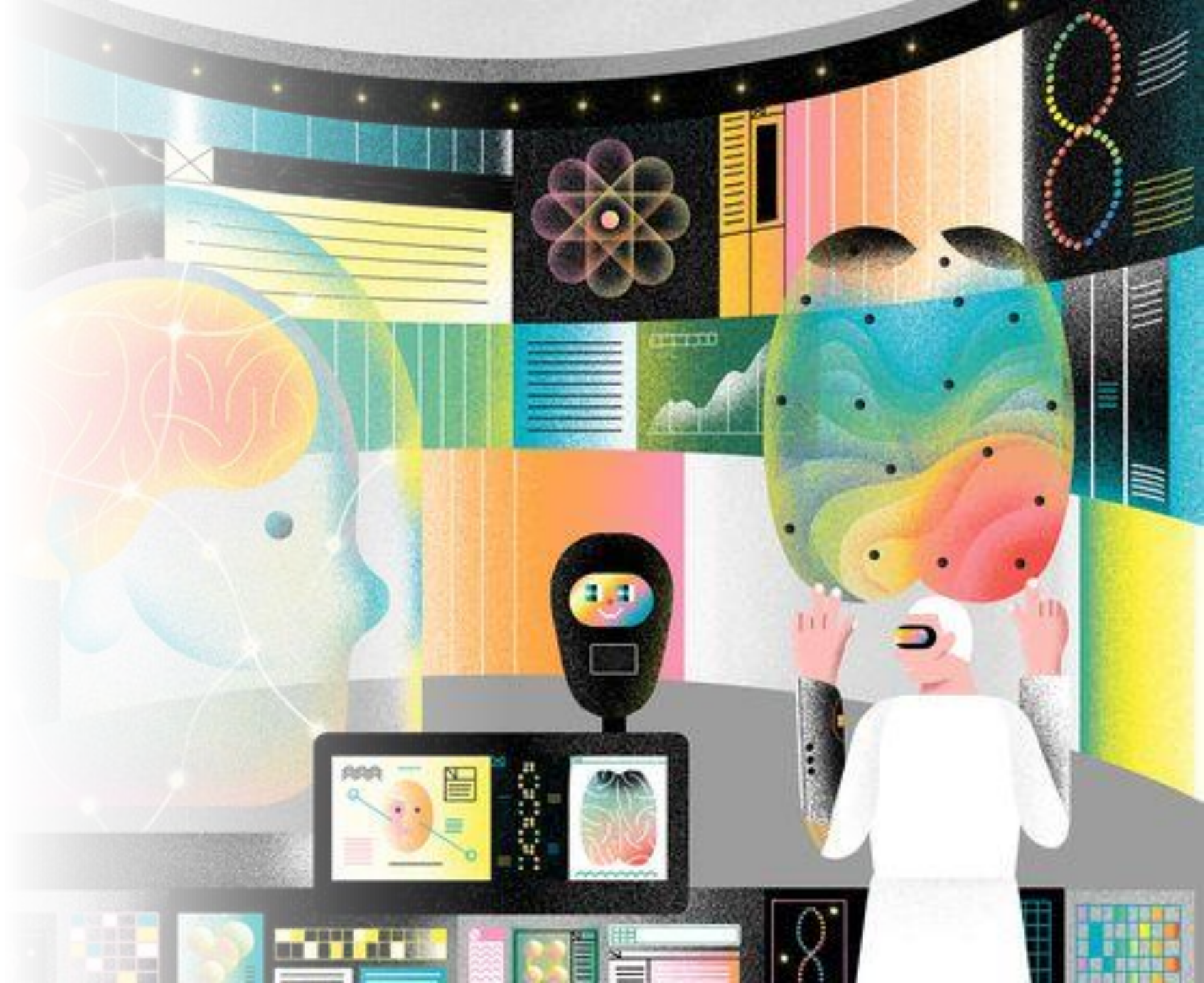
ULTRASONIC SENSOR



RGB SENSOR



- **WHICH CONTENTS ARE WE WORKING?**
- **WHICH OTHER PORPOSALS COULD BE MADE WITH THESE RESOURCES?**



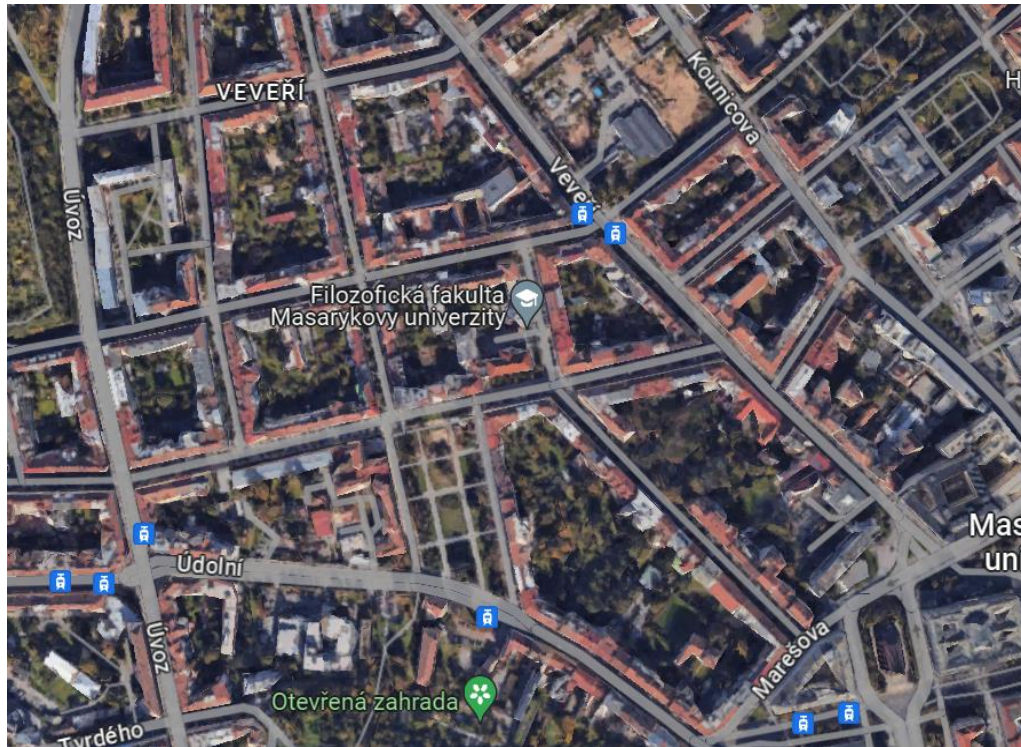


# INTELLIGENT FOOD DELIVERY CAR (Model formulation)

Is it possible nowadays to program an intelligent home delivery car?

Do you have any idea about **how to model this situation**?

Urban area



Restaurants zone







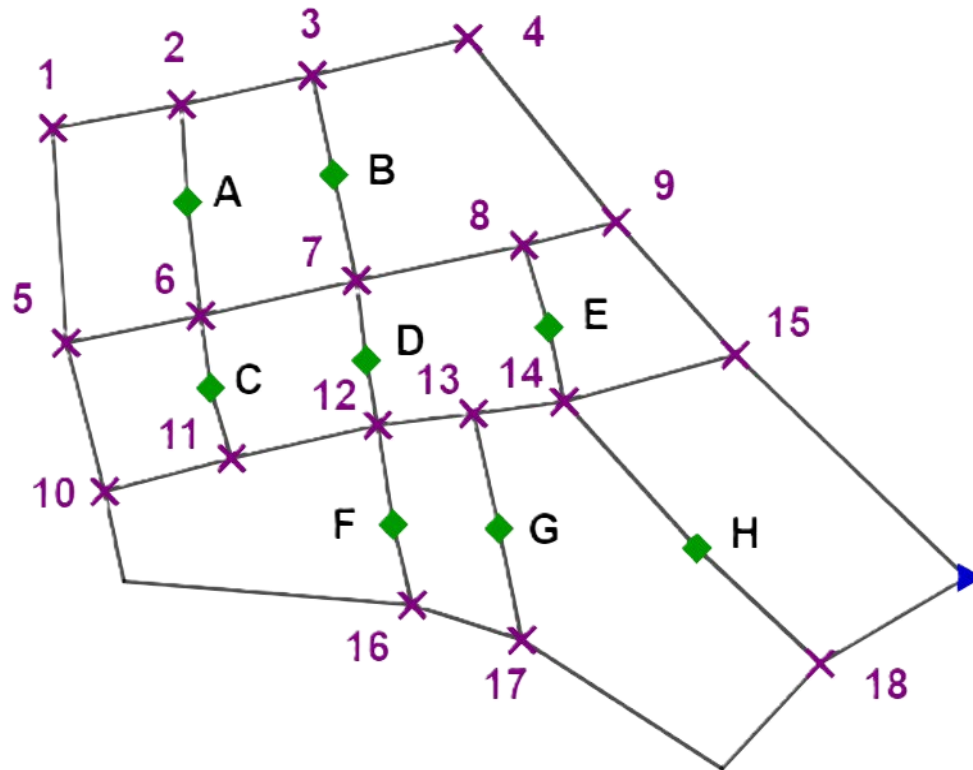


# INTELLIGENT FOOD DELIVERY CAR (Model formulation)

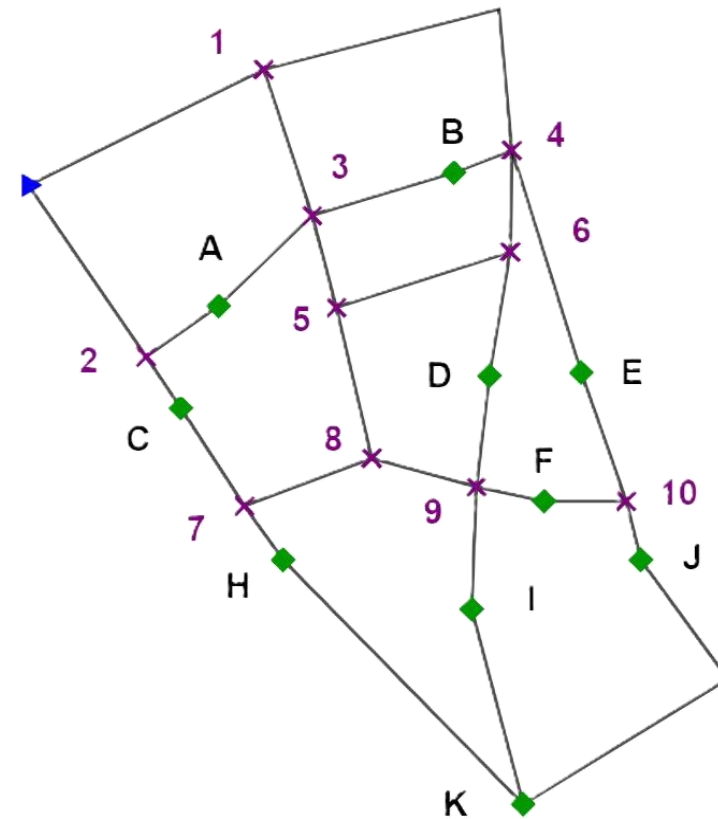
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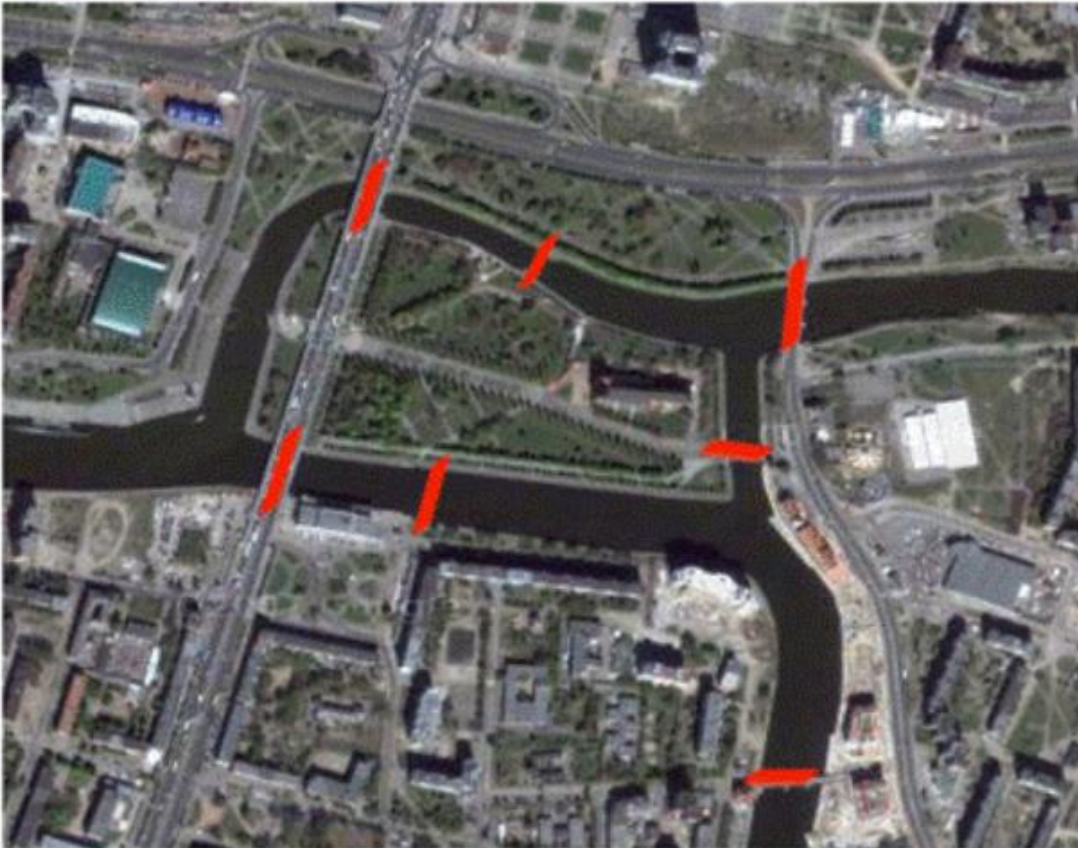


# INTRODUCTION TO GRAPH THEORY

## Problem of the Königsberg's bridges

Is it possible to pass through all the bridges without crossing any one two times?

**Requirement:** The path must start and end at the same point.



*Kaliningrado, previously Königsberg*

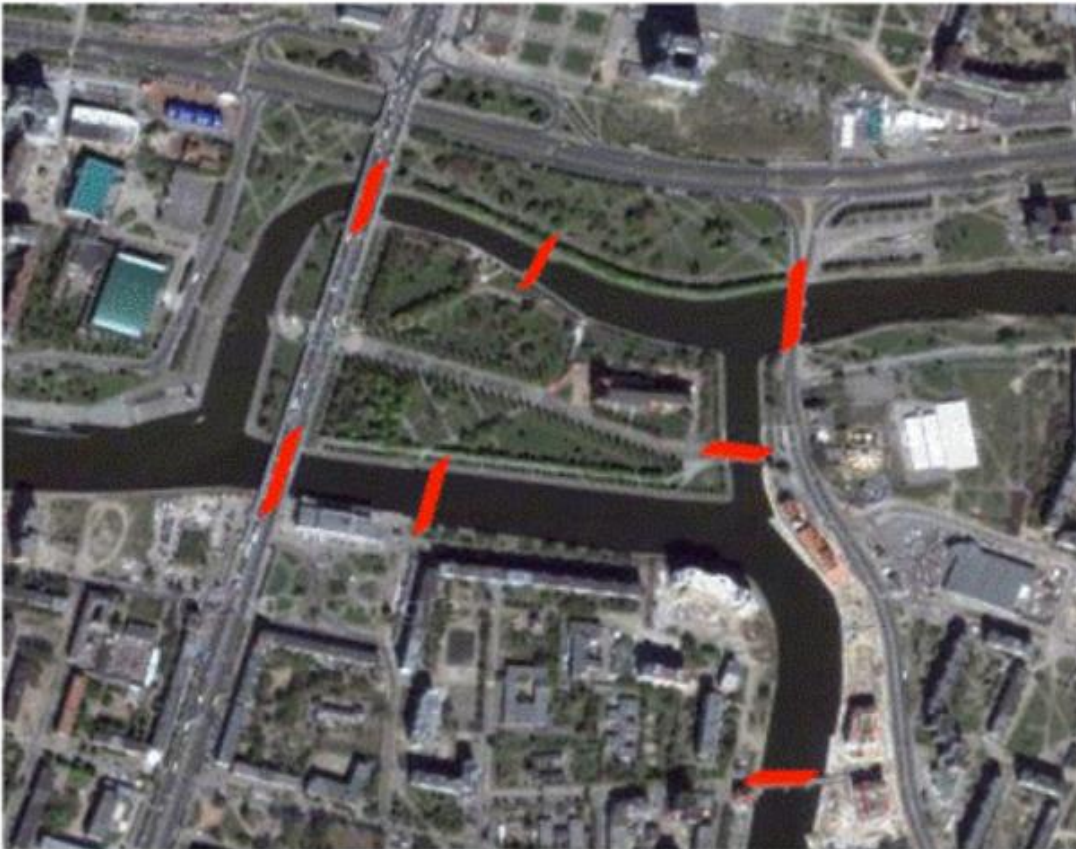


# INTRODUCTION TO GRAPH THEORY

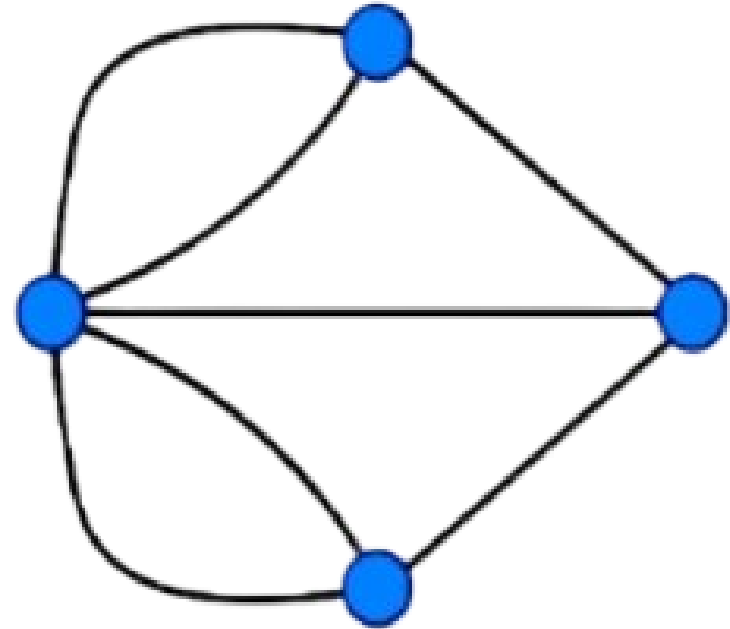
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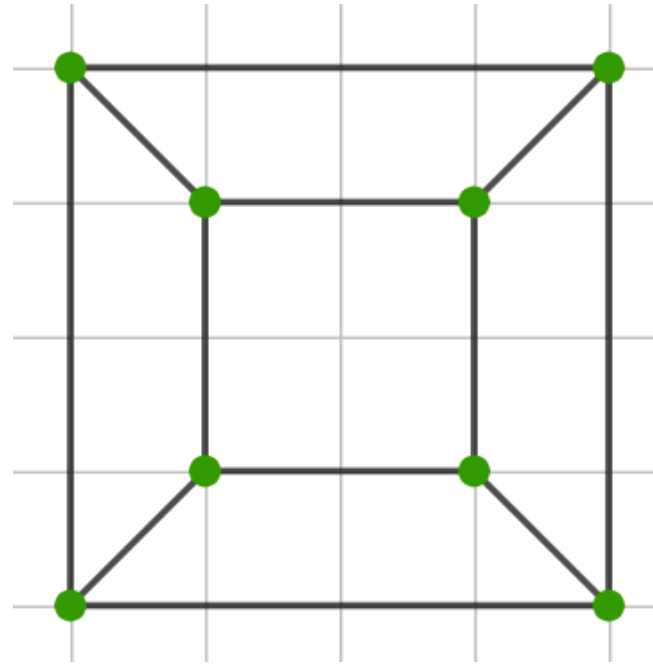
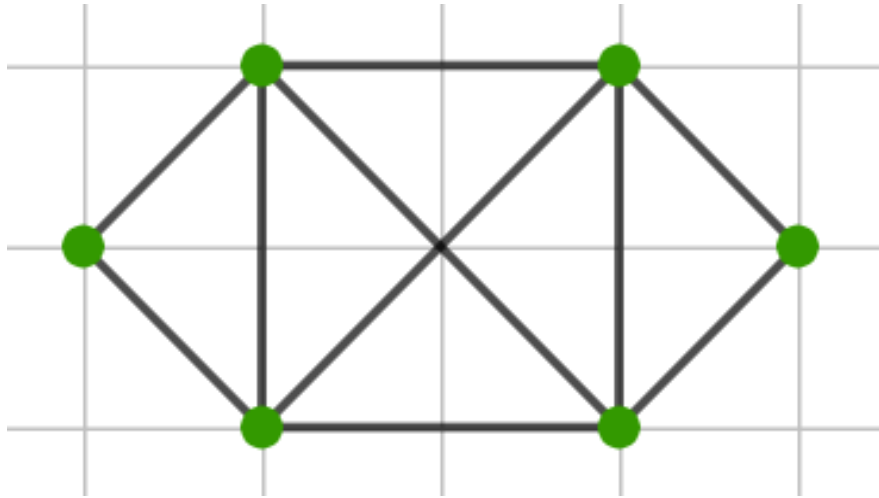


*Euler (1736)*

# INTRODUCTION TO GRAPH THEORY

**Can you find a Hamiltonian path? Is it the shortest one?**

A **Hamiltonian path** passes through each vertex exactly once and returns to the departure node

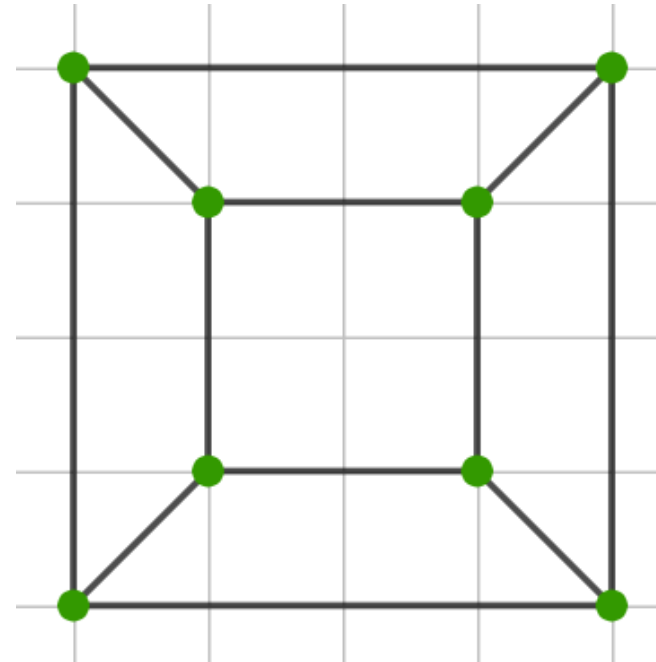
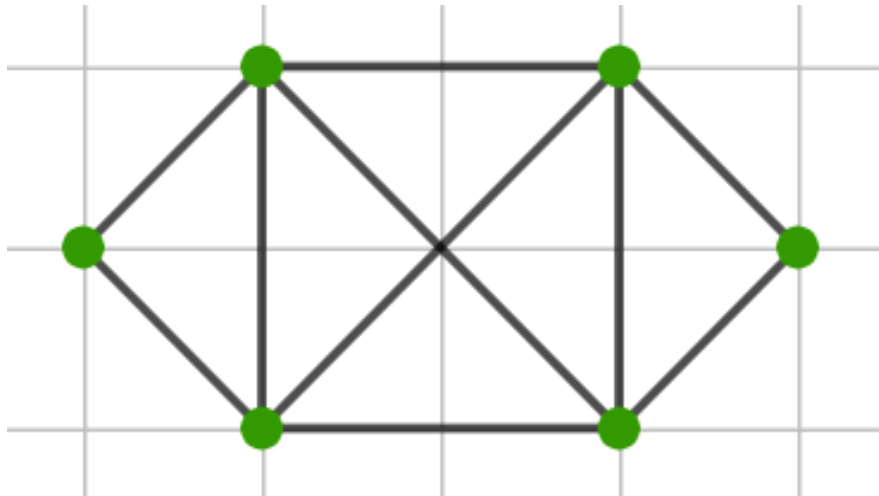




# INTRODUCTION TO GRAPH THEORY

**Can you find a Hamiltonian path? Is it the shortest one?**

A **Hamiltonian path** passes through each vertex exactly once and returns to the departure node



## Traveling salesman problem

Given a list of cities (nodes) and the distances (edges) between them, what is the **shortest possible path that visits each city (node) exactly once and returns to the departure city?**

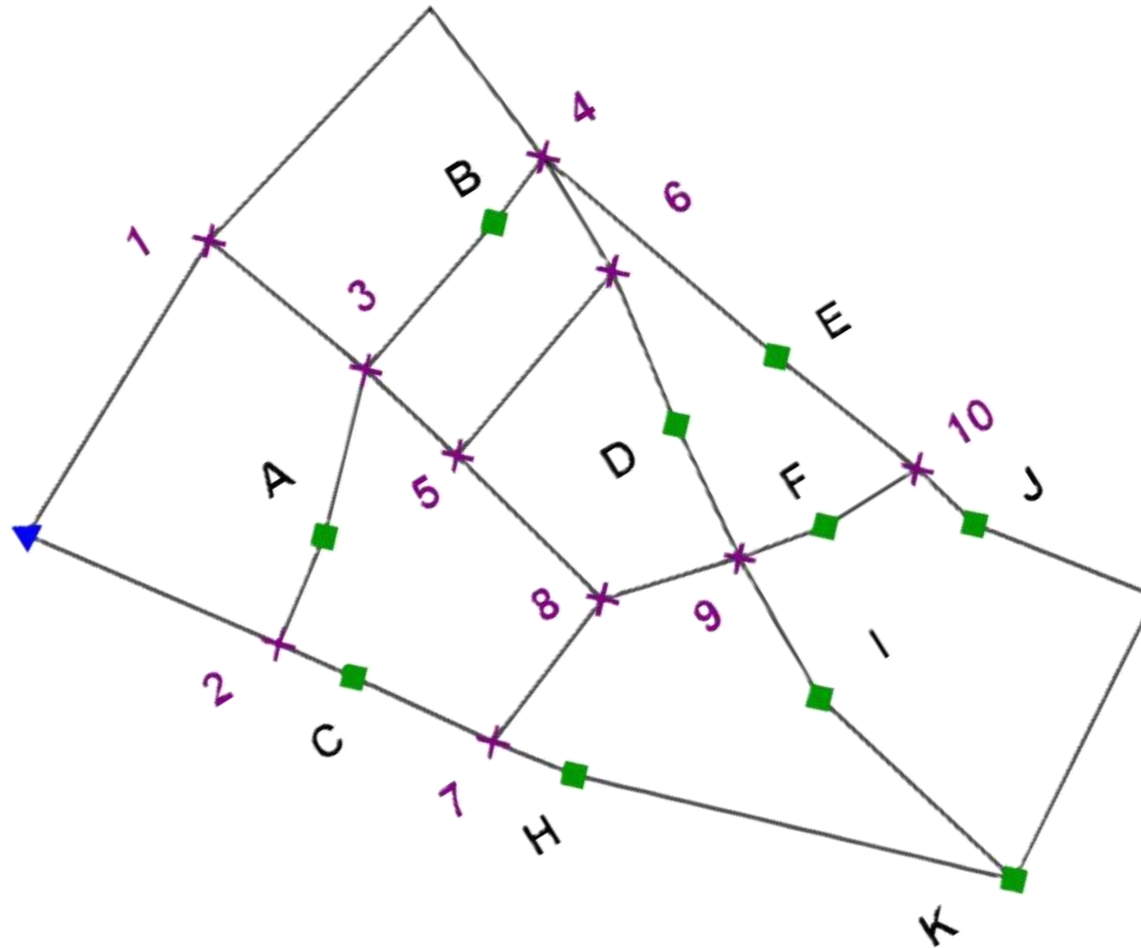
Famous because of the contrast between its simple formulation and the difficulty of finding an exact algorithm to solve it





# INTELLIGENT FOOD DELIVERY CAR (Route optimization)

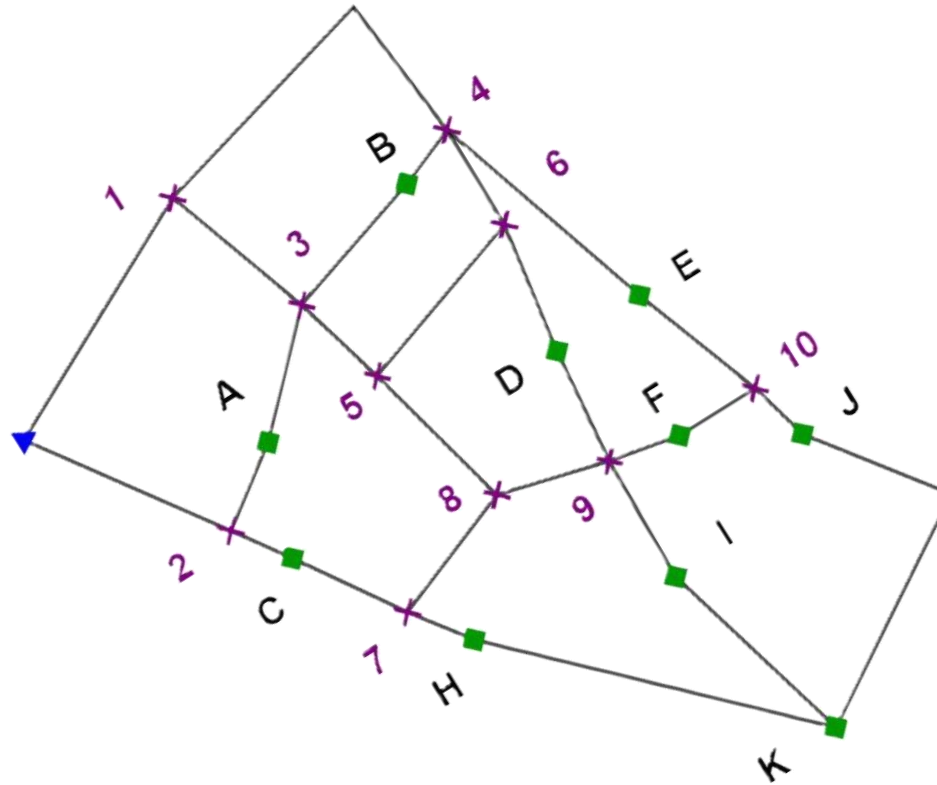
Restaurants area



Can you find a "Hamiltonian path"?

# INTELLIGENT HOME DELIVERY CAR (Route optimization)

## Restaurants area



Can you find a "Hamiltonian path"? Why?

Which is the maximum number of restaurants (nodes) that you can visit without repeating **anyone** (starting and finishing the route at the blue triangle)?



# INTRODUCTION TO GRAPH THEORY

## Traveling salesman problem (Algorithms)

An **algorithm** is as a **sequence of instructions** that can be used to solve a problem

If it provides an **optimal solution** (the most profitable), we say that the **algorithm is exact**

If it is **almost optimal** and we control the margin of error, the **algorithm is approximated**

If it produces a solution and we don't know how far is from the optimal one, it is **heuristic**

# INTRODUCTION TO GRAPH THEORY

## Traveling salesman problem (Algorithms)

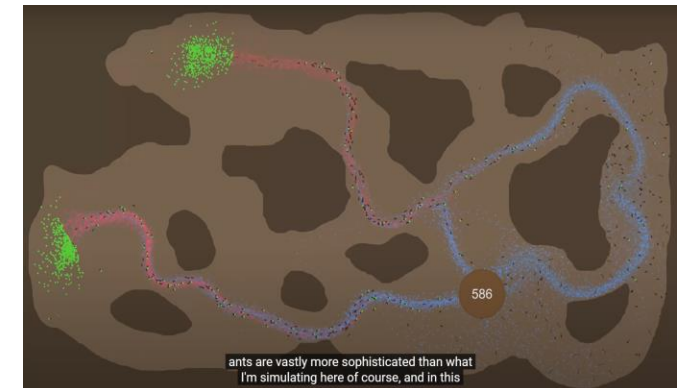
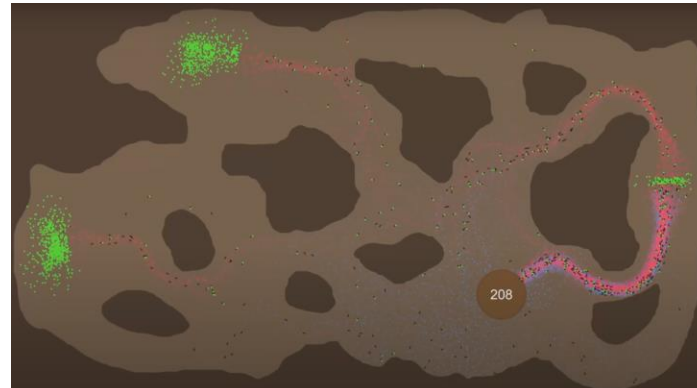
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### ANT'S COLONY OPTIMIZATION ALGORITHM

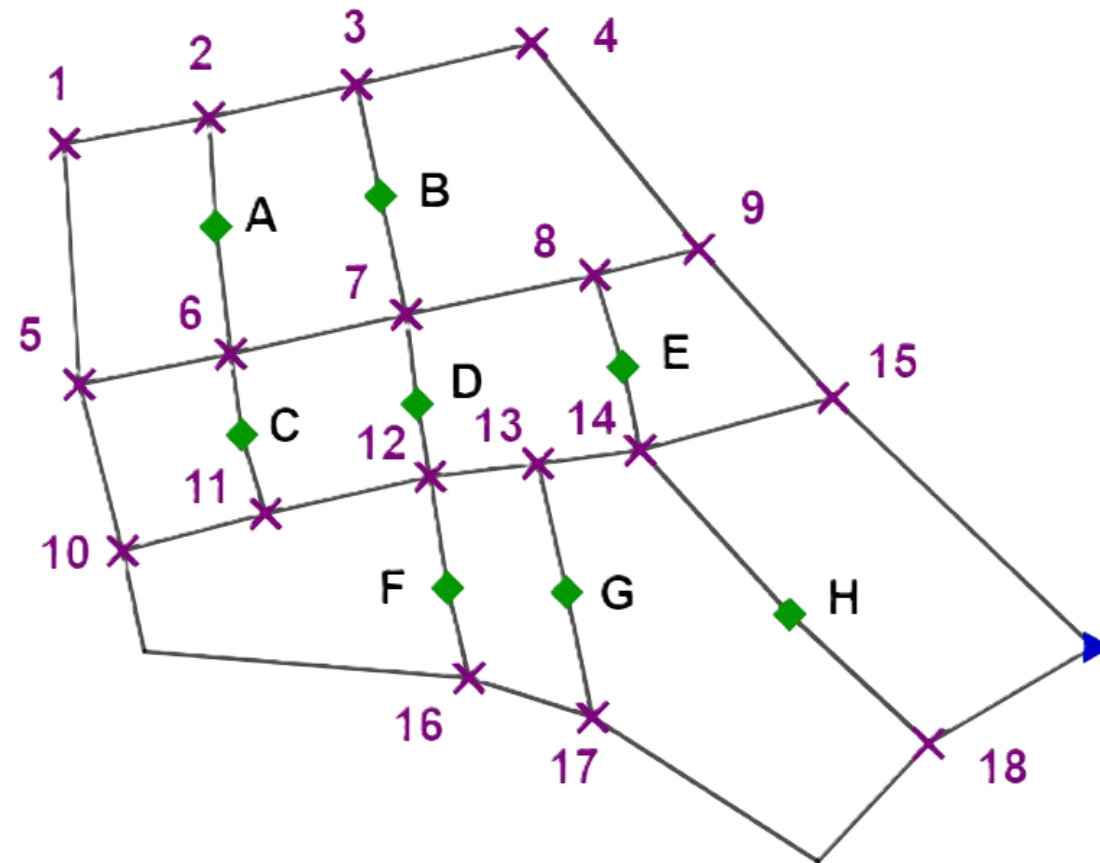


[Coding Adventure: Ant and Slime Simulations \(from 9' 8" to 10' 8"\)](#)



# INTELLIGENT FOOD DELIVERY CAR (Route optimization)

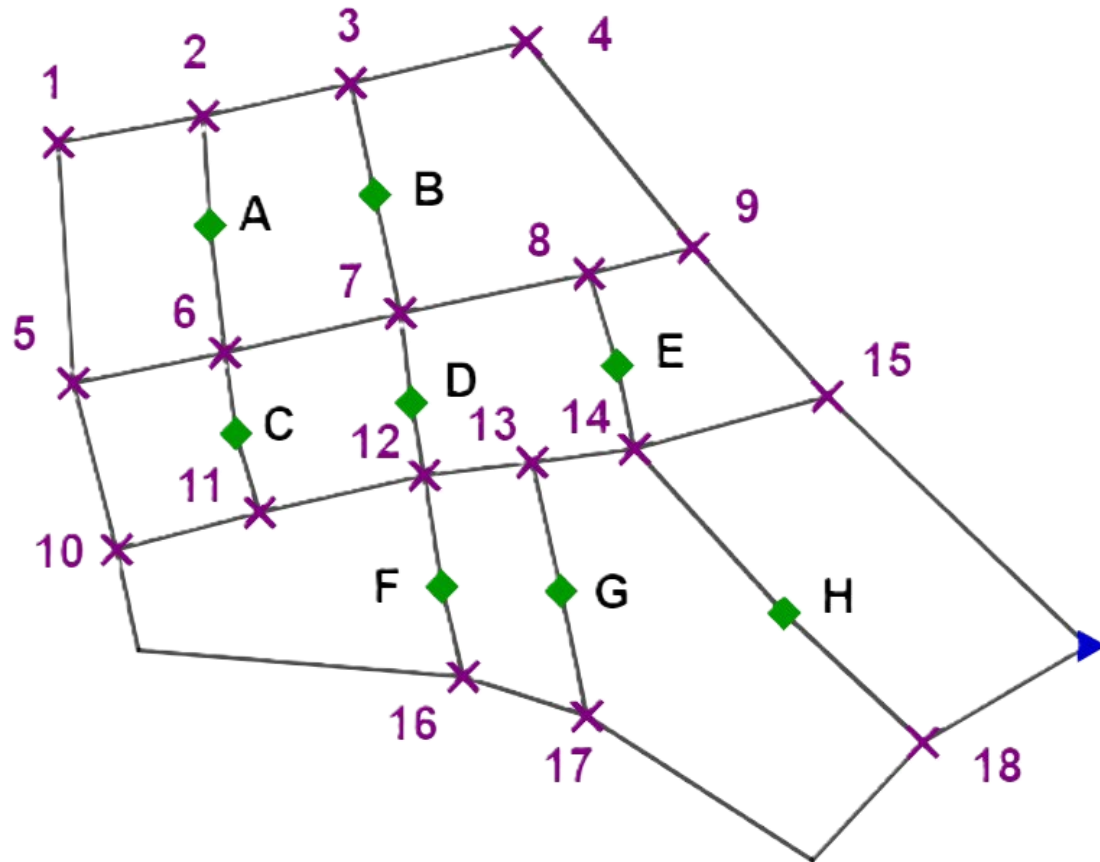
Urban area



How can you generate a RANDOM "Hamiltonian path"?

# INTELLIGENT FOOD DELIVERY CAR (Route optimization)

Urban area



How can you generate a  
RANDOM "Hamiltonian path"?

Random letters generator



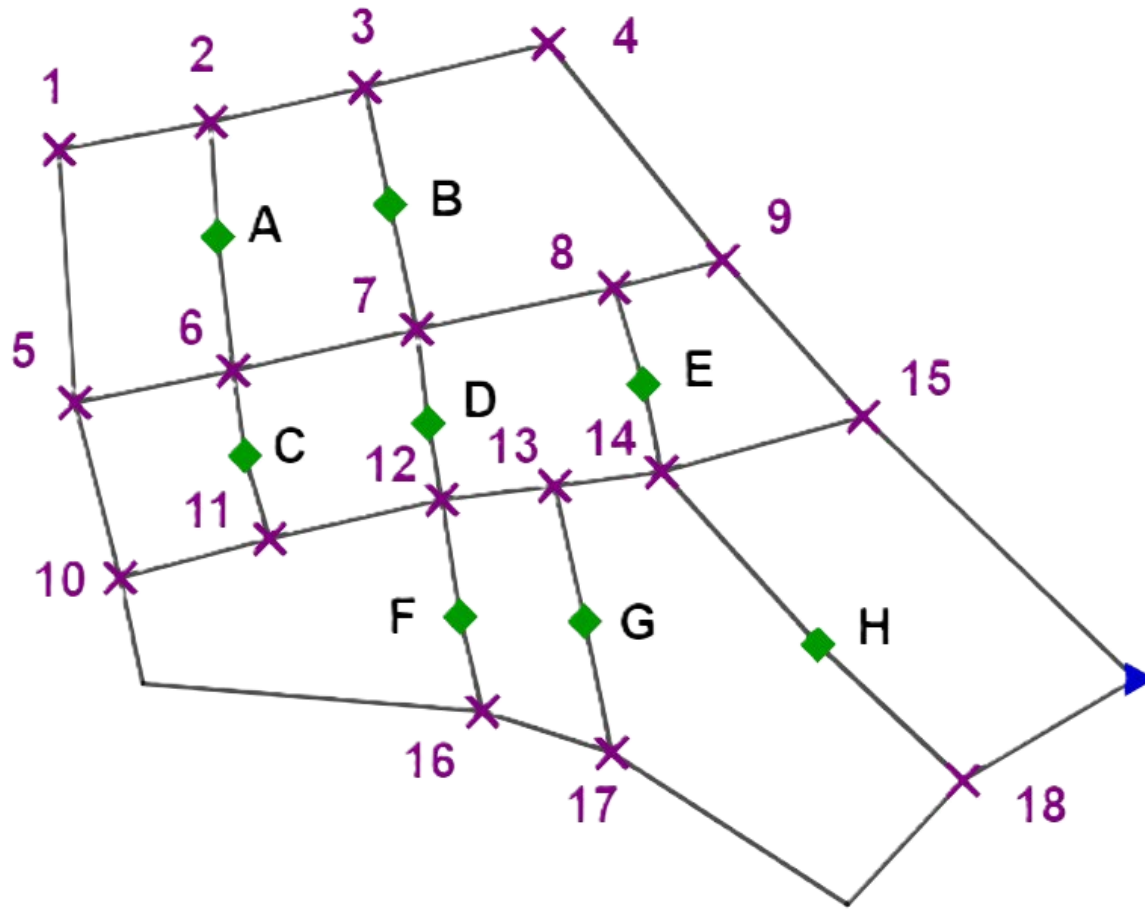
Registration of the Hamiltonian path





# INTELLIGENT FOOD DELIVERY CAR (Route optimization)

Urban area

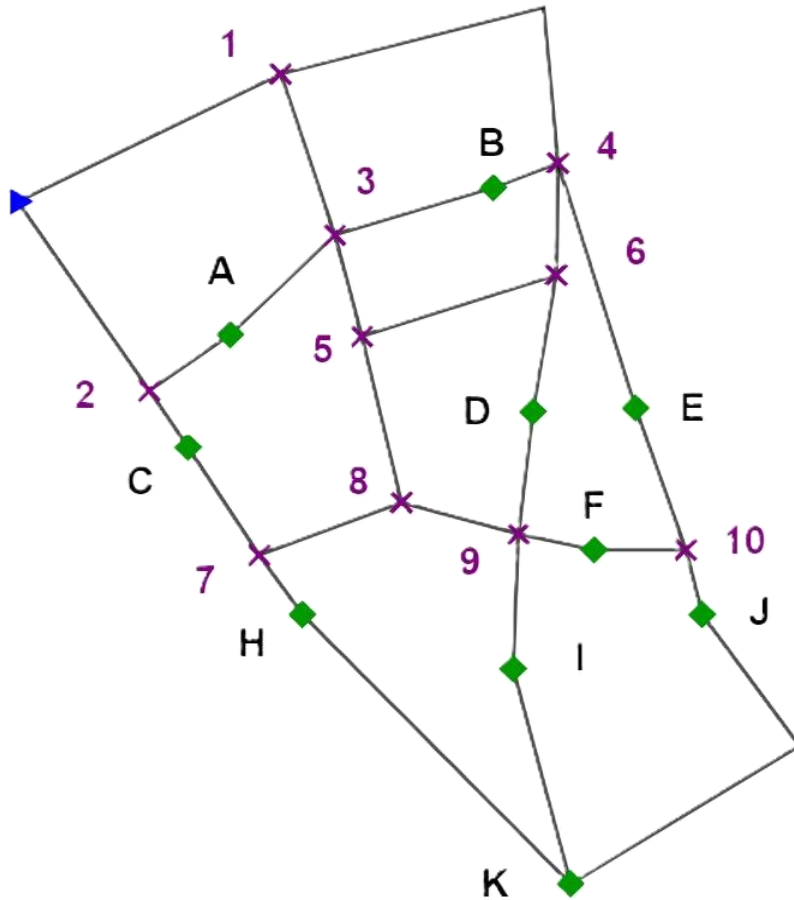


Do you think that we have already found the optimal solution?

What is the probability of succeeding with such a small number of iterations?

# INTELLIGENT FOOD DELIVERY CAR (Route optimization)

Restaurant area



How can you generate a  
RANDOM "Hamiltonian path"?

Random letters generator



Registration of the Hamiltonian path

**NEW**

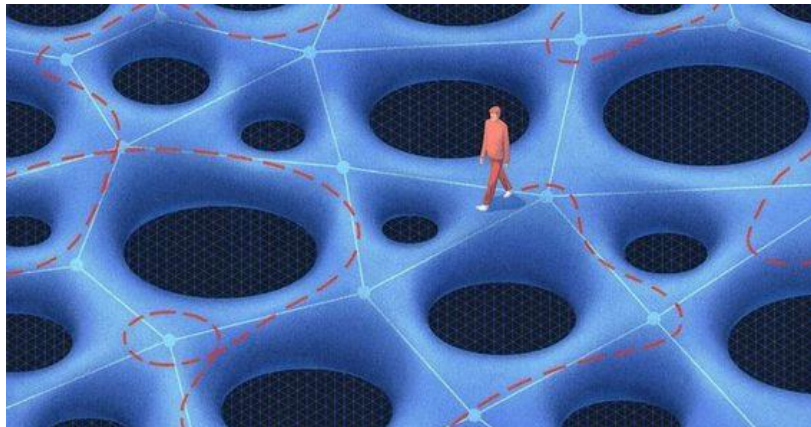




# INTELLIGENT FOOD DELIVERY CAR (Coding)

## DECISIONS

- How to follow the road
- When there is a crossing, how to know which direction to follow
- How to make stops at food/delivery stations



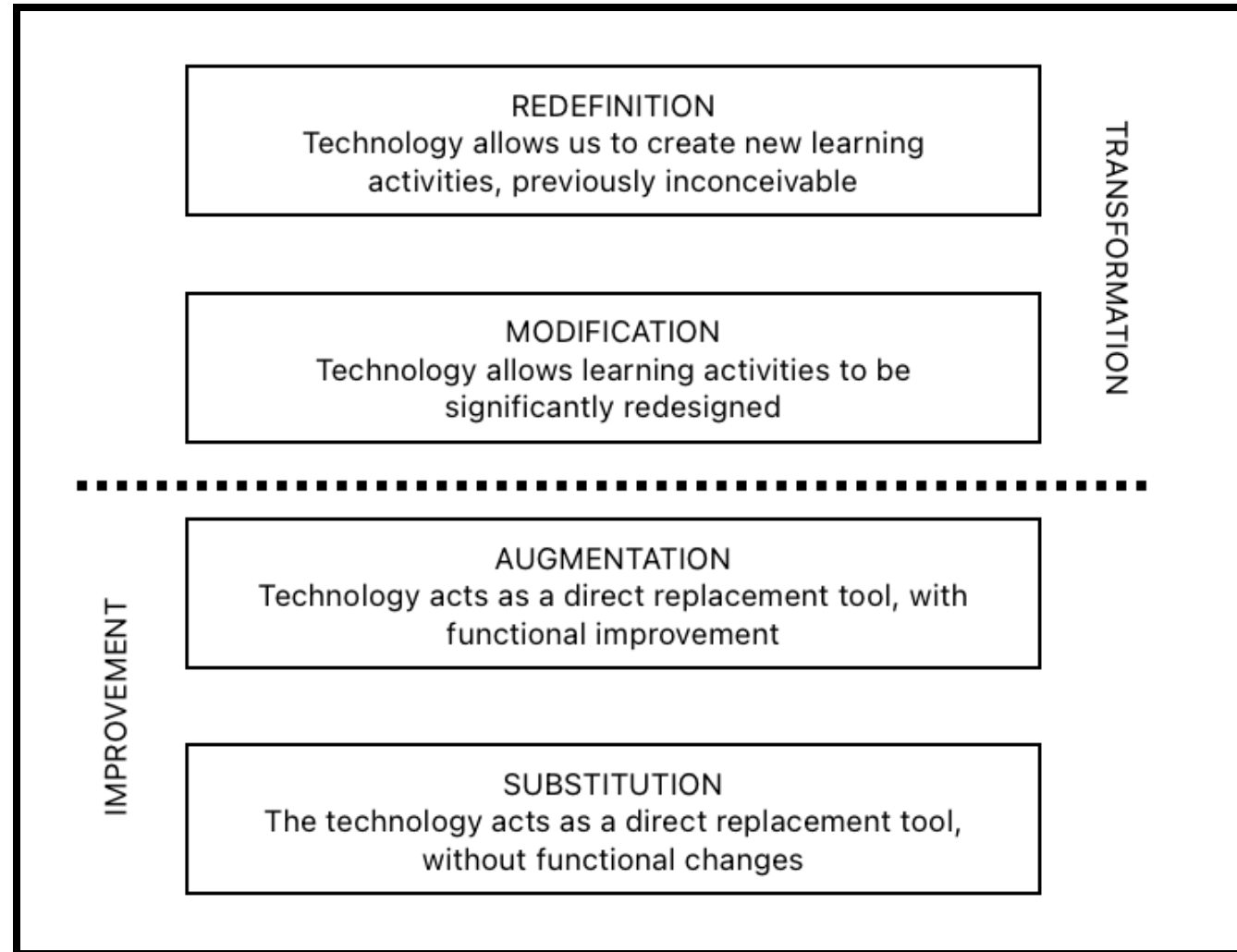
## ROLES

- Line-follow team (2 members)
- Programmers (2 members)
- Environment responsible (1 member)





# SAMR model





## FINAL QUESTIONNARIE BIP



**Acknowledgments.** Project **PID2021-122326OB-I00**  
financed by MCIN/AEI/10.13039/501100011033

