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$(M, g)$  is a Riemann manifold.

$\leadsto \exists!$  torsion-free affine connection  $\nabla$  s.t.  $\nabla g = 0$   
Levi-Civita connection of  $(M, g)$ .

- $\nabla g = 0 \implies$  induced parallel transport is orthogonal.
- Formula for the Christoffel symbols in terms of  $g$ .  
(torsion free  $\iff \Gamma_{ij}^k = \Gamma_{ji}^k$ ).

Prop. 6.29  $(M, g)$  Riem. mfd with Levi-Civita conn.  $\nabla$ .

Then the Riemannian curv.  $R \in \Gamma(\Lambda^2 T^*M \otimes \text{End}(TM))$ .

① As  $\begin{pmatrix} 0 \\ 4 \end{pmatrix}$ -tensor (via the metric) it is a section

$$\text{of } \underline{\Lambda^2 T^*M \otimes \Lambda^2 T^*M} \subseteq \Lambda^2 T^*M \otimes T^*M \otimes T^*M \doteq$$

$$g(R(\xi, \eta)(\rho), \sigma) \doteq \forall \xi, \eta, \rho, \sigma \in \Gamma(TM)$$

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$$- g(R(\xi, \eta)(\sigma), \rho) \doteq$$

$$\textcircled{2} \quad R(\zeta, \eta)(\rho) + R(\eta, \rho)(\zeta) + R(\rho, \zeta)(\eta) = 0$$

"Bianchi identity"

$$\forall \zeta, \eta, \rho \in T(TM)$$

(it holds for any torsion-free affine connection).

$$\textcircled{3} \quad g(R(\zeta, \eta)(\rho), \sigma) = g(R(\rho, \sigma)(\zeta), \eta) \quad (\text{Poisson symmetry})$$

(i.e.  $g(R(-, -)(-), -) \in T(\underline{S^2 \wedge^2 T^*M})$ )

Proof.

$$\nabla g = 0$$

① Follows from (\*) of Thm. 6.25.

$$\begin{aligned} \underline{g(\nabla_s \nabla_\eta e, v)} &= -g(\nabla_\eta e, \nabla_s v) + s \cdot g(\nabla_\eta e, v) \\ &= g(e, \underline{\nabla_\eta \nabla_s v}) - \underline{\eta \cdot g(e, \nabla_s v)} \\ &\quad - \underline{s \cdot g(e, \nabla_\eta v)} + \underline{\eta \cdot s \cdot g(e, v)}. \end{aligned}$$

$$\begin{aligned} \Rightarrow \underline{g(R(s, \eta)(e), v)} &= -g(R(s, \eta)(v), e) \\ &\quad + \cancel{\eta \cdot s \cdot g(e, v)} - \cancel{s \cdot \eta \cdot g(e, v)} \\ &\quad + \cancel{[s, \eta] \cdot g(e, v)} \end{aligned}$$

② Holds for any border-free volume connection

Exercise :  $[s, \eta] = \nabla_s \eta - \nabla_\eta s$ .

③ Follows from ① and ② =  $\left( R_g(s, \eta, \rho, \nu) \right)$   
 $= g(R(\rho, \eta)(\rho), \nu)$ .

- $R_g(\cancel{s, \eta}, \rho, \nu) + R_g(\eta, \rho, \cancel{s}, \nu) + \underbrace{R_g(\rho, s, \eta, \nu)}_{=0} = 0$
- $R_g(\eta, \rho, \nu, \cancel{s}) + R_g(\rho, \nu, \cancel{\eta}, s) + R_g(\nu, \eta, \rho, s) = 0$
- $R_g(\rho, \nu, \cancel{\eta}, s) + R_g(\nu, s, \cancel{\rho}, \eta) + R_g(s, \rho, \nu, \eta) = 0$
- $R_g(\nu, s, \cancel{\rho}, \eta) + R_g(s, \eta, \cancel{\nu}, \rho) + R_g(\eta, \nu, s, \rho) = 0$

Adding them gives:

$$2R_g(\underline{\rho}, \underline{\zeta}, \underline{\eta}, \underline{\nu}) = 2R_g(\underline{\eta}, \underline{\nu}, \underline{\rho}, \underline{\zeta})$$

□.

Prop. 6.30 Suppose  $(M, g^M)$  and  $(N, g^N)$  are Riem. mds with Levi-Civita connections  $\nabla^M$  and  $\nabla^N$  and let  $f: (M, g^M) \rightarrow (N, g^N)$  be isometry.

- ①  $f^* \left( \nabla_{\zeta}^N \eta \right) = \nabla_{f^* \zeta}^M f^* \eta \quad \forall \zeta, \eta \in T(TN)$ .
  - ②  $f^* R^N = R^M$  (equiv.  $(f^{-1})^* R^M = R^N$ ).
  - ③  $f$  maps geodesics to geodesics and  $f \circ \exp_x^M = \exp_{f(x)}^N \circ T_x f$ .
- (where defined)

Proof.

① see Thm. 6.14 (where we proved this for hypersurfaces).

② Follows from ① and def. of  $R^M$  and  $R^N$

$$\underline{R^M(f^* \zeta, f^* \eta)(f^* c)} = f^*(R^N(\zeta, \eta)(c)) \quad \forall \zeta, \eta, c \in T(TN)$$

③ For a curve  $c: I \rightarrow M$ ,  $f \circ c$  is a curve in  $N$  and has a vector field  $\eta$  along  $c$ ,  $t \mapsto T_{c(t)} f \eta(t)$  is a vector field along  $f \circ c$ .

$$\text{①} \Rightarrow T_{c(t)} f (\nabla_c^M \eta)(t) = \nabla_{f \circ c}^N T_{c(t)} f \eta(t)$$

$$\text{In particular, } (T_{c(t)} f \nabla_c^M c')(t) = (\nabla_{(f \circ c)}^N (f \circ c)')(t) \Rightarrow$$



$f$  maps geodesics to geodesics.

$c: t \mapsto \exp_x^M(t s_x)$  is a geodesic with  $c(0) = x$  and  $c'(0) = s_x$

and hence  $\tilde{c}: t \mapsto \underline{(f \circ \exp_x^M)}(t s_x)$  is a geodesic with  $\tilde{c}(0) = f(x)$

and  $\tilde{c}'(0) = T_x f s_x$ . By uniqueness,  $\tilde{c}(t) = \exp_{f(x)}^N(\underline{T_x f s_x})$

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Cor. 6.31 Suppose  $(M, g)$  is a connected Riem. mbd.

and  $f: (M, g) \rightarrow (M, g)$  an isometry. If  $\exists x \in M$

such that  $f(x) = x$  and  $T_x f = \text{Id}_{T_x M}$ , then

$f = \text{Id}_M$ .

□.

Def. 6.32  $(M, g)$  is a Riem. mfd. A vector field  $\zeta$  on  $M$  is called a Killing field (or infinitesimal isometry),

$$\text{if } \mathcal{L}_\zeta g = 0$$

$$\frac{d}{dt} \Big|_{t=0} (F_t^\zeta)^* g$$

$(\Leftrightarrow) F_t^{\zeta*} g = g$  whenever defined  
i.e.  $F_t^\zeta$  is a local isometry).

Prop. 6.33 (M, g) Riem. mfd.,  $\nabla$  Levi-Civito connection.

① A vector field  $\xi \in \Gamma(TM)$  is Killing

$$\iff g(\nabla_{\eta} \xi, \rho) + g(\nabla_{\rho} \xi, \eta) = 0 \quad (\text{Killing equation})$$

(i.e.  $\binom{0}{2}$ -tensor  $g(\nabla_{\xi}, -)$  is skew-symmetric).

② The set of Killing vector fields is a finite-dim. subalgebra of  $(\Gamma(TM), [\cdot, \cdot])$ .

Proof.

$$\begin{aligned}
 \textcircled{1} \quad \underline{\underline{d_s g}}(\eta, e) &= s \cdot g(\eta, e) - g(\overset{[s, \eta]}{\eta}, e) - g(\eta, \overset{[s, e]}{e}) \\
 &= \underbrace{s \cdot g(\eta, e)}_{\text{torsion-freeness of } \nabla} - \underline{\underline{g(\nabla_s \eta, e)}} + \underline{\underline{g(\nabla_\eta s, e)}} \\
 &= \underline{\underline{g(\nabla_\eta s, e)}} + \underline{\underline{g(\eta, \nabla_e s)}} \\
 &\quad \nabla g = 0
 \end{aligned}$$

(\*) Thm. 6.25

\textcircled{2} Killing equation is linear overdetermined system of PDEs.  
 $\Rightarrow$  solution space is subspace of  $\Gamma(TM)$ .

$\xi, \eta$  are Killing fields

$$d_{[\xi, \eta]} g = d_{\xi} d_{\eta} g - d_{\eta} d_{\xi} g = 0 - 0 = 0$$

$\Rightarrow$  set of Killing fields is subalgebra of  $(\Gamma(TM), [\cdot, \cdot])$

Finite-dimensionality follows from Cor. 6.30:

$\xi(x), (\nabla_{\xi})_x$  determines  $\xi$  on any connected component.

$$n + \frac{n(n-1)}{2} = \frac{n(n+1)}{2} \quad \text{dim}(M) = n$$

"dim( $\mathfrak{o}(n)$ )"

Finite-dimensionality of algebra of Killing fields is key to:

Thm. 6.34  $(M, g)$  is a Riem. mfd. of dim.  $n$ .

Then the isometry group  $\text{Isom}(M, g) = \{f: (M, g) \rightarrow (M, g) \mid f \text{ isometry}\}$   
(group w.r. to composition of maps.) is in a natural way a Lie group of dim.  $\leq \frac{n(n+1)}{2}$ .

Its Lie algebra is  $T_{\text{id}} \text{Isom}(M, g) = \{s \in \Gamma(TM) : s \text{ is Killing and complete}\}$   
with the Lie bracket given by the negative of the Lie bracket of vector fields.

### Ex. 1 $(\mathbb{R}^n, g_{\text{euc}})$

We have seen that  $F(x) = Ax + b$   $A \in O(n)$

is an isometry of  $(\mathbb{R}^n, g_{\text{euc}})$ .  $b \in \mathbb{R}^n$

$$\begin{aligned} \text{Euc}(n) &= \{F: \mathbb{R}^n \rightarrow \mathbb{R}^n : F(x) = Ax + b \text{ for } A \in O(n), b \in \mathbb{R}^n\} \\ &= \text{Isom}(\mathbb{R}^n, g_{\text{euc}}) \text{ by Cor. 6.31.} \end{aligned}$$

$F: \mathbb{R}^n \rightarrow \mathbb{R}^n$  isometry,  $F(0) = b \in \mathbb{R}^n$

$\Rightarrow \hat{F} = F - b$  is an isometry with  $\hat{F}(0) = 0$ .

$$T_0 \hat{F} =: A \in O(n)$$

$\Rightarrow \tilde{F} \circ A^{-1}$  is an isometry or a composite of isometries  
and  $(\tilde{F} \circ A^{-1})(b) = 0$

$$\Rightarrow T_b(\tilde{F} \circ A^{-1}) = T_b \tilde{F} \circ T_b A^{-1} = A \circ A^{-1} = \text{Id}_{\mathbb{R}^n}$$

" "

$$\Rightarrow \tilde{F} \circ A^{-1} = \text{Id}_{\mathbb{R}^n} \Leftrightarrow F = A + b$$

" "  
(F-b)

$$\dim(\text{Euc}(n)) = n + \frac{n(n-1)}{2} = \frac{n(n+1)}{2}.$$



Ex. 2  $(S^n, g_{rd})$

By construction of  $g_{rd}$  (being induced by  $\langle \cdot, \cdot \rangle$  on  $\underline{\mathbb{R}^{n+1}}$ )

$$O(n+1) \subseteq \text{Isom}(S^n, g_{rd}).$$

In fact,  $O(n+1) = \text{Isom}(S^n, g_{rd})$  again by Cor. 6.3  $\neq$

$$e_1 = (1, 0, \dots, 0) \in \mathbb{R}^{n+1}, \quad F \in \text{Isom}(S^n, g_{rd}).$$

$$\exists A \in O(n+1) \text{ s.t. } A F(e_1) = e_1 \quad \begin{array}{l} \parallel B \in O(n) \\ \parallel e_1^\perp \approx \mathbb{R}^n \end{array}$$

$$A \circ F \text{ is isometry fixing } e_1, \quad T_{e_1}(A \circ F) = T_{e_1} S^n \rightarrow T_{e_1} S^n$$

$$\left( \begin{array}{c|c} 1 & 0 \\ \hline 0 & B \end{array} \right) \in O(n+1)$$

$\tilde{F} := \left( \begin{array}{c|c} 1 & 0 \\ \hline 0 & B \end{array} \right) \circ A \circ F$  is an isometry fixing  $e_1$

and  $T_{e_1} \tilde{F} = \text{Id}_{T_{e_1} S^n}$ .

$\implies \tilde{F} = \text{Id}_{S^n} \iff F \in A^{-1} \cdot \left( \begin{array}{c|c} 1 & \\ \hline & B \end{array} \right) \in O(n+1)$ .

### Ex. 3 Hyperbolic space.

$\mathbb{R}^{u+1}$   $(x^0, x^1, \dots, x^u)$  coordinates.

equipped with the Lorentzian inner product (of signature  $(1, u)$ )

$$\langle x, y \rangle := -x^0 y^0 + \sum_{i=1}^u x^i y^i = x^t \begin{pmatrix} -1 & & \\ & 1 & \\ & & \ddots \\ & & & 1 \end{pmatrix} y$$

(Minkowski space).

$$H^u = \{ x \in \mathbb{R}^{u+1} : \langle x, x \rangle = -1, x^0 > 0 \} \subseteq \mathbb{R}^{u+1}$$

is an  $u$ -dim. submanifold.

$$T_x H^u = x^\perp \quad (g_{\text{hyp}})_x$$

Lorentzian inner product induces positive definite inner product  $\checkmark$  on

$$T_x H^k = x^\perp \quad \forall x \in H^k$$

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$$\{y \in \mathbb{R}^{k+1} : \langle x, y \rangle = 0\}$$

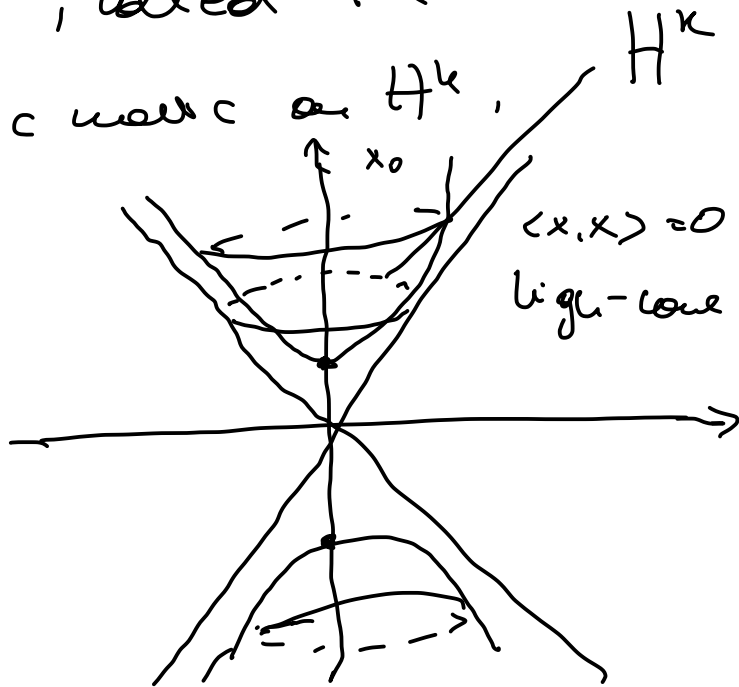
Lorentzian.

$\leadsto g_{hyp}$  is Riem. metric on  $H^k$ , called the

standard hyperbolic metric on  $H^k$ ,

What are geodesics?

What is the isometry group?







Proof. We know that  $\exp_x: U \rightarrow \tilde{U}$  is a diffeom.

for sufficiently small neighb.  $U$  of  $0 \in T_x M$  and  $\tilde{U}$  of  $x \in M$ .

By ③ of Prop. 6.29,  $\underline{f \circ \exp_x} = \exp_{f(x)} \circ \underline{T_x f} = \underline{\exp_x}$

$$\Rightarrow f|_{\exp_x(U)} = \text{Id}_{\tilde{U}} \leftarrow$$

$\parallel$   
 $\tilde{U}$

$$\Rightarrow \tilde{M} := \{y \in M : f(y) = y, T_y f = \text{Id}_{T_y M}\}$$

is a non-empty (since  $x \in \tilde{M}$ ) open subset.

But it is obviously also closed. By connectedness of  $M$ ,  $M = \tilde{M}$ .