

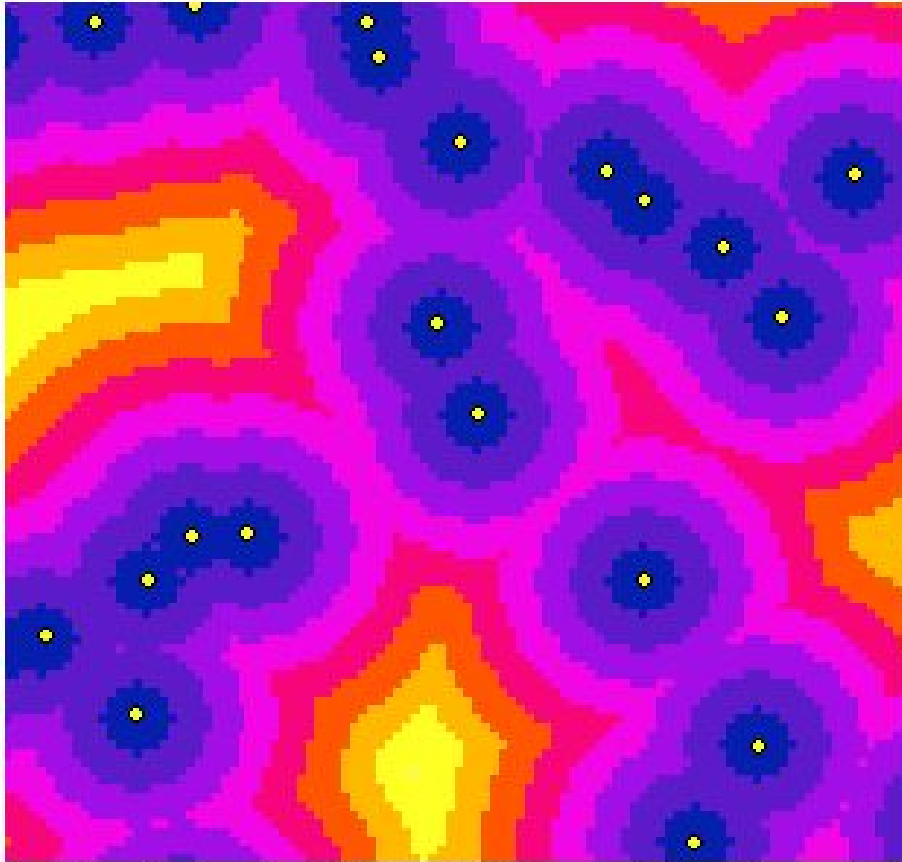
# 6 – VZDÁLENOSTNÍ ANALÝZY

# Distance Toolset

Tool	Description
<a href="#">Corridor</a>	Calculates the sum of accumulative costs for two input accumulative cost rasters.
<a href="#">Cost Allocation</a>	Calculates for each cell its nearest source based on the least accumulative cost over a cost surface.
<a href="#">Cost Back Link</a>	Defines the neighbor that is the next cell on the least accumulative cost path to the nearest source.
<a href="#">Cost Distance</a>	Calculates the least accumulative cost distance for each cell to the nearest source over a cost surface.
<a href="#">Cost Path</a>	Calculates the least-cost path from a source to a destination.
<a href="#">Euclidean Allocation</a>	Calculates, for each cell, the nearest source based on Euclidean distance.
<a href="#">Euclidean Direction</a>	Calculates, for each cell, the direction, in degrees, to the nearest source.
<a href="#">Euclidean Distance</a>	Calculates, for each cell, the direction, in degrees, to the nearest source.
<a href="#">Path Distance</a>	Calculates, for each cell, the least accumulative cost distance to the nearest source, while accounting for surface distance and horizontal and vertical cost factors.
<a href="#">Path Distance Allocation</a>	Calculates the nearest source for each cell based on the least accumulative cost over a cost surface, while accounting for surface distance and horizontal and vertical cost factors.
<a href="#">Path Distance Back Link</a>	Defines the neighbor that is the next cell on the least accumulative cost path to the nearest source, while accounting for surface distance and horizontal and vertical cost factors.

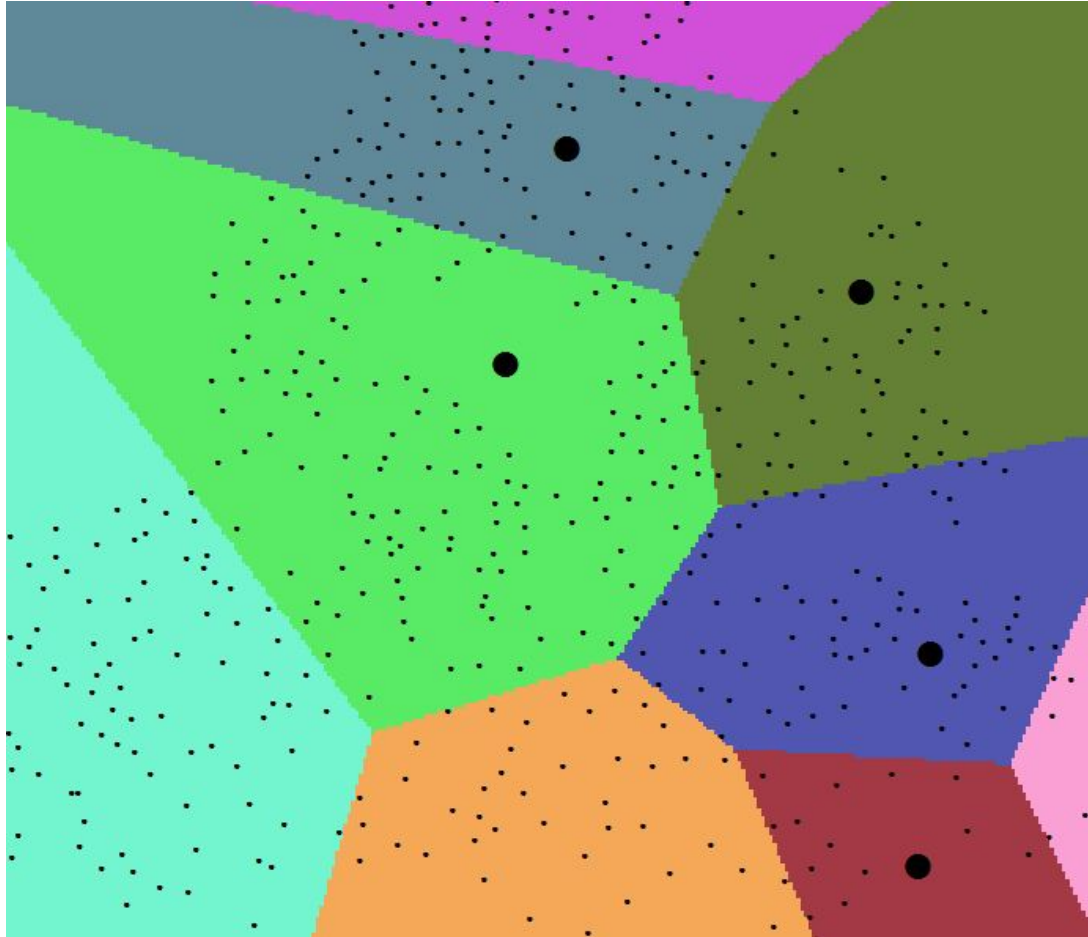
*Tools in the Distance toolset*

# I. Euclidian distance

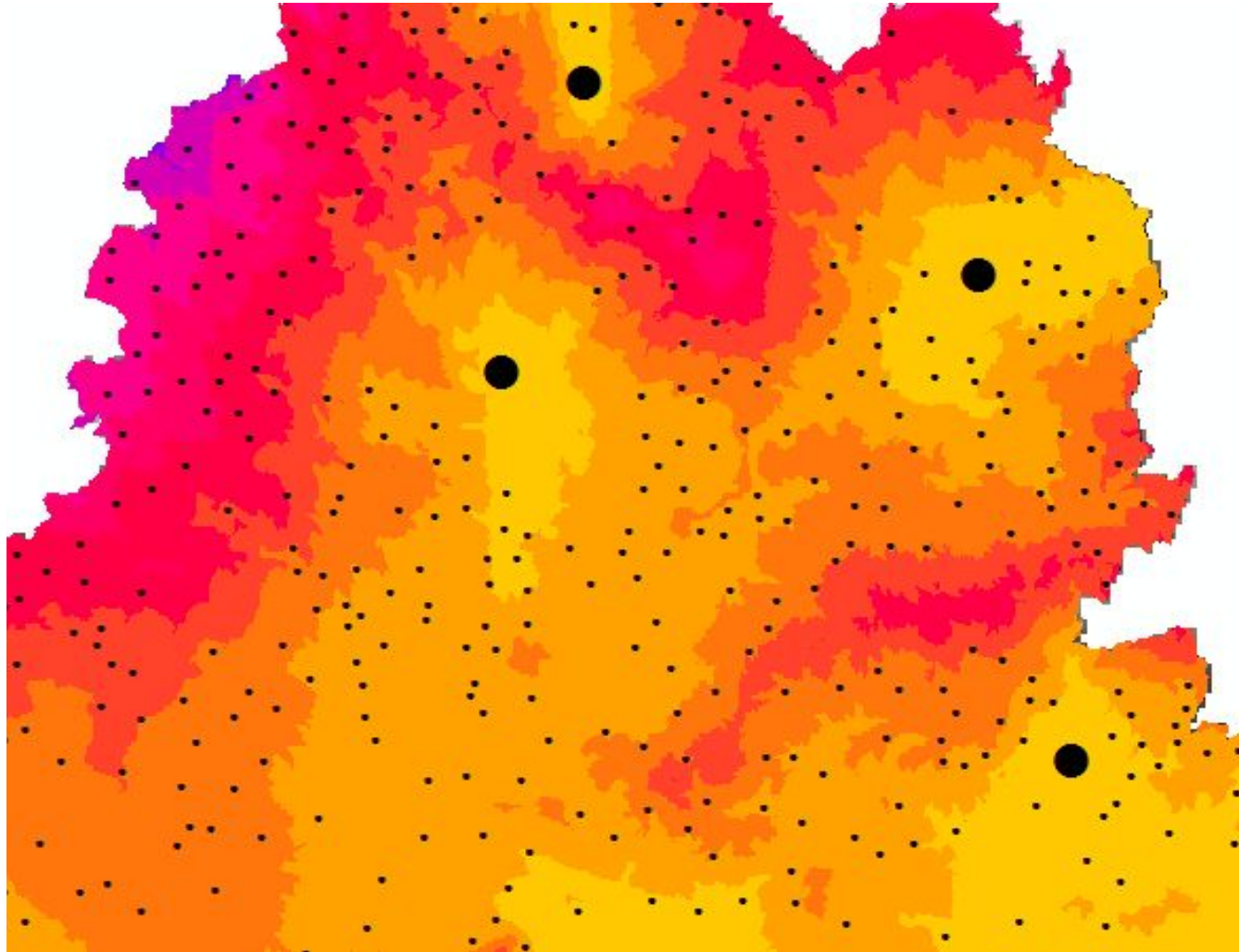


*Map showing the distance to the nearest town for each location*

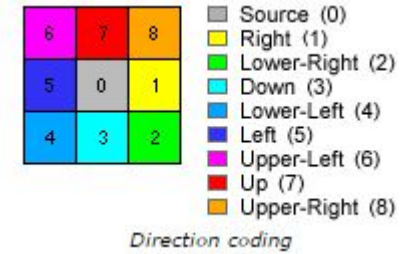
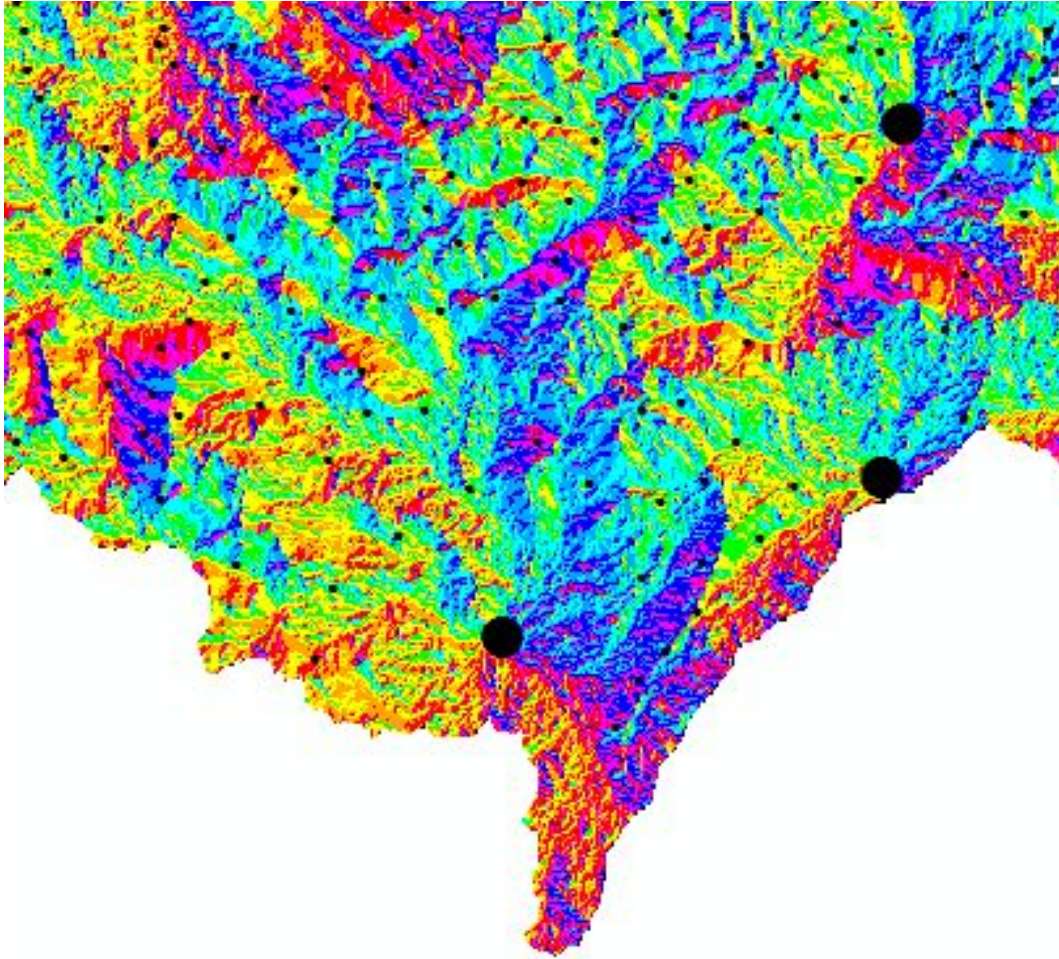
# II. Euclidian Allocation



# III. Cost Distance



# IV. Cost Backlink



# V. Cost Path

