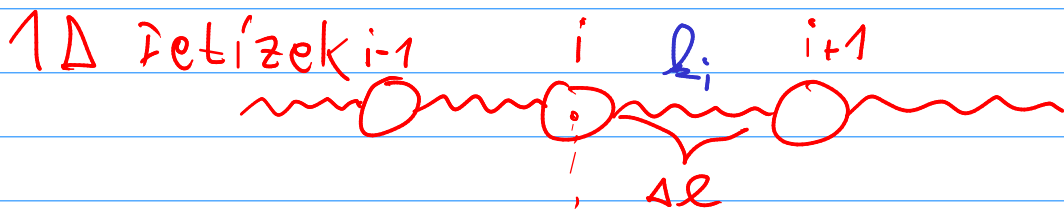
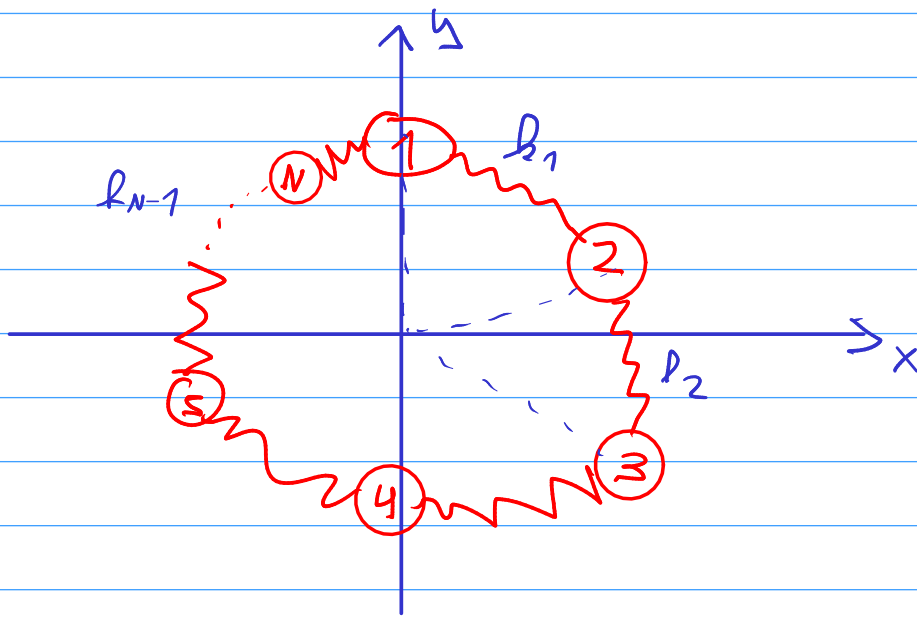


4 cvičení soustava N harmonických oscilátorů



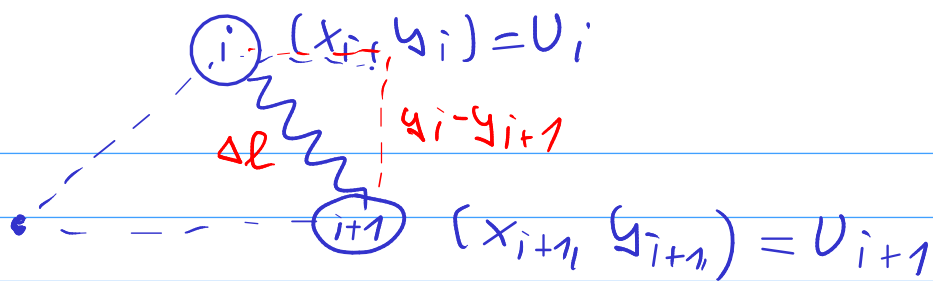
$$T = \frac{1}{2} \sum m_i \dot{x}_i^2; \quad V = \frac{1}{2} \sum k_i (\underbrace{x_{i+1} - x_i}_{\Delta l})^2$$

- Souřadnice
- ① $x_1, y_1; \quad U_1 = (x_1, y_1)$
 - ② $x_2, y_2; \quad U_2 = (x_2, y_2)$
 - ⋮
 - ④ $x_N, y_N; \quad U_N = (x_N, y_N)$

$$\vec{U} = (U_1, \dots, U_N), \quad U_i$$

$$T = \frac{1}{2} \sum_{i=1}^N m_i (\dot{x}_i^2 + \dot{y}_i^2) = \frac{1}{2} \sum m_i \dot{U}_i^2$$

$$V = \frac{1}{2} \sum k_i (\Delta l_i)^2$$



$$\begin{aligned} \Delta l &= \sqrt{(x_i - x_{i+1})^2 + (y_i - y_{i+1})^2} \\ &= \sqrt{(x_{i+1} - x_i)^2 + (y_{i+1} - y_i)^2} \\ &= \sqrt{(U_{i+1} - U_i)^2} \end{aligned}$$

$$(x_{i+1}, y_{i+1}) - (x_i, y_i)$$

$$T = \frac{1}{2} \sum_{i=1}^N m_i (\dot{x}_i^2 + \dot{y}_i^2) = \frac{1}{2} \sum_{i=1}^N m_i \dot{U}_i^2$$

$$V = \frac{1}{2} \sum_{i=1}^{N-1} k_i (U_{i+1} - U_i)^2 + \frac{1}{2} k_N (U_N - U_1)^2$$

$$\vec{U} = (U_1, \dots, U_N)$$

$$\downarrow (U_{i+1})^2 - 2U_{i+1}U_i + U_i^2$$

$$T = \frac{1}{2} \dot{\vec{U}}^T M \dot{\vec{U}}$$

$$= \frac{1}{2} (\dot{U}_1 \dots \dot{U}_N) \begin{pmatrix} m_{11} & & \\ & \dots & \\ & & m_{NN} \end{pmatrix} \begin{pmatrix} \dot{U}_1 \\ \vdots \\ \dot{U}_N \end{pmatrix}$$

$$V = \frac{1}{2} \vec{U}^T K \vec{U}$$

$$\frac{1}{2} (U_1 \dots U_N) \begin{pmatrix} k_1 + k_N - k_1 & & -k_N \\ -k_1 & k_2 + k_3 & \\ & & \dots \\ -k_N & & k_{N-1} + k_N \end{pmatrix} \begin{pmatrix} U_1 \\ \vdots \\ U_N \end{pmatrix}$$

$$M\ddot{U} = -KU$$



$$m_i = m$$

$$b_i = b$$

$$\ddot{U} m \mathbf{1} = -k \begin{pmatrix} -1 & 2 & -1 \\ -1 & & \end{pmatrix} U / m$$

$$\omega^2 = \frac{k}{m}$$

$$\ddot{\vec{U}} = -\omega^2 A \vec{U}$$

$A \Rightarrow$ vl. vektory

vl. hodnoty

$$V = c e^{-\omega^2 A t}$$

trik z QM.

$$S ; \quad AS = SA \quad \langle v_1, \dots, v_n \rangle$$

vl. hodnoty $S \Rightarrow$ vl. vektory $S =$

vl. vektory $A \Rightarrow$ vl. hodnoty A

$$A v_\alpha = \lambda_\alpha v_\alpha$$

$$S \tilde{v}_\beta = \lambda_\beta \tilde{v}_\beta$$

$$AS = SA$$

$$AS v_\alpha = S A v_\alpha$$

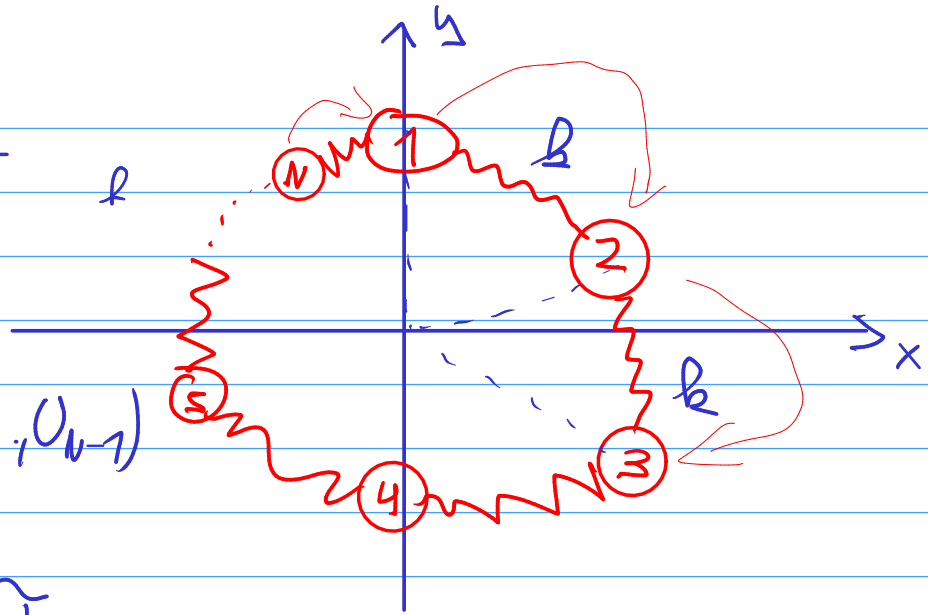
$$A(S v_\alpha) = \lambda_\alpha (S v_\alpha)$$

Cvičení 5

$$\vec{U} = (U_1, \dots, U_N)$$

$$\vec{Q} = (U_{N-1}, U_1, U_2, \dots, U_{N-1})$$

$$U \cdot S = \vec{Q}$$



$$(U_1 \dots U_N) \begin{pmatrix} 0 & 1 & & & \\ & \ddots & \ddots & & \\ & & \ddots & \ddots & \\ & & & \ddots & \ddots \\ 1 & & & & 0 \end{pmatrix} = (U_N, U_1, \dots, U_{N-1})$$

$$-\omega^2 A U = \ddot{U} \quad | \cdot S$$

$$-\omega^2 S A U = S \ddot{U}$$

$$-\omega^2 \tilde{A} \tilde{U} = \tilde{\ddot{U}}$$

$$S A = A S$$

$$\begin{pmatrix} 0 & 1 & & & \\ & \ddots & \ddots & & \\ & & \ddots & \ddots & \\ & & & \ddots & \ddots \\ 1 & & & & 0 \end{pmatrix} \begin{pmatrix} 2 & -1 & & & -1 \\ & \ddots & \ddots & & \\ & & \ddots & \ddots & \\ & & & \ddots & \ddots \\ -1 & & & & -12 \end{pmatrix} = \begin{pmatrix} -12 & -1 & & & 0 \\ 0 & -12 & -1 & & \\ & & \ddots & \ddots & \\ & & & \ddots & \ddots \\ -1 & & & & -12 \\ & & & & -12 & -1 \\ & & & & -12 & -1 \\ & & & & -12 & -1 \end{pmatrix}$$

S
A

$$AS = SA$$

$$AU = \lambda U$$

$$SV = \lambda^S V$$

$$ASU = SAU$$

$$= S\lambda^A U$$

$$= \lambda^A SU$$

U je v.l.v. A s λ^A

SU je v.l.v. A s λ^A

je-li λ^A násobná $\langle U \rangle \sim 1 \text{ dim}$

$$SU = cU$$

\Rightarrow vl. hodnoty matice $S = \begin{pmatrix} \lambda^1 & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \lambda^{N-1} \\ & & & & 1 \\ & & & & & 0 \end{pmatrix}$

$$S^N = I$$

$$SU = \lambda U \quad \vdots \quad S^{N-1}U = \lambda^{N-1}U$$

$$S^N U = \lambda^N U$$

$$U = \lambda^N U \Rightarrow \lambda^N = 1$$

$$\det(S - I) = 0$$

$$\begin{vmatrix} -\lambda & & & & \\ & -\lambda & & & \\ & & \ddots & & \\ & & & -\lambda & \\ & & & & 1 \\ & & & & & -\lambda \end{vmatrix}$$

$$= -\lambda \cdot (-1)^{1+1} \cdot D_{N-1}$$

$$+ 1 \cdot (-1)^{N+1} \cdot S_{N-1}$$

(*)

$$A_{N-1} = \begin{vmatrix} -\lambda & & & \\ & \ddots & & \\ & & -\lambda & \\ & & & -\lambda \end{vmatrix} = -\lambda \cdot A_{N-2} = -\lambda^{N-3} \cdot D_2 = -\lambda^{N-1}$$

$$A_2 = \begin{vmatrix} -\lambda & 1 \\ 0 & -\lambda \end{vmatrix} = -\lambda^2$$

$$S_{N-1} = \begin{vmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{vmatrix} = 1 \cdot S_{N-2} = S_2 = 1$$

$$\begin{vmatrix} 1 & 0 \\ \lambda & 1 \end{vmatrix} = 1$$

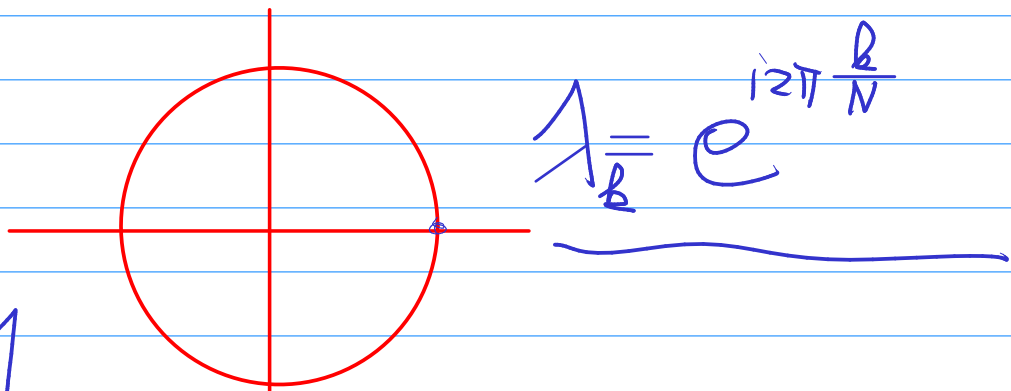
$$(*) = (-\lambda)^N + (-1)^{N-1} = (-1)^N (\lambda^N - 1) = 0$$

$$\lambda^N = 1$$

$$\lambda = r e^{i\varphi}$$

$$r e^{iN\varphi} = 1$$

$$e^{iN\varphi} = e^{i2\pi k}$$



$$S \vec{u}_k = \lambda_k u_k$$

$$\begin{pmatrix} 0 & 1 & & \\ & \ddots & & \\ & & 1 & \\ 1 & & 0 & 1 \end{pmatrix} \vec{u}_k = e^{i2\pi k/N} u_k \quad k \in \{1, \dots, N\}$$

$$\vec{U} = (U_1, \dots, iUN)$$

$$\vec{U}_R = (U_1^R, \dots, U_N^R)$$

$$U_1^R = e^{2\pi i \frac{k}{N}}$$

$$U_2^R = e$$

$$U_3^R = -1$$

$$\vdots$$

$$U_N^R = -1$$

$$\left(e^{2\pi i \frac{k}{N} \cdot 0}, e^{2\pi i \frac{k}{N} \cdot 1}, e^{2\pi i \frac{k}{N} \cdot 2}, \dots, e^{2\pi i \frac{k}{N} \cdot (N-1)} \right)$$

$$\left(1, e^{2\pi i \frac{k}{N}}, \left(e^{2\pi i \frac{k}{N}} \right)^2, \dots, \left(e^{2\pi i \frac{k}{N}} \right)^{N-1} \right)$$

= U_k

$$U^1 = \left(1, e^{2\pi i \frac{1}{N}}, \left(e^{2\pi i \frac{1}{N}} \right)^2, \dots, 1 \right)$$

$$U^2 = \left(1, e^{2\pi i \frac{2}{N}}, \dots \right)$$

vl. vektory $S \Rightarrow$ vl. vektory A

$$A \cdot \vec{U}_R = \lambda_R \vec{U}_R$$

$$A \begin{pmatrix} U_1^R \\ \vdots \\ U_N^R \end{pmatrix} = \lambda_R \begin{pmatrix} U_1^R \\ \vdots \\ U_N^R \end{pmatrix}$$

$$2U_1^R - U_2^R - U_N^R = \lambda_R U_1^R$$

$$2 \cdot 1 - 1 \cdot e^{2\pi i \frac{k}{N}} - e^{2\pi i \frac{k}{N} (N-1)} = \lambda_R \cdot 1$$

$$2 - e^{2\pi i \frac{b}{N}} - e^{2\pi i k - \frac{2\pi i k}{N}} = 1k$$

$$2 - e^{2\pi i \frac{k}{N}} - e^{\frac{-2\pi i k}{N}} = 1k$$

$$\cos(\) + i\sin(\) \quad \cos(\) - i\sin(\)$$

$$2 - \left(2 \cos \frac{2\pi k}{N} \right) = 1k$$

$$2 \left(1 - \cos \frac{2\pi k}{N} \right) = 1k \in \mathbb{R} \checkmark$$

Nepovinný AÚ t, x

$$L = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} k x^2$$

Přičete k L nějaký triviální L_0
tak aby výsledný $L+L_0$ $\neq \dot{x}$ ale jenom x, x