


TUTORIAL 1

1. Suppose V is a vector space over $\mathbb{K} = \mathbb{R}$ or \mathbb{C} .

$$GL(V) = \{\text{linear isomorphisms } V \rightarrow V\}$$

Its Lie algebra is $gl(V) = \{\text{linear maps } V \rightarrow V\}$
 $= V^* \otimes V$

with Lie bracket the commutator of endomorphisms of V :

$$[X, Y] = X \circ Y - Y \circ X \quad \forall X, Y \in gl(V).$$

Via choice of basis for V : $GL(V) \cong GL(n, \mathbb{K})$
 $gl(V) \cong gl(n, \mathbb{K})$

$[,] = \text{commutator of vectors}.$

Many Lie groups arise as Lie subgroups of $GL(V)$
consisting of linear isomorphisms of V preserving some additional
geometric structure on V .

- Suppose V is a real vector space.

Fix an orientation on V .

$GL_+(V) = \{ A \in GL(V) : A \text{ is orientation preserving} \}$

Viz choice of basis of V : $GL_+(V) = GL_+(n, \mathbb{R}) =$
 \mathfrak{G}

$$= \{ A \in \mathrm{GL}(n, \mathbb{R}) : A \text{ preserves standard orientation on } \mathbb{R}^n \}$$

$$= \{ A \in \mathrm{GL}(n, \mathbb{R}) : \det(A) > 0 \}.$$

$\mathrm{GL}(V) \cong \mathrm{GL}(n, \mathbb{R})$ has two connected components
 and $\mathrm{GL}_+(V) = (\mathrm{GL}(V))_+$.

If we fix not only on orientation but a volume form
 $\omega \in \Lambda^n V^*$ on V ,

$$\mathrm{SL}(V) = \{ A \in \mathrm{GL}(V) : A \text{ preserves } \omega \} \subseteq \mathrm{GL}_+(V)$$

$$SL(V) \simeq SL(n, \mathbb{R}) = \{ A \in GL(n, \mathbb{R}) : A \text{ preserves standard volume form } \mathbb{R}^n \}$$

$\left(\lambda_1 \cdot \lambda_2 \cdots \lambda_n, \text{ where } \lambda_i \text{ is diag} \right)$

(maps to the standard basis)

$$= \{ A \in GL(n, \mathbb{R}) : \det(A) = 1 \}.$$

- Lie group $\rightarrow \det(AB) = \det(A)\det(B)$.
- $SL(n, \mathbb{R}) = f^{-1}(0)$ $f = \det - 1 : GL(n, \mathbb{R}) \rightarrow \mathbb{R}$
 C^∞ and regular.

$$\begin{aligned} T_{Id} f &= T_{Id} \det \\ &\stackrel{\text{def}}{=} \text{tr} : gl(n, \mathbb{R}) \rightarrow \mathbb{R} \end{aligned} \quad \Rightarrow \quad SL(n, \mathbb{R}) \subseteq GL(n, \mathbb{R}) \subseteq H_n(\mathbb{R})$$

$$\implies \mathfrak{sl}(n, \mathbb{R}) = \ker(T_{\text{tr}}) = \{x \in \mathfrak{gl}(n, \mathbb{R}) : \text{tr}(x) = 0\}.$$

$$\dim(SL(n, \mathbb{R})) = \dim(\mathfrak{sl}(n, \mathbb{R})) = n^2 - 1.$$

For a complex vector space V fix a complex volume form ω giving rise to the standard orientation on V .

$$GL(V) \cong GL(n, \mathbb{C}) \subseteq \mathbb{C}^{n^2} \text{ open set rel.}$$

$$GL(n, \mathbb{C}) \text{ is connected} \quad : \det_{\mathbb{C}} : GL(n, \mathbb{C}) \rightarrow \mathbb{C} \setminus \{0\}$$

$$SL(V) = \{ A \in GL(V) : A \text{ preserves } \omega \} \cong \{ A \in GL(n, \mathbb{C}) : \det_{\mathbb{C}}(A) = 1 \}$$

connected.

It is a complex Lie subgroup, since $f = \det_C - 1$ is
homomorph.

$$\text{Lie}(SL(n, \mathbb{C})) = T_{\text{id}} SL(n, \mathbb{C})$$

is

$$\{ X \in gl(n, \mathbb{C}) : \text{tr}(X) = 0 \} .$$

$$\dim_{\mathbb{C}} (SL(n, \mathbb{C})) = n^2 - 1$$

$$\dim_{\mathbb{R}} (SL(n, \mathbb{C})) = 2n^2 - 2 .$$

- V is a real vector space. Equip it with a non-degenerate symmetric bilinear form $b: V \times V \rightarrow \mathbb{R}$ of signature (p, q) ($\dim(V) = p+q =: n$) .

$$O(V, b) = \{ A \in GL(V) : \underline{b(Av, Aw) = b(v, w)} \quad \forall v, w \in V \}.$$

Up to isomorphism, \exists a unique such bilinear form of sign. (p, q) on V , hence we can find an identification,

$$O(V, b) = O(\mathbb{R}^n, \underset{\nearrow}{\langle \cdot, \cdot \rangle}) =: \underline{O(p, q)}$$

where $\langle x, y \rangle := x^T \underbrace{\begin{pmatrix} I_p & \\ & -I_q \end{pmatrix}}_{I_{p+q}} y$ is the standard inner product

$$O(p, q) = \{ A \in GL(n, \mathbb{R}) : A^T I_{p,q} A = I_{p,q} \}. \quad (p, q).$$

$\| f^{-1}(0) \|$ $f(A) = A^T I_{p,q} A - I_{p,q}$ C^α -cont.

$$\underbrace{f : GL(n, \mathbb{R}) \rightarrow M_n^{\text{sym}}(\mathbb{R})}_{\leftarrow} \quad$$

$$T_A f(x) = \frac{d}{dt} \Big|_{t=0} f(A + tX) = \underline{x^t I_{n,q} A + A^t I_{n,q} X}.$$

$$S \in M_n^{\text{sym}}(\mathbb{R}) \quad X = \frac{1}{2} A I_{n,q} S \quad T_A f(X) = S.$$

$\Rightarrow O(n,q)$ is a subfield.

$$\mathcal{O}(n,q) := \ker(T_{\text{id}} f) = \{ X \in gl(n, \mathbb{R}) : \underline{x^t I_{n,q}^t + I_{n,q} X = 0} \}$$

$$\Theta = 0 : \mathcal{O}(n) = \mathcal{O}(n,0) = \{ X \in gl(n, \mathbb{R}) : X^t = -X \}$$

$$\dim(O(n,q)) = \frac{n(n-1)}{2}.$$

$$A^t I_{r,q} A = I_{r,q} \implies \det(A^t) \det(I_{r,q}) \det(A) = \det(I_{r,q})$$

$$\iff \det(A)^2 = 1$$

$$\iff \underline{\det(A) = \pm 1} .$$

$$SO(r,q) = O(r,q) \cap SL(u, \mathbb{R}) = O(r,q) \cap GL_+^+(u, \mathbb{R}).$$

$$\underline{O_+(r,q)} \subset \underset{R}{SO(r,q)} \subseteq O(r,q) \implies \frac{SO(r,q)}{SO(u)} = \underline{\alpha(r,q)}$$

has two connected components

$$\text{For } q=0 : O_+(u) = SO(n)$$

$\therefore V$ is a complex vector space, then \exists up to isomorphism
only one non-degenerate symmetric bilinear form

$$b: V \times V \rightarrow \mathbb{C} \quad \text{on } V.$$

(no signature over \mathbb{C} !).

$$(V, b) \cong (\mathbb{C}^n, \langle \cdot, \cdot \rangle)$$

¹ standard inner product $\langle x, y \rangle = x^t y$

$$O(n, \mathbb{C}) = \{ A \in GL(n, \mathbb{C}) : A^t = A^{-1} \}$$

$$\mathfrak{o}(n, \mathbb{C})_{\text{sol.}} = \{ x \in gl(n, \mathbb{C}) : x^t = -x \}$$

$$\underline{SO(n, \mathbb{C})} = \underline{O_+(n, \mathbb{C})}$$

complex
lie groups
of tangent dim. $\frac{n(n-1)}{2}$

V is complex vector space ..

and let $b : V \times V \rightarrow \mathbb{C}$ be a Hermitian inner product of signature (p, q)

(\cdot b is non-degenerate $\lambda \in \mathbb{C}$)

$$- b(\lambda v, w) = \overline{\lambda} b(v, w)$$

$$b(v, \lambda w) = \lambda b(v, w)$$

$$b(v, w) = \overline{b(w, v)}.$$

$$U(V, b) = \{ A \in GL(V) : L(Av, Aw) \\ = b(v, w) \}$$

\exists up to isomorphism only one such b ,

hence we can find an identification

$$U(V, b) =: U(p, q) = \{ A \in GL(n, \mathbb{C}) : \langle Av, Aw \rangle = \langle v, w \rangle \\ \forall v, w \in \mathbb{C}^n \}$$

$$\approx \underbrace{\{ A \in GL(n, \mathbb{C}) : \overline{A}^t F_{p,q} A = F_{p,q} \}}$$

where $\langle v, w \rangle = \overline{v}^t I_{p,q} w$ is the standard inner product of signature (p, q) .

$$U(n) := U(n, 0) = \{ A \in GL(n, \mathbb{C}) : \overline{A}^t = A^{-1} \}$$

$$n=1 \quad U(1) = \{ \alpha \in \mathbb{C} \setminus \{0\} : \overline{\alpha} \alpha = 1 \} = \{ \alpha \in \mathbb{C} \setminus \{0\} : |\alpha| = 1 \}$$

$$= S^1$$

$$= \text{circle group}.$$

$$U(r,q) = f^{-1}(0) \quad f: GL(n, \mathbb{C}) \rightarrow W = \{x \in gl(n, \mathbb{C}): \bar{x}^t = x\}$$

$$f(A) = \bar{A}^t \Gamma_{r,q} A - \Gamma_{r,q}$$

smooth and regular.

$$T_A f(x) = \left. \frac{d}{dt} \right|_{t=0} f(A + t x) = \bar{A}^t \Gamma_{r,q} x + \bar{x}^t \Gamma_{r,q} A.$$

$\Rightarrow U(r,q)$ is a real submfld.

and $u(r,q) = T_{Id} U(r,q) = \{x \in gl(n, \mathbb{C}): \Gamma_{r,q} x + \bar{x}^t \Gamma_{r,q} = 0\}$

$$u(n) = \{x \in gl(n, \mathbb{C}), \underline{x = -\bar{x}^t}\}$$

$$\dim(U(r,q)) = n^2 \Rightarrow \underline{n(n-1)} + n \cdot \cancel{x \in u(n), x \in \mathbb{C}}$$

Note $u(n)$ is not a complex vector space:

$$X \in u(n), \alpha \in \mathbb{C} : \overline{\alpha X}^t = \overline{\alpha} \overline{X}^t \stackrel{\uparrow}{=} -\bar{\alpha} X \neq -\alpha X$$

($U(r,q)$ is only a real Lie subgroup
of $GL(n, \mathbb{C})$!) unless $\alpha \in \mathbb{R}$.

$U(2)$ real Lie algebra

$$\begin{aligned} u(2) &= \{ X \in gl(2, \mathbb{C}) : X = -\bar{X}^t \} \\ &= \left\{ \begin{pmatrix} x & b+iy \\ a+ib & y \end{pmatrix} : x, y, a, b \in \mathbb{R} \right\}, \end{aligned}$$

Pauli matrices :

$$\sigma_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$\{\underline{i\sigma_0}, \underline{i\sigma_1}, \underline{i\sigma_2}, \underline{i\sigma_3}\}$ is a basis of the real vector space $u(2)$.

$$\begin{pmatrix} ix & a+ib \\ -a+ib & iy \end{pmatrix} = \frac{x+y}{2} i\sigma_0 + b i\sigma_1 + a i\sigma_2 + \frac{x-y}{2} i\sigma_3.$$

Remark : $\sigma_0, \dots, \sigma_3$ form complex basis of $gl(2, \mathbb{C})$.

$$\text{For } A \in U(p,q) \text{ we have } \det_{\mathbb{C}}(A) \frac{\det_{\mathbb{C}}(\bar{A}^t)}{\det_{\mathbb{C}}(A)} = 1$$

$\Rightarrow |\det_{\mathbb{C}}(A)|^2 = 1$

$$\underbrace{\det_{\mathbb{C}} : U(p,q) \rightarrow U(1)}_{\leftarrow} \Rightarrow SU(p,q) = \{ A \in U(p,q) : \det_{\mathbb{C}}(A) = 1 \}$$

is a real lie ~~subgroup~~ of dim $n^2 - 1$.

$$su(p,q) = \{ X \in gl(n, \mathbb{C}) : I_{p,q} X = -\bar{X}^t \bar{I}_{p,q}, \text{tr}(X) = 0 \}$$

• V vector space over $\mathbb{K} = \mathbb{R}, \mathbb{C}$.

\exists a unique up to isomorphism symplectic structure on V (i.e. $\omega_v : V \times V \rightarrow \mathbb{K}$ non-deg., skew-sym. bilinear form).

We can identify, $(V, \omega_v) \cong (\mathbb{K}^{2n}, \omega)$

$\omega(x, y) = x^t J_n y$. ^{↑ standard symplectic form.}

$Sp(2n, \mathbb{K}) = \{ A \in GL(2n, \mathbb{K}) : \omega(Ax, Ay) = \omega(x, y) \quad \forall x, y \in \mathbb{K}^{2n} \}$
 $= \{ A \in GL(2n, \mathbb{K}) : A^t J_n A = J_n \}$.

$$f(A) = A^t J_n A - J_n \quad f(A)^t = -f(A)$$

$\Rightarrow \mathrm{Sp}(2n, \mathbb{K})$ is a real (complex) Lie group

and $\mathrm{Sp}(2n, \mathbb{K}) = \ker(\mathrm{T}_{\text{def}}) = \{ x \in \mathfrak{gl}(2n, \mathbb{K}) \mid J_n x + x^t J_n = 0 \}$

$$\dim_{\mathbb{K}} \mathrm{Sp}(2n, \mathbb{K}) = 2n^2 + n$$
$$\begin{pmatrix} A & B \\ C & -A^t \end{pmatrix} \quad B = B^t \\ C = C^t.$$

$$U(n) = O(2n) \cap GL(n, \mathbb{C}) \cap \mathrm{Sp}(2n, \mathbb{R})$$

$$= O(2n) \cap GL(n, \mathbb{C}) = O(2n) \cap \mathrm{Sp}(2n, \mathbb{R})$$

$$= GL(n, \mathbb{C}) \cap \mathrm{Sp}(2n, \mathbb{R}).$$

\rightarrow Kähler manifold.

2. G lie group

$$\textcircled{1} \quad R_x = v^* L_{-x} \quad \forall x \in \mathfrak{g}.$$

$$(gh)^{-1} = g^{-1}h^{-1} \longleftrightarrow v \circ \rho^h = \underline{\lambda_{h^{-1}} \circ v}$$

If $\xi \in X_L(G)$, then $\underline{v^* \xi} \in X_R(G)$.

$$\underline{(\rho^h)^* v^* \xi} = \underline{(v \circ \rho^h)^* \xi} = (\lambda_{h^{-1}} \circ v)^* = v^* \underline{\lambda_{h^{-1}}^* \xi} = v^* \xi$$

$\forall h \in G$.

$$v^* s(e) = (T_e v)^{-1} \xi(e) = -\xi(e) \quad \text{if } \xi = L_{\xi(e)}$$

② follows from ①

$$[L_x, L_y] = L_{[x,y]}$$

$$\begin{aligned} [R_x, R_y] &= [v^* L_{-x}, v^* L_{-y}] = v^* [L_{-x}, L_{-y}] \\ &= v^*(L_{[x,y]}) = -R_{[x,y]}. \end{aligned}$$

③ (D, L_x) is a vector field on $G \times G$

which is μ -related to L_x . $T_{e \cdot h} X$

$$(T_{(g,h)}\mu)(o_g, L_x(h)) = T_h g L_x(h) = T_e(g h) x$$

Similarly, for (R_y, b) and R_y . $= L_x(g h)$.

$\Rightarrow D = \underbrace{[(b, L_x), (R_y, b)]}_{[L_x, R_y]} \text{ is } \mu\text{-related to}$

Since μ is surjective, this shows $[L_x, R_y](g) = 0$
 $\forall g \in G$.