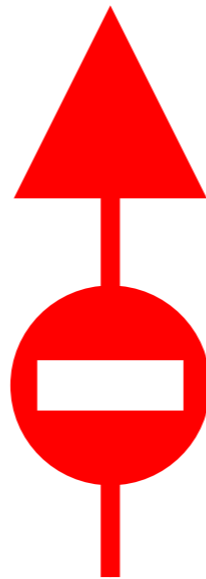


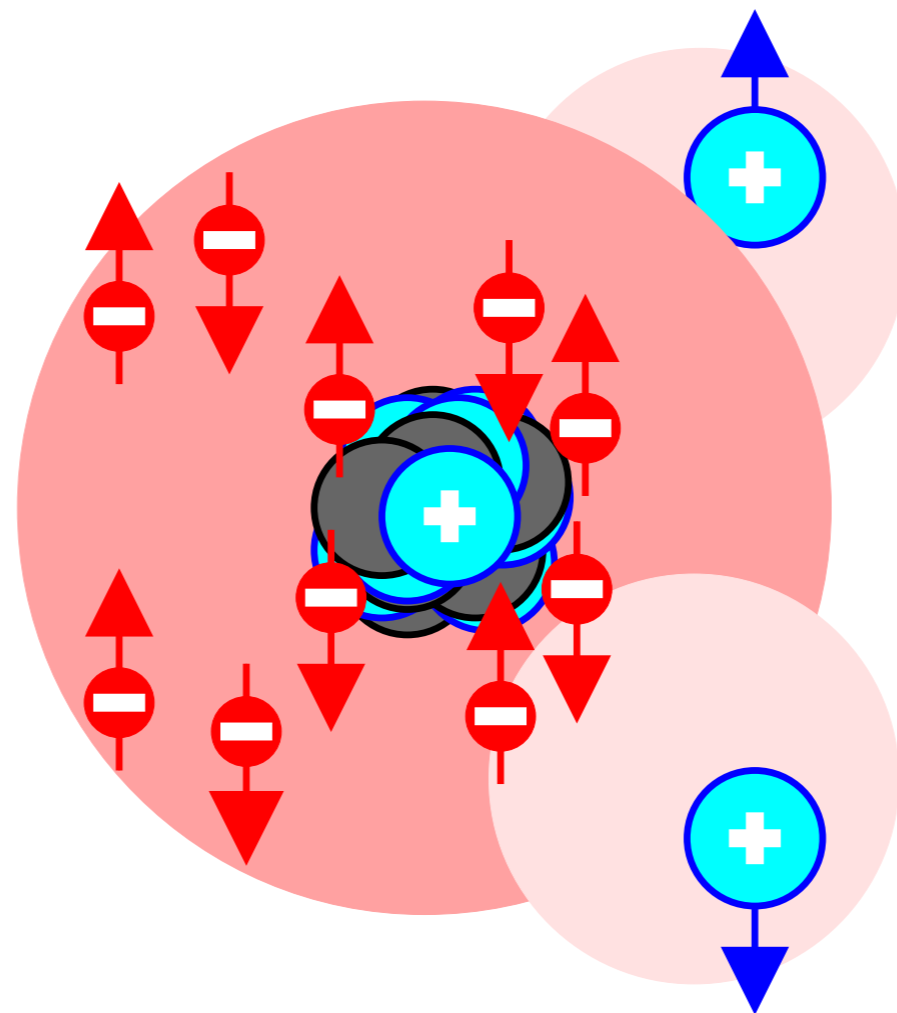
Lecture 6: Ensemble of non-interacting spins

1 particle:



$$\Psi(x, y, z, c_\alpha)$$

28 particles:

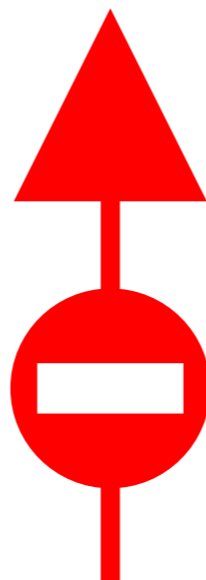


$$\Psi(x(\text{O}), x(\text{H1}), x(\text{H2}), x(\text{e1}), x(\text{e2}), \dots)$$

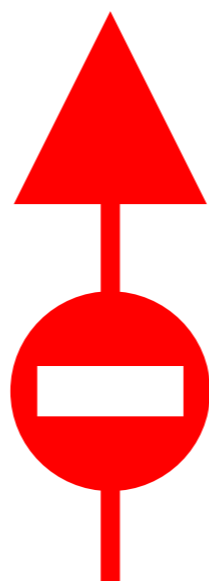
1 000 000 000 000 000 000 000 000 000 000 particles:



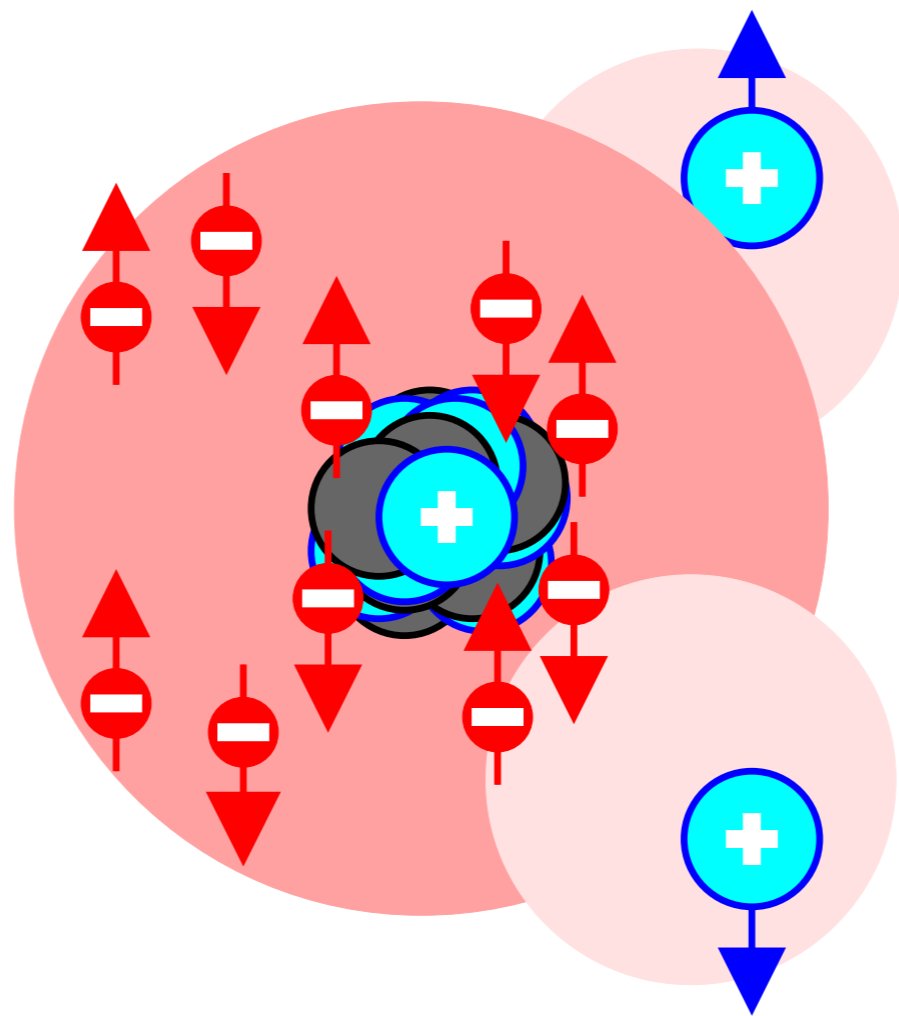
Ψ ???



$$\Psi(x, y, z, c_\alpha)$$



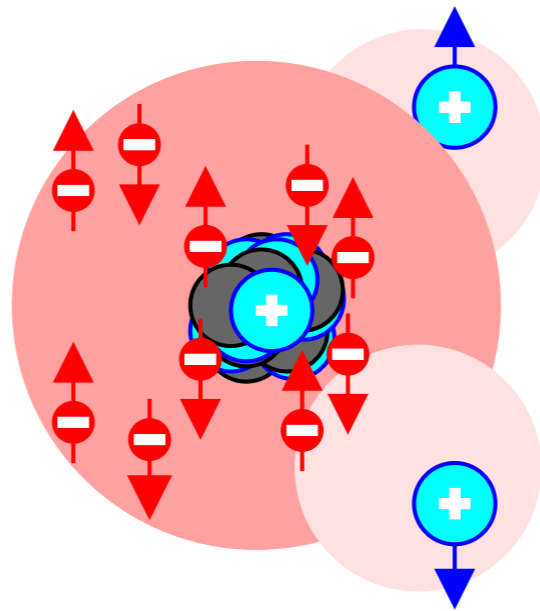
$$\psi = \sqrt{\frac{1}{h^3}} \cdot e^{\frac{i}{\hbar} p_x x} \cdot e^{\frac{i}{\hbar} p_y y} \cdot e^{\frac{i}{\hbar} p_z z} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$



$$\psi =$$

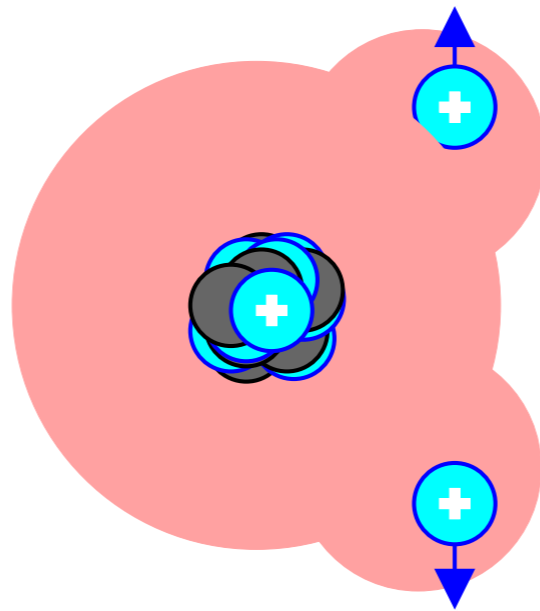
$$\phi(x(\text{O}), x(\text{H1}), x(\text{e1}), \dots) \cdot \psi(c_{\alpha,1}, c_{\alpha,2}) ?$$

- electron motions: $> 10^{16} \text{ s}^{-1}$
- molecular rotations: 10^8 s^{-1} (20 kDa protein) to 10^{12} s^{-1} (water)
- magnetic moment precession: $\sim 10^9 \text{ s}^{-1}$



- electron motions: $> 10^{16} \text{ s}^{-1}$
- molecular rotations: 10^8 s^{-1} (20 kDa protein) to 10^{12} s^{-1} (water)
- magnetic moment precession: $\sim 10^9 \text{ s}^{-1}$ at $B_0 = 24 \text{ T}$

electrons as "blurred cloud of a given shape":



● electron motions: 10^{16} s^{-1}

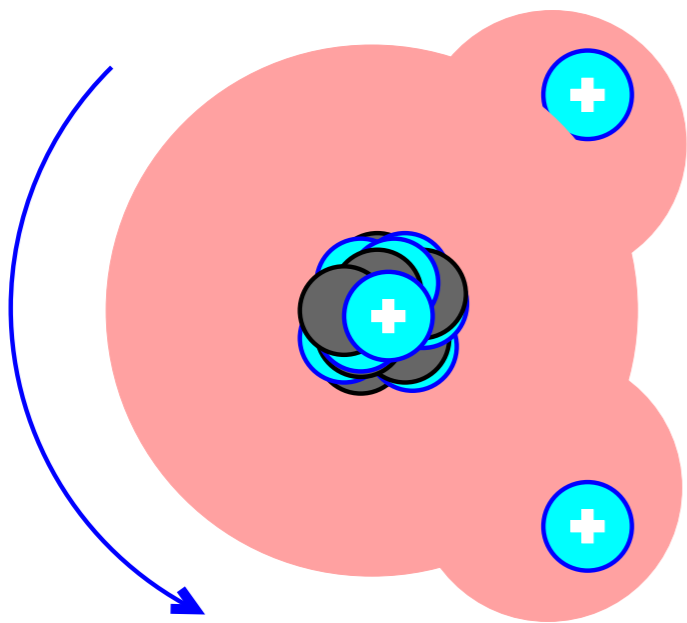
● molecular rotations: 10^8 s^{-1} (20 kDa protein) to 10^{12} s^{-1} (water)

● magnetic moment precession: $\sim 10^9 \text{ s}^{-1}$ at $B_0 = 24 \text{ T}$

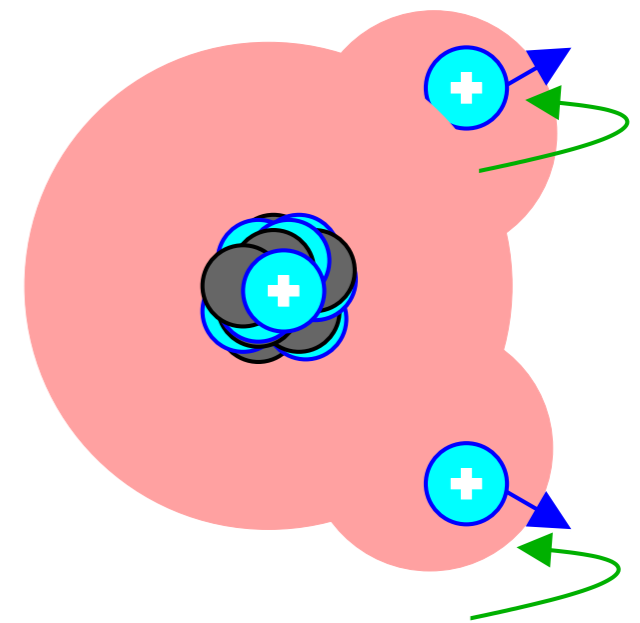
molecular motions

← almost independent →

magnetic moment precession



← almost independent →





$$\Psi = \phi(x_1, x_2, x_3, \dots) \cdot \psi(c_1, c_2, c_3, \dots)$$



$$\psi(c_1, c_2, c_3, \dots) = \psi_1(c_1) \cdot \psi_2(c_2) \cdot \psi_3(c_3) \dots ?$$

Is it possible to separate ψ of individual magnetic moments?

Yes, if interactions of magnetic moments

- depend only on external fields
⇒ interactions change energy eigenvalues, not eigenfunctions
- the external fields are homogeneous (same in the whole sample)
not true in MRI.

Then, $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ form basis for all ψ 's
⇒ operators are represented by 2×2 matrices.

Pure state:

Expected value $\langle A \rangle$ of a quantity A for *single nucleus*:

$$\langle A \rangle = \text{Tr} \left\{ \begin{pmatrix} c_\alpha c_\alpha^* & c_\alpha c_\beta^* \\ c_\beta c_\alpha^* & c_\beta c_\beta^* \end{pmatrix} \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \right\}$$

Mixed state:

Expected value $\langle A \rangle$ for *multiple nuclei with the same basis*:

$$\begin{aligned}\langle A \rangle &= \text{Tr} \left\{ \begin{pmatrix} c_{\alpha,1} c_{\alpha,1}^* & c_{\alpha,1} c_{\beta,1}^* \\ c_{\beta,1} c_{\alpha,1}^* & c_{\beta,1} c_{\beta,1}^* \end{pmatrix} \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} + \begin{pmatrix} c_{\alpha,2} c_{\alpha,2}^* & c_{\alpha,2} c_{\beta,2}^* \\ c_{\beta,2} c_{\alpha,2}^* & c_{\beta,2} c_{\beta,2}^* \end{pmatrix} \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} + \dots \right\} \\ &= \text{Tr} \left\{ \left(\begin{pmatrix} c_{\alpha,1} c_{\alpha,1}^* & c_{\alpha,1} c_{\beta,1}^* \\ c_{\beta,1} c_{\alpha,1}^* & c_{\beta,1} c_{\beta,1}^* \end{pmatrix} + \begin{pmatrix} c_{\alpha,2} c_{\alpha,2}^* & c_{\alpha,2} c_{\beta,2}^* \\ c_{\beta,2} c_{\alpha,2}^* & c_{\beta,2} c_{\beta,2}^* \end{pmatrix} + \dots \right) \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \right\} \\ &= \mathcal{N} \text{Tr} \left\{ \underbrace{\begin{pmatrix} \overline{c_{\alpha} c_{\alpha}^*} & \overline{c_{\alpha} c_{\beta}^*} \\ \overline{c_{\beta} c_{\alpha}^*} & \overline{c_{\beta} c_{\beta}^*} \end{pmatrix}}_{\hat{\rho}} \underbrace{\begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}}_{\hat{A}} \right\} = \mathcal{N} \text{Tr} \{ \hat{\rho} \hat{A} \}.\end{aligned}$$

$\hat{\rho}$ is the (probability) density matrix

- Two-dimensional basis for \mathcal{N} uncoupled nuclei.
- Statistical approach: *macroscopic* result – *mixed state*
no insight into *microscopic* states.
- Choice of the basis of ψ is encoded in definition of $\hat{\rho}$
(eigenfunctions of \hat{I}_z)
- The state is described not by a vector, but by a matrix
 $\hat{\rho}$ is a matrix like matrices representing the operators.

Populations

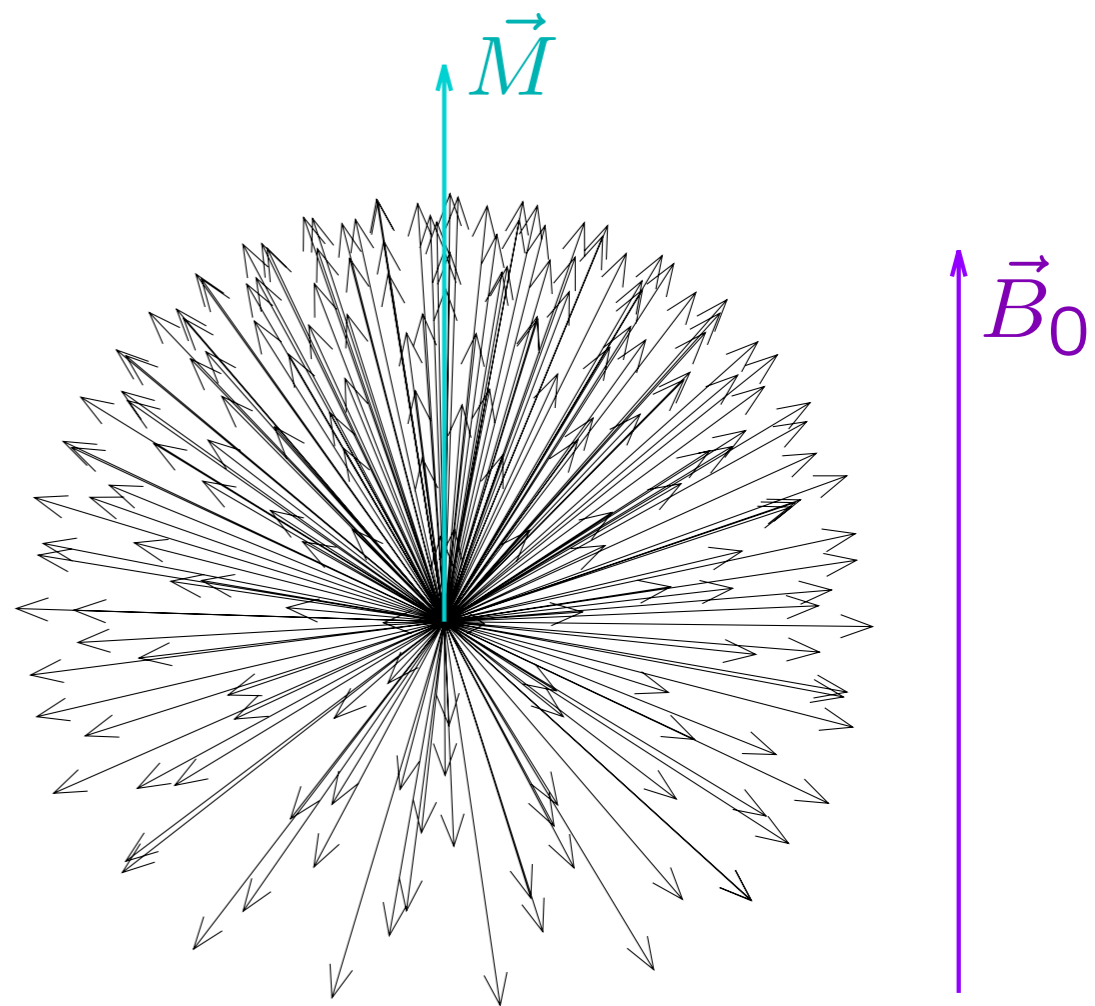
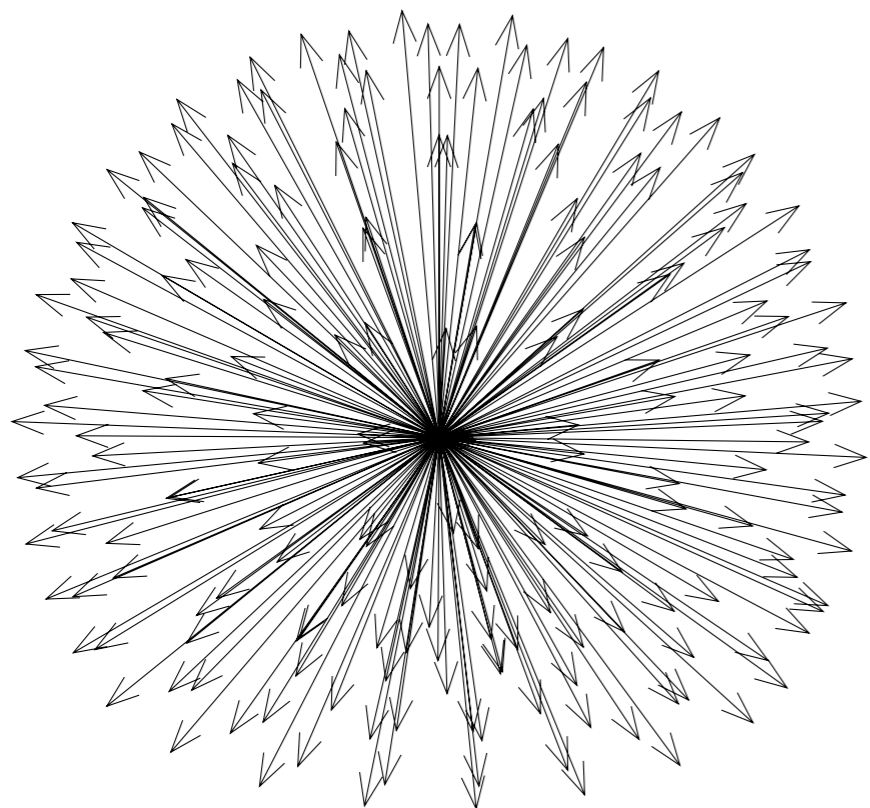
- *Diagonal elements* of $\hat{\rho}$ or matrices with diagonal elements only.
- describe *longitudinal polarization* of $\vec{\mu}$ (distribution along \vec{B}_0)
- real numbers, $\overline{c_\alpha c_\alpha^*} + \overline{c_\beta c_\beta^*} = 1$
- $\overline{c_\alpha c_\alpha^*} = 1/2$: no net polarization along \vec{B}_0
equal populations of the α and β states

It does not indicate that all spins must be either in α or β state!

Any combination of superposition states,

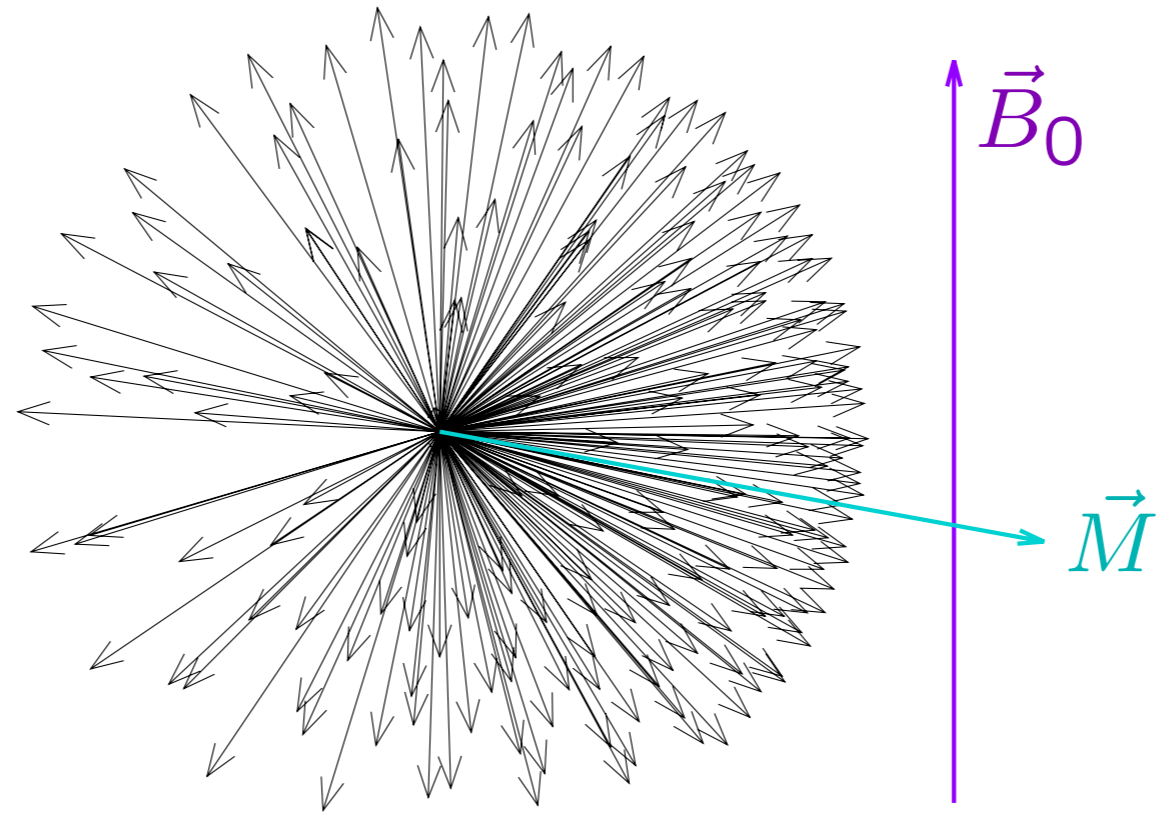
$\vec{\mu}$ pointing in all possible directions as long as $M_z = 0$

Probability of 50 % spins in α state, 50 % spins in β state negligible

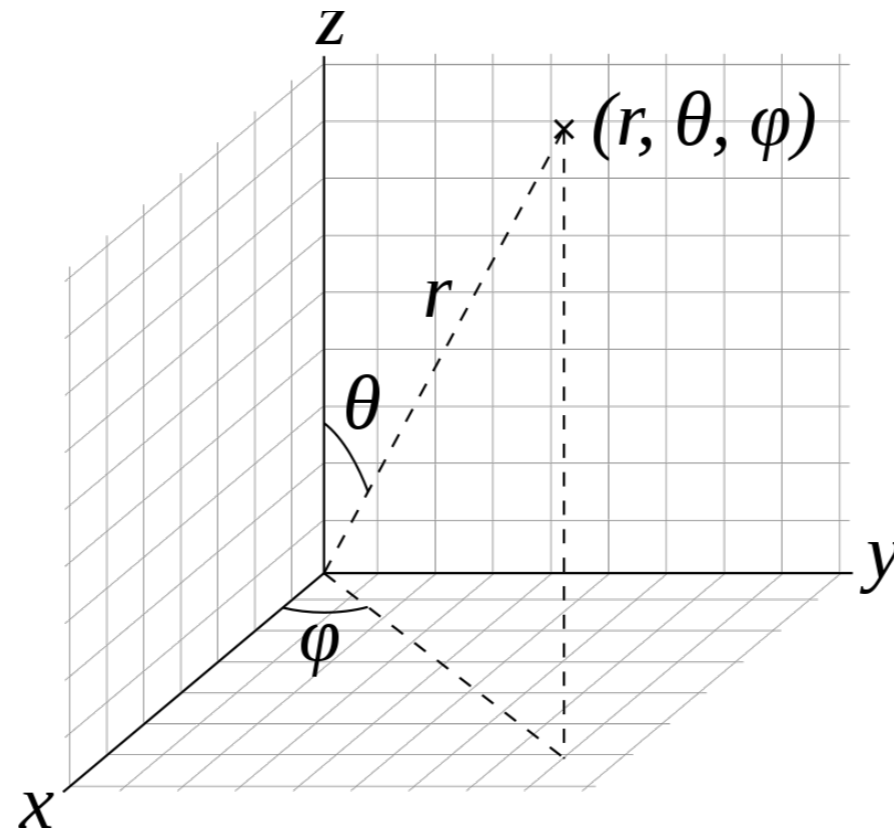


Coherences

- *Off-diagonal elements* or matrices with diagonal elements only
- *Pure state*: $c_\beta c_\alpha^* = |c_\alpha||c_\beta|e^{-i(\phi_\alpha - \phi_\beta)}$
- *Mixed state*: $\overline{c_\beta c_\alpha^*}$ is complex number $\overline{|c_\alpha||c_\beta|} \cdot \overline{e^{-i(\phi_\alpha - \phi_\beta)}}$
amplitude $\overline{|c_\alpha||c_\beta|}$, phase given by $e^{-i(\phi_\alpha - \phi_\beta)}$
- $\overline{c_\beta c_\alpha^*} \cdot \overline{c_\alpha c_\beta^*} = 1$
- Describe *transverse polarization* of $\vec{\mu}$ in the plane $\perp \vec{B}_0$
with magnitude $\overline{|c_\alpha||c_\beta|}$ and in direction given by the phase.
- *Incoherent superposition of states* α, β : $\overline{e^{-i(\phi_\alpha - \phi_\beta)}} = 0 \Rightarrow \overline{c_\beta c_\alpha^*} = 0$
- *Coherent superposition of states* α, β : $\overline{c_\beta c_\alpha^*} \neq 0$
- *Coherent evolution*: $\phi_{\alpha,j}$ and $\phi_{\beta,j}$ vary, but with identical frequency ω_0 for all j : $\overline{e^{-i(\phi_\alpha - \phi_\beta)}} = \overline{e^{-i(\phi_\alpha(0) - \phi_\beta(0))}} \cdot e^{i\omega_0 t}$



Phases and coherences



$$|\vartheta_j, \varphi_j\rangle = \begin{pmatrix} \cos \frac{\vartheta_j}{2} e^{-i\frac{\varphi_j}{2}} \\ \sin \frac{\vartheta_j}{2} e^{+i\frac{\varphi_j}{2}} \end{pmatrix} = \begin{pmatrix} c_{\alpha,j} \\ c_{\beta,j} \end{pmatrix} = c_{\alpha,j}|\alpha\rangle + c_{\beta,j}|\beta\rangle$$

$$\overline{c_{\beta}c_{\alpha}^*} = \overline{\cos \frac{\vartheta}{2} \sin \frac{\vartheta}{2} e^{+i\varphi}} = \frac{1}{2} \overline{\sin \vartheta e^{+i\varphi}} \quad 2 \sin a \cos a = \sin(2a)$$

Phases and coherences

Independent distribution of ϑ and φ :

$$\overline{c_\beta c_\alpha^*} = \overline{\cos \frac{\vartheta}{2} \sin \frac{\vartheta}{2} e^{+i\varphi}} = \frac{1}{2} \overline{\sin \vartheta e^{+i\varphi}} = \frac{1}{2} \overline{\sin \vartheta} \cdot \overline{e^{+i\varphi}}$$

Evolution in \vec{B}_0 : Hamiltonian $\hat{H} = -\gamma B_0 \hat{I}_z = \omega_0 \hat{I}_z$

$$c_\alpha(t) = c_\alpha(t=0) e^{+i\frac{\gamma B_0}{2}t} = \cos \frac{\vartheta}{2} e^{-i\frac{\varphi(t=0)}{2}} e^{-i\frac{\omega_0}{2}t}$$

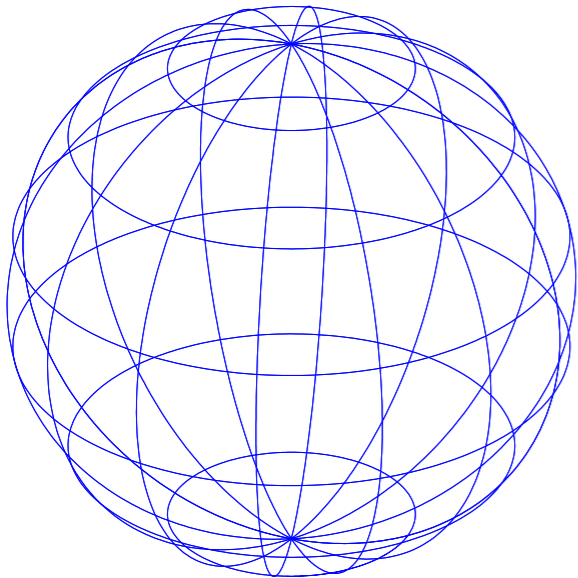
$$c_\beta(t) = c_\beta(t=0) e^{-i\frac{\gamma B_0}{2}t} = \sin \frac{\vartheta}{2} e^{+i\frac{\varphi(t=0)}{2}} e^{+i\frac{\omega_0}{2}t}$$

$$\overline{c_\beta c_\alpha^*}(t) = \frac{1}{2} \overline{\sin \vartheta} \overline{e^{i\varphi(t=0)}} e^{i\omega_0 t}$$

Coherent *evolution* if $\omega_0 = \gamma B_0$ is the same for all j

Phases and coherences

Defined $\varphi(t=0) = 0 \Rightarrow \vartheta$ distributed on the whole sphere

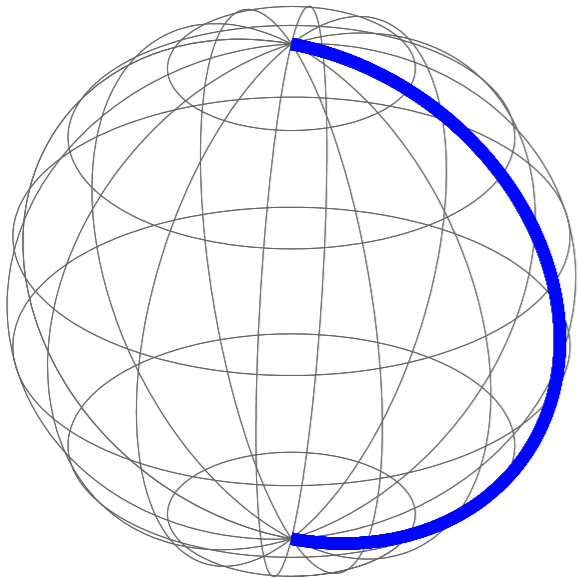


$$\overline{e^{i\varphi(t=0)}} = 0 \quad \Rightarrow \quad \overline{\cos \vartheta} = 0 \quad \overline{\sin \vartheta} = 0$$

Incoherent *superposition* of $|\alpha\rangle$ and $|\beta\rangle$

Phases and coherences

Random distribution of $\varphi(t=0) \Rightarrow \vartheta$ distributed on a meridian



$$\overline{e^{i\varphi(t=0)}} = 1 \quad \Rightarrow \quad \overline{\cos \vartheta} = 0 \quad \overline{\sin \vartheta} = \frac{1}{2}$$

Coherent *superposition* of $|\alpha\rangle$ and $|\beta\rangle$

Basis:

- Any 2×2 matrix can be written as a linear combination of four 2×2 matrices. Such four matrices can be used as a *basis*

Example:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = a \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + b \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + c \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Basis:

- A good basis is a set of *orthonormal* matrices:

$$\text{Tr}\{\hat{A}_j^\dagger \hat{A}_k\} = \delta_{jk}$$

$$j, k \in \{1, 2, 3, 4\},$$

$$\delta_{jk} = 1 \text{ for } j = k, \delta_{jk} = 0 \text{ for } j \neq k,$$

\hat{A}_j^\dagger is an *adjoint* matrix of \hat{A}_j

(*adjoint matrix*: matrix obtained from \hat{A}_j by exchanging rows and columns and replacing all numbers with their complex conjugates.)

E.g., for $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ and $\begin{pmatrix} e & f \\ g & h \end{pmatrix}$:

$$\text{calculate } \begin{pmatrix} a^* & c^* \\ b^* & d^* \end{pmatrix} \begin{pmatrix} e & f \\ g & h \end{pmatrix} = \begin{pmatrix} a^*e + c^*g & a^*f + c^*h \\ b^*e + d^*g & b^*f + d^*h \end{pmatrix}$$

$$\text{Trace: } a^*e + c^*g + b^*f + d^*h$$

Example:

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = a \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + b \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + c \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

The basis is orthonormal, e.g.:

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \text{ trace: } 0 + 0 = 0$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \text{ trace: } 0 + 0 = 1$$

Basis sets: Cartesian

$$\begin{aligned}\sqrt{2}\mathcal{I}_t &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & \sqrt{2}\mathcal{I}_z &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\ \sqrt{2}\mathcal{I}_x &= \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} & \sqrt{2}\mathcal{I}_y &= \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}\end{aligned}\quad (1)$$

$$\mathcal{I}_t = \frac{1}{2} \hat{1} \quad \mathcal{I}_x = \frac{1}{\hbar} \hat{I}_x \quad \mathcal{I}_y = \frac{1}{\hbar} \hat{I}_y \quad \mathcal{I}_z = \frac{1}{\hbar} \hat{I}_z \quad (2)$$

Basis sets: Single-element

$$\mathcal{I}_\alpha = \mathcal{I}_t + \mathcal{I}_z = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\mathcal{I}_\beta = \mathcal{I}_t - \mathcal{I}_z = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\mathcal{I}_+ = \mathcal{I}_x + i\mathcal{I}_y = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\mathcal{I}_- = \mathcal{I}_x - i\mathcal{I}_y = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad (3)$$

Basis sets: Mixed

$$\sqrt{2}\mathcal{I}_t = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \sqrt{2}\mathcal{I}_z = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\mathcal{I}_+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \mathcal{I}_- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad (4)$$

Liouville - von Neumann equation

evolution in time

$$\frac{d\hat{\rho}}{dt} = \frac{i}{\hbar}(\hat{\rho}\hat{H} - \hat{H}\hat{\rho}) = \frac{i}{\hbar}[\hat{\rho}, \hat{H}] = -\frac{i}{\hbar}[\hat{H}, \hat{\rho}] \quad (5)$$

or in the units of (angular) frequency

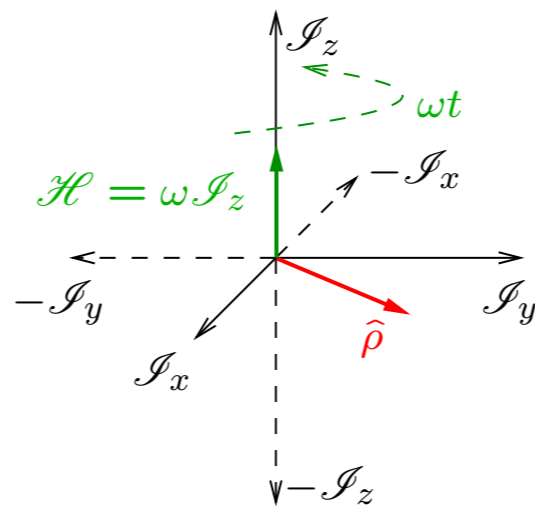
$$\frac{d\hat{\rho}}{dt} = i(\hat{\rho}\mathcal{H} - \mathcal{H}\hat{\rho}) = i[\hat{\rho}, \mathcal{H}] = -i[\mathcal{H}, \hat{\rho}]. \quad (6)$$

$$\mathcal{H} = \frac{1}{\hbar} \hat{H} \quad (7)$$

If $\hat{\rho} = c\mathcal{I}_j$, $\mathcal{H} = \omega\mathcal{I}_l$, and $[\mathcal{I}_j, \mathcal{I}_k] = \pm i\mathcal{I}_l$,
then the density matrix evolves as

$$\hat{\rho} = c\mathcal{I}_j \quad \longrightarrow \quad c\mathcal{I}_j \cos(\omega t) \pm c\mathcal{I}_k \sin(\omega t)$$

rotation about \mathcal{I}_l in abstract 3D space defined by the basis $\mathcal{I}_j, \mathcal{I}_k, \mathcal{I}_l$.



General strategy

1. Define $\hat{\rho}$ at $t = 0$
2. Describe evolution of $\hat{\rho}$ using the relevant Hamiltonians usually several steps
3. Calculate the expectation value of the measured quantity (magnetization components in the x, y plane) according to Eq. 1
$$\langle M_+ \rangle = \langle M_x + iM_y \rangle = \mathcal{N} \text{Tr} \{ \hat{\rho} \hat{M}_+ \}$$

The procedure requires knowledge of

1. relation(s) describing the initial state of the system ($\hat{\rho}(0)$)
2. all Hamiltonians (\mathcal{H})
3. the operator representing the measurable quantity (\hat{M}_+)

HOMework:

$$\hat{\rho}(0) = \mathcal{I}_y$$

$$\mathcal{H} = \omega \mathcal{I}_z$$

$$\omega = \pi \times 10^5 \text{ rad/s}$$

$$t = 2.5 \times 10^{-5} \text{ s}$$

