





$$t = \varphi(\tau)$$

Reparametrizace

$f(\tau) = f(\varphi(\tau))$  nový parametr

mělo by platit

$$\left\langle \frac{df}{dt}, \frac{d^2f}{dt^2} \right\rangle \stackrel{?}{=} \left\langle \frac{df}{d\tau}, \frac{d^2f}{d\tau^2} \right\rangle$$

$= \omega$

$$\frac{df}{d\tau} = \frac{df}{dt} \cdot \frac{d\varphi}{d\tau}$$

$$\frac{d^2f}{d\tau^2} = \left( \frac{d^2f}{dt^2} \cdot \frac{d\varphi}{d\tau} \right) + \frac{df}{dt} \cdot \frac{d^2\varphi}{d\tau^2}$$

skalární funkce

$$(a, b, c) \perp \frac{df}{dt} = \left( \frac{df}{dt}, \frac{d^2f}{dt^2}, \frac{d^3f}{dt^3} \right)$$

$$\perp \frac{d^2f}{dt^2}$$

$$\perp \frac{d^3f}{dt^3}$$

$$\frac{de_1}{ds} \perp e_1 \quad (e_1, e_1) = 1 \quad \left| \frac{d}{ds} \right.$$

$$e_1, \frac{de_1}{ds} \text{ generují } \vec{w}$$

$$2 \left( \frac{de_1}{ds}, e_1 \right) = 0$$

$\Rightarrow \frac{de_1}{ds}$  ležící na přímce  
hlavní normály

$$\Phi(s) = x(s)^2 + y(s)^2 - \frac{z}{f(0)} y(s)$$

$$= (s + \alpha(s))^2 + \left( \frac{f(0)}{2} s^2 + \beta(s) \right)^2$$

$$- \frac{z}{f(0)} \left( \frac{f(0)}{2} s^2 + \beta(s) \right) =$$

žijící uvertit,  $\forall i \quad \frac{d^i \Phi(0)}{ds^i} = 0$

tedy  $i = 0, 1, 2$

•  $\Phi(0) = 0$

$$= s^2 + 2s\alpha(s) + \alpha(s)^2 + \frac{f(0)}{4} s^4 + f(0) s^2 \beta(s)$$

$$+ \mathcal{B}(s)^2 - \cancel{s^2} - \frac{2}{\mathcal{H}(0)} \mathcal{B}(s)$$

$f(t)$  obecný parametěr

$f(t(s)) = f(s)$  v parametrizaci  
 v rep. no oblok

$$\left\| \frac{df}{ds} \right\| = 1$$

||

$$\left\| \frac{df}{dt} \cdot \frac{dt}{ds} \right\| = 1$$

> 0

$$\left\| \frac{df}{dt} \right\| \cdot \frac{dt}{ds} = 1$$