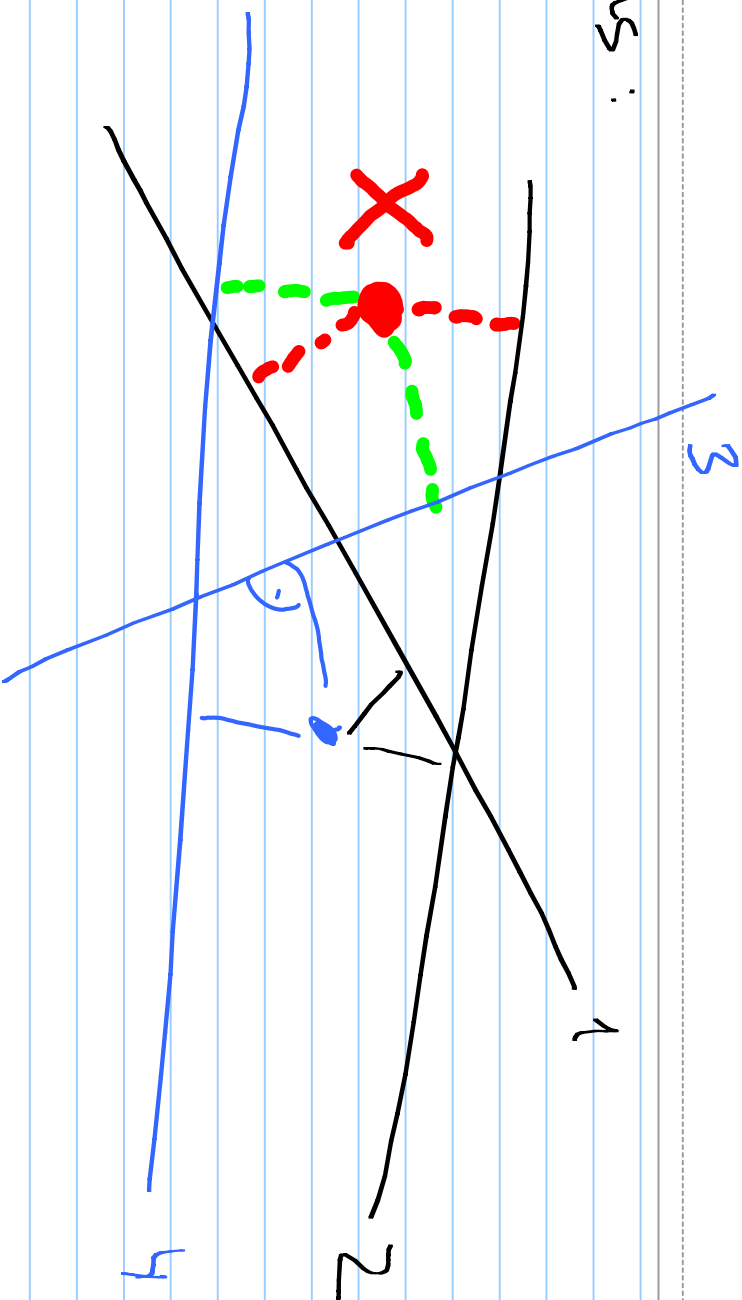


Pappus:

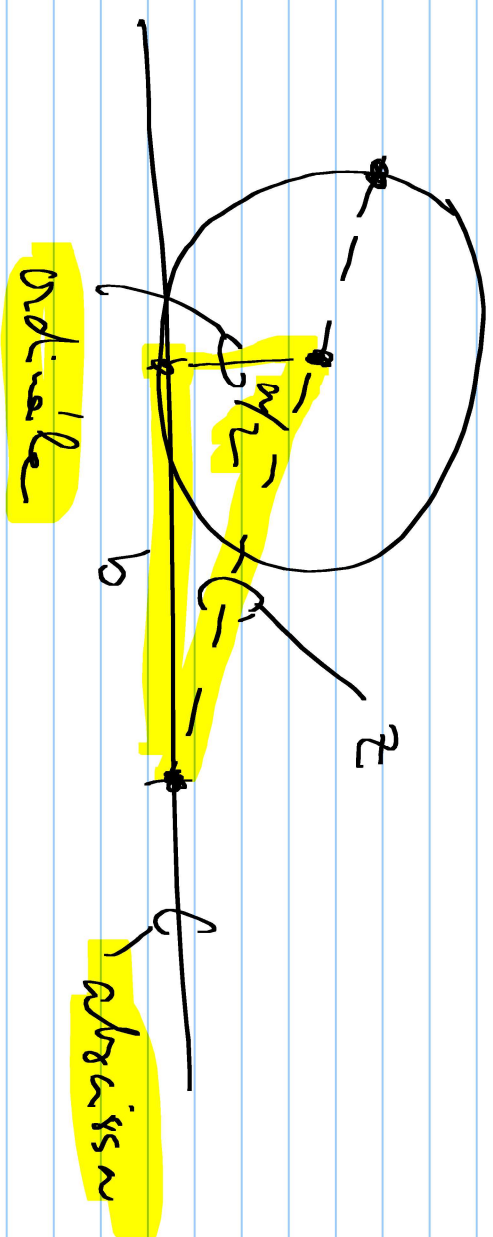


poloha X ostroú opíe najkrm lenivlaxcím

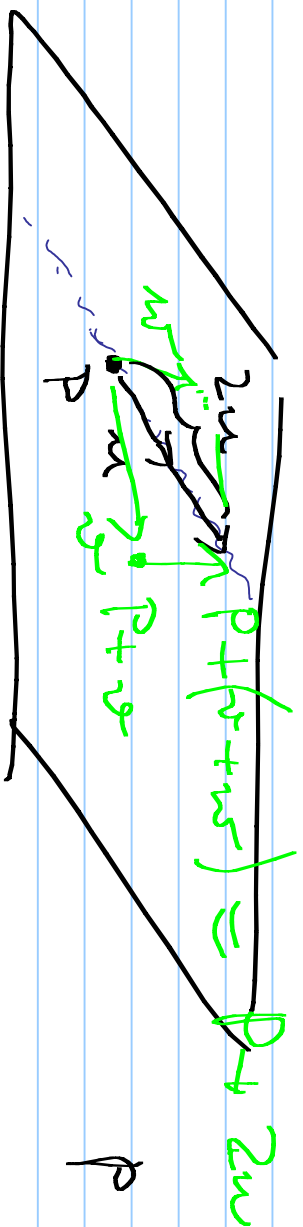
Descartes

$$z^2 = az + b^2$$

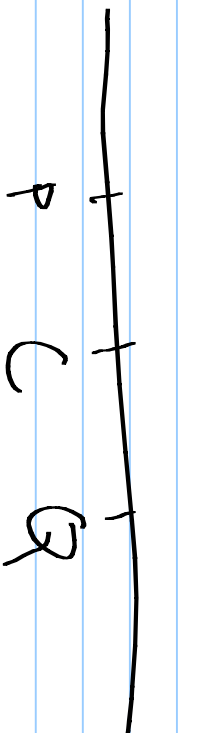
$$\left(z - \frac{1}{2}a\right)^2 - \frac{1}{4}a^2 = b^2$$



Analytische geometrie drus : VEKTOR



$$P = P + \vec{r}$$



$$\frac{|PC|}{|QP|}$$

Parallelogramm

$$2u = r + s$$

lineare lineare Relation:

$$\mathbb{R}^2 = \text{span}$$

$$a, b \in \mathbb{R} = \text{skalar}$$

$$\mathbb{R}^2 \sim \mathbb{R}^2$$

$$M = (m_1, m_2)$$

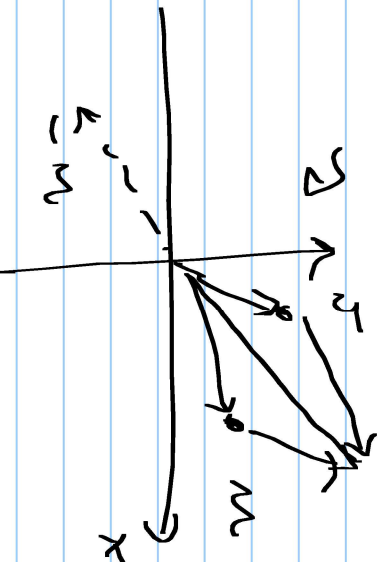
$$n + v = (n_1 + v_1, n_2 + v_2)$$

$$N = (n_1, n_2)$$

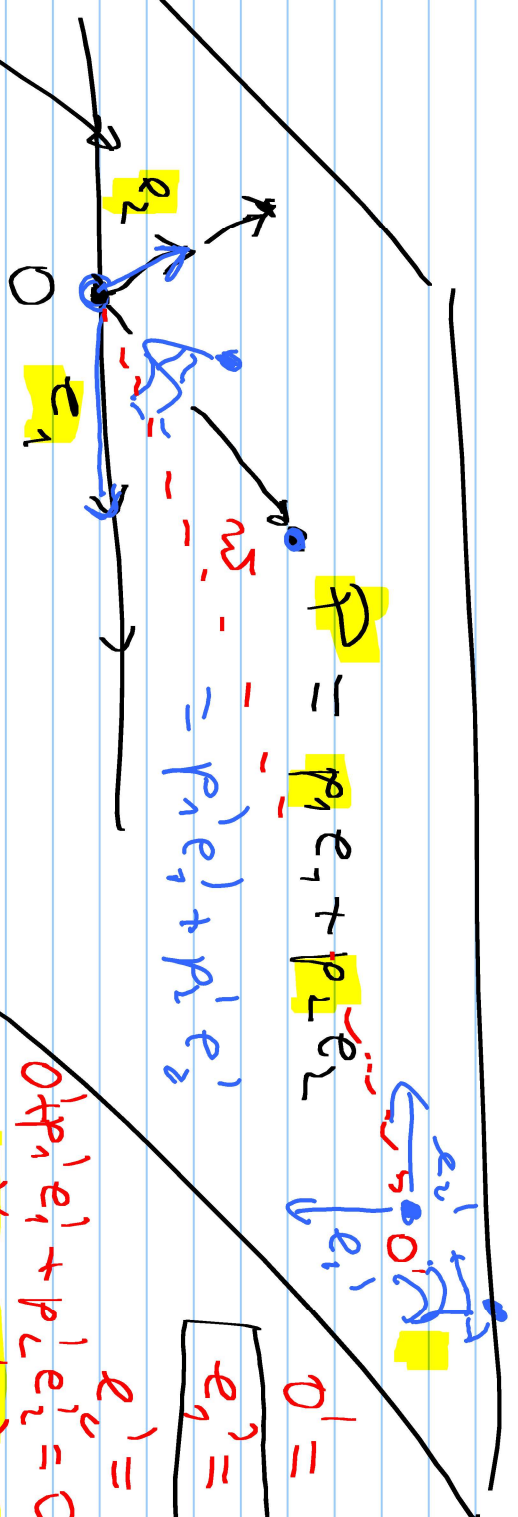
$$v = (v_1, v_2)$$

$$a n + b v =$$

$$(a n_1 + b v_1, a n_2 + b v_2)$$



Satz 1.12:



$$p = p_1 e_1 + p_2 e_2$$

$$v = p_1' e_1 + p_2' e_2$$

$$0' = 0 + 0$$

$$e_1' = a e_1 + b e_2$$

$$e_2' = c e_1 + d e_2$$

$$0 + p_1' e_1 + p_2' e_2 = 0 + 0 + p_1' (a e_1 + b e_2) + p_2' (c e_1 + d e_2)$$

matrix (x-matrix) $\begin{pmatrix} p_1' & p_2' \\ a & b \\ c & d \end{pmatrix}$ mit den Spaltenvektoren e_1 und e_2

$$p = 0 + 0 + p_1' a e_1 + p_1' b e_2 + p_2' c e_1 + p_2' d e_2$$

$$u = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

$$\begin{pmatrix} a & c \\ b & d \end{pmatrix} \cdot \begin{pmatrix} p_1 \\ p_2 \end{pmatrix} = \begin{pmatrix} ap_1 + cp_2 \\ bp_1 + dp_2 \end{pmatrix}$$

$$A \cdot (B+C) = A \cdot B + A \cdot C$$

$$A+B = B+A$$

$$A \cdot E = A$$

"

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$e_1 = ae_1 + be_2$$

$$A \cdot (B \cdot C) = (A \cdot B) \cdot C$$

$$P = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} + \begin{pmatrix} a & c \\ b & d \end{pmatrix} \cdot \begin{pmatrix} p_1 \\ p_2 \end{pmatrix} = \begin{pmatrix} p_1 \\ p_2 \end{pmatrix}$$

$$a_1 x_1 + a_2 x_2 = b_1$$

$$a_3 x_1 + a_4 x_2 = b_2$$

$$\begin{pmatrix} a_1 & a_2 \\ a_3 & a_4 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$B \cdot A \neq E$$

$$A \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$a \cdot b = c \quad a \neq 0$$

$$\underbrace{B \cdot A}_{=E} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = B \cdot \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$b = \frac{c}{a}$$

$$A^{-1} \text{ exist } \Leftrightarrow \det A = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

$$\det A = ad - bc \neq 0$$

$$ax + by = s$$

$$\underbrace{cx + dy = t}$$

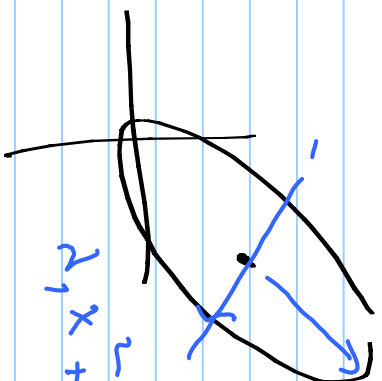
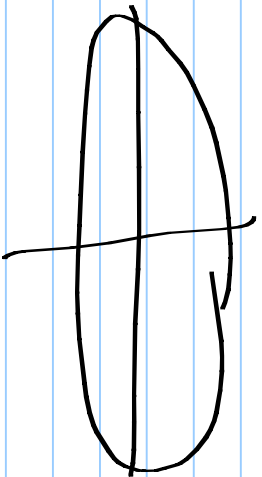
$$u = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

$$\|u\|^2 = u_1^2 + u_2^2$$

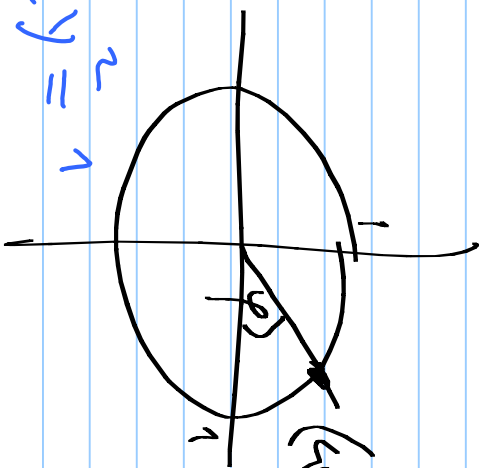
$$\|u\|^2 = u^T \cdot u$$

$$\left\| \begin{pmatrix} a \\ c \end{pmatrix} \cdot \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \right\| = \|u_1\|$$

Skalarprodukt



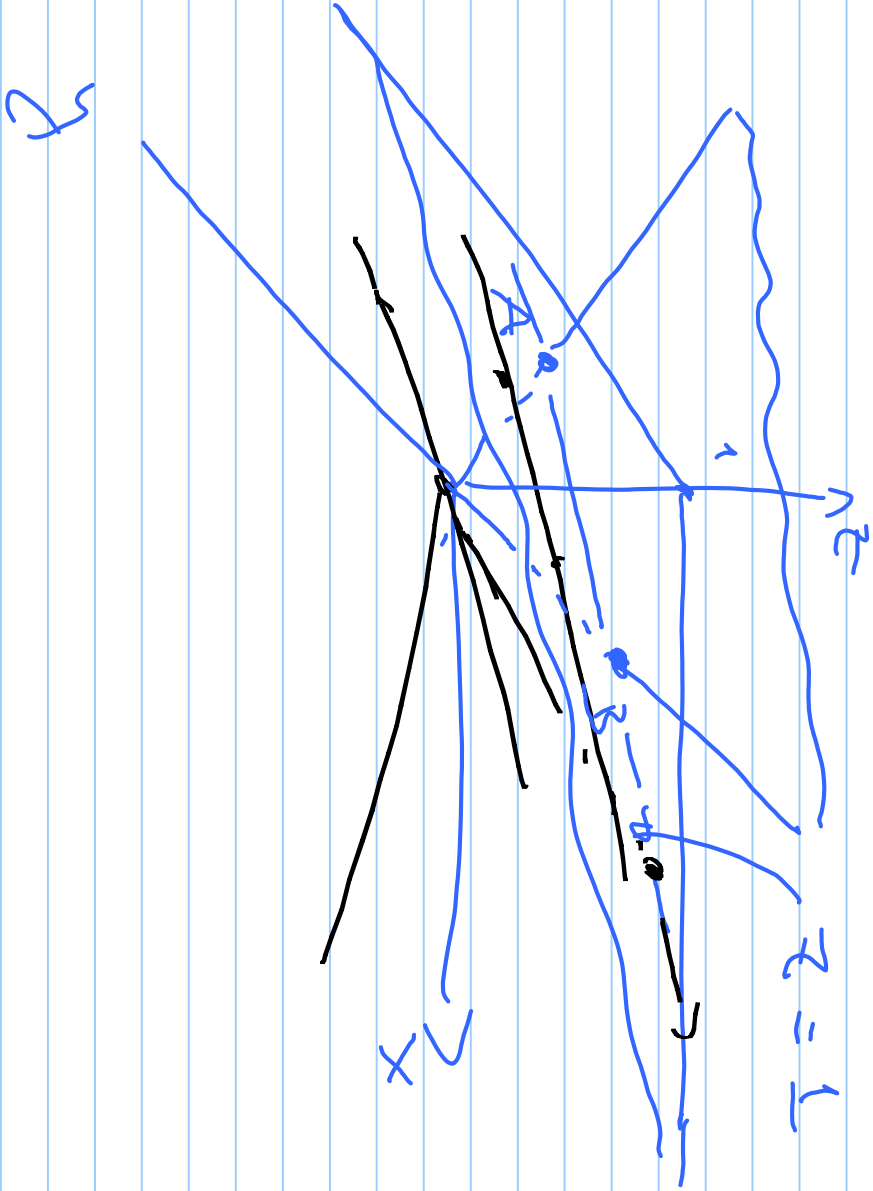
$$\lambda_1 x + \lambda_2 y = 1$$



$(\cos \varphi, \sin \varphi)$



$$|AC| + |CB| = |AB|$$



$(z: \Gamma: X)$