

$A \otimes A \xrightarrow{m} A$   
 $d \downarrow \quad \downarrow d$   
 $A \otimes A \xrightarrow{m} A$

$d(x \cdot y) = (dx)y + (-1)^{|x|} x \cdot (dy)$   
 gradovaná derivace = Leibnizovo po.

Def.  $\varphi: C \rightarrow C$  je **gradovaná koderivace**, jestliže komutuje

$C \xrightarrow{\Delta} C \otimes C$   
 $\varphi \downarrow \quad \downarrow \varphi \otimes id + id \otimes \varphi$   
 $C \xrightarrow{\Delta} C \otimes C$

$(id \otimes \varphi)(x \otimes y) = (-1)^{|x||y|} x \otimes \varphi(y)$

pomocí prvku: Nechť  $\Delta(x) = \sum x_i \otimes x^i$ . Potom  $\Delta(\varphi(x)) = \sum (\varphi(x_i) \otimes x^i + (-1)^{|x_i||x^i|} x_i \otimes \varphi(x^i))$

### Bar konstrukce

Nechť  $A$  je augmentovaná dga,  $\bar{A} = \ker \varepsilon$  augmentační ideál

Definujeme  $BA = T^c(\bar{A}[1])$  jako grad. koderivace  $\bar{A}$  posunutě o +1  $(\bar{A}[1])_{n+1} = \bar{A}_n$

Na  $BA$  definujeme diferenciál, který bude koderivací,

takže  $BA$  bude dgc. Píšme pro  $x \in A_n$   $sx \in (A[1])_{n+1}$

$d(sx_1 \otimes \dots \otimes sx_n) = d^{\otimes}(\dots) + d^{alg}(\dots) =$

$\uparrow$  diferenciál na  $\bigoplus_{n \geq 1} \bar{A}[1]^{\otimes n}$

$= \sum \pm sx_1 \otimes \dots \otimes sx_{i-1} \otimes sdx_i \otimes sx_{i+1} \otimes \dots \otimes sx_n$   
 $+ \sum sx_1 \otimes \dots \otimes sx_{i-1} \otimes s(x_i x_{i+1}) \otimes sx_{i+1} \otimes \dots \otimes sx_n$

Let us study coderivations on  $T^c V$  more concretely

$x \in T^c V \xrightarrow{\Delta^{(m)}} T^c V \otimes \dots \otimes T^c V$   
 $d \downarrow \quad \downarrow d$   
 $T^c V \xrightarrow{\Delta^{(u)}} T^c V \otimes \dots \otimes T^c V$

$y = dx \leftarrow y = \sum y_n$

$q: T^c V \rightarrow V$  projection onto the summand  $V^{\otimes 1}$

To compute  $dx$ , we study  $\boxed{x = x_1 \otimes \dots \otimes x_k}$

$q^{\otimes u} d \Delta^{(u)}(x_1 \otimes \dots \otimes x_k) =$   
 $= \sum q^{\otimes u} (id^{\otimes (i-1)} \otimes d \otimes id^{\otimes (n-i)}) \Delta^{(u)}(x_1 \otimes \dots \otimes x_k) =$   
 $= \sum q^{\otimes u} ( (x_1 \otimes \dots \otimes x_{i-1} \otimes (x_i \otimes \dots \otimes x_j) \otimes x_{j+1} \otimes \dots \otimes x_k) )$   
 $= \sum x_1 \otimes \dots \otimes x_{i-1} \otimes \underbrace{(d(x_i \otimes \dots \otimes x_j))_1}_{\text{the part in length 1}} \otimes x_{j+1} \otimes \dots \otimes x_k$

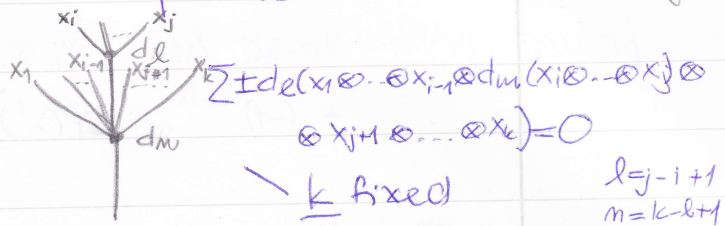
Define  $(dC)_1$  by  $d_e$  if  $l = j-i+1$

$d_e: V^{\otimes l} \subseteq T^c V \xrightarrow{d} T^c V \xrightarrow{q} V$   
 $= \sum x_1 \otimes \dots \otimes x_{i-1} \otimes d_e(x_i \otimes \dots \otimes x_j) \otimes x_{j+1} \otimes \dots \otimes x_k$   
 where s.t.  $l = j-i+1$

The point:  $d_\ell: V^{\otimes \ell} \rightarrow V$  can be arbitrary!

$A = \bar{A} \otimes k[t]$  graded  $k$ -module

Def.  $A_n$  <sup>(weak)</sup>  **$A_\infty$ -algebra**  $A$  is a dg-coalgebra structure on  $T^c \bar{A}[1]$  'cause it's differential  
 More concretely, it consists of maps  $d_\ell: \bar{A}[1]^{\otimes \ell} \rightarrow \bar{A}[1]$  deg -1 satisfying  $d^2=0$ .



Ex for low  $\ell$ :

•  $\ell=0$ :  $d_0: k \rightarrow \bar{A}[1]$  of deg -1  
 $\uparrow \mapsto \mathcal{R} \in A_2$

•  $\ell=1$ :  $d_1: \bar{A}[1] \rightarrow \bar{A}[1]$  of deg -1 "differential", but not quite  $\bar{A} \rightarrow \bar{A}$

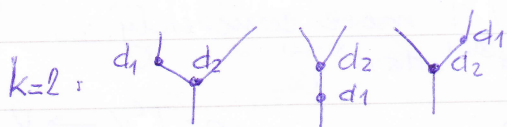
$d^2=0$  condition:  $k=0$   $\begin{matrix} d_0 \\ | \\ d_1 \end{matrix} \dots d_1(\mathcal{R})=0$



$d_1 d_1(x) \pm [d_1, x] = 0$   
 $d^2 \varphi = [\mathcal{R}, \varphi]$

•  $\ell=2$ :  $d_2: \bar{A}[1] \otimes \bar{A}[1] \rightarrow \bar{A}[1]$  deg -1  
 $m_2: \bar{A} \otimes \bar{A} \rightarrow \bar{A} \rightarrow \bar{A}$  deg 0  
 multiplication "A-bar"?

From now on, assume  $d_0=0$ . Then  $d_1 d_1=0$ .  $\rightarrow$  weak  $A_\infty$ -algebra



$d_1 d_1 x \otimes y = 0$   
 $x \otimes d_1 d_1 y = 0$   
 $d_1 x \otimes d_1 y$   
 $d_1 x \otimes d_1 y$  } by  $k=1$   
 } canceled out

$(d^2(x \otimes y)) = (d(\pm d_2(x \otimes y) \pm d_1 x \otimes y \pm x \otimes d_1 y)) = 0$   
 $= \pm d_1 d_2(x \otimes y) \pm d_2(d_1 x \otimes y) \pm d_2(x \otimes d_1 y)$   
 $= \pm d_1(x \cdot y) \pm (d_1 x) \cdot y \pm x \cdot d_1 y = 0$   
 $\rightarrow$  multiplication on  $A$  is a chain map



$\pm [d_1 d_3](x \otimes y \otimes z) = \pm d_1 d_3(x \otimes y \otimes z) \pm d_3(d_1 x \otimes y \otimes z) \pm d_3(x \otimes d_1 y \otimes z) \pm d_3(x \otimes y \otimes d_1 z) = 0$   
 $= \pm d_2(d_2(x \otimes y) \otimes z) \pm d_2(x \otimes d_2(y \otimes z)) = \pm (xy)z \pm x(yz)$

etc.

u. In general,  $\bar{A}[1] \xrightarrow{d} \bar{A}[1]$

$$s: \bar{A} \rightarrow \bar{A}[1] \quad \boxed{\text{deg } 1}$$

$$x \mapsto sx = x$$

$$\begin{array}{ccc} \bar{A} & \xrightarrow{m_2} & \bar{A} \\ \uparrow s & & \uparrow s \\ \bar{A} \otimes \bar{A} & & \bar{A} \end{array}$$

$m_2: \bar{A} \otimes \bar{A} \rightarrow \bar{A}$  has degree  $l + (-1) + (-1) = \underline{l-2}$

$m_1: \bar{A} \rightarrow \bar{A}$  diff

$m_2: \bar{A} \otimes \bar{A} \rightarrow \bar{A}$  mult.

$m_3: \bar{A} \otimes \bar{A} \otimes \bar{A} \rightarrow \bar{A}$  assoc. htpy

In particular, any augmented dga  $A$  is an  $A_{\infty}$ -algebra

by setting:  $m_1 = d$  (differential in  $A$ ),  $m_2 = \mu$  (mult. in  $A$ ),  $m_3 = 0, m_4 = 0, \dots$

$-d^2 = 0$  condition is  $[d_1, d_4] = 0 \dots$

$$\begin{array}{ccc} (-1)^{|x||y|} \bar{A}[1] \otimes \bar{A}[1] & \xrightarrow{d_2} & \bar{A}[1] \\ \uparrow s \otimes s & & \uparrow s \\ \bar{A} \otimes \bar{A} & \xrightarrow{m_2} & \bar{A} \\ (x \otimes y) & & (x \cdot y) \end{array}$$

also  $d_1(x) = -s dx$

$$d_2(sx \otimes sy) = (-1)^{|x|} s(x \cdot y)$$

$$\begin{aligned} d(sx_1 \otimes \dots \otimes sx_k) &= \sum \pm d_1(sx_i) \otimes \dots \otimes sx_k \\ &= \sum \pm sx_1 \otimes \dots \otimes sx_{i-1} \otimes s(dx_i) \otimes sx_{i+1} \otimes \dots \otimes sx_k \\ &= \sum \pm sx_1 \otimes \dots \otimes sx_{i-1} \otimes s(x_i x_{i+1}) \otimes sx_{i+2} \otimes \dots \otimes sx_k \end{aligned}$$

$\rightarrow T^c \bar{A}$  with the differential is called **bar** of  $A$ , denoted **BA**.

Dual situation:

an  $A_{\infty}$ -coalgebra  $C = \bar{C} \oplus k[\bar{C}]$  (a graded  $k$ -module)

is a dga-structure on  $T^c \bar{C}[1]$  tensor algebra

Again  $d: T^c \bar{C}[1] \rightarrow T^c \bar{C}[1]$  is determined by maps  $d_e: \bar{C}[1] \rightarrow \bar{C}[1]^{\otimes l}$ , namely  $d(x_1 \otimes \dots \otimes x_k) = \sum \pm x_1 \otimes \dots \otimes x_{i-1} \otimes d_e(x_i) \otimes x_{i+1} \otimes \dots \otimes x_k$

require:  $d_0 = 0$

$$d_e: \bar{C}[1] \rightarrow \bar{C}[1]^{\otimes l} \quad \text{deg } -1$$

$$w_e = \bar{c} \rightarrow \bar{c}^{\otimes l} \quad \text{deg } l-2$$

$d^2 = 0$  also translates into a condition on  $w_e$ 's.

(Ex.)  $C$  a dgc  $\Rightarrow C$  an  $A_{\infty}$ -coalg. By setting  $w_1 = d, w_2 = \Delta, w_3 = 0, w_4 = 0, \dots$

$$\begin{aligned} d(\bar{s}^1 x_1 \otimes \dots \otimes \bar{s}^1 x_k) &= \sum \pm \bar{s}^1 x_1 \otimes \dots \otimes \bar{s}^1 x_{i-1} \otimes \bar{s}^1 dx_i \otimes \bar{s}^1 x_{i+1} \otimes \dots \otimes \bar{s}^1 x_k \\ &\quad + \sum \pm \bar{s}^1 x_1 \otimes \dots \otimes \bar{s}^1 x_{i-1} \otimes (\bar{s}^1 \otimes \bar{s}^1) \Delta x_i \otimes \bar{s}^1 x_{i+1} \otimes \dots \otimes \bar{s}^1 x_k \end{aligned}$$

This dga is denoted by  $\Omega C$  ... **cobar** of  $C$ .

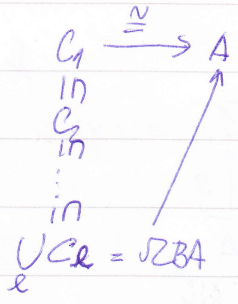
$$\text{DGA} \begin{array}{c} \xrightarrow{B} \\ \xleftarrow{\Omega} \end{array} \text{DGC}$$

**Theorem:** Let  $k$  be a field. Then  $\exists \mathcal{R}BA \xrightarrow{\text{dga-map}} A$  a  $q$ -iso.  
 $\exists \mathcal{C} \xrightarrow{\text{dgc-map}} B \mathcal{R}C$  a  $q$ -iso.

Pf:  $\mathcal{R}BA$  as an algebra is generated by  $\bar{s}^{-1}(s_{x_1} \otimes \dots \otimes s_{x_n}) =: (x_1 \dots | x_n)$   
 The map  $\mathcal{R}BA \rightarrow A$  sends  $(x) \mapsto x$   
 $(x_1 \dots | x_n) \mapsto 0 \quad n > 1$

There are subcomplexes of  $\mathcal{R}BA$  formed by products  $(x_1 \dots | x_n) \dots (z_1 \dots | z_m)$  with  $n + \dots + m \leq l$

each  $A_k$  is free ( $k$  field) restrict  $x_i$ 's to basis elts



show:  $\mathcal{C} \mathcal{C}_{\leq l-1}$  is contractible

contraction:  $(x)(x_1 \dots | x_n) \xrightarrow{h} (x | x_1 \dots | x_n)$  (the rest)  
 any other product  $\mapsto 0$

$DGC \xrightleftharpoons[\mathcal{B}]{\mathcal{R}} DGA$  it is an adjunction

$$\text{Hom}_{DGA}(\mathcal{R}C, A) \cong TC(C, A) \cong \text{Hom}_{DGC}(C, BA) \quad (*)$$

$\mathcal{R}C = T(\bar{s}^{-1}C)$  with a suitable differential  
 "twisting cochains"

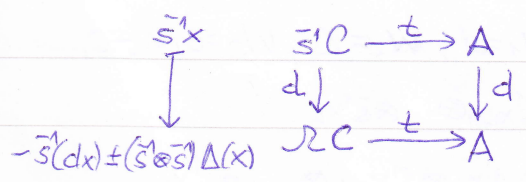
uniquely determined by  $\bar{s}^{-1}C \xrightarrow{t} A \quad ((\bar{s}^{-1}C)^{\otimes n} \xrightarrow{t^{\otimes n}} A^{\otimes n} \xrightarrow{\text{mult.}} A)$

subject to the condition that the algebra map induced by  $t$  commutes with the differential:

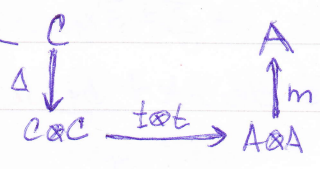
$$dt(x \cdot y) = d(t(x) \cdot t(y)) = d(t(x) \cdot t(y) \pm t(x) \cdot dt(y)) = -td(x)t(y) \mp t(x)td(y) =$$

suppose that  $td = -dt$  on  $x, y$   
 $= t(-d(x) \cdot y \mp x \cdot d(y)) = -td(x \cdot y)$

$\Rightarrow$  if  $td + dt = 0$  on  $\bar{s}^{-1}C$  then  $td + dt = 0$  on  $\mathcal{R}C$



in terms of  $t: C \rightarrow A$   
 $\frac{tdx \pm m(t \otimes t) \Delta(x)}{dt(x)} = 0$  twisting cochain condition



Cartan  
 $M-C$  equation  $[dt] + t^2 = 0$

The "dual version" is the same / proving (\*)

u.

counit ... the DGA-map that corresponds to the identity

$$\text{id}: BA \rightarrow BA \quad (C=BA)$$

$\Omega BA \rightarrow A$  *canonical twisting cochain*

↑  
write  $(x_1, \dots, x_n)$  for  $\bar{S}^{-1}(Sx_1 \otimes \dots \otimes Sx_n)$

$$(x_1, \dots, x_n) \mapsto \begin{cases} x_i & n=1 \\ 0 & \text{else} \end{cases}$$

$$\begin{array}{c} T^c(CSA) \\ \parallel \\ BA \end{array} \rightarrow A \quad \begin{cases} x_i & n=1 \\ 0 & \text{else} \end{cases}$$

**Theorem** This map  $\Omega BA \rightarrow A$  is a htpy equivalence if all  $k$ -modules are free (projective) - in particular, this is the case for  $k$  a field.

Pf.  $F_n =$  subcomplex of  $\Omega BA$  formed by elts of length  $\leq n$

where  $\text{length}(x_1, \dots, x_n) = n$  and  $\text{length}(x \cdot y) = \text{length}(x) + \text{length}(y)$

$$d(xy) = (dx)y \pm x(dy) \pm (x)(y) \pm (xy)$$

$F_n \subseteq \Omega BA \rightarrow A$  is an iso  
 $\{(x) \mid x \in A\}$

$$F_1 \subseteq F_2 \subseteq \dots \text{ and } \Omega BA = \bigcup_e F_e$$

$$H_x(\Omega BA) \cong \text{colim} (H_x F_1 \rightarrow H_x F_2 \rightarrow \dots)$$

(directed colimits are exact)

Therefore, ETS (= enough to show) :  $F_{e-1} \hookrightarrow F_e$  q-iso

The LES for  $0 \rightarrow F_{e-1} \rightarrow F_e \rightarrow F_e/F_{e-1} \rightarrow 0$  shows that it is enough that  $H_x(F_e/F_{e-1}) = 0$ . (a htpy id  $\sim 0$ )

A contraction of  $F_e/F_{e-1}$  is given by  $(x)(x_1, \dots, x_n) \cdot \{ \mapsto \pm (x|x_1, \dots, x_n) \}$

the diff on  $F_e/F_{e-1}$  is

$$d(x_1, \dots, x_n) = \sum \pm (x_1, \dots, x_{i-1}, dx_i, x_{i+1}, \dots, x_n) \pm \sum \pm (x_1, \dots, x_i)(x_{i+1}, \dots, x_n)$$

else  $\mapsto 0$   
the generators of  $\Omega BA$   $\{ (1, \dots, 1), \dots, (1, \dots, 1) \}$   
basis elts of  $A$

$$\begin{array}{ccc} \begin{matrix} n \geq 1 \\ (x_1, \dots, x_n) \end{matrix} & \xrightarrow{h} & 0 \\ & \searrow d & \downarrow d \\ \begin{matrix} \pm (x_1)(x_2, \dots, x_n) \text{ + other terms} \end{matrix} & \xrightarrow{h} & 0 \end{array}$$

$(x_1|x_2, \dots, x_n)$

If  $q$ -iso's are thought of as iso's then we get an equiv.

$$\mathbb{D}(\mathcal{DGC}) \simeq \mathbb{D}(\mathcal{DGA})$$

"derived category"

(later)

Improvement:  $\mathcal{DGC} \xrightleftharpoons[\mathcal{B}]{\text{nilt}} \mathcal{A}_{\infty}\text{-Alg}$

$BA = T^c(SA)$  with a correct differential =  $\mathcal{A}_{\infty}$ -str.

$\mathcal{A}_{\infty}C \dots$  add freely  $m_2, m_3, \dots$  to  $\bar{S}^1C$  with a suitable diff  
 $m_3(m_2(x, y), z, w)$

$$d(\bar{S}^1x) = \pm \bar{S}^1(dx) \pm m_2(\bar{S}^1 \otimes \bar{S}^1) \Delta^{(2)}x \leftarrow \mathcal{A}_{\infty}C$$

$$\pm m_3(\bar{S}^1 \otimes \bar{S}^1 \otimes \bar{S}^1) \Delta^{(3)}x$$

$$\pm \dots$$

Ex  $\mathcal{A}_{\infty}BA$   $d(x_1 | x_2 | x_3) =$  the same as in  $\mathcal{A}_{\infty}BA + m_3((x_1), (x_2), (x_3))$

The same works (with a lot of work, HOPEFULLY)  $\mathcal{D}(\mathcal{DGC}_{\text{nilt}}) \simeq \mathcal{D}(\mathcal{A}_{\infty}\text{-Alg})$

Consequence: For an  $\mathcal{A}_{\infty}$ -alg.  $A$ , we have  $\mathcal{A}_{\infty}BA \xrightarrow{q\text{-iso}} A$

Send all  $m_3$ 's,  $m_4$ 's to zero

$\mathcal{A}_{\infty}BA$

**Theorem:**

is  $q$ -iso

Rectification: Any  $\mathcal{A}_{\infty}$ -alg is  $q$ -iso to a dga.

Our goal now:  $A \dots \mathcal{A}_{\infty}\text{-Alg}$ ,  $f: A \xrightarrow{\sim} A'$  chain htpy equiv

$\Rightarrow A'$  is also an  $\mathcal{A}_{\infty}$ -alg and  $f$  is an " $\mathcal{A}_{\infty}$ -map"

Together:  $\mathcal{A}_{\infty}\text{-alg} =$  something htpy equiv. to a dga

Homotopy equiv's and strong deformation retractions (SDR)

SDR:  $(f, g, h): C \Rightarrow D$

where  $f: C \rightarrow D$  ch. map deg 0

$g: D \rightarrow C$  ch. map deg 0

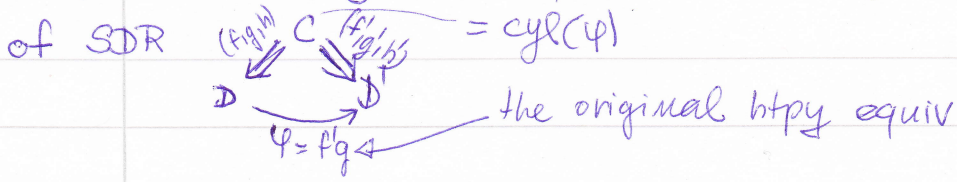
$h: C \rightarrow C$  deg 1

s.t.  $f \circ g = \text{id}$

$\text{id} - g \circ f = [d, h]$

$f \circ h = 0, h \circ g = 0, h^2 = 0$

Proposition: Any htpy equiv "can be replaced" by a Span of SDR



Suppose  $A$  is an  $A_{\infty}$ -alg.

$$A \xrightarrow[\quad]{\quad} A'$$

$f$  is a part of a SDR  $(f, g, h)$

$BA \rightarrow BA'$  ? what is the differential?  
 $T^c(SA) \rightarrow T^c(SA')$

with a certain differential

differential  $\equiv$  operations  $m_l: A'^{\otimes l} \rightarrow A'$  deg  $l-2$

$$m_l(x_1 \otimes \dots \otimes x_l) = \sum_{T \text{ tree}} \pm \prod m_{m_i} (h_{m_2} \dots (g_{m_1} \dots (g_{x_2} \dots (g_{x_3} \dots (h_{m_3} (g_{x_{l-2}} \dots g_{x_{l-1}}) \dots g_{x_l})) \dots))$$

what about coalg. ~~maps~~  $BA \rightarrow BA'$  ?

$$\text{tw. c. } BA \rightarrow A'$$

$$\text{i.e. } \bar{S}^1 BA \rightarrow A'$$

$$\oplus \bar{S}^1(SA)^{\otimes l} \rightarrow A'$$

$$(x_1 \dots x_l) \mapsto \sum_{T \text{ tree}} \pm \prod h_{m_i}$$

Def.  $A_{\infty}$ -map  $A \rightarrow A'$  = coalg. map  $BA \rightarrow BA'$

8-15.6- away