

## 6 cvičení Spec. typy Lagrangianů

### 1) Triviální Lagrangiany

$$L = \frac{1}{2} m \dot{x}^2$$

$$L_0 = ? \quad \text{tak že } L + L_0 \sim (t, x, \dot{x})$$

$$L_0 = \frac{d}{dt} (f(t, x, \dot{x}))$$

$$= \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x} \dot{x} + \frac{\partial f}{\partial \dot{x}} \ddot{x}$$

$$- \frac{1}{2} m \ddot{x} x$$

$$\int \frac{1}{2} m \dot{x}^2 dt = \frac{1}{2} m \int \dot{x} \dot{x} dt \\ = - \frac{1}{2} m \int x \ddot{x}$$

- per partes
- inverzní variační problém

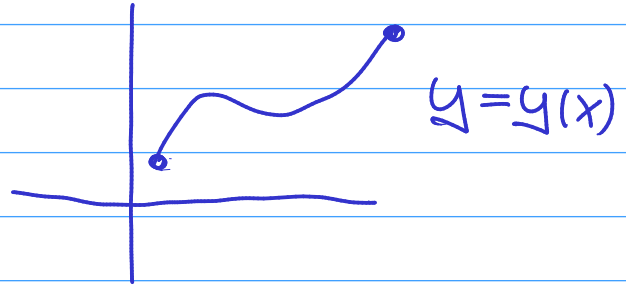
$$\frac{\partial^2 y}{\partial t^2} - \frac{\partial y^2}{\partial x^2} = 0$$

$$y = y(x, t)$$

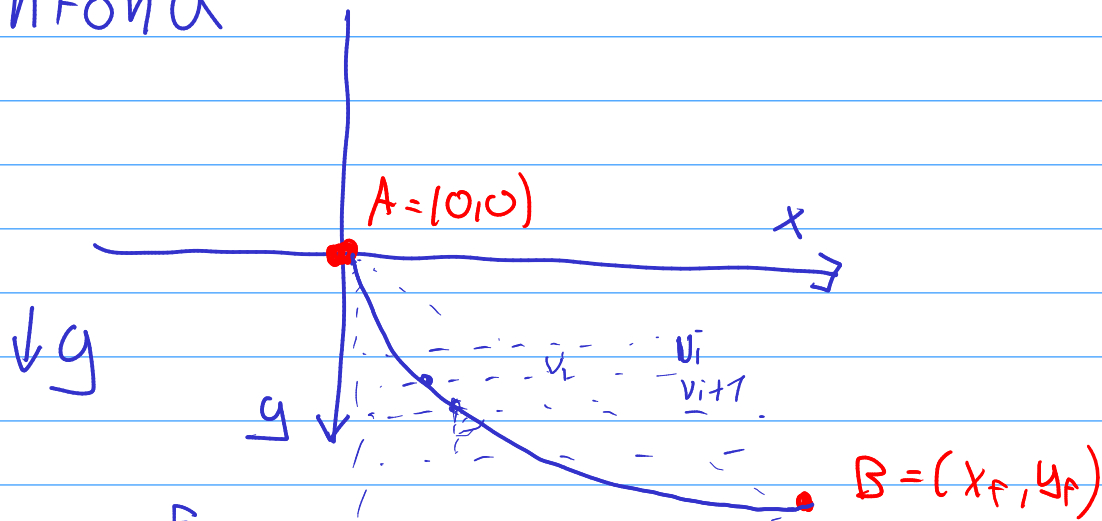
$$L = \frac{1}{2} m \left( \frac{\partial^2 y}{\partial t^2} - \frac{\partial^2 y}{\partial x^2} \right) + \frac{d}{dt} f(y, y_x, y_t)$$

$$L = \frac{1}{2} m \left( \left( \frac{\partial y}{\partial t} \right)^2 - \left( \frac{\partial y}{\partial x} \right)^2 \right)$$

2)  $L = L(y, y')$



### Brachistochrone



$$T = \int_0^T dt = \int_0^F \frac{ds}{v}$$

$$\frac{1}{2} m v^2 = m g y$$

$$I[y] = \int_0^{x_f} \frac{\sqrt{1 + y'(x)^2}}{\sqrt{2gy}} dx$$

$L$

$$v = \sqrt{2gy}$$

$$L = T - V$$

$$L = \frac{\sqrt{1+y'(x)^2}}{\sqrt{2gy}}$$

$$\frac{\partial L}{\partial y'} y' - L = \text{konst}$$

$$\frac{1}{\sqrt{2gy}} \frac{y'}{\sqrt{1+y'^2}} - \frac{\sqrt{1+y'(x)^2}}{\sqrt{2gy}} = k$$

$$\Rightarrow \frac{y'^2 - (1+y'^2)}{\sqrt{2gy} \sqrt{1+y'^2}} = \frac{-1}{\sqrt{2gy(1+y'^2)}} = k$$

$$2gy(1+y'^2) = C$$

$$y' = \sqrt{\frac{K-y}{y}}$$

$$\cos^2 x + \sin^2 x = 1$$

$$x = x_0 + \int \sqrt{\frac{y}{K-y}} dy = \left. \begin{array}{l} y = K \sin^2 t \\ dy = 2K \sin t \cos t dt \end{array} \right\}$$

$$\sqrt{\frac{y}{K(1-\frac{y}{K})}}$$

$$\Rightarrow x = x_0 + \int dt \sqrt{\frac{K \sin^2 t}{K \cos^2 t}} \quad K \sin t \cos t$$

$$x = x_0 + \int dt k \sin^2 t$$

$$x = x_0 + kt - \frac{k}{2} \sin 2t \quad \left( \begin{array}{l} x(0) = 0 \\ \Rightarrow x_0 = 0 \end{array} \right)$$

$$y = k \sin^2 t = \frac{k}{2} - \frac{k}{2} \cos 2t$$

$$x = R(\theta - \sin \theta)$$

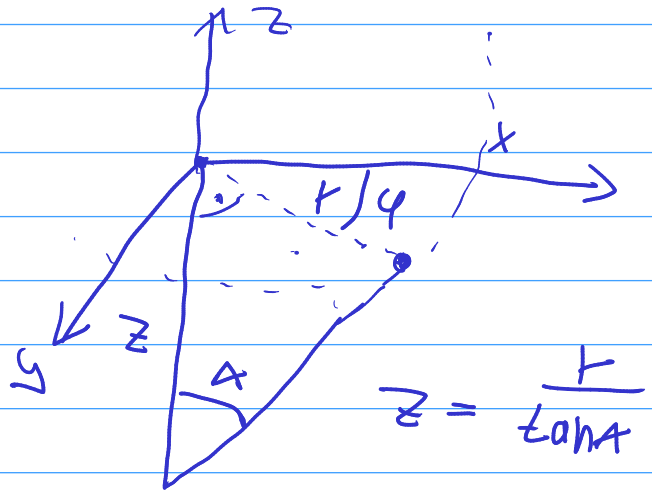
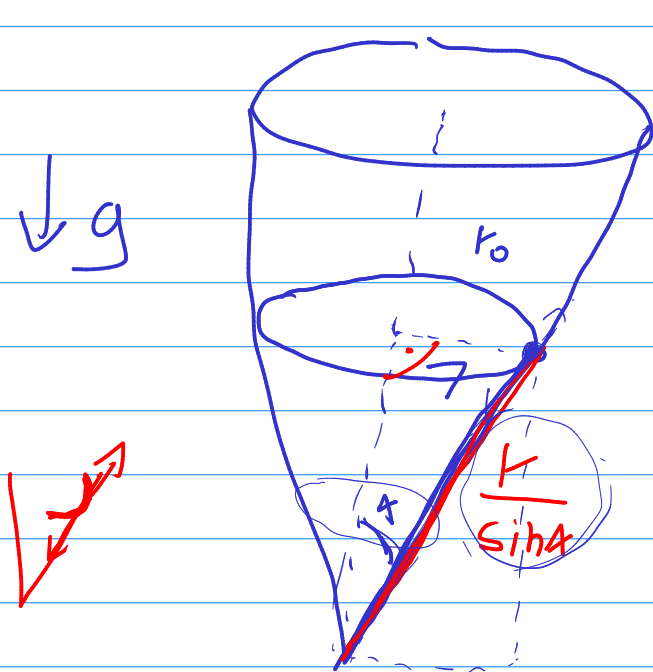
$$y = R(1 - \cos \theta)$$

$$\left. \begin{array}{l} x(T) = x_p \\ y(T) = y_p \end{array} \right\} \quad x = \frac{x_p t}{T - \frac{\sin T}{2}} - \frac{x_p \sin 2t}{2T - \sin 2T}$$

$$x_p = \frac{x_A}{\frac{T - \sin 2T}{2}} (t - 2 \sin 2t)$$

$$y_p = \frac{y_p}{2 \sin^2 T} - \frac{1}{2} y_p \frac{\cos 2t}{\sin^2 T}$$

$$3) L = L(x, y, \dot{y}) \quad L \sim y$$



$$x = r \cos \varphi$$

$$y = r \sin \varphi$$

$$z = \frac{r}{\tan \alpha}$$

$$L = \frac{1}{2} m v^2 - m g z$$

$$L = \frac{1}{2} m \left( (\dot{r} \cos \varphi - r \sin \varphi \dot{\varphi})^2 + (\dot{r} \sin \varphi + r \cos \varphi \dot{\varphi})^2 + \frac{\dot{r}^2}{\tan^2 \alpha} \right) - m g \frac{r}{\tan \alpha}$$

$$\dots$$

$$L = \frac{1}{2} m \left( \dot{r}^2 + r^2 \dot{\varphi}^2 + \frac{\dot{r}^2}{\tan^2 \alpha} \right) - m g \frac{r}{\tan \alpha}$$

$$L = \frac{1}{2} m \left( \frac{\dot{r}^2}{\sin^2 \alpha} + r^2 \dot{\varphi}^2 \right) - m g \frac{r}{\tan \alpha}$$

$$1 + \frac{1}{\tan^2 \alpha} = \frac{\tan^2 \alpha + 1}{\tan^2 \alpha} = \frac{\frac{\sin^2 \alpha}{\cos^2 \alpha} + \frac{\cos^2 \alpha}{\cos^2 \alpha}}{\frac{\sin^2 \alpha}{\cos^2 \alpha}} = \frac{\sin^2 \alpha + \cos^2 \alpha}{\sin^2 \alpha} = \frac{1}{\sin^2 \alpha}$$

$$L = L(x, y, y')$$

$$(x, y) \rightarrow (u, v)$$

$$L = \frac{y^2}{x^2 y'^2}$$

$$y \rightarrow f(u, v)$$

$$x \rightarrow f(u, v)$$

$$\frac{\partial L}{\partial v} = 0$$

??

$L \propto \varphi$

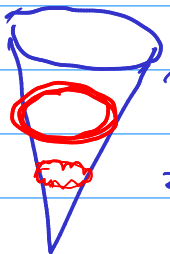
$$\frac{\partial L}{\partial \dot{\varphi}} = \text{konst}$$

$$m r^2 \dot{\varphi} = \text{konst} = L$$

$$\frac{\partial L}{\partial r} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{r}} \right)$$

$$\frac{-mg}{\sin^2 A} + m r \dot{\varphi}^2 = \frac{m}{\sin^2 A} \ddot{r}$$

$$\ddot{r} = \frac{L^2 \sin^2 A}{m^2 r^3} - g \cos A \sin A \quad | \cdot \dot{r}$$



- 1)  $r = r_0 = \text{konst}$   $\omega$   $r = r(t)$   
2)  $r = r_0 + \epsilon \delta(t)$   $\Omega$  } Harvard 6.18

$$\ddot{r} \dot{r} = \dot{r} A \frac{1}{r^3} - B \dot{r}$$

$$\frac{d}{dt} \left( \frac{1}{2} \dot{r}^2 \right) = -\frac{A}{2} \frac{d}{dt} \left( \frac{1}{r^2} \right) - B \frac{d}{dt} (r)$$

$$\frac{1}{2} \dot{r}^2 + \frac{A}{2r^2} + B r = C$$

$$\frac{dr}{dt} = \sqrt{-\frac{A}{r^2} - 2B r + C}$$

Zadání na příště



Zadání čas  $T$  jaká bude trajekto  
rie letadla tak aby  $S$  (uzavřená tražť)  
byla co největší