

$$\text{INN} \left[ \mathcal{U}_2, \dots, \mathcal{U}_n \right] = \mathcal{U}$$

$$\left( \varphi \mapsto \text{id}_{\mathcal{U}_1} \right) \left( \mathcal{U}_2 \right) = \mathcal{U}_1$$

$$\varphi(\text{INN}) \subseteq \mathcal{U}$$

$$\mathcal{U}_1 \text{ is LN}$$

Zio gno

$$\sum_{j=1}^n c_j u_j = 0 \stackrel{?}{=} c_1 = \dots = c_n = 0$$

$$\left( \varphi \rightarrow \text{id}_V \right) \left( \sum_{j=1}^n c_j u_j \right) \stackrel{\text{ind. prod}}{=} \sum_{j=1}^n c_j (\varphi \text{id}_V)(u_j) = \sum_{j=1}^n c_j u_{j-1}$$

$$\Rightarrow c_1 u_1 = 0 \Rightarrow c_1 = 0 \quad \Rightarrow \quad c_2 = \dots = c_n = 0$$

$A \sim B$

$\cup$   
 $\cup$

$A \sim \bigcup_A = \bigcup_B \sim B$

$\subseteq$   
 $A \sim B$

$u_1, T(u_1), \dots,$

$u_2, T(u_2), \dots,$

$\dots$

$u_p, T(u_p),$

$T = \varphi - \text{Mid}_w$

$T a_1^{-1}(u_1)$

$T a_2^{-1}(u_2)$

$T a_p^{-1}(u_p)$

DR. WILDON

$$T = \mathbf{0}$$

Zeroldime lin. Körper  $\checkmark$

$$U_1 \dots U_m$$

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$$T \neq \mathbf{0}$$

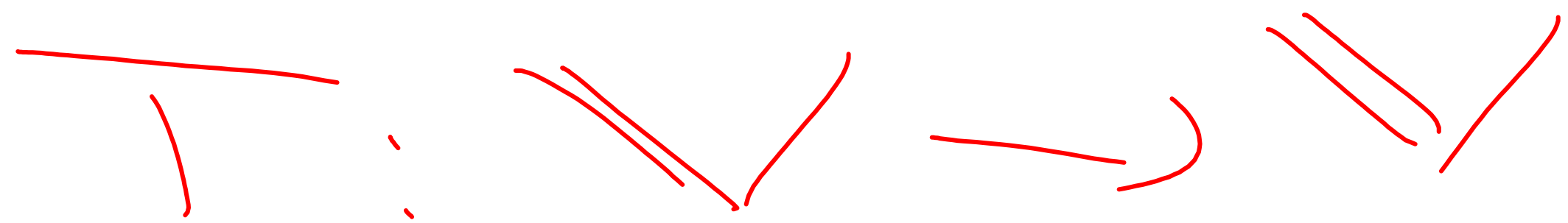
$$\lambda = \dim \operatorname{Im} T + \dim \ker T$$

$$\dim V = 1$$

$$T^2 = \mathbf{0}$$

$$\Rightarrow T = \mathbf{0}$$

$\dim V = n \quad \forall \mathbb{R} \subset \mathbb{C} \text{ no pda!}$



$$\dim V = \dim \overline{\text{Im } T} + \dim \overline{\text{Ker } T}$$

a)  $\dim \overline{\text{Ker } T} = 0 \Rightarrow T \text{ linj } \mathbb{R} \mathbb{C}$

b)  $\dim \overline{\text{Ker } T} = \dim V \Rightarrow T = 0$  není možná.

$$c) \quad 0 < \dim I_m T < \dim W$$

$$\exists \quad T/I_m T : I_m T \rightarrow I_m T$$

$$\Rightarrow$$

$$u_1, \dots, u_r$$

$$f_1, \dots, f_r$$

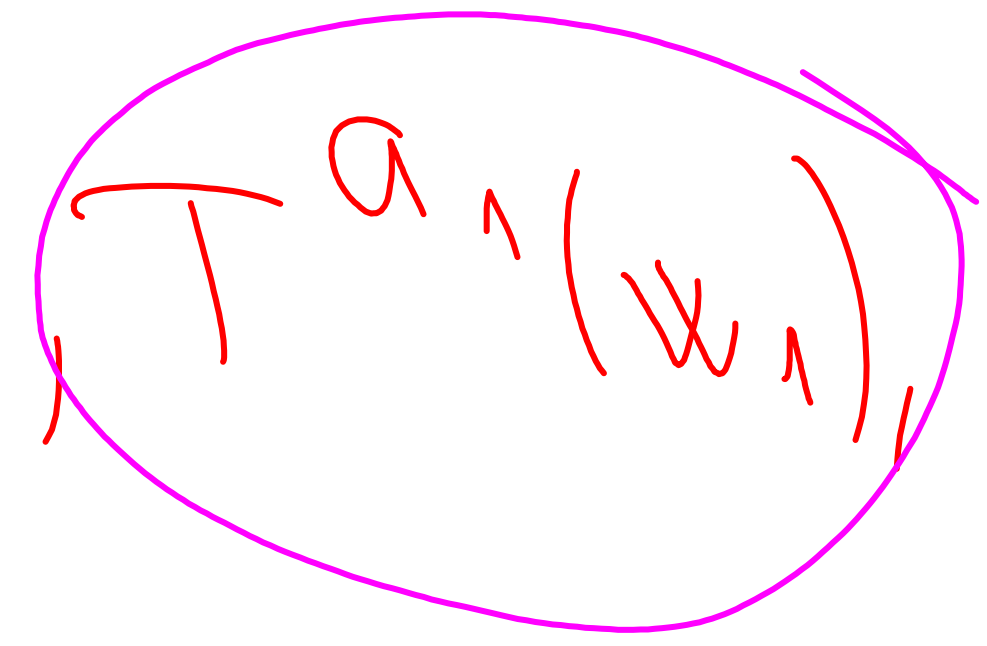
$$u_1, \dots, u_r \text{ basis } I_m T \quad \left( \begin{array}{c} T a_1 \dots \\ (U_1) \end{array} \right), \dots, \left( \begin{array}{c} T a_r \dots \\ (U_r) \end{array} \right)$$

$u_1 \in \text{Int}, \dots, u_2 \in \text{Int}$

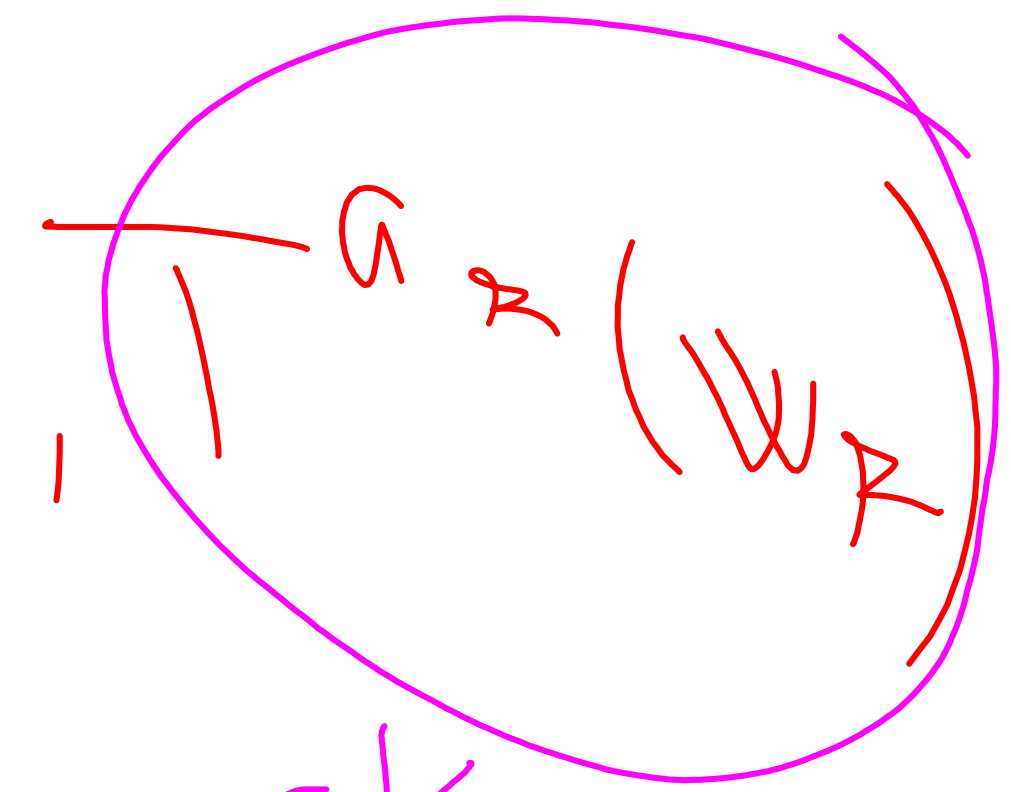
$\exists u_1 \in \mathbb{V}, T(u_1) = u_1, \dots$

$\dots, u_2 \in \mathbb{V}, T(u_2) = u_2$

$u_1 \in \mathbb{V}, T(u_1) = u_1, \dots$



$\in \text{Ker } T$

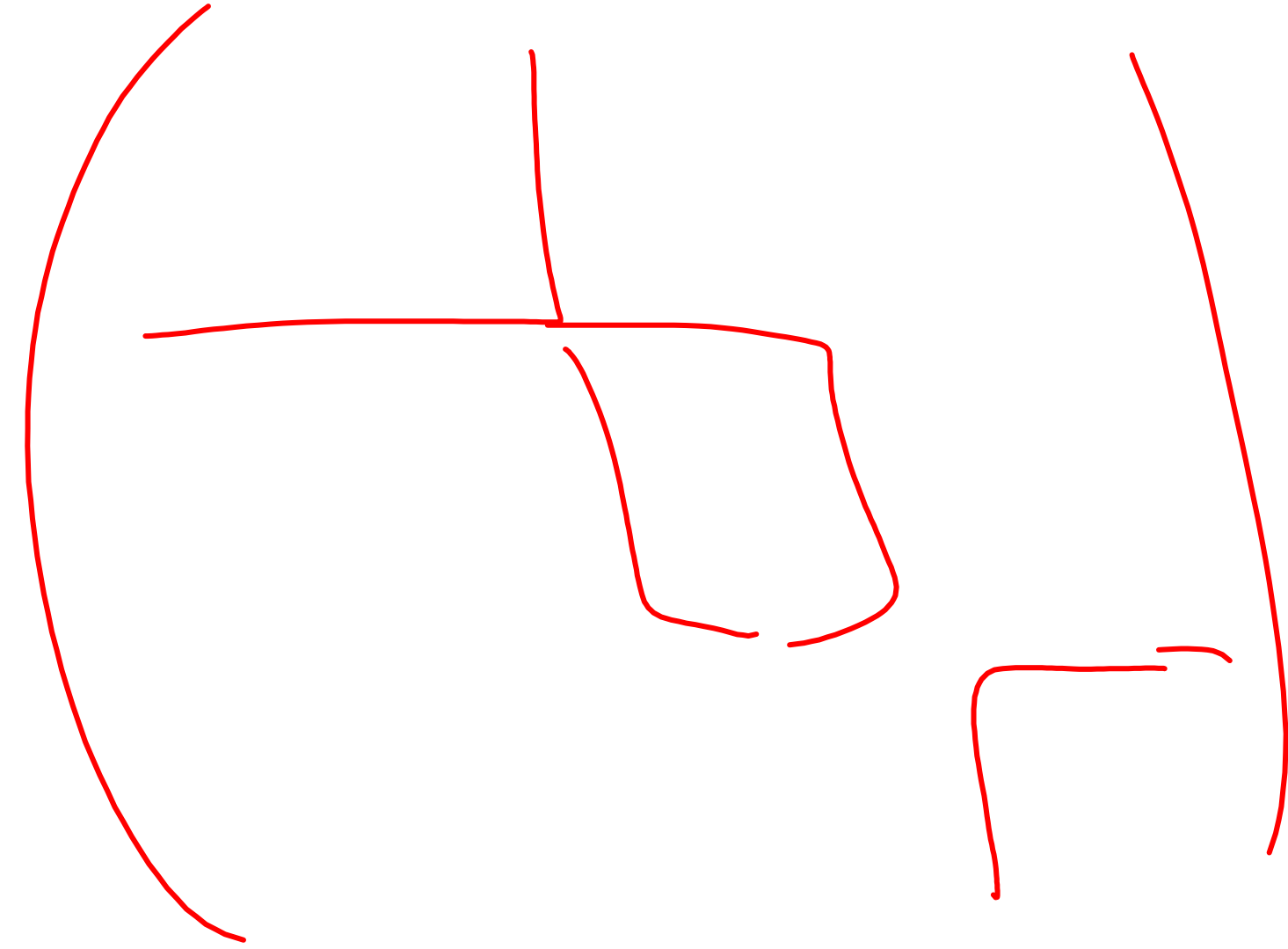


$\in \text{Ker } T$



$$T / \text{Ken}(U-X_1)^D : \text{Ken}(U-X_{21a})^D \rightarrow \text{Ken}(U-X_{1a})^D$$

JBLot



L.2.6.

~~$\mathbb{A}$~~  h.c.  $\varphi$

$$\text{Ken}(\varphi - \mathbb{A} \text{id}_V) \subseteq \text{Ken}(\varphi - \mathbb{A} \text{id}_V)^2$$

$$\subseteq \dots \subseteq \text{Ken}(\varphi - \mathbb{A} \text{id}_V)^n$$

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③  $\text{Ker}(\varphi - \text{id}_V) \supseteq \text{Im}(\varphi - \text{id}_V) = \{0\}$

$\Downarrow$

$\text{Im}(\varphi - \text{id}_V) \subseteq \text{Ker}(\varphi - \text{id}_V) \Rightarrow \text{Im}(\varphi - \text{id}_V) = \{0\}$

$(\varphi - \text{id}_V) \downarrow \{0\} = \{0\} \Rightarrow \{0\} \subseteq \text{Ker}(\varphi - \text{id}_V)$

$\Rightarrow (\varphi - \text{id}_V) \downarrow \{0\} = \{0\} \Rightarrow \{0\} \subseteq \text{Ker}(\varphi - \text{id}_V)$

$\Rightarrow \underline{\{0\}} = \{0\}$



$w_1, \dots, T^{\alpha_1}(w_1), \dots, w_2, \dots, T^{\alpha_2}(w_2),$

$R_1, \dots, R_n$   $\leadsto$  BAI ZH  $\checkmark$

LN

$$C^{\wedge} w_1 + \dots + \underline{C^{\wedge} T^{\alpha_1}(w_1) + \dots}$$

$$+ C^{\bowtie} w_2 + \dots + \underline{C^{\bowtie} T^{\alpha_2}(w_2) + \dots}$$

$$\underline{+ d_1 R_1 + \dots + d_n R_n = 0}$$

Pa aplikasi T dan name

$$C_1^1 u_1 + \dots + C_{a_1-1}^1 T^{a_1-1} (u_1) + \dots$$

$$+ C_1^R u_R + \dots + C_{a_R-1}^R T^{a_R-1} (u_R) = 0$$

2 IND. PRINT.

$$C_1^1 = \dots = C_{a_1-1}^1 = 0 =$$
$$\dots = C_{a_R-1}^R$$

$Z$  AdS,  $\mathbb{R}$   
 $T a_1(w_1) \dots T a_r(w_r), \mathbb{R}_1, \dots, \mathbb{R}_r$

ig keine Kont Madame i

$$C a_1 = 0 \parallel C a_2 \parallel \dots \parallel C a_r = d_1 \parallel \dots \parallel d_n.$$

$\Rightarrow$  LN

$$\begin{array}{c}
 W_1, T(W_1), \dots, T^{a_1}(W_1), \dots \\
 \dots, W_2, T(W_2), \dots, T^{a_2}(W_2)
 \end{array}$$

$$\mathbb{R}_1, \dots, \mathbb{R}_n$$

$$\dim \text{Im } T = a_1 + \dots + a_n$$

$$\dim V = \dim \text{Im } T + \dim \text{Ker } T$$



$$\begin{aligned}
 \dim V &= a_1 + a_2 + \dim \text{Ker } T \\
 &= (a_1 + 1) + (a_2 + 1) + \underbrace{1}_{\text{VI}}
 \end{aligned}$$