

# **Modeling of geochemical processes**

**Linear system of differential equations**

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## Modeling of geochemical processes

### Dynamic models

Matrix  $\mathbf{K}$  is diagonalized into  $\mathbf{U} \mathbf{\Lambda} \mathbf{U}^{-1}$  . Then

$$\frac{d\mathbf{x}}{dt} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^{-1} \mathbf{x}$$

Multiplying by  $\mathbf{U}^{-1}$  from left side gives  $\mathbf{U}^{-1} \frac{d\mathbf{x}}{dt} = \mathbf{\Lambda} \mathbf{U}^{-1} \mathbf{x}$

Because  $\mathbf{U}^{-1}$  is a matrix of constants, it is  $\frac{d\mathbf{U}^{-1}\mathbf{x}}{dt} = \mathbf{\Lambda} \mathbf{U}^{-1} \mathbf{x}$

Let us substitute for  $\mathbf{U}^{-1}\mathbf{x} = \mathbf{y}$  . Then  $\frac{d\mathbf{y}}{dt} = \mathbf{\Lambda} \mathbf{y}$

This equation can be split into a set of individual equations,  $\frac{dy_i}{dt} = \lambda_i y_i$  ,

which can be solved at initial conditions,  $t = 0$ ,  $y = y_0$  as  $y_i = e^{\lambda_i t} y_{i0}$

# Modeling of geochemical processes

## Dynamic models

The set of the equations can be expressed in vectors as

$$\mathbf{y} = e^{\Lambda t} \mathbf{y}_0 \quad \text{and, after re-substitution, as} \quad \mathbf{U}^{-1} \mathbf{x} = e^{\Lambda t} \mathbf{U}^{-1} \mathbf{x}_0$$

Multiplying matrix  $\mathbf{U}$  from left side gives the expression for vector  $\mathbf{x}$

$$\mathbf{x} = \mathbf{U} e^{\Lambda t} \mathbf{U}^{-1} \mathbf{x}_0$$

$$\mathbf{x} = \sum_i e^{\lambda_i t} (i^{\text{th}} \text{ column of } \mathbf{U})(i^{\text{th}} \text{ row of } \mathbf{U}^{-1}) \mathbf{x}_0$$

$$\mathbf{x} = \sum_i e^{\lambda_i t} \mathbf{U} \mathbf{e}_i \mathbf{e}_i^T \mathbf{U}^{-1} \mathbf{x}_0$$

$$\mathbf{x} = \sum_i e^{\lambda_i t} \mathbf{U}_i \mathbf{x}_0$$

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## Dynamic models

**Example:** system of differential equations

$$\frac{dx_1}{dt} = 2x_1$$

$$\frac{dx_2}{dt} = x_1 + x_2$$

$$\frac{d\mathbf{x}}{dt} = \begin{bmatrix} 2 & 0 \\ 1 & 1 \end{bmatrix} \mathbf{x}$$

Initial conditions:  $t = 0$ ,  $x_1 = 1$   $x_2 = -1$

$$\mathbf{x}_0 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\frac{d\mathbf{x}}{dt} = \mathbf{A} \mathbf{x}$$

$$\mathbf{A} = \begin{bmatrix} 2 & 0 \\ 1 & 1 \end{bmatrix} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^{-1} = \begin{bmatrix} \frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -\sqrt{2} & 0 \\ -1 & 1 \end{bmatrix}$$

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## Dynamic models

In general:

$$\mathbf{x} = e^{\lambda_1 t} \mathbf{U}_1 \mathbf{x}_0 + e^{\lambda_2 t} \mathbf{U}_2 \mathbf{x}_0$$

$$\mathbf{x} = e^{2t} \begin{bmatrix} \sqrt{2}/2 \\ \sqrt{2}/2 \end{bmatrix} \begin{bmatrix} -\sqrt{2} & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + e^t \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\mathbf{x} = e^{2t} \begin{bmatrix} -1 \\ -1 \end{bmatrix} + e^t \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

$$x_1 = -e^{2t}$$

$$x_2 = -e^{2t} - 2e^t$$