







## Purpose

- find reliable estimates of X(T) for large T(i.e. rare events),
- + even for  ${\mathcal T}$  larger than the period of observation, • including estimates of the uncertainty of X(T)
  - $min \{x_1, ..., x_n\} = -max\{x_1, ..., x_n\}$

### Main steps

- Choose an *appropriate* parametric distribution function
  Calibrate it such that it describes available data well
- Extrapolate distribution function

Which is "appropriate" distribution?











# Modelling Peak Over Threshold (POT)

• Select a threshold u

- should be large enough to be in asymptotic limit • Extract the exceedances from the dataset n values out of the total N data values
- exceedances need to be mutually independent
- Fit GPD to exceedances, yields conditional distr.: prob(X > x | X > u) = 1-GPD(x - u; σ, ξ)
  Estimate uncond. distribution and return values prob(X > x) = prob(X > u) · (1-GPD(x - u; σ, ξ)) with prob(X>u) estimated as n/N(the third model parameter)

Return values X(7) from the unconditional distribution

# Modelling Peak Over Threshold (POT)

 $\ensuremath{\mbox{Exceedances}}$  are identically distributed, may be violated e.g. by seasonality, by trends

- Exceedances are independent
- may be violated by serial correlation
- much more critical than for block maximum approach
  in general solved by *declustering* of original data
- e.g. exceedances should be separated by at least × days.



# Modelling Peak Over Threshold (POT)

## Threshold Selection

Fitting data to a GPD Over a Range of Thresholds and stability of the parameter estimates is checked





# **BM** versus POT

#### вм

- Theoretical assumptions are less critical in practice.
- Independence of maxima can be achieved by selecting large block size.
- More easy to apply
- Estimation uncertainties can be large because small sample size.

#### РОТ

- More efficient if a "small" threshold is justified. (More independent exceedances than block maxima.)
- Independence assumption is critical in practice. Need declustering techniques.
   Needs diagnostics for threshold selection. Choice somewhat ambiguous in practice.
- Less easy to apply in practice.

## **BM versus POT**

- The POT approach typically utilizes more of the available data than the block maxima approach.
- However, it can be common for threshold excesses to cluster above a high threshold; especially with atmospheric data – consequently confidence intervals too narrow
- The block maxima approach may include points that are not very extreme
- In some cases it might miss extreme values simply because a larger value occurred somewhere else in the block (e.g., the second, or third, point that exceeds the threshold).
- The block maxima approach typically satisfies the independence assumption to a good approximation, and is easily interpretable in terms of return values.

#### General comments

- When analyzing extremes of atmospheric phenomena, one often encounters **non-stationarity** in the data (the df is not constant over time)
- The df for the extremes may have a gradual trend or shift over time; even abrupt changes
- The usual method for analyzing such data is to fit an EVD with parameters that vary as a function of a **covariate** (e.g., time is often used)
- Validation and assesment of uncertainty
- Tests of goodness-of-fit
- Standard errors and confidence intervals .
- Q-Q plot comparison of observed and estimated quantiles • All observed extremes must be feasible to occur under the fitted distribution
- Otherwise shape parameter should be adjusted
- .
- Return level estimates for large T are prone to large sampling errors Confidence decreases rapidly when the period is more than about two
- times the length of the original data















