

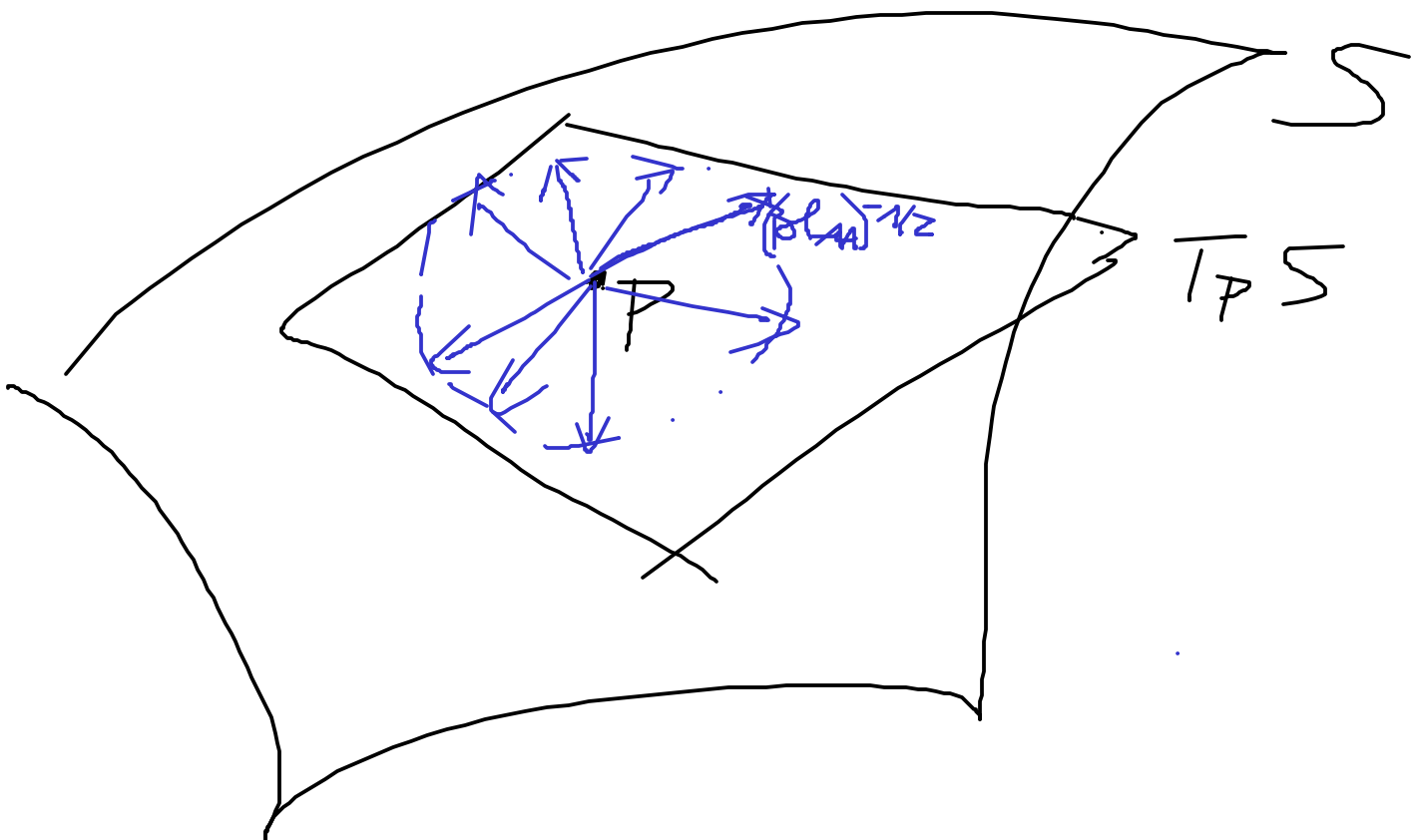
S

$$A \in T_p S$$

$$\Phi_2(A) = \dot{\gamma}$$

$f(t)$ 曲线

$$\Phi_2(A) := \left(\frac{d^2 \gamma}{dt^2}, h \right)$$



$$\Phi_1(a_1 f_1 + a_2 f_2) = \frac{1}{|ze|}$$

$$ze = \frac{\Phi_2(a_1 f_1 + a_2 f_2)}{\Phi_1(a_1 f_1 + a_2 f_2)}$$

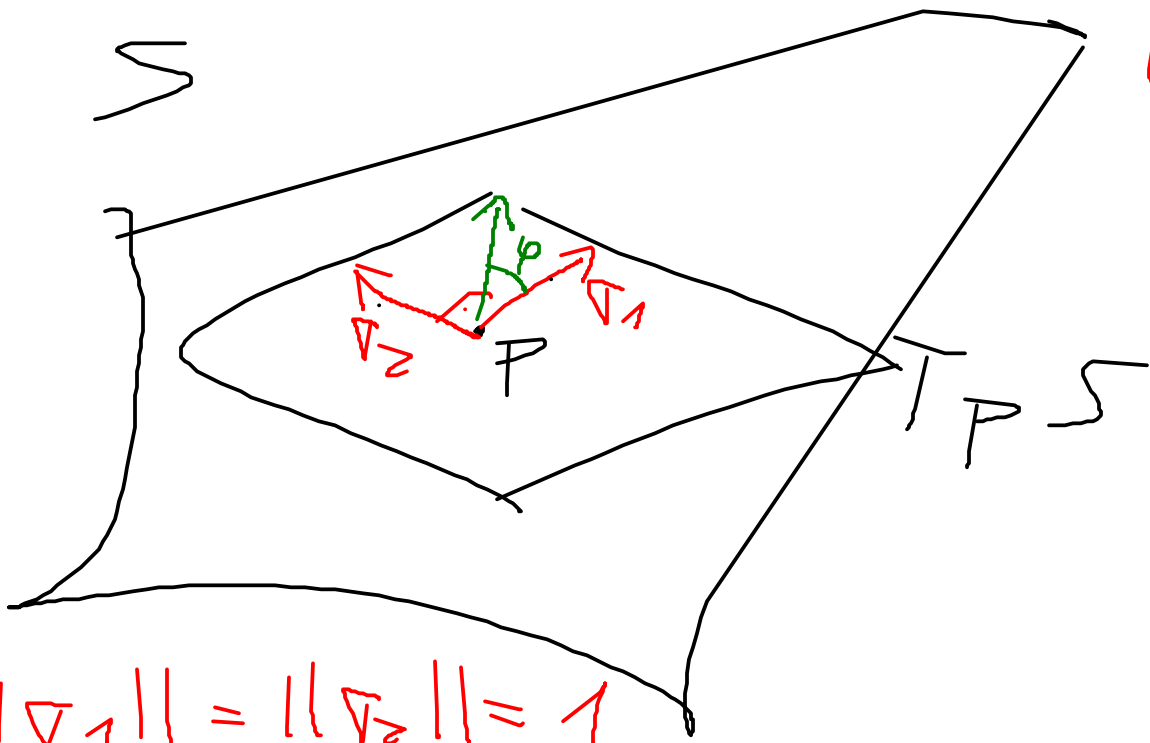
$$|\Phi_2(a_1 f_1 + a_2 f_2)| = 1$$

$$g_{11} a_1 b_1 + g_{12} (a_1 b_2 + a_2 b_1) + g_{22} a_2 b_2 = 0$$

$$(g_{11} a_1 + g_{12} a_2) b_1 + (g_{12} a_1 + g_{22} a_2) b_2 = 0$$

↓

$$(h_{11} a_1 + h_{12} a_2) b_1 + (h_{12} a_1 + h_{22} a_2) b_2 = 0$$



local
5-metric

$$\|\nabla_1\| = \|\nabla_2\| = 1$$

2-metric param. take care, it's

$$f_1 = \nabla_1 \quad \Rightarrow \quad g_{11} = g_{22} = 1, \quad g_{12} = 0$$

$$f_2 = \nabla_2 \quad , \quad h_{12} = 0$$

$$\mathcal{L}(A) = \frac{\overline{\mathcal{D}_2(A)}}{\overline{\mathcal{D}_1(A)}}$$

$$\mathcal{D}_1(f_i) = g_{ii} = 1$$

$$\mathcal{L}(\nabla_1) = \mathcal{L}e_1 = \frac{h_{11}}{1}$$

$$\|\mathcal{B}\| = 1$$

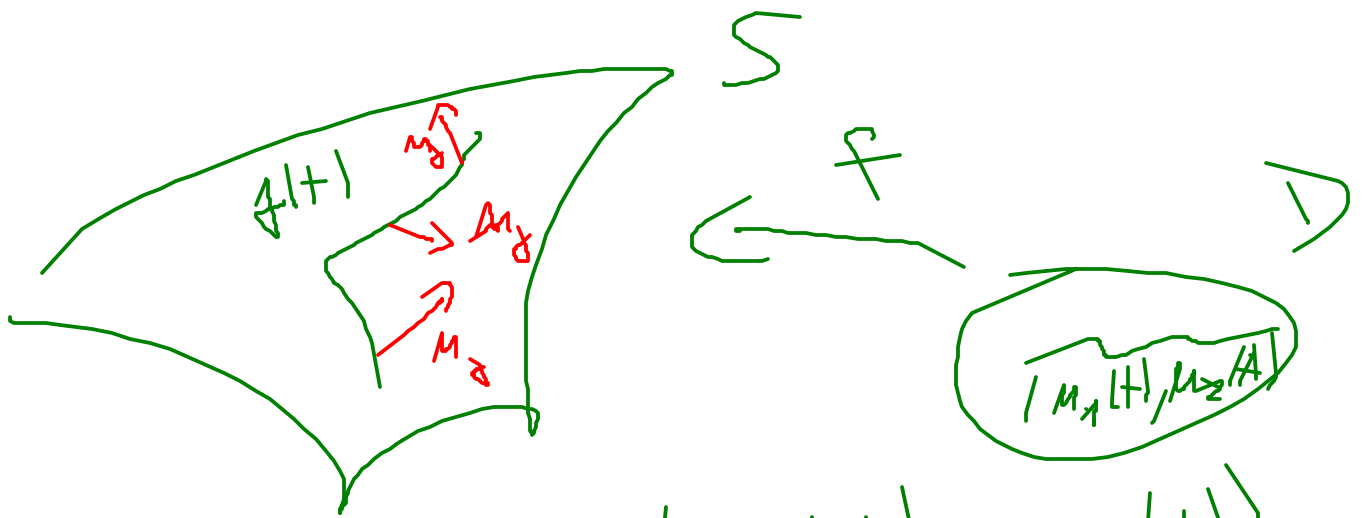
$$\mathcal{B} = \cos\varphi \cdot \nabla_1 + \sin\varphi \cdot \nabla_2$$

$\nabla_1 = f_1$ $\nabla_2 = f_2$

$$|e(B)| = \frac{\Phi_2(B)}{\Phi_1(B)} = \frac{\quad}{\quad}$$

$$\Phi_2(B) = h_{11} \cos^2 \varphi + h_{12} (\dots) + h_{22} \sin^2 \varphi$$

$$|e(B)| = |e_1| \cos^2 \varphi + |e_2| \sin^2 \varphi$$



$$dA(t) = F(\mu_1(t), \mu_2(t))$$

$$\mu_2(t) = \mu(\mu_1(t), \mu_2(t))$$

$$\langle m, m \rangle = 1 \quad | \partial_1$$

$$\langle m_1, m \rangle + \langle m_1, m_2 \rangle = 0 \Rightarrow m \perp m_1$$

$$\langle \delta_{ij} | M_j \rangle = -h_{ij}$$