


Tutorial 3

Homework 3

$$\left. \begin{array}{l} f, g \in C^0(N) \\ (f+g)(n) \end{array} \right\} := f(n) + g(n) \in \mathbb{R}.$$

① M, N topolog. spaces, $F: M \rightarrow N$ continuous map.

$$F^*: C^0(N) \rightarrow C^0(M)$$

$$F^*(f) = f \circ F: M \rightarrow \mathbb{R}$$

② F^* linear,

$$f, g \in C^0(N), \lambda \in \mathbb{R}$$

$$\Rightarrow \boxed{F^*(f + \lambda g) = F^*f + \lambda F^*g}$$

$$F^*(f + \lambda g)(m) = ((f + \lambda g) \circ F)(m) \stackrel{\text{def}}{=} \underline{f(F(m)) + \lambda g(F(m))}$$

$$(f + \lambda g)(F(m)) \quad \leftarrow$$

$$= (F^*f + \lambda F^*g)(m).$$

⑥ Assume M, N (smooth) m.f.d.s.

F is smooth $\iff F^*(C^\infty(N)) \subseteq C^\infty(M)$.

' \implies ' $g \in C^\infty(N)$

$F^*g = g \circ F : M \rightarrow \mathbb{R}$ is smooth by composition of smooth fcts.

' \impliedby ' Fix $x \in M$ and let (U, u) be a chart of N with $F(x) \in U$. We can extend u to a smooth fct

$$\tilde{u} : N \rightarrow \mathbb{R}^n \quad \tilde{u} = \begin{pmatrix} \tilde{u}^1 \\ \vdots \\ \tilde{u}^n \end{pmatrix}$$

s.t. (w.l.o.g.) $\tilde{u}|_U = u$.

By assumption, $F^* \tilde{u}^i = \tilde{u}^i \circ F: M \rightarrow \mathbb{R}$ is smooth $\forall i$.

Suppose (V, v) is a chart on N with $x \in V$.

$$\Rightarrow \begin{array}{ccc} \tilde{u} \circ F \circ v^{-1} & : & v(V \cap F^{-1}(U)) \rightarrow \tilde{u}(U) \\ \parallel & & \parallel \\ & & v(V \cap F^{-1}(U)) \quad \quad \quad u(U) \end{array}$$

$$\underline{u \circ F} \circ v^{-1}$$

is smooth by comp. of smooth local maps.

Hence, F is smooth by def. of smoothness for maps $M \rightarrow N$.

③ Assume F is a homeom. between spaces M and N .

$F^{-1}: N \rightarrow M$ continuous inverse.

F is a diffeom. $\Leftrightarrow F^*: C^0(N) \rightarrow C^0(M)$ is an isomorphism.

$$F \circ F^{-1} = \text{id}_N \quad F^{-1} \circ F = \text{id}_M$$

$$(F \circ F^{-1})^* = \text{id}_N^* = \text{id}_{C^0(N)} \quad (F \circ F^{-1})^* g = g \circ F \circ F^{-1}$$

$$= (F^{-1})^* F^* g$$

$$\underbrace{(F^{-1})^* \circ F^*}$$

$$\Rightarrow \boxed{(F^{-1})^* = (F^*)^{-1}}$$

So the statement follows from (b) -

$$u = \text{id}$$

$$(2) \quad \zeta(x, y, z) = 2 \frac{\partial}{\partial x} - \frac{\partial}{\partial y} + 3 \frac{\partial}{\partial z} \quad \text{v.f. on } \mathbb{R}^3$$

In cylindrical coordinates: $v^{-1}(r, \varphi, z) = (r \cos \varphi, r \sin \varphi, z = z)$

Jacobian of $u \circ v^{-1} = \text{id} \circ v^{-1}$

$$\begin{pmatrix} \cos \varphi & -r \sin \varphi & 0 \\ \sin \varphi & r \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Inverse is

$$\frac{1}{r} \begin{pmatrix} r \cos \varphi & r \sin \varphi & 0 \\ -\sin \varphi & \cos \varphi & 0 \\ 0 & 0 & r \end{pmatrix}$$

$$\frac{1}{r} \begin{pmatrix} r \cos \varphi & r \sin \varphi & 0 \\ \sin \varphi & \cos \varphi & 0 \\ 0 & 0 & r \end{pmatrix} \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} =$$

$$= \begin{pmatrix} 2 \cos \varphi - \sin \varphi \\ -\frac{2}{r} \sin \varphi - \frac{1}{r} \cos \varphi \\ 3 \end{pmatrix}$$

$$\zeta = (2 \cos \varphi - \sin \varphi) \frac{\partial}{\partial r} - \frac{2 \sin \varphi + \cos \varphi}{r} \frac{\partial}{\partial \varphi} + 3 \frac{\partial}{\partial z}$$

In spherical coordinates:

$$v^{-1}(r, \varphi, \theta) = (r \sin \theta \cos \varphi, r \sin \theta \sin \varphi, r \cos \theta)$$

Jacobian of ~~id~~ Void

$$\left. \begin{array}{l} -\frac{1}{r^2 \sin \theta} \left(\begin{array}{lll} -r^2 \sin^2 \theta \cos \varphi & -r^2 \sin^2 \theta \sin \varphi & -r^2 \sin \theta \cos \theta \\ r \sin \varphi & -r \cos \varphi & 0 \\ -r \sin \theta \cos \theta \cos \varphi & -r \sin \theta \cos \theta \sin \varphi & r \sin^2 \theta \end{array} \right) \end{array} \right\}$$

$$\Rightarrow \zeta = \left(2 \cos \varphi \sin \theta - \sin \theta \sin \varphi + 3 \cos \theta \right) \frac{\partial}{\partial r}$$

$$- \frac{2 \sin \varphi + \cos \varphi}{r \sin \theta} \frac{\partial}{\partial \varphi}$$

$$+ \frac{2 \cos \theta \cos \varphi - \cos \theta \sin \varphi - 3 \sin \theta}{r} \frac{\partial}{\partial \theta}$$

Jacobian $\text{d}o v^{-1}$:

$$\begin{pmatrix} \sin \theta \cos \varphi & -r \sin \theta \sin \varphi & r \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & r \sin \theta \cos \varphi & r \cos \theta \sin \varphi \\ \cos \theta & 0 & -r \sin \theta \end{pmatrix}$$

$$\textcircled{3} \quad M = \{ (x, y, z) \in \mathbb{R}^3 : x^2 + y^2 = 1 \}$$

$$M = f^{-1}(0) \quad f(x, y, z) = x^2 + y^2 - 1$$

$$T_{(x, y, z)} M = \ker \left(T_{(x, y, z)} f \right) = \{ (x', y', z') \in \mathbb{R}^3 : xx' + yy' = 0 \}$$

$$\begin{aligned} \text{grad } f(x, y, z) &= T_x f \begin{pmatrix} x^2 - 1 \\ xy \\ xz \end{pmatrix} = 2x \left(\underline{x^2 + y^2 - 1} \right) = 0 \\ &\quad \text{für } (x, y, z) \in M. \end{aligned}$$

Hence, ξ is tangent to M (i.e. $\xi|_M \in \mathcal{X}(M)$).

$$\eta \cdot f(x, y, z) = T_x f \begin{pmatrix} x \\ y \\ 2xz^2 \end{pmatrix} = 2x^2 + 2y^2 \neq 0$$

for $(x, y, z) \in M$.

$\Rightarrow \eta$ is not tangent to M .

(4) $M = \mathbb{R}^2$ $\xi(x, y) = y \frac{\partial}{\partial x}(x, y)$ $\eta(x, y) = \frac{x^2}{z} \frac{\partial}{\partial y}(x, y)$.

$$[\xi, \eta] = \left[y \frac{\partial}{\partial x}, \frac{x^2}{z} \frac{\partial}{\partial y} \right] = y^x \frac{\partial}{\partial y} - \frac{x^2}{z} \frac{\partial}{\partial x}.$$

$c(t) = \begin{pmatrix} c_1(t) \\ c_2(t) \end{pmatrix}$ is an integral curve for $[s, \eta]$

$$\Leftrightarrow \quad c_1'(t) = -\frac{c_1^2(t)}{2}$$

$$c_2'(t) = c_1(t)c_2(t).$$

$$\Rightarrow \quad c_1(t) = \frac{2}{t+a} \quad a \text{ constant}$$

$$c_2(t) = (t+a)^2 \cdot b \quad b \text{ constant.}$$

Initial condition: $c(0) = (x, y) \Rightarrow a = \frac{2}{x}$ and $b = \frac{x^2 y}{4}$

$$\Rightarrow \quad c_{(x,y)}(t) = F^{[s, \eta]}(t, (x, y)) = \left(\frac{2x}{2+t x}, \left(t + \frac{2}{x}\right)^2 \frac{x^2 y}{4} \right)$$

Not defined for $t = -\frac{z}{x}$; hence $[s, \eta]$ is not complete.

Some applications of the Frobenius Theorem.

Ex. Consider the following linear system of PDEs for $f: \mathbb{R}^3 \rightarrow \mathbb{R}$

$$(*) \quad -2z^2 \frac{\partial f}{\partial x} + 2x \frac{\partial f}{\partial z} = 0$$

$$-3z^2 \frac{\partial f}{\partial y} + 2y \frac{\partial f}{\partial z} = 0$$

Does (*) has any non-constant solutions?

$$\left. \begin{aligned} X &= -2z^2 \frac{\partial}{\partial x} + 2x \frac{\partial}{\partial z} \\ Y &= -3z^2 \frac{\partial}{\partial y} + 2y \frac{\partial}{\partial z} \end{aligned} \right\}$$

Span a rank 2 distribution

E on the subset

$$V = \{ (x, y, z) \in \mathbb{R}^3 : z \neq 0 \} \\ \subseteq \mathbb{R}^3$$

$$(X \cdot f = 0 \quad Y \cdot f = 0 \quad \text{is } (*) \text{)}.$$

$$\text{Moreover, } [X, Y] = -12xz \frac{\partial}{\partial y} + 8yz \frac{\partial}{\partial x} = \frac{4x}{z} Y - \frac{4y}{z} X$$

Hence, E is integrable by Frobenius. Then,

$\Rightarrow \exists$ locally around any $(x_0, y_0, z_0) \in V$ a chart (U, u)
s.t. E is spanned by $\frac{\partial}{\partial u_1}$ and $\frac{\partial}{\partial u_2}$.

(*) in coordinates $\begin{pmatrix} u^1(x,y,z) \\ u^2(x,y,z) \\ u^3(x,y,z) \end{pmatrix}$ is equiv. to $\frac{\partial f}{\partial u^1} = \frac{\partial f}{\partial u^2} = 0$.

Hence, $f = u^3$ is a solution and any identity in u suffic.
smooth weight h. of (x_0, y_0, z_0) is of the form $f(x,y,z) = g(u^3(x,y,z))$
for smooth fct. g in one variable.

Ex. System of PDEs for $f: \mathbb{R}^2 \rightarrow \mathbb{R}$.

$$\frac{\partial f}{\partial x}(x,y) = \alpha(x,y, f(x,y)) \quad (**)$$

$$\frac{\partial f}{\partial y}(x,y) = \beta(x,y, f(x,y))$$

α, β smooth fcts
def. on open subset $V \subseteq \mathbb{R}^3$.

Q When does (***) has a solution?

Necessary conditions for α and β :

$$\left(\frac{\partial}{\partial y} \alpha(x, y, f(x, y)) = \frac{\partial}{\partial x} \beta(x, y, f(x, y)) \right) \checkmark$$

since $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$

Chain rule \Rightarrow $\frac{\partial \alpha}{\partial y} + \beta \frac{\partial \alpha}{\partial z} = \frac{\partial \beta}{\partial x} + \alpha \frac{\partial \beta}{\partial z}$ (***)

(***) is the necessary condition for (**) to have a solution in a neighborhood of any point (x_0, y_0) with arbitrary value $f(x_0, y_0) = z_0$.

By Frobenius' Theorem, (***) is also sufficient: it implies that for any $(x_0, y_0, z_0) \in V$ there exists a neighborhood U of $(x_0, y_0) \in \mathbb{R}^2$ and a unique solution $f: U \rightarrow \mathbb{R}$ of (**) with $f(x_0, y_0) = z_0$.

Why? (**) prescribes the tangent plane to be the graph of f . The collection of the tangent planes defines a rank 2 distribution of V and (***) is equivalent to involutivity.

Suppose $f: U \rightarrow \mathbb{R}$ were a solution ($U \subseteq \mathbb{R}^2$ open subset) of $(*)$

Then $\psi: U \rightarrow \mathbb{R}^3$

$$\psi(x, y) = (x, y, f(x, y)) \quad (\psi \text{ param. of solut. gr}(f).)$$

is a diffeom. onto $\text{gr}(f)$.

$T_{\psi(x, y)} \text{gr}(f)$ is spanned by $\left\{ \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\}$

$$T_{(x, y)} \psi \left(\frac{\partial}{\partial x} \right) = \frac{\partial}{\partial x} + \frac{\partial f}{\partial x} \frac{\partial}{\partial z}$$

$$T_{(x, y)} \psi \left(\frac{\partial}{\partial y} \right) = \frac{\partial}{\partial y} + \frac{\partial f}{\partial y} \frac{\partial}{\partial z}$$

$$X = \frac{\partial}{\partial x} + \alpha \frac{\partial}{\partial z} \quad \text{v.f. on } V.$$

$$Y = \frac{\partial}{\partial y} + \beta \frac{\partial}{\partial z}$$

Span a rank 2 din. E on V.

E is involutive $\Leftrightarrow (**)$ holds.

* In this case through any point $(x_0, y_0, z_0) \in V$

\exists an integral subset. $N \subseteq V \subseteq \mathbb{R}^3$ with locally LOS

the form $g(t)$ for a smooth fd. $f: U \rightarrow \mathbb{R}$, U open
 $f(x_0, y_0) = z_0$. w:pl. of (x_0, y_0)