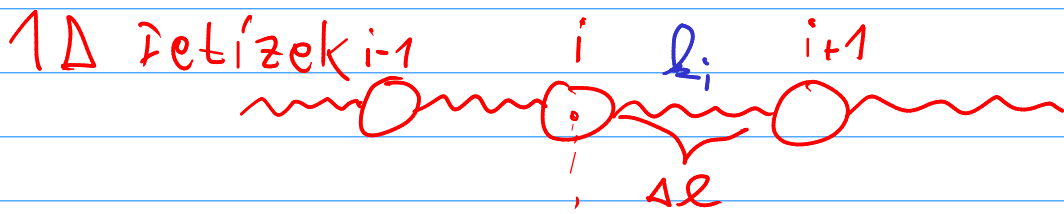
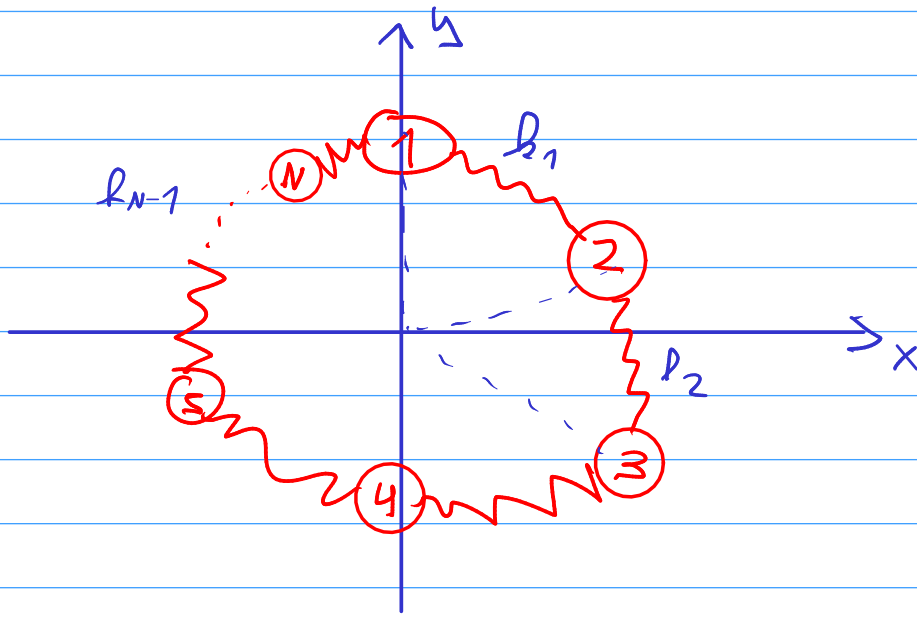


4 cvičení soustava N harmonických oscilátorů



$$T = \frac{1}{2} \sum m_i \dot{x}_i^2; \quad V = \frac{1}{2} \sum k_i (\underbrace{x_{i+1} - x_i}_{\Delta l})^2$$

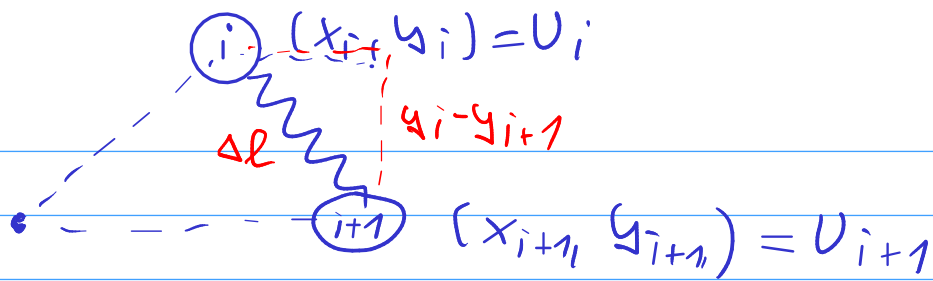
Souřadnice

①	$x_1, y_1; \quad U_1 = (x_1, y_1)$
②	$x_2, y_2; \quad U_2 = (x_2, y_2)$
⋮	
④	$x_N, y_N; \quad U_N = (x_N, y_N)$

$$\vec{U} = (U_1, \dots, U_N), \quad U_i$$

$$T = \frac{1}{2} \sum_{i=1}^N m_i (\dot{x}_i^2 + \dot{y}_i^2) = \frac{1}{2} \sum m_i \dot{U}_i^2$$

$$V = \frac{1}{2} \sum k_i (\Delta l_i)^2$$



$$\begin{aligned} \Delta l &= \sqrt{(x_i - x_{i+1})^2 + (y_i - y_{i+1})^2} \\ &= \sqrt{(x_{i+1} - x_i)^2 + (y_{i+1} - y_i)^2} \\ &= \sqrt{(U_{i+1} - U_i)^2} \end{aligned}$$

$$(x_{i+1}, y_{i+1}) - (x_i, y_i)$$

$$T = \frac{1}{2} \sum_{i=1}^N m_i (\dot{x}_i^2 + \dot{y}_i^2) = \frac{1}{2} \sum_{i=1}^N m_i \dot{U}_i^2$$

$$V = \frac{1}{2} \sum_{i=1}^{N-1} k_i (U_{i+1} - U_i)^2 + \frac{1}{2} k_N (U_N - U_1)^2$$

$$\vec{U} = (U_1, \dots, U_N)$$

$$\downarrow (U_{i+1})^2 - 2U_{i+1}U_i + U_i^2$$

$$T = \frac{1}{2} \dot{\vec{U}}^T M \dot{\vec{U}}$$

$$= \frac{1}{2} (\dot{U}_1 \dots \dot{U}_N) \begin{pmatrix} m_{11} & & \\ & \dots & \\ & & m_{NN} \end{pmatrix} \begin{pmatrix} \dot{U}_1 \\ \vdots \\ \dot{U}_N \end{pmatrix}$$

$$V = \frac{1}{2} \vec{U}^T K \vec{U}$$

$$\frac{1}{2} (U_1 \dots U_N) \begin{pmatrix} k_1 + k_N - k_1 & & -k_N \\ -k_1 & k_2 + k_3 & \\ & & \dots & k_{N-1} + k_N \end{pmatrix} \begin{pmatrix} U_1 \\ \vdots \\ U_N \end{pmatrix}$$

$$b_i = b$$

$$\begin{pmatrix} 2b & -b & & & \\ -b & 2b & & & \\ & & \ddots & & \\ & & & 2b & -b \\ -b & & & & 2b \end{pmatrix}$$

$$= b \begin{pmatrix} 2 & -1 & & & \\ -1 & 2 & & & \\ & & \ddots & & \\ & & & 2 & -1 \\ -1 & & & & 2 \end{pmatrix}$$

$$L = T - V = \frac{1}{2} \dot{v}_i M_{ij} \dot{v}_j - \frac{1}{2} v_i k_{ij} v_j$$

$$\frac{\partial L}{\partial v_B} = \frac{d}{dt} \frac{\partial L}{\partial \dot{v}_B}$$

$$\frac{\partial L}{\partial v_B} = -\frac{1}{2} \delta_{iB} k_{ij} v_j - \frac{1}{2} v_i k_{iB}$$

$$= -\frac{1}{2} \underline{k_{Bj}} v_j - \frac{1}{2} v_i \underline{k_{iB}} = -\vec{v}^T \underline{k} = v^i k_{iB}$$

$$k = k^T \Leftrightarrow k_{ij} = k_{ji}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{v}_B} = \ddot{v} M$$

$$\ddot{U} M = -K U$$



$$m_i = m$$

$$b_i = b$$

$$\ddot{U} m \mathbf{1} = -b \begin{pmatrix} -1 & 2 & -1 \\ & & \\ & & \end{pmatrix} U / m$$

$$\omega^2 = \frac{b}{m}$$

$$\ddot{U} = -\omega^2 A U$$

$A \Rightarrow$ vl. vektory

vl. hodnoty

trik z QM.

$$S ; \quad AS = SA \quad \langle v_1, \dots, v_n \rangle$$

vl. hodnoty $S \Rightarrow$ vl. vektory $S =$

vl. vektory $A \Rightarrow$ vl. hodnoty A

$$A v_A = \lambda_A v_A$$

$$S \tilde{v}_B = \lambda_B \tilde{v}_B$$

$$AS = SA$$

$$AS v_A = S A v_A$$

$$A(S v_A) = \lambda_A (S v_A)$$